# ON JORDAN ARCS AND LIPSCHITZ CLASSES OF FUNCTIONS DEFINED ON THEM 

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## Introduction

Let the equations

$$
x=f(t), \quad y=g(t) \quad(0 \leqslant t \leqslant 1)
$$

define a continuous arc in the plane $E_{2}$ and let us assume that the derivative of $g(t)$ with respect to $f(t)$ vanishes everywhere. According to Lebesgue ([4], p. 296) this means that

$$
\lim _{h \rightarrow 0} \frac{g(t+h)-g(t)}{f(t+h)-f(t)}=0 \quad(0 \leqslant t \leqslant 1),
$$

where we ignore as $h \rightarrow 0$ those values of $h$ which produce simultaneously vanishing increments $\Delta f$ and $\Delta g$ and where the above limit relation is assumed to hold, by definition, in the interior of any common interval of constancy for $f$ and $g$. Lebesgue showed that $g(t)$ is necessarily constant provided that we assume $f(t)$ to be of bounded variation. R. Caccioppoli [2] and J. Petrovski [6] showed that $g(t)$ is constant even without the last additional assumption concerning $f(t)$.
H. Whitney [8] showed that the situation is different for skew arcs: Whitney constructs in the complex $x$-plane a Jordan arc

$$
\begin{equation*}
J: x=f(t) \quad(0 \leqslant t \leqslant 1), \tag{1}
\end{equation*}
$$

[^0]and also a real-valued, non-decreasing, non-constant continuous function $g(t)$ in $[0,1]$ such that
\[

$$
\begin{equation*}
\lim _{h \rightarrow 0} \frac{g(t+h)-g(t)}{|f(t+h)-f(t)|}=0 \quad \text { for all } t \text { in }[0,1] . \tag{2}
\end{equation*}
$$

\]

It is clear that the point $(f(t), g(t))$ describes a Jordan are, in the 3 -dimensional space, which is rising while having, in view of (2), everywhere vanishing slopes with respect to the complex $x$-plane which is thought of as horizontal. For a particularly simple example of such a skew are (whose projection $J$ is the are of H. von Koch) see G. Glaeser ([3], 57-58).

Our first result is
Theorem 1. There exists in the complex x-plane a Jordan arc $J$, having the following properties: Let $v$ and $v^{\prime}$ be distinct points of $J$ and let $J\left(v, v^{\prime}\right)$ be the subarc of $J$ having $v, v^{\prime}$ as end points while $m_{2} J\left(v, v^{\prime}\right)$ denotes its 2-dimensional Lebesgue measure. To every positive $\varepsilon$ there corresponds a constant $C_{\varepsilon}$ such that for all subarcs

$$
\begin{equation*}
0<m_{2} J\left(v, v^{\prime}\right)<C_{\varepsilon}\left|v-v^{\prime}\right|^{2-\varepsilon} . \tag{3}
\end{equation*}
$$

An arc enjoying these properties will be constructed in § 1 below. Before we discuss the significance of Theorem 1 let us first show how it furnishes one more example of an arc of the kind first constructed by Whitney. To obtain it we erect at each point $v$, of $J$, an ordinate $y=G(v)=m_{2} J(0, v)$. This is a continuous point-function on $J$ which increases strictly in view of the first inequality (3): If $J(0, v)$ is a proper subare of $J\left(0, v^{\prime}\right)$ then $G\left(v^{\prime}\right)-G(v)=m_{2} J\left(v, v^{\prime}\right)>0$. By (3)

$$
\frac{G\left(v^{\prime}\right)-G(v)}{\left|v^{\prime}-v\right|}=\frac{m_{2} J\left(v, v^{\prime}\right)}{\left|\left|v-v^{\prime}\right|\right.}<C_{\varepsilon}\left|v-v^{\prime}\right|^{1-\varepsilon} .
$$

If we select $\varepsilon<1$ and let $v^{\prime} \rightarrow v$ we see that the skew arc described by $(v, G(v)), v \in J$, has everywhere a vanishing slope.

Observe that the $\varepsilon$ appearing in Theorem 1 is required to be positive. This is not an accident because of

Theorem 2. Let $J$ be a plane Jordan arc such that $m_{\mathrm{a}} J>0$. Then

$$
\begin{equation*}
\varlimsup_{v^{\prime} \rightarrow v} \frac{m_{2} J\left(v, v^{\prime}\right)}{\left|v-v^{\prime}\right|^{2}}=+\infty \tag{4}
\end{equation*}
$$

holds at almost all points $v$, of $J$, in the sense of the $m_{2}$-measure.

