# Global properties of differential operators of constant strength 

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## 1. Introduction

For differential operators $P(D)$ with constant coefficients there is a rather complete theory on existence and regularity of solutions of the equation $P(D) u=f$. There exists a solution in every relatively compact open subset of $\mathbf{R}^{n}$ for an arbitrary right hand side $f \in \mathscr{D}^{\prime}\left(\mathbf{R}^{n}\right)$ (semi-global existence theorem). In an open set $\Omega \subset \mathbf{R}^{n}$ the equation can be solved with $u \in C^{\infty}(\Omega)$ for every $f \in C^{\infty}(\Omega)$ if $\Omega$ is $P$-convex and with $u \in \mathscr{D}^{\prime}(\Omega)$ for every $f \in \mathscr{D}^{\prime}(\Omega)$ if $\Omega$ is strongly $P$-convex. These results are exposed in Hörmander [4, Ch.III].

The class of differential operators of constant strength with variable coefficients (Definition 2.2 below) is closely related to operators with constant coefficients. An operator $P(x, D)$ of constant strength defined in an open set $\Omega \subset \mathbf{R}^{n}$ can be considered as a bounded perturbation of the operator $P_{x_{0}}(D)$ with constant coefficients obtained by freezing the coefficients of $P$ at a fixed point $x_{0} \in \Omega$. Peetre [9] proved that the equation

$$
\begin{equation*}
P(x, D) u=f \tag{1.1}
\end{equation*}
$$

can be solved locally for any $f$ (c.f. Hörmander [4, Ch. VII]). Also theorems on differentiability of solutions can be extended to differential operators of constant strength. The operator $P(x, D)$ is hypoelliptic in $\Omega$ if it has constant strength and for every $x \in \Omega$ the operator $P_{x}(D)$ is hypoelliptic (Hörmander [4, Theorem 7.4.1]). M. Taylor [11] has proved that conversely if $P$ is hypoelliptic and of constant strength then $P_{x}(D)$ is hypoelliptic for every $x$.

However a semiglobal existence theorem is not valid for all operators of constant strength. In fact by Pliš [10] there is an elliptic operator $P_{0}$ of order 4 in $\mathbf{R}^{3}$ such that there is a function $\varphi \in C_{0}^{\infty}$ with

$$
{ }^{t} P_{0} \varphi=0
$$

A necessary condition for solvability of the equation $P_{0} u=f$ in a neighborhood of $\operatorname{supp} \varphi$ is then that $\langle f, \varphi\rangle=0$. There are operators $P$ of constant strength such that no finite number of linear conditions on $f$ are sufficient for solvability of the equation (1.1) in a relatively compact open subset $\Omega^{\prime}$ of the set $\Omega$ where $P$ is defined. One example of such an operator is the operator $P_{0}$ above considered as an operator in $\mathbf{R}^{4}$ independent of the last variable. The adjoint of this operator has infinitely many linearly independent solutions with support in a fixed compact set. On the other hand if $P$ is hypoelliptic of constant strength then

$$
N=\left\{\varphi \in \mathscr{E}^{\prime} ;{ }^{t} P \varphi=0\right\} \subset C_{0}^{\infty}
$$

Standard compactness arguments give that $N \cap \mathscr{E}^{\prime}(K)$ is finite dimensional for every compact set $K$ in $\Omega$ and one can show that the equation (1.1) can be solved in a neighborhood of $K$ if

$$
\langle f, \varphi\rangle=0, \quad \varphi \in N \cap \mathscr{E}^{\prime}(K)
$$

In Section 3 below we shall give a condition which is sufficient for solvability of the equation (1.1) in an open set $\Omega^{\prime} \subset \subset \Omega$ when $P$ has constant strength and the right hand side satisfies a finite number of linear conditions (Theorem 3.1). The condition involves so called localizations of $P$ at infinity. If $P$ has constant coefficients then a localization of $P$ at infinity is a differential operator $Q(D) \neq 0$ which is a limit of

$$
a_{j} P\left(D+\xi_{j}\right)
$$

when $\xi_{j \rightarrow \infty}$ in $\mathbf{R}^{n}$ and $a_{j} \in \mathbf{R}^{+}$. Localizations at infinity can be defined even for operators of constant strength (Definition 2.3). The condition of Theorem 3.1 is that for no localization $Q$ of $P$ at infinity there should exist $w \in \mathscr{E}^{\prime}(\Omega), w \neq 0$, such that ${ }^{t} Q w=0$. This is also necessary for existence with finite codimension in open relatively compact sets if the solution is required to have the same regularity as in the constant coefficient case (Theorem 3.7). After Theorem 3.7 we give a result which clarifies somewhat the meaning of the condition of Theorem 3.1 (Theorem 3.9).

From Theorem 3.1 it is easy to deduce that if $\Omega$ is $P$-convex then there exists a solution $u \in C^{\infty}(\Omega)$ of the equation (1.1) for any $f$ in a space of finite codimension in $C^{\infty}(\Omega)$ (Theorem 3.6). Then it follows from Theorem 1.2.4 in Hörmander [7] that the same is true with $C^{\infty}(\Omega)$ replaced by $\mathscr{P}^{\prime}(\Omega)$ if $\Omega$ is strongly $P$-convex. But to be able to decide if a domain is strongly $P$-convex one needs theorems on singularities of solutions.

In Section 4 we prove some results on existence of singular solutions, which imply certain necessary conditions for $\Omega$ to be strongly $P$-convex. These are generalizations of the following theorem of Hörmander [6].

Theorem 1.1. Let $P(D)$ be a differential operator with constant coefficients and let $Q(D)$ be a localization of $P$ at infinity such that $\Lambda^{\prime}(Q)$, the orthogonal space of

$$
\Lambda(Q)=\left\{\eta \in \mathbf{R}^{n} ; Q(\xi+t \eta)=Q(\xi), \text { all } \xi \in \mathbf{R}^{n}, t \in \mathbf{R}\right\}
$$

is different from $\{0\}$. Then there exists a solution $u \in \mathscr{D}^{\prime}\left(\mathbf{R}^{n}\right)$ of the equation $P(D) u=0$ such that sing supp $u=\Lambda^{\prime}(Q)$.

The definition of the space $A(Q)$ can be generalized to operators of constant strength (Definition 2.5). When $P(x, D)$ is of constant strength in an open set $\Omega \subset \mathbf{R}^{n}$ it is natural to replace $\Lambda^{\prime}(Q)$ by a component $\Sigma_{0}$ of $\Sigma \cap \Omega$ where $\Sigma$ is an affine subspace parallel to $\Lambda^{\prime}(Q)$. With a method of proof similar to the one used in the constant coefficient case one can obtain a result which shows that the statement of Theorem 1.1 with $\Lambda^{\prime}(Q)$ replaced by $\Sigma_{0}$ is valid for an operator $P$ of constant strength if $\Omega$ is small (Theorem 4.2). This gives a new proof of the result of Taylor [11] mentioned above. A global version of Theorem 1.1 is true for an operator of constant strength if some additional conditions hold (Theorem 4.4). We do not know if these are satisfied in general but if $P$ has analytic coefficients they are fulfilled.

I would take the opportunity to thank my teacher, Professor Lars Hörmander, who suggested these problems to me and has given much valuable advice during the work.

## 2. Definitions and notations

First we recall the definition of an operator of constant strength. If $P(D)$, $D=-i \partial / \partial x$, is a differential operator with constant coefficients the function $\widetilde{P}$ is defined by

$$
\tilde{P}(\xi)=\left(\sum_{\alpha}\left|P^{(\alpha)}(\xi)^{2}\right|\right)^{1 / 2}
$$

$\widetilde{P}$ belongs to the class $\mathscr{K}$ of positive functions $k$ such that

$$
\begin{equation*}
k(\xi+\eta) \leqq(1+C|\xi|)^{N} k(\eta), \quad \text { all } \quad \xi, \eta \in \mathbf{R}^{n} \tag{2.1}
\end{equation*}
$$

for some positive constants $C$ and $N$. The functions

$$
\begin{equation*}
h_{s}(\xi)=\left(1+|\xi|^{2}\right)^{5 / 2} \tag{2.2}
\end{equation*}
$$

belong to $\mathscr{K}$ and are much used.
Definition 2.1. Let $P_{1}$ and $P_{2}$ be differential operators with constant coefficients. Then $P_{1}<P_{2}$, i.e., $P_{1}$ is weaker than $P_{2}$, if there is a constant $C$ such that $\widetilde{P}_{1}(\xi) / \widetilde{P}_{2}(\xi) \equiv C$ for all $\xi \in \mathbf{R}^{n}$, and $P_{1} \sim P_{2}$, i.e., $P_{1}$ and $P_{2}$ are equally strong, if $P_{1}<P_{2}$ and $P_{2}<P_{1}$.

If $P=P(x, D)$ is a differential operator with variable coefficients defined in
an open set $\Omega \subset \mathbf{R}^{n}$ then for each fixed $x \in \Omega$ one can consider the operator $P_{x}$ with constant coefficients obtained by freezing the coefficients at $x$.

Definition 2.2. A differential operator $P$ defined in an open set $\Omega \subset \mathbf{R}^{n}$ is of constant strength if $P_{x} \sim P_{x^{\prime}}$ for arbitrary $x, x^{\prime} \in \Omega$.

In this paper all differential operators will be assumed to have $C^{\infty}$ coefficients. The letters $P$ and $Q$ will always denote differential operators of constant strength assumed to be defined in an open set $\Omega \subset \mathbf{R}^{n}$ although that is not stated each time.

A localization at infinity of an operator $P$ of constant strength should as in the constant coefficient case be defined as the limit of

$$
a_{j} P\left(x, D+\eta_{j}\right)
$$

when the sequence $\eta_{j} \rightarrow \infty$ in $\mathbf{R}^{n}$ and $a_{j} \in \mathbf{R}^{+}$are normalizing constants. In view of Definition 2.2 it is natural to take a fixed $x_{0} \in \Omega$, define $\widetilde{P}=\widetilde{P}_{x_{0}}$, set $a_{j}=1 / \widetilde{P}\left(\eta_{j}\right)$ and thus consider

$$
\begin{equation*}
P\left(x, D+\eta_{j}\right) / \widetilde{P}\left(\eta_{j}\right) \tag{2.3}
\end{equation*}
$$

There is a subsequence of the sequence $\eta_{j}$ such that the limit of (2.3) actually exists. For if $R$ has constant coefficients and is weaker than $P_{x_{0}}$ then the order of $R$ is at most equal to the order of $P_{x_{0}}$ so $\left\{R ; R \prec P_{x_{0}}\right\}$ is finite dimensional. Let $P_{1}, \ldots, P_{N}$ be a basis of this vector space. We can write

$$
P(x, D)=\sum_{v=1}^{N} c_{v}(x) P_{v}(D)
$$

where $c_{v} \in C^{\infty}$. Since $P_{v}<P_{0}$ the coefficient of $D^{\alpha}$ in $P_{v}\left(D+\eta_{j}\right) / \widetilde{P}\left(\eta_{j}\right)$ is a bounded function of $\eta_{j}$ for $v=1, \ldots, N$ and all multiindices $\alpha$. Thus there is a subsequence $\eta_{j_{k}}$, which we for simplicity assume is identical with the sequence $\eta_{j}$, such that the coefficient of $D^{\alpha}$ in

$$
P_{v}\left(D+\eta_{j}\right) / \widetilde{P}\left(\eta_{j}\right)
$$

has a limit for $v=1, \ldots, N$ and all $\alpha$. Then it is clear that there is a differential operator $Q(x, D)$ with $C^{\infty}$ coefficients such that for all $\alpha$ the coefficient of $D^{\alpha}$ in (2.3) tends to the corresponding coefficient in $Q(x, D)$ in the $C^{\infty}(\Omega)$ topology. If another point $x_{1}$ is chosen to define $\widetilde{P}$ then $Q$ will just be replaced by a constant times $Q$. Now we can state

Definition 2.3. If $P$ is a differential operator of constant strength let $L(P)=$ $=\left\{Q(x, D) ; Q(x, D)=\lim P\left(x, D+\eta_{j}\right) / \tilde{P}\left(\eta_{j}\right)\right.$ for some sequence $\left.\eta_{j} \in \mathbf{R}^{n}, \eta_{j} \rightarrow \infty\right\}$. The elements of $L(P)$ are called localizations of $P$ at infinity.

An operator $Q \in L(P)$ has constant strength for

$$
\tilde{Q}_{x}(\xi)=\lim \widetilde{P}_{x}\left(\xi+\eta_{j}\right) / \widetilde{P}\left(\eta_{j}\right)
$$

A localization $R$ of $Q$ at $\infty$ is a localization of $P$ at $\infty$ for if $\theta_{j}$ is the sequence
defining $R$ then it is easily seen that there are subsequences $\eta_{j_{v}}$ and $\theta_{j_{v}}$ such that $\xi_{v}=\eta_{j_{v}}+\theta_{j_{v}} \rightarrow \infty$ and

$$
R(x, \xi)=\lim P\left(x, \xi+\xi_{v}\right) / \widetilde{P}\left(\xi_{v}\right)
$$

The adjoint ${ }^{t} P$ of $P$ has constant strength if $P$ has and $\left({ }^{t} P\right)_{x}(D) \sim P_{x}(-D)$ for every $x$ (Hörmander [4, Lemma 7.1.2]). Clearly we have

$$
{ }^{t} Q(x, D)=\lim ^{t} P\left(x, D-\eta_{j}\right) / \tilde{P}\left(\eta_{j}\right)
$$

so the adjoint of a localization of $P$ at $\infty$ is after multiplication by a positive constant a localization of ${ }^{t} P$ at $\infty$.

The following proposition shows that one need not consider all sequences $\eta_{j}$ in order to obtain all localizations of $P$.

Proposition 2.4. Let $Q \in L(P)$. Then there is a polynomial in $t$

$$
\begin{equation*}
\eta(t)=\sum_{j=0}^{J} \theta_{j} t^{j}, \quad \theta_{j} \in \mathbf{R}^{n}, \quad \eta(t) \rightarrow \infty \quad \text { as } \quad t \rightarrow \infty, \tag{2.4}
\end{equation*}
$$

a number $a>0$ and an integer $\sigma \supseteqq 0$ such that

$$
Q(x, \xi)=\lim _{t \rightarrow \infty} P(x, \xi+\eta(t)) / a t^{\sigma} .
$$

Proof. Let $Q$ be defined by a sequence $\eta_{j}$. After possibly passing to a subsequence we may assume that $P_{v}\left(\xi+\eta_{j}\right) / \widetilde{P}\left(\eta_{j}\right)$ has a limit $Q_{v}$ for all $P_{v}$ in a basis of $\left\{R ; R<P_{x_{0}}\right\}$. It is sufficient to prove that there exist $\eta(t), a, \sigma$ such that $Q_{v}(\xi)=$ $=\lim P_{\nu}(\xi+\eta(t)) / a t^{\sigma}$ for all $v$. But that is just Proposition 2.2 in Hörmander [6] applied to the vector valued function $\xi \rightarrow\left(P_{1}(\xi), \ldots, P_{N}(\xi)\right)$. The proof of that proposition is valid with obvious modifications for a vector valued function.

If $P$ has constant coefficients we define $\Lambda(P)$ as in the introduction. If $P_{1} \prec P_{2}$ then $\Lambda\left(P_{2}\right) \subset \Lambda\left(P_{1}\right)$. For let $\eta \in \Lambda\left(P_{2}\right)$. Then

$$
\left|P_{1}(\xi+t \eta)\right| \leqq \widetilde{P}_{1}(\xi+t \eta) \leqq C \widetilde{P}_{2}(\xi+t \eta)=C \widetilde{P}_{2}(\xi) .
$$

Hence $P_{1}(\xi+t \eta)$ must be independent of $t$. Thus the following definition is independent of the point $x_{0}$ chosen.

Definition 2.5. If $P$ has constant strength let $\Lambda(P)=\Lambda\left(P_{x_{0}}\right)$. The orthogonal space of $\Lambda(P)$ is denoted by $\Lambda^{\prime}(P)$.