This result allows an application to the notion of lower quadratic length of arcs. We use the following

Definition 1. Let the complex-valued function $x=f(t),(0 \leqslant t \leqslant 1)$, describe a continuous arc $B$ in the plane. If $t_{0}=0<t_{1}<t_{2}<\cdots<t_{n}=1$, we define the lower quadratic length of $B$ by

$$
\begin{equation*}
L^{(2)} B=\lim \sum_{i=1}^{n}\left|f\left(t_{i}\right)-f\left(t_{i-1}\right)\right|^{2}, \tag{5}
\end{equation*}
$$

where the limes inferior is taken as $\max \left|t_{i}-t_{i-1}\right| \rightarrow 0$.
It was shown by A. Ville [7] that $L^{(2)} B=0$ provided that $m_{2} B=0$. It now turns out that the additional condition may be ignored since we have the following

Theorem 3. The lower quadratic length of any plane continuous arc vanishes.
Using Theorem 2 we first prove Theorem 3 for the case of a Jordan arc (Section 2.2). A lemma to the effect that any continuous arc may be reduced to a Jordan arc by removing appropriate loops easily allows to complete a general proof of Theorem 3 (Section 2.3).

In contrast to Theorem 2 we have a different situation for Jordan ares of finite $\alpha$-dimensional Hausdorff measure; we state this as

Theorem 4. Let $\mathbf{l}<\alpha<2$. There are plane Jordan arcs of finite and positive $\Lambda^{\alpha}$-measure such that

$$
\begin{equation*}
\frac{\Lambda^{\alpha} J\left(v, v^{\prime}\right)}{\left|v-v^{\prime}\right|^{\alpha}}<K \tag{6}
\end{equation*}
$$

for all subarcs $J\left(v, v^{\prime}\right)$.
However, a weaker analogue of Theorem 2 still holds which shows that the exponent $\alpha$ of $\left|v-v^{\prime}\right|^{\alpha}$ in (6) can not be increased. Indeed, we have

Theorem 5. If $J$ is a plane Jordan arc such that $0<\Lambda^{\alpha} J<\infty, 1<\alpha<2$ then

$$
\begin{equation*}
\varlimsup_{v^{\prime} \rightarrow v} \frac{\Lambda^{\alpha} J\left(v, v^{\prime}\right)}{\left|v-v^{\prime}\right|^{\alpha}} \geqslant 1 \tag{7}
\end{equation*}
$$

at almost all points $v$ in the sense of the $\Lambda^{\alpha}$-measure.
We turn now to a discussion of Lipschitz classes of point-functions $G(v)$ defined on an arc $J$. We shall use the following

Definition 2. Let $\phi(x)$ be defined for $x>0$ and be positive, continuous, nondecreasing and such that $\phi(+0)=0$. Let $J$ be a Jordan arc and $G(v)$ be defined on $J$.

We write $G(v) \in \operatorname{Lip}, \phi(x)$ provided that there is a finite-valued positive function $A(v)$ such that

$$
\begin{equation*}
\left|G(v)-G\left(v^{\prime}\right)\right|<A(v) \phi\left(\left|v-v^{\prime}\right|\right), \quad\left(v, v^{\prime} \in J, v \neq v^{\prime}\right) \tag{8}
\end{equation*}
$$

and we say that $G(v)$ is of Lipschitz class $\phi(x)$ along J. If $A(v)$ is bounded we write

$$
G(v) \in \mathrm{U} \operatorname{Lip}_{J} \phi(x)
$$

and say that $G(v)$ is uniformly of Lipschitz class $\phi(x)$ along $J$.
It is well known that if $J$ is the segment $[0,1]$ and $\phi(x)=o(x)$, as $x \rightarrow \mathbf{0}$, then constants are the only elements of the class $\operatorname{Lip}_{J} \phi(x)$. The situation is different for plane arcs $J$ : For the arc $J$ of Theorem 1 and the function $G(v)=m_{2} J(0, v)$ we see from (3) that

$$
G(v) \in \mathrm{U} \operatorname{Lip}_{J} x^{2-\varepsilon} \quad(\varepsilon>0),
$$

while $G(v)$ is certainly not constant.
What about the class $\mathrm{U} \operatorname{Lip}_{J} x^{2}$ obtained by letting here $\varepsilon$ become zero? The answer becomes obvious if we apply our Theorem 3. Indeed, let $G(v)$ satisfy the inequality

$$
\left|G(v)-G\left(v^{\prime}\right)\right|<A\left|v-v^{\prime}\right|^{2} \quad\left(v, v^{\prime} \in J ; A \text { const. }\right) .
$$