The ciass of operators of constant strength is invariant under linear changes of coordinates. Therefore we can choose the coordinate system so that

$$
A^{\prime}(P)=\left\{x ; x_{k}=0, k=j+1, \ldots, n\right\} .
$$

Then obviously

$$
P(x, D)=\sum_{\alpha} a^{\alpha}\left(x^{\prime}, x^{\prime \prime}\right) D_{x^{\prime}}^{\alpha}
$$

where $x^{\prime}=\left(x_{1}, \ldots, x_{j}\right), x^{\prime \prime}=\left(x_{j+1}, \ldots, x_{n}\right)$ and $D_{x^{\prime}}^{\alpha}$ is a partial derivative which does not contain $\partial / \partial x_{k}$ for $k=j+1, \ldots, n$. Consider a fixed $x^{\prime \prime}$ and let
$\Sigma=\left\{\left(x^{\prime}, x^{\prime \prime}\right) ; x^{\prime} \in \mathbf{R}^{j}\right\}$. The restriction of $P$ to $\Sigma$ defines an operator of constant strength in the open set $\Sigma \cap \Omega$ in $\mathbf{R}^{j}$. We write $P_{\Sigma}$ for that operator.

It is immediate from the definitions that $\Lambda^{\prime}(Q) \subset \Lambda^{\prime}(P)$ if $Q \in L(P)$. Moreover $\operatorname{dim} \Lambda^{\prime}(Q)<\operatorname{dim} \Lambda^{\prime}(P)$ if the sequence $\eta_{j}$ defining $Q$ tends to $\infty$ modulo $\Lambda(P)$. For if $\theta_{J}$ is the coefficient of the largest power of $t$ in (2.4) and $\eta(t) \rightarrow \infty$ $\bmod \Lambda(P)$ then we may assume that $\theta_{J} \ddagger \Lambda(P)$. But $\theta_{J} \in \Lambda(Q)$ since

$$
\eta\left(t+s t^{1-J} / J\right)=\eta(t)+s \theta_{J}+O(1 / t)
$$

so that for every real $s$

$$
Q(x, \xi)=\lim _{t \rightarrow \infty} P(x, \xi+\eta(t)) / a t^{\sigma}=Q\left(x, \xi+s \theta_{J}\right)
$$

If the sequence $\eta_{j}$ is bounded $\bmod \Lambda(P)$ then $Q$ is clearly of the form $P\left(x, \xi+\xi_{0}\right) / \widetilde{P}\left(\xi_{0}\right)$ for some $\xi_{0} \in \mathbf{R}^{n}$. For all $Q \in L(P)$ we have $\operatorname{dim} \Lambda^{\prime}(Q)<n$ for either $\eta_{j} \rightarrow \infty$ modulo $\Lambda(P)$ and then $\operatorname{dim} \Lambda^{\prime}(Q)<\operatorname{dim} \Lambda^{\prime}(P) \leqq n$ or the sequence $\eta_{j}$ is bounded modulo $\Lambda(P)$ and then $\operatorname{dim} \Lambda^{\prime}(Q) \leqq \operatorname{dim} \Lambda^{\prime}(P)<n$.

These remarks show that if $Q$ is a localization of $P$ at infinity $\bmod \Lambda(P)$ then $Q$ is somewhat simpler than $P$. If we take a localization $R$ of $Q$ at infinity $\bmod \Lambda(Q)$ we get a still simpler localization of $P$, and so on. When proving an extension of Theorem 1.1 one should first look at the simplest localizations of order $\neq 0$. Therefore we state

Definition 2.6. A differential operator $Q$ of constant strength is of local type if $\Lambda^{\prime}(Q) \neq\{0\}$ and all localizations of $Q$ which are defined by a sequence $\eta_{j}$ which tends to infinity modulo $\Lambda(Q)$ are of order 0 .

Let $Q$ be of local type and choose the coordinate system so that $\Lambda^{\prime}(Q)=$ $=\left\{\left(x^{\prime}, x^{\prime \prime}\right) ; x^{\prime \prime}=0\right\}$. The definition implies that $Q_{x}$ is then a hypoelliptic polynomial in the $\xi^{\prime}$ variables for all $x$, that is

$$
Q^{(\alpha)}\left(x^{\prime}, x^{\prime \prime}, \xi^{\prime}\right) / Q\left(x^{\prime}, x^{\prime \prime}, \xi^{\prime}\right) \rightarrow 0
$$

when $\xi^{\prime} \rightarrow \infty$ if $\alpha \neq 0$.
The following proposition will imply that in order to prove an extension of Theorem 1.1 it is sufficient to consider localizations of local type.

Proposition 2.7. For every $Q \in L(P)$ there is an operator $Q^{\prime} \in L(P)$ of local type such that $\Lambda^{\prime}\left(Q^{\prime}\right) \subset \Lambda^{\prime}(Q)$.

Proof. If $Q$ is of local type there is nothing to prove. Otherwise one can find $Q_{1}$ of positive order which is a localization of $Q$ at infinity modulo $\Lambda^{\prime}(Q)$. Then $\Lambda^{\prime}\left(Q_{1}\right) \subset \Lambda^{\prime}(Q)$ and $\operatorname{dim} \Lambda^{\prime}\left(Q_{1}\right)<\operatorname{dim} \Lambda^{\prime}(Q)$. If $Q_{1}$ is of local type the proof is finished, otherwise there is a non constant $Q_{2}$ which is a localization of $Q_{1}$ at infinity modulo $\Lambda^{\prime}\left(Q_{1}\right)$, and so on. We get a $Q_{N}$ of local type after a finite number of steps, for the dimensions of the spaces $\Lambda^{\prime}(Q), \Lambda^{\prime}\left(Q_{1}\right), \ldots$ are strictly decreasing. The operator $Q_{N}$ belongs to $L(P)$ so the proof is complete.

## 3. Existence theorems

As before let $P$ be a differential operator of constant strength in an open set $\Omega \subset \mathbf{R}^{n}$. In this section we prove some existence theorems for the equation $P u=f$ on compact subsets of $\Omega$.

First we introduce suitable Banach spaces. Let $k \in \mathscr{K}$ and $1 \leqq p \leqq \infty$. The space $\mathscr{B}_{p, k}$ is the set of temperate distributions $u$ such that $\hat{u}$ is a function and $\hat{u} k \in L^{p}$. It is a Banach space with the norm

$$
\|u\|_{p, k}=\left((2 \pi)^{-n} \int|\hat{u}(\xi) k(\xi)|^{p} d \xi\right)^{1 / p}
$$

and if $p \neq \infty$ its dual space is $\mathscr{B}_{p^{\prime}, k^{\prime}}$, where $1 / p+1 / p^{\prime}=1$ and $k^{\prime}(\xi)=1 / k(-\xi)$. If $p \neq \infty$ then $C_{0}^{\infty}$ is dense in $\mathscr{B}_{p, k}$. If $k, k_{1} \in \mathscr{K}$ and $k_{1}(\xi) / k(\xi) \rightarrow 0$ when $\xi \rightarrow \infty$ then a sequence which is bounded in $\mathscr{B}_{p, k}$ and has supports in a fixed compact set has a subsequence which converges in $\mathscr{B}_{p, k_{1}}$. For the proofs of these facts see Hörmander [4, section 2.2]. Let $\Omega^{\prime}$ be open and relatively compact. In the study of the equation $P u=f$ in $\Omega^{\prime}$ we use the quotient spaces

$$
\mathscr{B}_{p, k}\left(\bar{\Omega}^{\prime}\right)=\mathscr{B}_{p, k} / N_{p, k}\left(\Omega^{\prime}\right)
$$

where

$$
N_{p, k}\left(\Omega^{\prime}\right)=\left\{u \in \mathscr{B}_{p, k} ; u=0 \text { in } \Omega^{\prime}\right\} .
$$

If $p \neq \infty$ the dual space of $\mathscr{B}_{p, k}\left(\bar{\Omega}^{\prime}\right)$ is $V_{p^{\prime}, k^{\prime}}\left(\bar{\Omega}^{\prime}\right)$, the annihilator of $N_{p, k}\left(\Omega^{\prime}\right)$ in $\mathscr{B}_{p^{\prime}, k^{\prime}}$. It is obvious that $C_{0}^{\infty}\left(\bar{\Omega}^{\prime}\right) \subset V_{p^{\prime}, k^{\prime}}\left(\bar{\Omega}^{\prime}\right) \subset \mathscr{E}^{\prime}\left(\bar{\Omega}^{\prime}\right)$.

A differential operator $P$ of constant strength in $\Omega \supset \supset \Omega^{\prime}$ induces a continuous linear map

$$
P: \mathscr{B}_{p, k \boldsymbol{P}}\left(\bar{\Omega}^{\prime}\right) \rightarrow \mathscr{B}_{p, k}\left(\bar{\Omega}^{\prime}\right) .
$$

The space $\mathscr{B}_{p, k \tilde{P}}\left(\bar{\Omega}^{\prime}\right)$ is clearly independent of the point $x_{0}$ chosen to define $\tilde{P}$. The following theorem gives a sufficient condition for the image of $P$ to have finite codimension.

Theorem 3.1. Let $\Omega$ be an open set in $\mathbf{R}^{n}$ and let $P$ be a differential operator of constant strength in $\Omega$. Assume that

$$
\begin{equation*}
Q \in L(P), \quad w \in \mathscr{E}^{\mathscr{O}}(\Omega), \quad{ }^{t} Q w=0 \Rightarrow w=0 . \tag{3.1}
\end{equation*}
$$

Then

$$
N=\left\{w \in \mathscr{E}^{\prime}(\Omega) ;{ }^{t} P w=0\right\} \subset C_{0}^{\infty}(\Omega)
$$

Let $\Omega^{\prime}$ be open, $\Omega^{\prime} \subset \subset \Omega$. Then $N^{\prime}=N \cap \mathscr{E}^{\prime}\left(\bar{\Omega}^{\prime}\right)$ is finite dimensional. If $f \in \mathscr{B}_{p, k}\left(\bar{\Omega}^{\prime}\right)$ and $\langle f, \varphi\rangle=0$ for all $\varphi \in N^{\prime}$ there exists some $u \in \mathscr{B}_{p, k \bar{P}}\left(\bar{\Omega}^{\prime}\right)$ such that $P u=f$ in $\Omega^{\prime}$.

Theorem 3.1 applies to hypoelliptic operators of constant strength, for if $P_{x}(D)$ is hypoelliptic for all $x$ then every $Q \in L(P)$ is a nowhere vanishing function.

In this case the result is of course very well known. Operators $P$ with analytic coefficients also satisfy the condition (3.1). In fact every localization $Q$ of $P$ has analytic coefficients. Let $w \in \mathscr{E}^{\prime}(\Omega)$ and ${ }^{t} Q w=0$. Denote the principal part of $Q$ by $q$. One can find $v \in \mathbf{R}^{n}$ such that $q\left(x_{0}, v\right) \neq 0$ and then $q(x, v) \neq 0$ for all $x \in \Omega$ since $Q$ has constant strength. Holmgren's uniqueness theorem now implies that $w=0$ in a neighborhood of an affine hyperplane parallel to $\{x ;\langle x, v\rangle=0\}$ if this is true on one side. Hence $w$ is identically 0 . This also shows that the space $N$ is $\{0\}$ when $P$ has analytic coefficients. More generally if each $Q \in L(P)$ has the unique continuation property over all hyperplanes parallel to $\{x ;\langle x, v\rangle=0\}$ for some $v$ then (3.1) holds. We have that situation for example if $L(P)$ only contains operators of order 1 , for a first order operator of constant strength has constant coefficients in the principal part after multiplication by a $C^{\infty}$ function and a suitable local change of coordinates. For a proof of this see for example DuistermaatHörmander [3].

Proof of Theorem 3.1. First we show that $N \subset C_{0}^{\infty}$. So let $w \in \mathscr{E}^{\prime}(\Omega) \backslash C_{0}^{\infty}$ and ${ }^{t} P w=0$. In order to make use of (3.1) we take a point $\xi \in \mathbf{R}^{n}$ and observe that

$$
\begin{equation*}
0=\exp (-i\langle\cdot, \xi\rangle)^{t} P(\cdot, D) w / \widetilde{P}(-\xi)={ }^{t} P(\cdot, D+\xi)(\exp (-i\langle\cdot, \xi\rangle) w) / \widetilde{P}(-\xi) \tag{3.2}
\end{equation*}
$$

Suppose that there exists a sequence $\xi_{j} \in \mathbf{R}^{n}$ and constants $t_{j} \in \mathbf{C}$ such that $\xi_{j} \rightarrow \infty$ and $t_{j} \exp \left(-i\left\langle\cdot, \xi_{j}\right\rangle\right) w$ converges in $\mathscr{E}^{\prime}$ to a distribution $w_{0} \neq 0$ when $j \rightarrow \infty$. We may assume that

$$
{ }^{t} P\left(\cdot, D+\xi_{j}\right) / \tilde{P}\left(-\xi_{j}\right) \rightarrow{ }^{t} Q(\cdot, D)
$$

for some $Q \in L(P)$. Then by multiplying (3.2) with $t_{j}$ and letting $j$ tend to infinity it follows that ${ }^{t} Q w_{0}=0$. But that contradicts (3.1) so the following lemma will complete the proof that $N \subset C_{0}^{\infty}$.

Lemma 3.2. Let $w \in \mathscr{E}^{\prime} \backslash C_{0}^{\infty}$. Then there is a sequence $\xi_{j} \rightarrow \infty$ in $\mathbf{R}^{n}$, constants $t_{j} \in \mathbf{C}$ and a distribution $w_{0} \in \mathscr{E}^{\prime}$ not equal to 0 such that $t_{j} \exp \left(-i\left\langle\cdot, \xi_{j}\right\rangle\right) w \rightarrow w_{0}$ in $\mathscr{E}^{\prime}$.

Proof. It is sufficient to show that there are constants $C$ and $N$ and a sequence $\xi_{j \rightarrow \infty}$ such that

$$
\begin{equation*}
\left|\hat{w}\left(\xi+\xi_{j}\right) / \hat{w}\left(\xi_{j}\right)\right| \leqq C(1+|\xi|)^{N}, \quad \forall \xi \in \mathbf{R}^{n} . \tag{3.3}
\end{equation*}
$$

In fact this means that the sequence $\exp \left(-i\left\langle\cdot, \xi_{j}\right\rangle\right) w / \tilde{w}\left(\xi_{j}\right)$ is bounded in $\mathscr{B}_{\infty, h_{-N}}$ where $h_{-N}$ is defined by (2.2). Then there is a subsequence $\xi_{j_{k}}$ of $\xi_{j}$ such that

$$
\exp \left(-i\left\langle\cdot, \xi_{j_{k}}\right)\right) w / \hat{w}\left(\xi_{j_{k}}\right)
$$

has a limit $w_{0}$ in $\mathscr{B}_{\infty, h_{-N-1}}$. It is clear that $w_{0} \neq 0$ for $\hat{w}_{0}(0)=1$. To prove (3.3) note that since $w \in \mathscr{E}^{\prime} \backslash C_{0}^{\infty}$ there is a number $M$ such that

$$
|\hat{w}(\xi)| \leqq C_{1}(1+|\xi|)^{M+1 / 2}
$$

for some $C_{1}>0$ and

$$
f(R)=\sup _{|\xi|=R}|\hat{w}(\xi)|(1+R)^{-M}
$$

is not a bounded function of $R$. Then $f(R) \leqq C_{1}(1+R)^{1 / 2}$ so

$$
S_{j}=\sup _{R \geqq 0}(f(R)-R / j)<\infty
$$

and is attained at a point $R_{j}$. The numbers $S_{j}$ tend to infinity for if they were bounded then $f$ would be bounded. Then $\boldsymbol{R}_{\boldsymbol{j}}$ must also tend to infinity. For $R \geqq-\boldsymbol{R}_{j}$ we have
(3.4) $\quad f\left(R+R_{j}\right) / f\left(R_{j}\right) \leqq\left(S_{j}+\left(R+R_{j}\right) / j\right) / f\left(R_{j}\right)=\left(f\left(R_{j}\right)+R / j\right) / f\left(R_{j}\right) \leqq 1+|R|$
if $j$ is large enough. Let $\xi_{j}$ be a point where

$$
\left|\xi_{j}\right|=R_{j}, \quad f\left(R_{j}\right)=\left|\hat{w}\left(\xi_{j}\right)\right|\left(1+R_{j}\right)^{-M}
$$

For given $\xi \in \mathbf{R}^{n}$ put $R=\left|\xi+\xi_{j}\right|-R_{j}$. Then $-R_{j} \leqq R$ and $|R| \leqq|\xi|$. The definition of $f$ gives that

$$
\left|\hat{w}\left(\xi+\xi_{j}\right)\right| \equiv f\left(\left|\xi+\xi_{j}\right|\right)\left(1+\mid \xi+\xi_{j}\right)^{M}=f\left(R_{j}+R\right)\left(1+R_{j}+R\right)^{M} .
$$

Thus

$$
\left|\hat{w}\left(\xi+\xi_{j}\right) / \hat{w}\left(\xi_{j}\right)\right| \leqq f\left(R_{j}+R\right)\left(1+R_{j}+R\right)^{M} /\left(f\left(R_{j}\right)\left(1+R_{j}\right)^{M}\right) \leqq(1+|R|)(1+|R|)^{|M|}
$$

The last inequality follows from (3.4) and the fact that

$$
\left(1+R_{j}+R\right)^{M} /\left(1+R_{j}\right)^{M} \leqq(1+|R|)^{|M|} .
$$

Hence (3.3) is valid and the lemma is proved.
Now it is easy to obtain that the space $N^{\prime}$ in Theorem 3.1 is finite dimensional. For $N^{\prime}$ is a closed subspace of $L^{2}$. The injection $N^{\prime} \rightarrow \mathscr{H}_{(1)}$ is everywhere defined so by the closed graph theorem

$$
\|\varphi\|_{(1)} \leqq C\|\varphi\|_{(0)}, \quad \varphi \in N^{\prime}
$$

A sequence in $\mathscr{E}^{\prime}\left(\bar{\Omega}^{\prime}\right)$ which is bounded in $\mathscr{H}_{(1)}$ has a subsequence which converges in $L^{2}$ so this inequality implies that $N^{\prime}$ is locally compact. A Banach space which is locally compact is finite dimensional so it follows that $N^{\prime}$ is finite dimensional.

We shall complete the proof of Theorem 3.1 by applying the Hahn-Banach theorem. For that we need the estimate in the following lemma.

Lemma 3.3. Let the hypothesis of Theorem 3.1 be fulfilled. For all $k \in \mathscr{K}$ and $p \in[1, \infty]$ there is a constant $B$ such that if $h=k \widetilde{P}^{\prime}$ then

$$
\begin{equation*}
\|v\|_{p, k} \leqq B\left\|^{t} P v\right\|_{p, h} \quad \text { if } \quad v \in V_{p, k}\left(\bar{\Omega}^{\prime}\right) \quad \text { and }\langle v, \varphi\rangle=0, \forall \varphi \in N^{\prime} . \tag{3.5}
\end{equation*}
$$

The same $B$ can be used for all $k$ satisfying (2.1) with fixed $C$ and $N$.

Proof. Assume that the statement of the lemma is not true. Then for all positive integers $j$ there exists $v_{j} \in V_{p, k}\left(\bar{\Omega}^{\prime}\right)$ orthogonal to $N^{\prime}$ and $k_{i}$ satisfying (2.1) such that

$$
\begin{equation*}
1=\left\|v_{j}\right\|_{p, k_{j}}>j\left\|^{t} P v_{j}\right\|_{p, h_{j}} \tag{3.6}
\end{equation*}
$$

where $h_{j}=k_{j} \tilde{P}^{\prime}$. It is easiest to get a contradiction from (3.6) if $p=\infty$ so we consider that case first. One can then find $\xi_{j}$ such that

$$
\begin{equation*}
\hat{v}_{j}\left(\xi_{j}\right) k_{j}\left(\xi_{j}\right) \rightarrow 1 \tag{3.7}
\end{equation*}
$$

Define $w_{j}$ by

$$
\hat{w}_{j}(\xi)=k_{j}\left(\xi_{j}\right) \hat{v}_{j}\left(\xi+\xi_{j}\right)
$$

By the equality in (3.6) and (2.1) we have

$$
\left|\hat{w}_{j}(\xi)\right| \leqq(1+C|\xi|)^{N}
$$

so there is a subsequence which we also denote by $w_{j}$ which has a limit $w$ in $\mathscr{E}^{\prime}$. Obviously $w \neq 0$ for (3.7) means that $\hat{w}_{j}(0) \rightarrow 1$. By the remarks before Definition 2.3 any sequence $\xi_{j}$ in $\mathbf{R}^{n}$ has a subsequence which defines a localization of $P$. If $\xi_{j}$ does not tend to $\infty$ then the localization is just a constant times a translation of $P$. Thus after possibly passing to a subsequence

$$
Q_{j}(\cdot, \xi)={ }^{t} P\left(\cdot, \xi+\xi_{j}\right) / \widetilde{P}\left(-\xi_{j}\right) \rightarrow^{t} Q(\cdot, \xi)
$$

Note that

$$
\widehat{Q_{j} w_{j}}=\widehat{{ }^{2} P v_{j}}\left(\cdot+\xi_{j}\right) k_{j}\left(\xi_{j}\right) / \widetilde{P}\left(-\xi_{j}\right)
$$

From the inequality in (3.6) it follows that $Q_{j} w_{j}$ tends to 0 in the space $\mathscr{B}_{\infty, h_{-s}}$ if $s$ is the constant occurring instead of $N$ in the estimate (2.1) for $h$ and $h_{-s}^{-s}$ is defined by (2.2). Hence ${ }^{t} Q w=0$. Then the sequence $\xi_{j}$ cannot tend to infinity because (3.1) is valid, so we may assume that $\xi_{j}$ has a limit $\xi_{0} \in \mathbf{R}^{n}$. Then

$$
{ }^{t} Q(\cdot, \xi)={ }^{t} P\left(\cdot, \xi+\xi_{0}\right) / \widetilde{P}\left(-\xi_{0}\right), \quad w=A v_{0} \exp \left(-i\left\langle\cdot, \xi_{0}\right\rangle\right)
$$

where $v_{0}$ is a limit of $v_{j}$ in $\mathscr{E}^{\prime \prime}$ and $A$ is a limit of $k_{j}\left(\xi_{j}\right)$. Clearly $v_{0}$ is orthogonal to $N^{\prime}$ and not equal to 0 . But the fact that ${ }^{t} Q w=0$ implies now that ${ }^{t} P v_{0}=0$, that is, $v_{0} \in N^{\prime}$. This is a contradiction so Lemma 3.3 is proved in the case $p=\infty$.

To be able to use the same idea of proof if $p \neq \infty$ one needs a lemma.
Lemma 3.4. Let $k \in \mathscr{K}$ and $p<\infty$. For $\eta \in \mathbf{R}^{n}$ define a function $k_{\eta} \in \mathscr{K}$ by

$$
\begin{equation*}
k_{\eta}(\xi)=\left(1+|\xi-\eta|^{2}\right)^{-M / 2} k(\xi), \quad \xi \in \mathbf{R}^{n} \tag{3.8}
\end{equation*}
$$

Let $K$ be a compact set in $\mathbf{R}^{n}$. If $M$ is sufficiently large the function $\eta \rightarrow\|u\|_{\infty, k_{n}}$ belongs to $L^{\mathrm{p}}$ and the norm $\|u\|_{p, k}$ is equivalent to the norm

$$
\|u\|_{p, k}=\left(\int\|u\|_{\infty, k_{\eta}}^{p} d \eta\right)^{1 / p}
$$

for $u \in \mathscr{E}^{\prime}(K) \cap \mathscr{B}_{p, k}$.

Proof. It is clear that $\|u\|_{\infty, k_{\eta}} \equiv|\hat{u}(\eta) \mathrm{k}(\eta)|$ so

$$
\|u\|_{p, k}^{p} \leqq \int\|u\|_{\infty, k_{n}}^{p} d \eta
$$

To prove the opposite estimate choose $\chi \in C_{0}^{\infty}$ such that $\chi=1$ in a neighborhood of $K$. Then $\hat{u}=(2 \pi)^{-n} \hat{u} * \hat{\chi}$ if $u \in \mathscr{E}^{\prime}(K)$. If $M$ is large there is a positive constant $C_{1}$ such that

$$
k(\xi) \leqq C_{\mathbf{1}}(1+|\xi-\theta|)^{M} k(\theta) \quad \text { for all } \quad \xi, \theta \in \mathbf{R}^{n}
$$

and for $M>0$ we have

$$
(1+|\xi-\eta|)^{-M} \leqq\left(1+\mid \theta-\eta^{\prime}\right)^{-M}(1+|\xi-\theta|)^{M} \quad \text { for all } \quad \xi, \eta, \theta \in \mathbf{R}^{n} .
$$

From these estimates, the fact that $\hat{u}=(2 \pi)^{-n} \hat{u} * \hat{\chi}$ and Hölder's inequality it follows that

$$
\left|k(\xi)(1+|\xi-\eta|)^{-M} \hat{u}(\xi)\right| \leqq C_{1}\left\|\hat{\chi}(1+|\cdot|)^{2 M}\right\|_{p^{\prime}}\left(\int \mid \hat{u}(\theta) k(\theta)(1+|\theta-\eta|)^{-M \mid p} d \theta\right)^{1 / p}
$$

If $M p>n$ we obtain by integrating with respect to $\eta$ that there is a constant $C$ independent of $u \in \mathscr{E}^{\prime}(K) \cap \mathscr{B}_{p, k}$ such that

The proof is complete.

$$
\int\|u\|_{\infty, k_{\eta}}^{p} d \eta \leqq C\|u\|_{p, k}^{p}
$$

End of the proof of Lemma 3.3. Recall that $h=k \tilde{P}^{\prime}$. Define $k_{\eta}$ by (3.8) and $h_{\eta}$ in the same way. By Lemma 3.4 one can choose $M$ so large that $\|u\|_{p, k}$ and $\left\|\|u\|_{p, k}\right.$ as well as $\|u\|_{p, h}$ and $\|u\|_{p, h}$ are equivalent for $u \in \mathscr{E}^{\prime}\left(\bar{\Omega}^{\prime}\right)$. The functions $k_{\eta}$ satisfy the estimate (2.1) with the same constants for all $\eta$. Thus it follows from the first part of the proof that

$$
\|v\|_{\infty, k_{n}} \leqq B\left\|^{t} P v\right\|_{\infty, h_{n}} \quad \text { if } \quad v \in V_{p, k}\left(\bar{\Omega}^{\prime}\right) \quad \text { and } \quad v \perp N^{\prime}
$$

Now (3.5) follows by integrating with respect to $\eta$. This completes the proof of Lemma 3.3.

End of the proof of Theorem 3.1. Let $f \in \mathscr{B}_{p}, k\left(\bar{\Omega}^{\prime}\right)$ and $v \in C_{0}^{\infty}\left(\bar{\Omega}^{\prime}\right)$. The estimate (3.5) gives

$$
|\langle f, v\rangle| \leqq B\|f\|_{p, k}\left\|^{t} P v\right\|_{p^{\prime},(k \S)^{\prime}}
$$

if $v \perp N^{\prime}$. If $f \perp N^{\prime}$ this inequality is in fact valid for all $v \in C_{0}^{\infty}\left(\bar{\Omega}^{\prime}\right)$ for $v$ can be written $v=v_{1}+v_{2}$ with $v_{1} \perp N^{\prime}, v_{2} \in N^{\prime}$ and when $v_{2} \in N^{\prime}$ both sides are 0 . The linear form

$$
{ }^{t} P v \rightarrow\langle f, v\rangle
$$

is thus continuous on a subspace of $V_{p^{\prime},(k \tilde{P})^{\prime}}\left(\bar{\Omega}^{\prime}\right)$. By the Hahn-Banach theorem it can be extended to a continuous linear form $u$ on $V_{p^{\prime},(k \widetilde{F})^{\prime}}\left(\bar{\Omega}^{\prime}\right)$ such that $\left\langle u,{ }^{t} P v\right\rangle=$ $=\langle f, v\rangle$ for all $v \in C_{0}^{\infty}\left(\bar{\Omega}^{\prime}\right)$. That means $P u=f$ in $\Omega^{\prime}$ and $u \in \mathscr{B}_{p, k \bar{P}}\left(\bar{\Omega}^{\prime}\right)$ if $p^{\prime} \neq \infty$. This completes the proof of Theorem 3.1 in case $p \neq 1$.

From the estimate (3.5) one can obtain the following result which contains an existence theorem for the $C^{\infty}$ case and the statement of Theorem 3.1 for $p=1$. The method of proof is well known.

Theorem 3.5. Let $\Omega$ be an open subset of $\mathbf{R}^{n}$ and let $P$ be an operator of constant strength in $\Omega$. Assume that (3.1) is fulfilled. Let

$$
F=\bigcap_{j=1}^{\infty} \mathscr{B}_{p_{j}, k_{j}}, \quad F_{1}=\bigcap_{j=1}^{\infty} \mathscr{B}_{p_{j}, k_{j} \tilde{F}},
$$

where $1 \leqq p_{j}<\infty$ and $k_{j} \in \mathscr{K}$. If $\Omega^{\prime} \subset \subset \Omega, f \in F$ and $\langle f, \varphi\rangle=0$ for all $\varphi \in C_{0}^{\infty}\left(\bar{\Omega}^{\prime}\right)$ such that ${ }^{t} P \varphi=0$ then there exists $u \in F_{1}$ such that $P u=f$ in $\Omega^{\prime}$.

Proof. $F$ and $F_{1}$ are Fréchet spaces and so is

$$
F_{0}=\left\{f \in F ; f=0 \text { in } \Omega^{\prime}\right\}
$$

and the quotient space $F_{q}=F / F_{0}$. The dual space of $F_{q}$ is

$$
F_{q}^{\prime}=\left\{w ; w \in \mathscr{B}_{p_{j}^{\prime}, k_{j}^{\prime}} \text { for some } j,\langle w, f\rangle=0 \text { if } f \in F_{0}\right\}
$$

This is of course a subspace of $\mathscr{E}^{\prime \prime}\left(\bar{\Omega}^{\prime}\right)$ containing $C_{0}^{\infty}\left(\bar{\Omega}^{\prime}\right)$. We have to show that the image of $P: F_{1} \rightarrow F_{q}$ is the annihilator of

$$
N^{\prime}=\left\{\varphi \in F_{q}^{\prime} ;{ }^{t} P \varphi=0\right\}
$$

That follows if the range of ${ }^{t} P$ is weakly closed in $F_{1}^{\prime}$ (see e.g. Dieudonné-Schwartz [2, Th. 7]). By a theorem of Banach (see Bourbaki [1, Ch. III, Th. 5]) this means that the intersection of the range of ${ }^{t} P$ and the unit ball in $\mathscr{B}_{p_{j}^{\prime},\left(k_{j} \tilde{P}\right)^{\prime}}$ shall be weakly closed for every $j$. The weak topology is metrizable on the unit ball since it is equivalent to the weak topology on the unit ball of a dual of a separable Banach space. Let us therefore consider a sequence

$$
v_{v} \in F_{q}^{\prime}, \quad{ }^{t} P v_{v}=w_{v}, \quad\left\|w_{v}\right\|_{p_{j}^{\prime},\left(\bar{P}_{k_{j}}\right)^{\prime}} \leqq 1
$$

and suppose that $w_{v}$ tends to a limit $w$ weakly in $F_{1}^{\prime}$. We may assume that $v_{v} \perp N$ so the estimate (3.5) gives that

$$
\left\|v_{v}\right\|_{p^{\prime}, k_{j}^{\prime}} \leqq B .
$$

Then there is a subsequence of $v_{v}$ which has a weak limit $v$ in $F^{\prime}$. Clearly $v \in F_{q}^{\prime}$ and ${ }^{t} P v=w$ so the proof is complete.

The following global existence theorem in a $P$-convex open set is proved in the same way as Theorem 3.5. As usual $\mathscr{B}_{p, k}^{\text {loc }}(\Omega)$ is the space of $u \in \mathscr{D}^{\prime}(\Omega)$ such that $\varphi u \in \mathscr{B}_{p, k}$ for all $\varphi \in C_{0}^{\infty}(\Omega)$.

Theorem 3.6. Let $\Omega$ be an open set and let $P$ be a differential operator of constant strength in $\Omega$. Assume that (3.1) is fulfilled and that $\Omega$ is $P$-convex, that is, for each compact subset $K$ of $\Omega$ there exists a compact subset $K^{\prime}$ of $\Omega$ such that

$$
\operatorname{supp}^{t} P w \subset K, \quad w \in \mathscr{E}^{\prime}(\Omega) \Rightarrow \operatorname{supp} w \subset K^{\prime}
$$

Let

$$
\mathscr{F}=\bigcap_{j=1}^{\infty} \mathscr{B}_{p_{j}, k_{j}}^{\mathrm{loc}}(\Omega), \quad \mathscr{F}_{1}=\bigcap_{j=1}^{\infty} \mathscr{B}_{p_{j}, k_{j} p}^{\mathrm{loc}}(\Omega)
$$

where $k_{j} \in \mathscr{K}$ and $1 \leqq p_{j}<\infty$ for all $j$. For every $f \in \mathscr{F}$ which is orthogonal to the finite dimensional space

$$
N=\left\{\varphi \in C_{0}^{\infty}(\Omega) ;{ }^{t} P \varphi=0\right\}
$$

one can then find $u$ such that $u \in \mathscr{F}_{1}$ and $P u=f$.
Proof. That $N$ is finite dimensional follows from the $P$-convexity and Theorem 3.1. $\mathscr{F}$ and $\mathscr{F}_{1}$ are Fréchet spaces. The dual space of $\mathscr{F}$ is

$$
\mathscr{F}^{\prime}=\left\{w \in \mathscr{E}^{\prime}(\Omega) ; w \in \mathscr{B}_{p^{\prime}, k_{j}^{\prime}}, \text { some } j\right\}
$$

and the dual space $\mathscr{F}_{1}^{\prime}$ of $\mathscr{F}_{1}$ is defined in the same way except with $\left(k_{j} \tilde{P}\right)^{\prime}$ instead of $k_{j}^{\prime}$. We have to prove that the range of $P$ in $\mathscr{F}$ is the annihilator of $N$. As in the proof of Theorem 3.5 it follows that this means that the intersection of the range of ${ }^{t} P$ in $\mathscr{F}_{1}^{\prime}$ and the unit ball in $\mathscr{E}^{\prime}(K) \cap \mathscr{B}_{p_{j}^{\prime},\left(k_{j} \tilde{P}\right)^{\prime}}$ is weakly closed in $\mathscr{F}_{1}^{\prime}$ for every $j$ and every $K \subset \subset \Omega$. Let $\mathscr{W}$ be a filter in this intersection. Thus

$$
w \in \mathscr{E}^{\prime}(K), \quad w={ }^{t} P v \quad \text { for some } \quad v \in \mathscr{F}^{\prime}, \quad\|w\|_{p_{j}^{\prime},\left(k_{j} \tilde{P}\right)^{\prime}} \leqq 1
$$

for every element $w$ of a set in $\mathscr{W}$. We may assume that $v$ is orthogonal to $N$. The $P$-convexity condition and Lemma 3.3 give then that $v \in \mathscr{E}^{\prime}\left(K^{\prime}\right)$ for some compact set $K^{\prime}$ in $\Omega$ and

$$
\|v\|_{p^{\prime}, k_{j}^{\prime}} \leqq B
$$

The ball of radius $B$ in $\mathscr{B}_{p_{j}^{\prime}, k_{j}^{\prime}}$ is weakly compact in $\mathscr{F}^{\prime}$. The inverse image by ${ }^{t} P$ of $\mathscr{W}$ therefore has a cluster point $v_{0}$ weakly in $\mathscr{F}^{\prime}$. Then ${ }^{t} P v_{0}$ is a cluster point of $\mathscr{W}$ so the proof is complete.

We shall now prove a converse of Theorem 3.1 by first showing that estimates of the type (3.5) must be valid and then deducing such estimates for ${ }^{t} Q$ when $Q \in L(P)$.

Theorem 3.7. Let $\Omega$ and $\Omega^{\prime}$ be open sets such that $\Omega^{\prime} \subset \subset \Omega \subset \mathbf{R}^{n}$ and let $P$ be a differential operator of constant strength in $\Omega$. Let $p \neq \infty$ and assume that $P\left(\mathscr{B}_{p, k \bar{P}}\left(\bar{\Omega}^{\prime}\right)\right)$ has finite codimension in $\mathscr{B}_{p, k}\left(\bar{\Omega}^{\prime}\right)$ for all $k \in \mathscr{K}$. Then for all $k \in \mathscr{K}$
and all $Q \in L(P)$ there is a constant $C$ such that

$$
\begin{equation*}
\|v\|_{p^{\prime}, k^{t} \bar{Q}} \leqq C\left\|^{\boldsymbol{t}} Q v\right\|_{p^{\prime}, k}, \quad v \in C_{0}^{\infty}\left(\Omega^{\prime}\right) . \tag{3.9}
\end{equation*}
$$

If $w \in \mathscr{E}^{\prime}\left(\Omega^{\prime}\right), Q \in L(P)$ and ${ }^{t} Q w=0$ then $w=0$.
One example of an operator such that the condition (3.1) is not fulfilled was given in the introduction. Another can be constructed in the following way. Let $P_{0}(x, D)$ be the operator of Theorem 2 in Pliš [10] considered as an operator in $\mathbf{R}^{\mathbf{4}}$. Denote the last variable in $\mathbf{R}^{4}$ by $y$. If

$$
P(x, y, D)=D_{y}^{2} P_{0}\left(x, D_{x}\right)+D_{y} Q_{1}\left(x, D_{x}\right)+Q_{2}\left(x, D_{x}\right)
$$

where $Q_{1}$ and $Q_{2}$ are of order $\leqq 3$ then $P$ has constant strength. Since $P_{0}\left(x, D_{x}\right) \in L(P)$ the condition (3.1) is not satisfied. Thus Theorem 3.7 shows that the conclusion of Theorem 3.1 cannot hold for this $P$.

Proof of Theorem 3.7. Let $k_{0}$ be any function in $\mathscr{K}$ and set $h_{0}=k_{0} / \widetilde{P}$. Let $\varphi_{1}, \ldots, \varphi_{N}$ be representatives for a basis in $\mathscr{B}_{p, h_{0}}\left(\bar{\Omega}^{\prime}\right) / P\left(\mathscr{B}_{p, k_{0}}\left(\bar{\Omega}^{\prime}\right)\right)$. The space $C^{\infty}\left(\bar{\Omega}^{\prime}\right)$ is dense in $\mathscr{B}_{p, h_{0}}\left(\bar{\Omega}^{\prime}\right)$ since $p \neq \infty$, and $P\left(\mathscr{B}_{p, k_{0}}\left(\bar{\Omega}^{\prime}\right)\right)$ is closed as it has finite codimension and $P$ is continuous. Therefore $\varphi_{1}, \ldots, \varphi_{N}$ can be chosen in $C^{\infty}\left(\bar{\Omega}^{\prime}\right)$. Define a continuous linear operator $T$ from $\mathscr{B}_{p, k_{0}}\left(\bar{\Omega}^{\prime}\right) \oplus \mathbf{C}^{N}$ to $\mathscr{B}_{p, h_{0}}\left(\bar{\Omega}^{\prime}\right)$ by

$$
T\left(v, a_{1}, \ldots, a_{N}\right)=P v+\sum_{v=1}^{N} a_{v} \varphi_{v}
$$

The adjoint ${ }^{t} T$ of $T$ is a continuous linear operator from $V_{p^{\prime}, h_{0}^{\prime}}\left(\bar{\Omega}^{\prime}\right)$ to $V_{p^{\prime}, k_{0}}\left(\bar{\Omega}^{\prime}\right) \oplus$ $\oplus \mathbf{C}^{N}$ and

$$
\left.{ }^{t} T(v)={ }^{t} P v,\left\langle\varphi_{1}, v\right\rangle, \ldots,\left\langle\varphi_{N}, v\right\rangle\right) .
$$

Since $T$ is surjective ${ }^{t} T$ is injective and its image is closed. Then by the closed graph theorem it has a continuous inverse so

$$
\begin{equation*}
\|v\|_{p^{\prime}, h_{0}^{\prime}} \leqq C\left(\|t P v\|_{p^{\prime}, k_{0}^{\prime}}+\sum_{v=1}^{N}\left|\left\langle v, \varphi_{v}\right\rangle\right|\right), \quad v \in V_{p^{\prime}, h_{0}^{\prime}}\left(\bar{\Omega}^{\prime}\right) . \tag{3.10}
\end{equation*}
$$

From this inequality we are going to obtain (3.9) for given $Q \in L(P)$ and $k \in \mathscr{K}$. For some sequence $\xi_{j} \rightarrow \infty$ we have

$$
{ }^{t} Q(\cdot, \xi)=\lim ^{t} P\left(\cdot, \xi+\xi_{j}\right) / \tilde{P}\left(-\xi_{j}\right)
$$

To get ${ }^{t} Q$ instead of ${ }^{t} P$ in (3.10) it is natural to replace $v$ by $\exp \left(i\left\langle x, \xi_{j}\right\rangle\right) v$ and divide both sides by $\widetilde{P}\left(-\xi_{j}\right)$. Indeed, $\left\|^{t} P v\right\|_{p^{\prime}, k_{0}^{\prime}}$ is then replaced by

$$
\begin{equation*}
\left\|t P\left(\cdot, D+\xi_{j}\right) v / \widetilde{P}\left(-\xi_{j}\right)\right\|_{p^{\prime}, k_{j}} \tag{3.11}
\end{equation*}
$$

where

$$
k_{j}(\xi)=1 / k_{0}\left(-\xi-\xi_{j}\right)
$$

The term $\|v\|_{p^{\prime}, h_{0}^{\prime}}$ is replaced by
with the notation

$$
\begin{gather*}
\|v\|_{p^{\prime}, \widetilde{P}_{j} k_{j}}  \tag{3.12}\\
\tilde{P}_{j}(\xi)=\widetilde{P}\left(-\xi-\xi_{j}\right) / \widetilde{P}\left(-\xi_{j}\right) .
\end{gather*}
$$

The sum is replaced by

$$
\sum_{v=1}^{N}\left|\widehat{\varphi_{v} v}\left(-\xi_{j}\right) / \tilde{P}\left(-\xi_{j}\right)\right|
$$

Now let $j$ tend to infinity. Then the sum obviously tends to 0 since $v \varphi_{v} \in C_{0}^{\infty}$ if $v \in C_{0}^{\infty}\left(\Omega^{\prime}\right)$. The functions

$$
{ }^{t} P\left(\cdot, D+\xi_{j}\right) v / \widetilde{P}\left(-\xi_{j}\right)
$$

tend to ${ }^{t} Q v$ in $\mathscr{S}$. Clearly $\widetilde{P}_{j} \rightarrow^{t} \widetilde{Q}$ uniformly on every compact set and $\widetilde{P}_{j}$ is uniformly bounded by a power of $(1+|\xi|)$. Assume that $k_{j}(\xi)$ tends to $k(\xi)$ uniformly on every compact set and is uniformly bounded by a power of $(1+|\xi|)$. Then if $p^{\prime} \neq \infty$ it follows by dominated convergence that the limits of (3.11) and (3.12) as $j \rightarrow \infty$ are $\left\|^{t} Q v\right\|_{p^{\prime}, k}$ and $\|v\|_{p^{\prime}, k^{t} \tilde{Q}}$ respectively. If $p^{\prime}=\infty$ it is also clear that we obtain (3.9) when $j \rightarrow \infty$. Thus the following lemma applied to $k^{\prime}$ will complete the proof of (3.9).

Lemma 3.8. Let $\xi_{j} \in \mathbf{R}^{n}, \xi_{j} \rightarrow \infty$ and $k \in \mathscr{K}$. Then there is a subsequence $\xi_{j_{k}}$ of $\xi_{j}$ and a function $k_{0} \in \mathscr{K}$ such that $k_{0}\left(\xi+\xi_{j_{k}}\right) \rightarrow k(\xi)$ uniformly on every compact set.

Proof. Take a sequence $r_{k} \in \mathbf{R}, r_{k} \rightarrow \infty$, and a subsequence $\xi_{j_{k}}$ of $\xi_{j}$ such that the sets $M_{k}=\left\{\xi ;\left|\xi-\xi_{j_{k}}\right| \leqq 2 r_{k}\right\}$ are all disjoint. To shorten notations we assume that $\xi_{j_{k}}=\xi_{k}$. Let $A_{k}=\left\{\xi ; r_{k} \leqq\left|\xi-\xi_{k}\right| \leqq 2 r_{k}\right\}$ and $m_{k}=\left\{\xi ;\left|\xi-\xi_{k}\right| \leqq r_{k}\right\}$. For $\xi \in A_{k}$ define $\tilde{\xi}^{k}$ by

$$
\frac{1}{2}\left(\xi-\xi_{k}+\tilde{\xi}-\xi_{k}\right)=r_{k}\left(\xi-\xi_{k}\right) /\left|\xi-\xi_{k}\right|
$$

The point $\tilde{\xi}$ is the reffection of $\xi$ in the tangent plane of $\partial m_{k}$ where the line through $\xi_{k}$ and $\xi$ cuts $\partial m_{k}$. Geometrically, or by writing down the lengths of $\xi-\eta$ and $\tilde{\xi}-\tilde{\eta}$ by the cosine theorem one easily sees that $|\tilde{\xi}-\tilde{\eta}| \leqq|\xi-\eta|$ if $\xi, \eta \in A_{k}$. Define a positive function $k_{0}$ by

$$
\begin{array}{ll}
k_{0}(\xi)=\dot{k}\left(\xi-\xi_{k}\right) & \text { when } \quad \xi \in m_{k} \\
k_{0}(\xi)=k\left(\tilde{\xi}-\xi_{k}\right) & \text { when } \xi \in A_{k} \\
k_{\mathbf{0}}(\xi)=k(0) & \text { when } \quad \xi \in \mathbf{R}^{n} \backslash \cup M_{k} .
\end{array}
$$

If $C$ and $N$ are the constants occurring in the estimate (2.1) for $k$ it is clear that

$$
\begin{equation*}
k_{0}(\xi) \leqq(1+C|\xi-\eta|)^{N} k_{0}(\eta) \tag{3.13}
\end{equation*}
$$

if both $\xi$ and $\eta$ belong to the same $m_{k}$ or the same $A_{k}$. If $\xi \in m_{k}$ and $\eta \in A_{k}$ take a point $\xi_{0} \in \partial m_{k}$ such that $\left|\xi-\xi_{0}\right| \leqq|\xi-\eta|$ and $\left|\eta-\xi_{0}\right| \leqq|\xi-\eta|$. Then by applying (3.13) first to $\xi$ and $\xi_{0}$ then to $\xi_{0}$ and $\eta$ we get

$$
k_{0}(\xi) \leqq(1+C|\xi-\eta|)^{2 N} k_{0}(\eta)
$$

If $\xi \in M_{k_{1}}$ and $\eta \in M_{k_{2}}$ we obtain in the same way by taking a point $\xi_{0}$ on $\partial M_{k_{1}}$ and applying this estimate twice that

$$
k_{0}(\xi) \leqq(1+C|\xi-\eta|)^{4 N} k_{0}(\eta) .
$$

Thus this last inequality is valid for all $\xi, \eta \in \mathbf{R}^{n}$ and the proof of the lemma is complete.

End of the proof of Theorem 3.7. To obtain the last statement of the theorem we just have to note that $C_{0}^{\infty}\left(\Omega^{\prime}\right)$ is dense in $\mathscr{E}^{\prime}\left(\Omega^{\prime}\right) \cap \mathscr{B}_{p^{\prime}, k^{\prime} \tilde{Q}}$ if $p \neq 1$. Hence (3.9) can be extended by continuity to $v \in \mathscr{E}^{\prime}\left(\Omega^{\prime}\right) \cap \mathscr{B}_{p^{\prime}, k t \check{Q}}$. Since any $v \in \mathscr{E}^{\prime}\left(\Omega^{\prime}\right)$ belongs to some $\mathscr{B}_{p, k}$ space with $p \neq 1, \infty$ it follows that the equation ${ }^{t} Q w=0$ cannot have any nontrivial solution in $\mathscr{E}^{\prime}\left(\Omega^{\prime}\right)$. This completes the proof of Theorem 3.7.

The following theorem shows that in order to verify that the condition (3.1) is fulfilled it is sufficient to consider $C_{0}^{\infty}$ densities in certain subspaces.

Theorem 3.9. Let $\Omega$ be an open set in $\mathbf{R}^{n}$ and let $P$ be a differential operator of constant strength in $\Omega$. Assume that for all $Q \in L(P)$ and all affine subspaces $\Sigma$ parallel to $\Lambda^{\prime}(Q)$

$$
\begin{equation*}
\varphi \in C_{0}^{\infty}(\Sigma \cap \Omega), \quad{ }^{t} Q_{\Sigma} \varphi=0 \Rightarrow \varphi=0 \tag{3.14}
\end{equation*}
$$

Then for all $Q \in L(P)$ we have

$$
\begin{equation*}
{ }^{t} Q w=0, \quad w \in \mathscr{E}^{\prime}(\Omega) \Rightarrow w=0 \tag{3.15}
\end{equation*}
$$

Recall that $Q_{\Sigma}$ is the operator $Q$ considered as a differential operator in the open set $\Sigma \cap \Omega$ of $\Sigma$.

Proof of Theorem 3.9. The theorem is proved by induction over the dimension $n$.

1. When $n=1$ all localizations of $P$ at infinity are nowhere vanishing functions so (3.15) is trivially valid.
2. Assume that the theorem is true for all differential operators in open sets of $\mathbf{R}^{j}$ when $j<n$ and let $P$ be an operator in $\Omega \subset \mathbf{R}^{n}$ satisfying the hypothesis of the theorem. Let $Q \in L(P)$. Then $\operatorname{dim} \Lambda^{\prime}(Q)<n$. Let $\Sigma$ be parallel to $\Lambda^{\prime}(Q)$ and consider the operator $Q_{\Sigma}$ in the open set $\Sigma \cap \Omega \subset \mathbf{R}^{j}$. If $R \in L(Q)$ then $R \in L(P)$.

Hence all $R \in L\left(Q_{\Sigma}\right)$ satisfy (3.14) and then the induction hypothesis gives that the conclusion of the theorem is valid for $Q_{\Sigma}$, that is

$$
R \in L\left(Q_{\Sigma}\right), \quad w \in \mathscr{E}^{\prime}(\Omega \cap \Sigma), \quad{ }^{t} R w=0 \Rightarrow w=0
$$

Here $\mathscr{E}^{\prime}(\Omega \cap \Sigma)$ denotes distributions of compact support in the open set $\Omega \cap \Sigma \subset \mathbf{R}^{j}$ and not a space of distributions in $\mathbf{R}^{n}$. Thus $Q_{\Sigma}$ satisfies the condition (3.1) and therefore Theorem 3.1 and (3.14) imply that ${ }^{t} Q_{\Sigma}$ has no non trivial solution in $\mathscr{E}^{\circ}$. Then Lemma 3.3 gives that if $\Omega^{\prime} \subset \subset \Omega$ and $k \in \mathscr{K}$ there is a constant $C$ such that

$$
\begin{equation*}
\|\varphi\|_{2, k^{t} \tilde{Q}} \leqq C\left\|^{t} Q_{\Sigma} \varphi\right\|_{2, k} \text { for all } \varphi \in C_{0}^{\infty}\left(\Omega^{\prime} \cap \Sigma\right) \tag{3.16}
\end{equation*}
$$

We will prove such an estimate for functions $\Phi \in C_{0}^{\infty}(\Omega)$ with ${ }^{t} Q$ instead of ${ }^{t} Q_{\Sigma}$. Then (3.15) will follow easily. Choose coordinates ( $x^{\prime}, x^{\prime \prime}$ ) so that

$$
\Lambda^{\prime}(Q)=\left\{\left(x^{\prime}, x^{\prime \prime}\right) ; x^{\prime \prime}=0\right\}, \quad \Sigma=\left\{\left(x^{\prime}, x^{\prime \prime}\right) ; x^{\prime \prime}=x_{0}^{\prime \prime}\right\}
$$

Now ${ }^{t} \widetilde{Q}$ depends only on the $\xi^{\prime}$ variables. Let $\Omega^{\prime}$ be relatively compact in $\Omega$ and choose $\Phi \in C_{0}^{\infty}(\Omega)$ so that $\left(x^{\prime}, x_{0}^{\prime \prime}\right) \in \Sigma \cap \Omega^{\prime}$ if $\left(x^{\prime}, x^{\prime \prime}\right) \in \operatorname{supp} \Phi$. Then the function $\hat{\Phi}^{\prime \prime}\left(\cdot, \xi^{\prime \prime}\right)$ given by

$$
\hat{\Phi}^{\prime \prime}\left(x^{\prime}, \xi^{\prime \prime}\right)=\int \exp \left(-i\left\langle x^{\prime \prime}, \xi^{\prime \prime}\right\rangle\right) \Phi\left(x^{\prime}, x^{\prime \prime}\right) d x^{\prime \prime}
$$

belongs to $C_{0}^{\infty}\left(\Omega^{\prime} \cap \Sigma\right)$. Take $k_{1}$ and $k_{2} \in \mathscr{K}$ such that $k_{1}$ only depends on the $\xi^{\prime}$ variables and $k_{2}$ only depends on the $\xi^{\prime \prime}$ variables. If we apply (3.16) to $\hat{\Phi}^{\prime \prime}\left(x^{\prime}, \xi^{\prime \prime}\right)$, multiply by $k_{2}\left(\xi^{\prime \prime}\right)$ and integrate it follows that

$$
\begin{equation*}
\|\Phi\|_{2_{2} k^{t} \tilde{Q}} \leqq C\left\|^{t} Q\left(x^{\prime}, x_{0}^{\prime \prime}, D_{x^{\prime}}\right) \Phi\right\|_{2, k} \tag{3.17}
\end{equation*}
$$

if $k=k_{1} k_{2}$. To obtain ${ }^{t} Q\left(x^{\prime}, x^{\prime \prime}, D_{x^{\prime}}\right)$ in the right hand side note that since $Q$ has constant strength we have

$$
{ }^{t} Q\left(x^{\prime}, x^{\prime \prime}, D_{x^{\prime}}\right)-{ }^{t} Q\left(x^{\prime}, x_{0}^{\prime \prime}, D_{x^{\prime}}\right)=\sum_{j} c_{j}\left(x^{\prime}, x^{\prime \prime}\right) Q_{j}\left(D_{x^{\prime}}\right)
$$

with some $Q_{j}<^{t} Q_{x_{0}}, c_{j} \in C^{\infty}$ such that $c_{j}\left(x^{\prime}, x_{0}^{\prime \prime}\right)=0$. If the support of $\Phi$ is sufficiently near $\Sigma$ this shows that

$$
\begin{equation*}
\left\|{ }^{t} Q\left(x^{\prime}, x_{0}^{\prime \prime}, D_{x^{\prime}}\right) \Phi\right\|_{2, k} \leqq\|Q \Phi\|_{2, k}+1 /(2 C)\|\Phi\|_{2, k^{t}} \tilde{Q} \tag{3.18}
\end{equation*}
$$

The estimates (3.17) and (3.18) imply that

$$
\begin{equation*}
\|\Phi\|_{2, k^{t} \tilde{Q}} \leqq 2 C\left\|^{t} Q \Phi\right\|_{2, k} \tag{3.19}
\end{equation*}
$$

if the support of $\Phi$ belongs to

$$
\begin{equation*}
\left\{\left(x^{\prime}, x^{\prime \prime}\right) \in \Omega ;\left|x^{\prime \prime}-x_{0}^{\prime \prime}\right|<\varepsilon \text { and }\left(x^{\prime}, x_{0}^{\prime \prime}\right) \in \Sigma \cap \Omega^{\prime}\right\} \tag{3.20}
\end{equation*}
$$

and $\varepsilon$ is sufficiently small. The estimate (3.19) can be extended by continuity to $w \in \mathscr{B}_{2, k t \tilde{Q}}$ with support in the set (3.20). Now let $w \in \mathscr{E}^{\prime}(\Omega)$ and ${ }^{t} Q w=0$. There is a partition of unity in $\Omega$ consisting of functions $\chi_{v}$ depending only on the $x^{\prime \prime}$
variables such that an estimate of the form (3.19) is valid for each $\chi_{\nu} w$. Since $Q$ contains only derivatives in the $x^{\prime}$ variables we have ${ }^{t} Q\left(\chi_{\nu} w\right)=0$. It follows that $w=0$ so the proof is complete.

We shall end this section by considering operators $P$ of constant strength defined in an open set $\Omega \subset \mathbf{R}^{n}$ such that $\Lambda^{\prime}(P) \neq \mathbf{R}^{n}$. Then $P$ is a localization of itself at infinity. Thus (3.1) cannot hold if the adjoint of some $P_{\Sigma}$ with $\Sigma$ parallel to $\Lambda^{\prime}(P)$ has a non trivial solution in $\mathscr{E}^{\prime}$. Clearly a necessary condition for solvability of the equation $P u=f$ is in general that the restriction of $f$ to each $\Sigma$ parallel to $\Lambda^{\prime}(P)$ satisfies a number of linear conditions. Examples of operators with $\Lambda^{\prime} \neq \mathbf{R}^{n}$ are the non-hypoelliptic operators of local type. For these operators we shall prove an existence theorem which will be used in the next section.

First we introduce some convenient notations. For an operator $Q$ of local type there are coordinates

$$
\left(x^{\prime}, x^{\prime \prime}\right)=\left(x_{1}^{\prime}, \ldots, x_{n^{\prime}}^{\prime}, x_{1}^{\prime \prime}, \ldots, x_{n^{\prime \prime}}^{\prime \prime}\right)
$$

such that

$$
\Lambda^{\prime}(Q)=\left\{\left(x^{\prime}, x^{\prime \prime}\right) ; x^{\prime \prime}=0\right\}
$$

It is natural to assume that $Q$ is defined in a product domain

$$
\Omega_{c}=\Omega \times\left\{x^{\prime \prime} ;\left|x^{\prime \prime}\right|<c\right\}
$$

for some $\Omega$ open in $\mathbf{R}^{n^{\prime}}$ and $c>0$. For $\left|x^{\prime \prime}\right|<c$ we denote the operator $Q\left(x^{\prime}, x^{\prime \prime}, D_{x^{\prime}}\right)$ in $\Omega$ by $Q_{x^{\prime \prime}}$.

Theorem 3.10. Let $Q$ be of local type defined in a product domain $\Omega_{c}$ as above and let $\omega$ be relatively compact in $\Omega$. If $\varepsilon$ is small enough there is for each $x^{\prime \prime}$ with $\left|x^{\prime \prime}\right|<\varepsilon$ defined a linear operator $E_{x^{\prime \prime}}$ from $\mathscr{D}^{\prime}(\Omega)$ to $\mathscr{D}^{\prime}(\Omega)$ such that if $f \in C^{\infty}\left(\Omega_{\varepsilon}\right)$ and

$$
\begin{equation*}
u\left(\cdot, x^{\prime \prime}\right)=E_{x^{\prime \prime}}\left(f\left(\cdot, x^{\prime \prime}\right)\right) \tag{3.21}
\end{equation*}
$$

then $u \in C^{\infty}\left(\Omega_{\varepsilon}\right)$. In addition $Q u=f$ near $\bar{\omega} \times\left\{x^{\prime \prime} ;\left|x^{\prime \prime}\right|<\varepsilon\right\}$ if for certain finitely many functions $a_{1}, \ldots, a_{M} \in C^{\infty}\left(\Omega_{\varepsilon}\right)$ such that $a_{j}\left(\cdot, x^{\prime \prime}\right) \in C_{0}^{\infty}(\Omega)$ for all $x^{\prime \prime}, j$ we have

$$
\left\langle a_{j}\left(\cdot, x^{\prime \prime}\right), f\left(\cdot, x^{\prime \prime}\right)\right\rangle=0, \quad j=1, \ldots, M, \quad\left|x^{\prime \prime}\right|<\varepsilon .
$$

If there is a neighborhood of $\bar{\omega}$ where the equation $Q_{0} U=F$ can be solved for all $F$ then $E_{x^{\prime \prime}}$ can be chosen so that all $a_{j}$ vanish.

Proof. By Theorem 4.2 in Hörmander [5] there is for all $x^{\prime \prime}$ a properly supported pseudo-differential operator $A_{x^{\prime \prime}}$ in $\Omega$ which is a parametrix of $Q_{x^{\prime \prime}}$. The construction of $A_{x^{\prime \prime}}$ shows that its symbol is a $C^{\infty}$ function of ( $x^{\prime}, x^{\prime \prime}, \xi^{\prime}$ ). Thus

$$
\begin{equation*}
Q_{x^{\prime \prime}} A_{x^{\prime \prime}} G=G+T_{x^{\prime \prime}} G, \quad G \in \mathscr{D}^{\prime}(\Omega) \tag{3.22}
\end{equation*}
$$

where $T_{x^{\prime \prime}}$ is a properly supported integral operator in $\Omega$ with a kernel which is a $C^{\infty}$ function of $x^{\prime \prime}$ with values in $C^{\infty}(\Omega \times \Omega)$. If $T_{x^{\prime \prime}}$ is replaced by $K_{x^{\prime \prime}}=$ $=\chi T_{x^{\prime \prime}}$, where $\chi \in C_{0}^{\infty}(\Omega), \chi=1$ near $\bar{\omega}$, then (3.22) is still valid near $\bar{\omega}$. Since $T_{x^{\prime \prime}}$ is properly supported the kernel of $K_{x^{\prime \prime}}$ has support in a fixed compact set in $\Omega \times \Omega$ for all $x^{\prime \prime}$ near 0 . The equation $G+K_{x^{\prime \prime}} G=F$ can be solved by classical Fredholm theory. For the sake of completeness we give a proof.

Lemma 3.11. If $\varepsilon$ is sufficiently small then there exists for all $x^{\prime \prime}$ with $\left|x^{\prime \prime}\right|<\varepsilon$ a properly supported integral operator $R_{x^{\prime \prime}}$ with a kernel which is a $C^{\infty}$ function of $x^{\prime \prime}$ with values in $C_{0}^{\infty}(\Omega \times \Omega)$, such that

$$
\left(I+K_{x^{\prime \prime}}\right)\left(I+R_{x^{\prime \prime}}\right)=I-H_{x^{\prime \prime}}
$$

where

$$
H_{x^{\prime \prime}} F=\sum_{j=1}^{M}\left\langle a_{j}\left(\cdot, x^{\prime \prime}\right), F\right\rangle \varphi_{j}
$$

$\varphi_{j} \in C_{0}^{\infty}(\Omega)$ and $a_{j}$ are as in the statement of Theorem 3.10.
Proof. $K_{0}$ is a compact operator from $\mathscr{H}_{(s)}$ to $\mathscr{H}_{(s)}$ for all $s$ so it follows that $I+K_{0}$ is a Fredholm operator in all the spaces $\mathscr{H}_{(s)}$. Note that $F \in \mathscr{H}_{(s)}$ if and only if $F+K_{0} F \in \mathscr{H}_{(s)}$. Since $\psi+{ }^{t} K_{0} \psi=0$ implies that $\psi \in C_{0}^{\infty}(\Omega)$ there are finitely many linearly independent functions $\psi_{1}, \ldots, \psi_{M} \in C_{0}^{\infty}(\Omega)$ such that

$$
F \in \operatorname{Im}\left(I+K_{0}\right) \Leftrightarrow\left\langle F, \psi_{j}\right\rangle=0, \quad j=1, \ldots, M .
$$

The operator $I+K_{0}$ is bijective from the orthogonal complement of its null space in $L^{2}$ to its range in $L^{2}$. By the closed graph theorem it has a continuous inverse $Y$ between these spaces. Denote the orthogonal projection in $L^{2}$ on the null space of $I+{ }^{t} \bar{K}_{0}$ by $H_{0}$ and the orthogonal projection in $L^{2}$ on the null space of $I+K_{0}$ by $P_{0}$. Note that

$$
H_{0} F=\sum_{j=1}^{M}\left\langle F, \psi_{j}\right\rangle \Psi_{j}
$$

if $\psi_{1}, \ldots, \psi_{M}$ are chosen orthonormal in $L^{2}$. If $I+R_{0}=Y\left(I-H_{0}\right)$ then

$$
\left(I+R_{0}\right)\left(I+K_{0}\right) F=F-P_{0} F, \quad\left(I+K_{0}\right)\left(I+R_{0}\right) F=F-H_{0} F
$$

for all $F \in L^{2}$. After multiplication of the first identity by $K_{0}$ from the left we obtain

$$
K_{0} R_{0}+K_{0}^{2}+K_{0} R_{0} K_{0}+K_{0} P_{0}=R_{0}+K_{0}+K_{0} R_{0}+H_{0}
$$

It follows then that

$$
R_{0}=-H_{0}-K_{0}+K_{0} P_{0}+K_{0}^{2}+K_{0} R_{0} K_{0}
$$

This shows that $R_{0}$ is an operator with $C^{\infty}$ kernel of compact support in $\Omega \times \Omega$ for $K_{0}, H_{0}$ and $P_{0}$ have this property.

Put $\left(K_{x^{\prime \prime}}-K_{0}\right)\left(I+R_{0}\right)=V_{x^{\prime \prime}}$. Since $V_{0}=0$ there exists $\varepsilon>0$ such that the operator $I+V_{x^{\prime \prime}}$ has an inverse $I+S_{x^{\prime \prime}}$ in $L^{2}$, say, when $\left|x^{\prime \prime}\right|<\varepsilon$. This inverse is
a $C^{\infty}$ function of $x^{\prime \prime}$ with values in $L\left(L^{2}, L^{2}\right)$. A computation similar to the one carried out for $R_{0}$ above gives that

$$
S_{x^{\prime \prime}}=-V_{x^{\prime \prime}}+V_{x^{\prime \prime}}^{2}+V_{x^{\prime \prime}} S_{x^{\prime \prime}} V_{x^{\prime \prime}},
$$

so it follows that $S_{x^{\prime \prime}}$ is in fact an operator with a kernel which is a $C^{\infty}$ function of $x^{\prime \prime}$ with values in $C_{0}^{\infty}(\Omega \times \Omega)$. Thus the statement of the lemma holds for $I+R_{x^{\prime \prime}}=\left(I+R_{0}\right)\left(I+S_{x^{\prime \prime}}\right)$ and $H_{x^{\prime \prime}} F=\Sigma\left\langle\left(I+S_{x^{\prime \prime}}\right) F, \psi_{j}\right\rangle \bar{\psi}_{j}$, so the proof is complete.

End of the proof of Theorem 3.10. If we do not require that all the functions $a_{j}$ vanish then Lemma 3.11 shows that $E_{x^{\prime \prime}}=A_{x^{\prime \prime}}\left(I+R_{x^{\prime \prime}}\right)$ has the desired properties. The proof of Lemma 3.11 shows that if $K_{0}$ is 0 then $H$ will be 0 so all the functions $a_{j}$ vanish in that case. If the equation $Q_{0} U=F$ can be solved for all $F$ in an open set $\omega^{\prime} \supset \supset \omega$ then $A_{x^{\prime \prime}}$ can be modified so that $K_{0}$ becomes 0 . In fact by the closed graph theorem there is a continuous linear operator $B$ from $L^{2}\left(\omega^{\prime}\right)$ to $\mathscr{B}_{2, \bar{Q}}\left(\bar{\omega}^{\prime}\right)$ such that $Q_{0} B F=F$. Let $\psi \in C_{0}^{\infty}\left(\omega^{\prime}\right), \psi=1$ near $\bar{\omega}$. The operator $\psi B T_{x^{\prime \prime}}$ is properly supported and it has $C^{\infty}$ kernel since $Q_{0}$ is hypoelliptic. If $\tilde{A}_{x^{\prime \prime}}=A_{x^{\prime \prime}}-\psi B T_{x^{\prime \prime}}$ then

$$
Q_{x^{\prime \prime}}\left(\tilde{A}_{x^{\prime \prime}} G\right)=G+T_{x^{\prime \prime}} G-Q_{x^{\prime \prime}}\left(\psi B T_{x^{\prime \prime}} G\right)=G+\tilde{T}_{x^{\prime \prime}} G
$$

where the latter equality is a definition. We have $\tilde{T}_{0} G=0$ in the open set where $\psi=1$. Thus if $\chi$ has support in this set and $K_{x^{\prime \prime}}=\chi \widetilde{T}_{x^{\prime \prime}}$ then $K_{0}=0$. This completes the proof of the theorem.

## 4. Solutions with singularities in affine subspaces

In this section we prove extensions of Theorem 1.1. Let $P$ be of constant strength, defined in an open set $\Omega, Q \in L(P), \Sigma$ an affine subspace parallel to $\Lambda^{\prime}(Q)$ and $\Sigma_{0}$ a component of $\Sigma \cap \Omega$. The first step is to rephrase the negation of the statement of Theorem 1.1 as an inequality. For a positive integer $m$ let

$$
\mathscr{F}=\left\{u \in C^{m}(\Omega) ; u \in C^{\infty}\left(\Omega \backslash \Sigma_{0}\right), P u \in C^{\infty}(\Omega)\right\} .
$$

$\mathscr{F}$ is a Fréchet space with the weakest topology making the maps

$$
\mathscr{F} \ni u \rightarrow C^{m}(\Omega), \quad \mathscr{F} \ni u \rightarrow C^{\infty}\left(\Omega \backslash \Sigma_{0}\right), \quad \mathscr{F} \ni u \rightarrow P u \in C^{\infty}(\Omega)
$$

continuous. From the closed graph theorem one easily obtains the following lemma.
Lemma 4.1. Let $V$ be open, relatively compact in $\Omega$. If

$$
\left\{u ; u \in \mathscr{F}, u \in C^{m+1}(\bar{V})\right\}
$$

is of the second category in $\mathscr{F}$ then there exist $v \in \mathbf{Z}^{+}, K_{1} \subset \subset \Omega$ and $K_{2} \subset \subset \Omega \backslash \Sigma_{0}$ such that
$\sum_{|\alpha|=m+1} \sup _{V}\left|D^{\alpha} u\right| \leqq C\left\{\sum_{|\alpha| \leqq m} \sup _{K_{1}}\left|D^{\alpha} u\right|+\sum_{|\alpha| \leqq v} \sup _{K_{1}}\left|D^{\alpha}(P u)\right|+\sum_{|\alpha| \leqq v} \sup _{K_{2}}\left|D^{\alpha} u\right|\right\}$
for all $u \in C^{m+1}(\bar{V}) \cap \mathscr{F}$.
If we prove that (4.1) is always false when $V$ is a neighborhood of a point in $\Sigma_{0}$ then there exists a function $u \in \mathscr{F}$ such that $u$ is not in $C^{m+1}$ in a neighborhood of any point in $\Sigma_{0}$. For if $u \in \mathscr{F}$ and $u \in C^{m+1}$ in a neighborhood of some point in $\Sigma_{0}$ then

$$
u \in\left(\bigcup_{x_{0}, r} C^{m+1}\left(\left\{x ;\left|x-x_{0}\right| \leqq r\right\}\right)\right) \cap \mathscr{F}
$$

where the union is taken over a countable dense set of points $x_{0}$ in $\Sigma_{0}$ and countably many $r>0$. Since a countable union of sets of the first category in $\mathscr{F}$ is of the first category the assertion follows. This also shows that it is sufficient to consider $Q$ of local type. For by Proposition 2.7 there exists some $Q^{\prime}$ of local type such that $\Lambda^{\prime}\left(Q^{\prime}\right) \subset \Lambda^{\prime}(Q)$. If $x_{0} \in \Sigma_{0}$ is a given point one can therefore find a component $\Sigma_{0}^{\prime}$ of $\Sigma^{\prime} \cap \Omega$ for some $\Sigma^{\prime}$ parallel to $\Lambda^{\prime}\left(Q^{\prime}\right)$ such that $x_{0} \in \Sigma_{0}^{\prime} \subset \Sigma_{0}$. If we prove that (4.1) cannot be valid for any $K_{2} \subset \subset \Omega \backslash \Sigma_{0}^{\prime}$ then it cannot be valid for any $K_{2} \subset \subset \Omega \backslash \Sigma_{0}$. Hence it is no restriction to assume that $Q$ is of local type.

By Proposition 2.4 we may assume that

$$
Q(x, D)=\lim _{t \rightarrow \infty} P(x, D+\eta(t)) / a t^{\sigma}
$$

where $\eta(t)$ is a polynomial in $t, a>0$ and $\sigma$ is a positive integer. Note that

$$
R_{t}(x, D)=Q(x, D)-P(x, D+\eta(t)) / a t^{\sigma}
$$

has coefficients which are $O\left(t^{-1}\right)$. To prove that (4.1) is false one should construct functions $u^{t}$ such that the derivatives of $u^{t}$ of order $m+1$ are large compared with those of order $\leqq m, P u^{t}$ is small and $u^{t}$ is 0 in $K_{2}$. If $u_{0} \in C^{\infty}$ the function

$$
u^{t}=\exp (i\langle\cdot, \eta(t)\rangle) u_{0} / a t^{\sigma}
$$

or just $u$ for short, satisfies the first requirement if $t$ is large. We have

$$
P u=\exp (i\langle\cdot, \eta(t)\rangle) P(\cdot, D+\eta(t)) u_{0} / a t^{\sigma}
$$

so if $Q u_{0}=0$ then $P u$ will be equal to $-\exp (i\langle\cdot, \eta(t)\rangle) R_{t} u_{0}$ and thus the supremum of $|P u|$ over $K_{1}$ is $O\left(t^{-1}\right)$. To get a still better approximation we try to solve

$$
\exp (-i\langle\cdot, \eta(t)\rangle) P\left(u_{1} \exp (i\langle\cdot, \eta(t)\rangle) / a t^{\sigma}\right)=R_{t} u_{0}
$$

Since the left hand side is approximately $Q u_{1}$ and we only have an existence theorem for $Q$ we replace this equation by

$$
Q u_{1}=R_{t} u_{0}
$$

The coefficients of $R_{t}$ are $O\left(t^{-1}\right)$ so $u_{1}$ should be $O\left(t^{-1}\right)$. We have

$$
P\left(\left(u_{0}+u_{1}\right) \exp (i\langle\cdot, \eta(t)\rangle) / a t^{\sigma}\right)=-\exp (i\langle\cdot, \eta(t)\rangle) R_{t} u_{1}
$$

If we could solve $Q u_{2}=R_{t} u_{1}$ so that $u_{2}=O\left(t^{-2}\right), Q u_{3}=R_{t} u_{2}$ so that $u_{3}=O\left(t^{-3}\right)$, and so on we could define

$$
u^{t}=\sum_{j=0}^{N} u_{j} \exp (i\langle\cdot, \eta(t)\rangle) / a t^{\sigma} .
$$

Now the supremum of $|P u|^{t}$ over $K_{1}$ decreases as $t^{-N}$ as $t \rightarrow \infty$. By multiplying $u_{0}$ with a cutoff function which depends only on the variables of $\Lambda(Q)$ and is 0 in $K_{2}$ we could achieve that $u^{t}=0$ in $K_{2}$.

This idea of proof is easiest to carry through if the equation $Q u=f$ can be solved near. $\Sigma_{0} \cap K_{1}$ for an arbitrary right hand side, so we consider that case first. Then the equations $Q u_{1}=R_{t} u_{0}, Q u_{2}=R_{t} u_{1}$, and so on, can be solved successively if there is just one function $u_{0}$ such that $Q u_{0}=0$ to start with.

Theorem 4.2. Let $\Omega$ be open in $\mathbf{R}^{n}$ and let $P$ be a differential operator of constant strength in $\Omega$. Let $Q \in L(P)$ be of local type, let $\Sigma$ be an affine subspace parallel to $\Lambda^{\prime}(Q)$ and $\Sigma_{0}$ a component of $\Sigma \cap \Omega$. Assume that

$$
\begin{equation*}
v \in \mathscr{E}^{\prime}\left(\Sigma_{0}\right), \quad{ }^{t} Q_{\Sigma} v=0 \Rightarrow v=0 \tag{4.2}
\end{equation*}
$$

Denote by $S$ the set of all $x \in \Sigma_{0}$ such that for all $\omega \subset \subset \Sigma_{0}$ and all neighborhoods $V$ of $x$ there exists $U_{0} \in C^{\infty}\left(\Sigma_{0}\right)$ such that $Q_{\Sigma} U_{0}=0$ in $\omega$ and $U_{0} \not \equiv 0$ in $V \cap \Sigma_{0}$. Then for all positive integers $m$ there exists $u \in C^{m}(\Omega)$ such that $P u \in C^{\infty}(\Omega)$ and $S \subset$ sing supp $u \subset \Sigma_{0}$.

Proof. We have to prove that the inequality (4.1) is false for any neighborhood $V$ of a point $x_{0} \in S$ and given $K_{1}, K_{2}, v$. We shall construct functions $u^{t}$ as indicated above. Choose an open set $\Omega^{\prime}$ such that $K_{1} \cup K_{2} \subset \Omega^{\prime} \subset \subset \Omega$ and an open set $\omega \subset \subset \Sigma_{0}$ such that $\Sigma_{0} \cap \Omega^{\prime} \subset \subset \omega$. The coordinates $x=\left(x^{\prime}, x^{\prime \prime}\right), x^{\prime} \in \mathbf{R}^{n^{\prime}}, x^{\prime \prime} \in \mathbf{R}^{n^{\prime \prime}}$ can be chosen so that $\Sigma=\left\{x ; x^{\prime \prime}=0\right\}$. Put

$$
\omega_{\varepsilon}=\left\{x ; x^{\prime} \in \omega,\left|x^{\prime \prime}\right|<\varepsilon\right\}
$$

and define $Q_{x^{\prime \prime}}$ as before Theorem 3.10. If $\varepsilon$ is small then $\omega_{\varepsilon} \subset \subset \Omega, K_{2} \cap \omega_{\varepsilon}=\emptyset$ and the intersection of $\Omega^{\prime}$ with the boundary of $\omega_{\varepsilon}$ is contained in $\left\{x ;\left|x^{\prime \prime}\right|=\varepsilon\right\}$. The condition (4.2) implies that the equation $Q_{\Sigma} U=F$ can be solved for any $F$ in an open relatively compact subset of $\Sigma_{0}$. Then Theorem 3.10 gives that if $\varepsilon$ is sufficiently small one can for any $f \in C^{\infty}(\Omega)$ find $u \in C^{\infty}(\Omega)$ such that $Q u=f$ in $\omega_{\varepsilon}$.

We need a function $u_{0} \not \equiv 0$ such that $Q u_{0}=0$ in $\Omega^{\prime}$. Since $x_{0} \in S$ there is some $U_{0} \in C^{\infty}\left(\Sigma_{0}\right)$ such that $Q_{\Sigma} U_{0}=0$ near $\bar{\omega}$ and $U_{0} \neq 0$ in $V \cap \Sigma_{0}$. Choose a function $\chi \in C_{0}^{\infty}\left(\mathbf{R}^{n^{\prime \prime}}\right)$ such that $\chi=1$ near $\left\{x ; x^{\prime \prime}=0\right\}, \chi=0$ when $\left|x^{\prime \prime}\right|>\varepsilon / 2$, and a function $\psi \in C_{0}^{\infty}\left(\Sigma_{0}\right)$ such that $\psi=1$ near $\bar{\omega}$ and $Q_{\Sigma} U_{0}=0$ near $\operatorname{supp} \psi$. Let $u \in C^{\infty}(\Omega)$ be a solution of

$$
Q u=\psi Q_{x^{\prime \prime}} U_{0}
$$

in $\omega_{\varepsilon}$. Since $u\left(\cdot, x^{\prime \prime}\right)$ is a linear function of $\psi Q_{x^{\prime \prime}} U_{0}$ we have $u\left(\cdot, x^{\prime \prime}\right)=0$ when $x^{\prime \prime}=0$. Thus if $u_{0}=0$ when $\left|x^{\prime \prime}\right|>\varepsilon$ and $u_{0}\left(x^{\prime}, x^{\prime \prime}\right)=\left(\psi\left(x^{\prime}\right) U_{0}\left(x^{\prime}\right)-u\left(x^{\prime}, x^{\prime \prime}\right)\right) \chi\left(x^{\prime \prime}\right)$ when $\left|x^{\prime \prime}\right|<\varepsilon$, then $u_{0} \in C^{\infty}(\Omega), Q u_{0}=0$ in $\Omega^{\prime}, u_{0}=0$ when $\left|x^{\prime \prime}\right|>\varepsilon / 2$ and $u_{0}=U_{0}$ in $\Sigma_{0} \cap \omega$.

Now one can find $u_{1}, u_{2}, \ldots$ such that $Q u_{0}=R_{t} u_{0}, Q u_{2}=R_{t} u_{1}$, and so on. Since

$$
R_{t}(x, D)=\sum_{k=1}^{K} t^{-k} R_{k}(x, D)
$$

where $R_{k}$ are operators with $C^{\infty}$ coefficients, we just solve $Q u_{1, k}=R_{k} u_{0}$ for each $k$ and set

$$
u_{1}^{t}=\sum_{k=1}^{K} t^{-k} u_{1, k}
$$

The next right hand side, $R_{t} u_{1}^{t}$, will also be a sum of powers of $t$ with some functions as coefficients. For each coefficient function $c_{k}$ we take a solution $u_{2, k}$ of the equation $Q u_{2, k}=c_{k}$ and then define $u_{2}^{t}$ as a sum of powers of $t$ with the coefficients $u_{2, k}$ such that $Q u_{2}^{t}=R_{t} u_{1}^{t}$. In this way we continue with the following equations. Thus we take $u_{j, k} \in C^{\infty}(\Omega)$ such that

$$
\begin{array}{ll}
Q u_{1, k}=R_{k} u_{0} & k=1, \ldots, K \\
Q u_{2, k}=\sum_{i+\mu=k} R_{i} u_{1, \mu} & k=2, \ldots, 2 K  \tag{4.3}\\
\ldots \ldots \ldots \ldots \ldots \ldots & \\
Q u_{N, k}=\sum_{i+\mu=k} R_{i} u_{N-1, \mu} & k=N, \ldots, N K
\end{array}
$$

in $\omega_{\varepsilon}$. Since $u_{0}=0$ when $\left|x^{\prime \prime}\right|>\varepsilon / 2$ we can choose $u_{j, k}$ such that $u_{j, k}=0$ when $\left|x^{\prime \prime}\right|>\varepsilon / 2$ for all $j, k$. Thus the equations (4.3) are valid in $\Omega^{\prime}$ if we set $u_{j, k}=0$ outside $\omega_{\varepsilon}$. For $j=1,2, \ldots$ let

$$
u_{j}^{t}=\sum_{k=j}^{j K} t^{-k} u_{j, k}
$$

and write $u_{0}^{t}=u_{0}$. Then we have

$$
Q u_{j}^{t}=R_{t} u_{j-1}^{t}
$$

for all $j$. Now put

$$
u^{t}=\sum_{j=0}^{N} \exp (i\langle\cdot, \eta(t)\rangle) u_{j}^{t} / a t^{\sigma}
$$

The functions $u^{t}$ belong to $C^{\infty}(\Omega)$. They are constructed so that

$$
P u^{t}=-\exp (i\langle\cdot, \eta(t)\rangle) R_{t} u_{N}^{t}
$$

in $\Omega^{\prime}$ and $R_{t} u_{N}^{t}$ is a sum of powers of $t$ where the highest power occurring is $t^{-N-1}$. Recall that the highest power of $t$ in the expansion of $\eta(t)$ is $t^{J}$. Now look at the terms in (4.1) with $u=u^{t}$. The last term in the right hand side is zero and for some $C_{1}, C_{2}$ and $C>0$ we have

$$
\begin{gathered}
\sum_{|x| \leqq m} \sup _{K_{1}}\left|D^{\alpha} u^{t}\right| \leqq C_{1} t^{J_{m-\sigma}} \\
\sum_{|\alpha| \leqq v} \sup _{K_{1}}\left|D^{\alpha} P u^{t}\right| \leqq C_{2} t^{J v-(N+1)} \\
\sum_{|\alpha|=m+1} \sup _{V}\left|D^{\alpha} u^{t}\right|=C \sup _{V}\left|u_{0}\right| t^{J(m+1)-\sigma}+O\left(t^{J(m+1)-\sigma-1}\right) .
\end{gathered}
$$

If $N$ is so large that $J v-(N+1)<J(m+1)-\sigma$ we get a contradiction when $t \rightarrow \infty$ for $\sup _{V}\left|u_{0}\right| \neq 0$ since $u_{0}=U_{0}$ in $\Sigma_{0}$. This proves the theorem.

In general (4.2) is not fulfilled for an operator of local type. However if the domain $\Omega$ is small enough (4.2) holds and the set $S$ in Theorem 4.2 is not empty. That gives a new proof of the following corollary which was proved with other methods by Taylor [11]. It is a converse of Theorem 7.4.1 in Hörmander [4].

Corollary 4.3. Let $P$ be a differential operator of constant strength in an open set $\Omega \subset \mathbf{R}^{n}$. Assume that $\operatorname{sing} \operatorname{supp} u=\operatorname{sing} \operatorname{supp} P u$ for all $u \in \mathscr{D}^{\prime}(\Omega)$. Then $P_{x}$ is a hypoelliptic polynomial for all $x \in \Omega$, that is $P_{x}^{(\alpha)}(\xi) / P_{x}(\xi) \rightarrow 0$ when $\xi \rightarrow \infty$ if $\alpha \neq 0$.

Proof. If $P_{x}$ is not a hypoelliptic polynomial for some $x \in \Omega$ there exists some $Q \in L(P)$ of positive order. The proof of Proposition 2.7 shows that $Q$ can be chosen of local type. We have to verify that (4.2) is fulfilled for $\Sigma_{0}=\Sigma \cap \omega$ when $\Sigma$ is parallel to $\Lambda^{\prime}(Q)$ and $\omega$ is small enough and that the set $S$ in Theorem 4.2 is non-empty. Theorem 7.3.1 in Hörmander [4] shows that if $\omega$ is small there is a linear mapping $E: \mathscr{E}^{\prime}\left(\mathbf{R}^{n^{\prime}}\right) \rightarrow \mathscr{E}^{\prime}\left(\mathbf{R}^{n^{\prime}}\right)$ such that $E^{\ddagger} Q_{\Sigma} v=v$ in $\Sigma_{0}$ if $v \in \mathscr{E}^{\mathscr{E}}\left(\Sigma_{0}\right)$. This implies (4.2). That $S$ is non-empty follows from Lemma 4.7 below which states that there are infinitely many linearly independent $U \in \mathscr{D}^{\prime}\left(\Sigma_{0}\right)$ such that $Q_{\Sigma} U=0$ if $\omega$ is small. Since $Q_{\Sigma}$ is hypoelliptic it follows that $U \in C^{\infty}$. Now Theorem 4.2 shows that there exists $u \in \mathscr{D}^{\prime}(\omega)$ such that sing supp $u \neq \emptyset$ and $P u \in C^{\infty}$. This completes the proof.

Let $Q$ be any operator of local type and as before $\Sigma_{0}$ a component of $\Sigma \cap \Omega$ for some $\Sigma$ parallel to $\Lambda^{\prime}(Q)$. We know that (4.2) is in general not valid and we wish to prove that (4.1) cannot be true for any $K_{1} \subset \subset \Omega, K_{2} \subset \subset \Omega \backslash \Sigma_{0}, v \in \mathbf{Z}^{+}$ if $V$ is a neighborhood of $x_{0} \in \Sigma_{0}$, even if the hypothesis (4.2) is omitted. In order to deduce a contradiction from (4.1) as in the proof of Theorem 4.2 one must first have a function $u_{0}$ such that $Q u_{0}=0$ and $\sup _{V}\left|u_{0}\right| \neq 0$ and then be able to solve the system of equations (4.3). In the following theorem we will show that if we omit (4.2) but assume that the equation $Q_{\Sigma} U=0$ has infinitely many solutions which are
linearly independent in $\Sigma_{0} \cap V$, instead of just one, then it is possible to find such a function $u_{0}$.

Theorem 4.4. Let $P$ be a differential operator of constant strength in an open set $\Omega \subset \mathbf{R}^{n}$. Let $Q \in L(P)$ be of local type and let $\Sigma_{0}$ be a component of $\Sigma \cap \Omega$ where $\Sigma$ is an affine subspace parallel to $\Lambda^{\prime}(Q)$. Let' $S$ be the set of all $x \in \Sigma_{0}$ such that for all neighborhoods $V_{0}$ of $x$ in $\Sigma_{0}$ and all $\omega \subset \subset \Sigma_{0}$ the space $\left\{\left.u\right|_{V_{0}} ; u \in C^{\infty}\left(\Sigma_{0}\right), Q_{\Sigma} u=0\right.$ in $\left.\omega\right\}$ has infinite dimension. Here $\left.u\right|_{V_{0}}$ denotes the restriction of $u$ to $V_{0}$. Then for all positive integers $m$ there exists $u \in C^{m}(\Omega)$ such that $P u \in C^{\infty}(\Omega)$ and $S \subset \operatorname{sing} \operatorname{supp} u \subset \Sigma_{0}$.

Proof. It is sufficient to show that for all $V=\left\{x ;\left|x-x_{0}\right| \leqq r\right\}, x_{0} \in S$ the inequality (4.1) is not valid for any $K_{1}, K_{2}, v$. Assume that (4.1) is true for some neighborhood $V$ of $x_{0} \in S$ and some $K_{1}, K_{2}, v$. A contradiction will follow as in the proof of Theorem 4.2 if we show:
(4.4) For all $\omega \subset \subset \Sigma_{0}, N \in \mathbf{Z}^{+}$and $\varepsilon>0$ there exists $u_{0} \in C^{\infty}\left(\omega_{\varepsilon}\right)$ such that $\sup _{V}\left|u_{0}\right| \neq 0, Q u_{0}=0$ in $\omega_{\varepsilon}, u_{0}=0$ near $\left\{\left(x^{\prime}, x^{\prime \prime}\right) ;\left|x^{\prime \prime}\right|=\varepsilon\right\}$ and there are $u_{j, k} \in C^{\infty}\left(\omega_{\varepsilon}\right)$ vanishing near $\left\{\left(x^{\prime}, x^{\prime \prime}\right) ;\left|x^{\prime \prime}\right|=\varepsilon\right\}$ which are solutions of (4.3) in $\omega_{\varepsilon}$.

Here the coordinates and $\omega_{\varepsilon}$ are as in the proof of Theorem 4.2. Thus let $\omega, N$ and $\varepsilon$ be given. Take an open set $\omega^{\prime}$ such that $\omega \subset \subset \omega^{\prime} \subset \subset \Sigma_{0}$. Recall that Theorem 3.10 gives a number $\varepsilon^{\prime}>0$, which we may assume is equal to $\varepsilon$, and functions $a_{1}, \ldots, a_{M} \in C^{\infty}\left(\omega_{\varepsilon}^{\prime}\right)$ such that $a_{i}\left(\cdot, x^{\prime \prime}\right) \in C_{0}^{\infty}\left(\omega^{\prime}\right)$ for all $i$ and $x^{\prime \prime}$. If $f \in C^{\infty}\left(\omega_{\varepsilon}^{\prime}\right)$ and satisfies

$$
\left\langle a_{i}\left(\cdot, x^{\prime \prime}\right), f\left(\cdot, x^{\prime \prime}\right)\right\rangle=0 \quad \text { when } \quad\left|x^{\prime \prime}\right|<\varepsilon, \quad i=1, \ldots, M
$$

then there is a solution $u \in C^{\infty}\left(\Omega^{\prime}\right)$ given by (3.21) of the equation $Q u=f$ in $\omega_{\varepsilon}$.
We have to find a function $u_{0}$ which satisfies the conditions (4.4). Let $U_{1}, U_{2}, \ldots \in C^{\infty}\left(\Sigma_{0}\right)$ be solutions of the equation $Q_{0} U_{j}=0$ in $\omega^{\prime}$ which are linearly independent in $\Sigma_{0} \cap V$. Any linear combination

$$
u\left(x^{\prime}, x^{\prime \prime}\right)=\sum_{j=1}^{J} c_{j}\left(x^{\prime \prime}\right) U_{j}\left(x^{\prime}\right)
$$

with $c_{j} \in C^{\infty}\left(\mathbf{R}^{n^{\prime \prime}}\right)$ is a solution of $Q u=0$ in $\omega^{\prime} \cap \Sigma_{0}$. If we could find a solution of $Q u^{\prime}=Q u$ in $\omega_{\varepsilon}$ which vanishes when $x^{\prime \prime}=0$ we could define $u_{0}=u-u^{\prime}$ and thus obtain a non trivial solution of $Q u_{0}=0$ in $\omega_{\varepsilon}$. This is possible if

$$
\begin{equation*}
\left\langle a_{i}\left(\cdot, x^{\prime \prime}\right), Q u\left(\cdot, x^{\prime \prime}\right)\right\rangle=\sum_{j=1}^{J} c_{j}\left(x^{\prime \prime}\right)\left\langle a_{i}\left(\cdot, x^{\prime \prime}\right), Q_{x^{\prime \prime}} U_{j}\right\rangle=0 \tag{4.5}
\end{equation*}
$$

when $\left|x^{\prime \prime}\right|<\varepsilon, i=1, \ldots, M$. If $c_{1}, \ldots, c_{J}$ satisfy this condition we can in view of
(3.21) let

$$
\begin{equation*}
u_{0}\left(\cdot, x^{\prime \prime}\right)=\sum_{j=1}^{J} c_{j}\left(x^{\prime \prime}\right)\left(U_{j}-E_{x^{\prime \prime}} Q_{x^{\prime \prime}} U_{j}\right) \tag{4.6}
\end{equation*}
$$

This function $u_{0}$ belongs to $C^{\infty}\left(\omega_{\varepsilon}^{\prime}\right), Q u_{0}=0$ in $\omega_{\varepsilon}$ and $u_{0}=u$ in $\omega \cap \Sigma_{0}$.
Now we will find what conditions the functions $c_{j}$ have to satisfy in order that (4.3) can be solved. Consider the first row. Define $R_{k}$ for $k=1, \ldots, K$ as in the proof of Theorem 4.2. We can write

$$
R_{k}=\sum_{\alpha} R_{k}^{\alpha} D_{x^{\prime \prime}}^{\alpha}
$$

where $R_{k}^{\alpha}$ are differential operators not containing $D_{x^{\prime \prime}}$. In view of (4.6) we have

$$
\begin{equation*}
R_{k} u_{0}=\sum_{j} \sum_{\alpha} f_{k, \alpha, j}^{1}\left(x^{\prime}, x^{\prime \prime}\right)\left(D_{x^{\prime \prime}}^{\alpha} c_{j}\right) \tag{4.7}
\end{equation*}
$$

for some functions $f_{k, \alpha, j}^{1} \in C^{\infty}\left(\omega_{\varepsilon}^{\prime}\right)$. Thus the first row of (4.3) can be solved if

$$
\begin{gather*}
\left\langle R_{k} u_{0}\left(\cdot, x^{\prime \prime}\right), a_{i}\left(\cdot, x^{\prime \prime}\right)\right\rangle=\sum_{j=1}^{J} A_{k, i, j}^{1} c_{j}=0  \tag{4.8}\\
\left|x^{\prime \prime}\right|<\varepsilon, \quad i=1, \ldots, M, \quad k=1, \ldots, K
\end{gather*}
$$

where $A_{k, i, j}^{1}$ are differential operators with $C^{\infty}$ coefficients. The order of $A_{k, i, j}^{1}$ is less than or equal to the order of $P$. If (4.8) is fulfilled let

$$
\begin{equation*}
u_{1, k}\left(\cdot, x^{\prime \prime}\right)=E_{x^{\prime \prime}}\left(R_{k} u_{0}\left(\cdot, x^{\prime \prime}\right)\right), \quad k=1, \ldots, K \tag{4.9}
\end{equation*}
$$

We have $u_{1, k} \in C^{\infty}\left(\omega_{\varepsilon}^{\prime}\right)$ and the $u_{1, k}$ are by (3.21) solutions of the first row of (4.3) in $\omega_{\varepsilon}$. To solve the second row we note that the expression (4.7) for $R_{k} u_{0}$ combined with (4.9) shows that

$$
\begin{equation*}
\sum_{i+\mu=k} R_{i} u_{1, \mu}=\sum_{j} \sum_{\alpha} f_{k, \alpha, j}^{2}\left(x^{\prime}, x^{\prime \prime}\right)\left(D_{x^{\prime \prime}}^{\alpha} c_{j}\right) \tag{4.10}
\end{equation*}
$$

for some $f_{k, \alpha, j}^{2} \in C^{\infty}\left(\omega_{\varepsilon}^{\prime}\right)$. In the same way as above we see that the functions (4.10) satisfy the conditions for the existence of solutions $u_{2, k} \in C^{\infty}\left(\omega_{\varepsilon}^{\prime}\right)$ of the second row of (4.3) in $\omega_{\varepsilon}$ if

$$
\begin{equation*}
\sum_{j=1}^{J} A_{k, i, j}^{2} c_{j}=0 \quad \text { when } \quad\left|x^{\prime \prime}\right|<\varepsilon, \quad i=1, \ldots, M, \quad k=2, \ldots, 2 K \tag{4.11}
\end{equation*}
$$

for certain differential operators $A_{k, i, j}^{2}$ with $C^{\infty}$ coefficients. In this way we continue with the following rows in (4.3). Thus if the functions $c_{j}$ satisfy (4.5), (4.8), (4.11) and the corresponding conditions arising from the later rows, then for $u_{0}$ defined by (4.6) there exist $u_{j, k} \in C^{\infty}\left(\omega_{\varepsilon}^{\prime}\right)$ which are solutions of (4.3) in $\omega_{\varepsilon}$. We rewrite the conditions on $c_{j}$ as

$$
\begin{equation*}
\sum_{j=1}^{J} A_{i j} c_{j}=0 \quad \text { for } \quad i=1, \ldots, I \quad \text { when } \quad\left|x^{\prime \prime}\right|<\varepsilon \tag{4.12}
\end{equation*}
$$

All $A_{i j}$ are differential operators of order less than a fixed number $G$ which only depends on $N$ and the order of $P$. The number $I$ depends only on $N$ and $K$. The following lemma shows that it is possible to solve (4.12) if $J$ is large enough.

Lemma 4.5. Let $A_{i, j}, i=1, \ldots, I, j=1,2,3, \ldots, J$ be differential operators with $C^{\infty}$ coefficients in an open set $\Omega \subset \mathbf{R}^{n}$ such that order $A_{i j} \leqq G$ for all $i$ and $j$. If $J$ is larger than a certain number which only depends on $I$ and $G$, then in every neighborhood of a point $x_{0} \in \Omega$ one can find a point $x_{1}$ and $C^{\infty}$ functions $b_{1}, \ldots, b_{J}$ in a neighborhood of $x_{1}$ such that $b_{1}\left(x_{1}\right), \ldots, b_{y}\left(x_{1}\right)$ are not all 0 and

$$
\begin{equation*}
\sum_{j=1}^{J} A_{i j}\left(b_{j} \chi\right)=0, \quad i=1, \ldots, I \tag{4.13}
\end{equation*}
$$

if supp $\chi$ belongs to a sufficiently small neighborhood of $x_{1}$.
Proof. If

$$
\sum_{j=1}^{J} b_{j}^{t} A_{i j}=0 \quad \text { in } \Omega, \quad i=1, \ldots, I
$$

then (4.13) is valid for all $\chi \in \mathscr{D}^{\prime}(\Omega)$. For some $C^{\infty}$ functions $d_{\alpha, i, j}$ we have

$$
\sum_{j=1}^{J} b_{j}^{t} A_{i j}=\sum_{|\alpha| \leqq G}\left(\sum_{j=1}^{J} b_{j} d_{\alpha, i, j}\right) D^{\alpha}
$$

Label $(\alpha, i)$ for $i=1, \ldots, I,|\alpha| \leqq G$ as a sequence with indices $\sigma=1, \ldots, S$. It is thus sufficient to find $b_{j}$ such that

$$
\begin{equation*}
\sum_{j=1}^{J} d_{\sigma, j} b_{j}=0 \quad \text { for } \quad \sigma=1, \ldots, S \tag{4.14}
\end{equation*}
$$

where $S$ is a number which depends only on $I$ and $G$. The rank of the matrix $\left(d_{\sigma, j}(x)\right)$ is $\leqq S$ in $\Omega$. In a given neighborhood $\Omega_{1}$ of $x_{0}$ there is a point $x_{1}$ such that

$$
\operatorname{rank}\left(d_{\sigma, j}\left(x_{1}\right)\right)=\max _{x \in \Omega_{1}} \operatorname{rank}\left(d_{\sigma, j}(x)\right)=r
$$

Then we can assume that

$$
D(x)=\operatorname{det}\left(d_{\sigma, j}(x)\right)_{\sigma, j=1}^{r} \neq 0
$$

in a neighborhood of $x_{1}$. Assume that $J>S$. Let $b_{r+1}=1, b_{r+2}=\ldots=b_{J}=0$ and define $b_{1}, \ldots, b_{r}$ so that the equations (4.14) are satisfied for $\sigma=1, \ldots, r$. Then all $b_{j}$ are $C^{\infty}$ in a neighborhood of $x_{1}$. For all $x$ near $x_{1}$ the later equations are linear combinations of the first $r$ equations since the rank was maximal at $x_{1}$. Hence (4.14) is valid also for $\sigma=r+1, \ldots, S$ in a neighborhood of $x_{1}$. The proof is complete.

End of the proof of Theorem 4.4. We have to find solutions of (4.12). If $J$ is larger than a certain number we can by Lemma 4.5 choose a sequence $x_{v}^{\prime \prime} \rightarrow 0$ and functions $b_{1}^{1}, \ldots, b_{J}^{1}, \ldots, b_{1}^{v}, \ldots, b_{J}^{v}, \ldots \in C^{\infty}$ such that

$$
\sum_{j=1}^{J} A_{i j}\left(b_{j}^{v} \chi\right)=0, \quad i=1, \ldots, I
$$

if $\operatorname{supp} \chi$ is contained in a sufficiently small neighborhood of $x_{v}^{\prime \prime}$. For all $v$ some $b_{j}^{v}\left(x_{v}^{\prime \prime}\right)$ is equal to 1 . Let $c_{j}^{v}=b_{j}^{v} \chi_{v}$ where $\chi_{v} \in C_{0}^{\infty}\left(\mathbf{R}^{n^{\prime \prime}}\right), \chi_{v}\left(x_{v}^{\prime \prime}\right)=1$ and supp $\chi_{v}$ is contained in the permissible neighborhood of $x_{v}^{\prime \prime}$. Then for all $v$ the equations (4.12) are satisfied for $c_{j}=c_{j}^{v}$.

We claim that the function

$$
u_{0}\left(\cdot, x^{\prime \prime}\right)=\sum_{j=1}^{J} c_{j}^{v}\left(x^{\prime \prime}\right)\left(U_{j}-E_{x^{\prime \prime}} Q_{x^{\prime \prime}} U_{j}\right)
$$

satisfies (4.4) if $v$ is chosen large. Since the functions $c_{j}^{v}$ satisfy the conditions (4.12) we have $Q u_{0}=0$ and there exist $u_{j, k} \in C^{\infty}\left(\omega_{\varepsilon}^{\prime}\right)$ which are solutions of (4.3) in $\omega_{\varepsilon}$. We may choose $\chi_{v}$ such that $c_{j}^{v}=0$ when $|x|^{\prime \prime}>\varepsilon / 2$ and then clearly $u_{0}$ and $u_{j, k}$ vanish near $\left\{\left(x^{\prime}, x^{\prime \prime}\right) ;\left|x^{\prime \prime}\right|=\varepsilon\right\}$. To prove that $\sup _{v}\left|u_{0}\right| \neq 0$ if $v$ is chosen large note that

$$
E_{x_{v}^{\prime \prime}} Q_{x_{v}^{\prime \prime}} U_{j} \rightarrow 0 \text { in } L^{2}(\omega) \text { when } v \rightarrow \infty
$$

In fact $Q_{0} U_{j}=0$ and the norm of the operator $E_{x_{v}^{\prime \prime}}$ is bounded independently of $x_{v}^{\prime \prime}$. We may assume that $\left|b_{v}^{j}\left(x_{v}^{\prime \prime}\right)\right| \leqq 1$ for $j=1, \ldots, J$ and all $v$ and therefore take a subsequence which we also denote by $x_{v}^{\prime \prime}$ such that $b_{j}^{v}\left(x_{v}^{\prime \prime}\right) \rightarrow B_{j}$ when $v \rightarrow \infty$. One $B_{j}$ must be different from 0 . Hence

$$
\sum_{j=1}^{J} c_{v}^{j}\left(x_{v}^{\prime \prime}\right)\left(U_{j}-E_{x_{v}^{\prime \prime}} Q_{x_{v}^{\prime \prime}} U_{j}\right) \rightarrow \sum_{j=1}^{J} B_{j} U_{j}
$$

in $L^{2}(\omega)$ when $\nu \rightarrow \infty$. The limit is not identically 0 in $V \cap \Sigma_{0}$ since the functions $U_{j}$ were linearly independent in $V \cap \Sigma_{0}$. It follows that $u_{0}$ is not identically 0 in $V$ if we choose $v$ large. The proof of Theorem 4.4 is thus complete.

What remains in order to extend Theorem 1.1 to all operators of constant strength is to show that the set $S$ in Theorem 4.4 is equal to $\Sigma_{0}$. This is easy to prove if $Q$ has analytic coefficients. However in that case we always have (4.2) so we would only need to verify that for each $x \in \Sigma_{0}$ and $\omega$ such that $x \in \omega \subset \subset \Sigma_{0}$ there exists $u_{0} \in C^{\infty}\left(\Sigma_{0}\right)$ so that $Q_{\Sigma} u_{0}=0$ in $\omega$ and $x \in \operatorname{supp} u_{0}$. But since it follows by practically the same proof that $S$ is equal to $\Sigma_{0}$ we will prove that.

Theorem 4.6. Let $Q$ be a differential operator of constant strength with analytic coefficients. If $\Omega$ and $\Omega_{1}$ are open sets such that $Q$ is defined in a neighborhood of $\bar{\Omega}$ and $\Omega_{1} \subset \subset \Omega \subset \subset \mathbf{R}^{n}, n=1$, then the space $\left\{\left.u\right|_{\Omega_{1}} ; u \in \mathscr{B}_{2, \bar{\Omega}}(\bar{\Omega}), Q u=0\right.$ in $\left.\Omega\right\}$ has infinite dimension.

If $Q$ had constant coefficients the theorem would be trivial for then $Q$ has infinitely many different exponential solutions and these are linearly independent in any open set. In the following lemma we prove by means of a perturbation argument used in Hörmander [4, Ch. VII] that there are infinitely many linearly independent solutions in $\Omega_{1}$ if $\Omega_{1}$ is small. Lemma 4.7 also completes the proof of Corollary 4.3 .

Lemma 4.7. Let $Q$ be a differential operator of constant strength defined in a neighborhood of a point $x_{0}$. If $\Omega_{1}$ is a sufficiently small neighborhood of $x_{0}$ then the space $\left\{u \in \mathscr{B}_{2, \bar{\varrho}}\left(\bar{\Omega}_{1}\right) ; Q u=0\right\}$ has infinite dimension.

Proof. We can write

$$
Q(x, D)=Q_{x_{0}}(D)+\sum_{j} c_{j}(x) Q_{j}(D)
$$

with some $Q_{j} \prec Q_{x_{0}}, c_{j} \in C^{\infty}$ and $c_{j}\left(x_{0}\right)=0$. Let $E \in \mathscr{B}_{2, \tilde{Q}}^{\text {loc }}$ be a fundamental solution of $Q_{x_{0}}$. If $u \in L^{2}\left(\Omega_{1}\right)$ let $u_{0}$ be the function which is equal to $u$ in $\Omega_{1}$ and vanishes elsewhere. Denote by $E_{0}$ the linear operator

$$
L_{2}\left(\Omega_{1}\right) \ni u \rightarrow \text { restriction of }\left(E * u_{0}\right) \text { to } \Omega_{\mathbf{1}} \in \mathscr{B}_{2, \bar{Q}}\left(\bar{\Omega}_{1}\right) .
$$

As in the proof of Theorem 7.2.1 in Hörmander [4] we find that if $\Omega_{1}$ is sufficiently small there is for all $f \in L^{2}\left(\Omega_{1}\right)$ a unique $g \in L^{2}\left(\Omega_{1}\right)$ such that

$$
\begin{equation*}
g+\sum_{j} c_{j}(x) Q_{j} E_{0} g=f \tag{4.15}
\end{equation*}
$$

The operator $Q_{x_{0}}$ has infinitely many different exponential solutions $v_{1}, v_{2}, \ldots$. Let $g_{k}$ be the solution of (4.15) for

$$
f=-Q v_{k}=-\sum_{j} c_{j}(x) Q_{j}(D) v_{k}
$$

The functions

$$
u_{k}=v_{k}+E_{0} g_{k} \in \mathscr{B}_{2, \bar{\Omega}}\left(\bar{\Omega}_{1}\right)
$$

satisfy $Q u_{k}=0$ in $\Omega_{1}$. They are linearly independent since

$$
v_{k}=u_{k}-E_{0} Q_{x_{0}} u_{k}
$$

and the functions $v_{k}$ are linearly independent. This completes the proof of the lemma.

Proof of Theorem 4.6. We will prove that there are infinitely many linearly independent solutions in $\Omega_{1}$ which can be extended to solutions in $\Omega$. The method of proof is well known (see Malgrange [8, Ch. 3, Théorème 1]). Note that $\Omega_{1}$ may be replaced by a smaller subset. Let

$$
N=\left\{u \in \mathscr{B}_{2, \bar{Q}}(\bar{\Omega}) ; Q u=0\right\}, \quad N_{1}=\left\{u \in \mathscr{B}_{2, \bar{\Omega}}\left(\bar{\Omega}_{1}\right) ; Q u=0\right\}
$$

and let $R$ be the restriction operator $\mathscr{B}_{2, \widetilde{\Omega}}(\bar{\Omega}) \rightarrow \mathscr{B}_{2, \widetilde{Q}}\left(\bar{\Omega}_{1}\right)$. If we prove that the annihilator of $R(N)$ is equal to the annihilator of $N_{1}$ then the Hahn-Banach theorem implies that $\overline{R(N)}=N_{1}$. The space $N_{1}$ is infinite dimensional by Lemma 4.7 so then it will follow that $R(N)$ is infinite dimensional. The image of the map

$$
Q: \mathscr{B}_{2, \tilde{Q}}\left(\bar{\Omega}_{1}\right) \rightarrow \mathscr{B}_{2,1}\left(\bar{\Omega}_{1}\right)=L^{2}\left(\Omega_{1}\right)
$$

is equal to $\mathscr{B}_{2,1}\left(\bar{\Omega}_{1}\right)$ by Theorem 7.3.1 in Hörmander [4]. Hence the annihilator of $N_{1}$ is the image of ${ }^{t} Q$, that is

$$
N_{1}^{0}=\left\{t Q v \in V_{2, \tilde{\Omega}^{\prime}}\left(\bar{\Omega}_{1}\right) ; v \in V_{2,1}\left(\bar{\Omega}_{1}\right)\right\} .
$$

Here $V_{2,1}\left(\bar{\Omega}_{1}\right)$ is the space of functions in $L^{2}\left(\mathbf{R}^{n}\right)$ vanishing almost everywhere outside $\Omega_{1}$. The annihilator of $N$ is given in the same way with $\Omega_{1}$ replaced by $\Omega$. The annihilator of $R(N)$ consists of those elements in $V_{2, \tilde{Q}^{\prime}}\left(\bar{\Omega}_{1}\right)$ which annihi-
late $N$ when they are considered as elements of $V_{2, \tilde{Q}^{\prime}}\left(\bar{\Omega}_{1}\right)$ so we have

$$
R(N)^{0}=\left\{{ }^{t} Q v \in V_{2, \widetilde{\Omega}^{\prime}}\left(\bar{\Omega}_{1}\right) ; v \in V_{2,1}(\bar{\Omega})\right\} .
$$

Let $w \in R(N)^{0}$. Then $w={ }^{t} Q v$ for some $v \in V_{2, \mathbf{1}}(\bar{\Omega}) \subset \mathscr{E}^{\prime}(\bar{\Omega})$ and supp $w \subset \bar{\Omega}_{1}$. Holmgren's uniqueness theorem now implies, if $\Omega_{1}$ is chosen convex, that supp $v \subset \bar{\Omega}_{1}$, for a hyperplane which is non-characteristic at one point in $\Omega$ is non-characteristic everywhere since $Q$ has constant strength. Now it follows that $w \in N_{1}^{0}$, for $v \in V_{2,1}(\bar{\Omega})$ and supp $v \subset \bar{\Omega}_{1}$ means that $v \in V_{2,1}\left(\bar{\Omega}_{1}\right)$.

From Theorem 4.6 and Theorem 4.4 (or Theorem 4.2) we now obtain an extension of Theorem 1.1 to operators of constant strength with analytic coefficients.

Theorem 4.8. Let $P$ be a differential operator of constant strength with analytic coefficients in an open set $\Omega \subset \mathbf{R}^{n}$. Let $Q \in L(P)$ be of positive order, $\Sigma$ parallel to $\Lambda^{\prime}(Q)$ and $\Sigma_{0}$ a component of $\Sigma \cap \Omega$. Then there exists $u \in \mathscr{D}^{\prime}(\Omega)$ such that $P u \in C^{\infty}(\Omega)$ and sing supp $u=\Sigma_{0}$.

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