If $J$ is traced out by $x=f(t), 0 \leqslant t \leqslant 1$, and if $\alpha$ and $\beta$ are the endpoints of $J$ then

$$
|G(\beta)-G(\alpha)| \leqslant \Sigma\left|G\left(f\left(t_{i}\right)\right)-G\left(f\left(t_{i-1}\right)\right\rangle\right|<A \sum_{1}^{n}\left|f\left(t_{i}\right)-f\left(t_{i-1}\right)\right|^{2} .
$$

However, we know that the last-written sum will converge to zero for an appropriate sequence of divisions by virtue of Theorem 3. Thus $G(\alpha)=G(\beta)$. Since this argument may be applied to any subarc we have established

Theorem 6. If $J$ is a plane Jordan arc and the function $G(v)$ is uniformly of the Lipschitz class $x^{2}$ along $J$, then $G(v)$ is necessarily a constant.

Let now $J$ be a Jordan are in the plane such that

$$
\Lambda_{\alpha} J<\infty \quad(1<\alpha<2) .
$$

By Theorem 4 we see that Theorem 6 does not generalize to such ares, for if $J$ is an are as described by Theorem 4 and $G(v)=\Lambda^{\alpha} J(0, v)$ then ( 6 ) implies that $G(v) \in \mathrm{U} \operatorname{Lip}_{J} x^{\alpha}$ while $G(v)$ is not constant. However, a slightly weaker analogue of Theorem 6 holds which we state as

Theorem 7. If $J$ is a plane Jordan arc of finite $\Lambda^{\alpha}$-measure, $1<\alpha<2$, and $G(v)$ is of Lipschitz class $\phi(x)$ along $J$, then

$$
\begin{equation*}
\phi(x)=o\left(x^{\alpha}\right) \quad \text { as } \quad x \rightarrow 0, \tag{9}
\end{equation*}
$$

implies that $G(v)$ is a constant.
We conclude our Introduction with a few results when the Jordan arc $J$ is in a space of dimension higher than two. There is a natural generalization of Theorem 7:

If $J \subset E_{n}, \Lambda^{\alpha} J<\infty, \mathbf{1}<\alpha \leqslant n$ and $G(v) \in \operatorname{Lip}_{I} \phi(x)$, then

$$
\begin{equation*}
\phi(x)=o\left(x^{\alpha}\right) \tag{10}
\end{equation*}
$$

implies that $G(v)$ in a constant.
Theorem 7 and its generalization just stated suggest that if $J$ is an are of the real Hilbert space $H$, again the class Lip, $\phi(x)$ will contain only constants provided that the scale-function $\phi(x)$ tends to zero sufficiently fast as $x \rightarrow+0$. However, it is a curious fact that such is not the case and we state this as our last

Theorem 8. Let $\phi(x)$ be a given scale-function subject to the conditions of Definition 2. There are in the Hilbert space $H$ Jordan arcs $J$ such that the class $\mathrm{U}_{\operatorname{Lip}}{ }^{\boldsymbol{p}} \phi(x)$ contains functions which are not constants.

Observe that the scale-function $\phi(x)$ may tend to zero as fast as we wish.

## § 1. Proof of Theorem 1

1.1. The construction of the arc $J$. Let $S_{0}$ be the unit-square, one side of which connects $x=0$ to $x=1$. This and all following squares will be assumed to be closed. We shall now construct a continuum $J_{1}$ as follows: Let

$$
\begin{equation*}
\theta_{n}=\frac{1}{2}-\frac{1}{16 n^{2}} \quad(n=1,2, \ldots) . \tag{1.1}
\end{equation*}
$$

In $S_{0}$ we construct four corner squares $s_{1}^{1}, s_{1}^{2}, s_{1}^{3}, s_{1}^{4}$ of sides $=\theta_{1}$. We now connect these squares by three segments (or links) as shown in fig. l, obserwing that two of these links lie along the two vertical sides of $S_{0}$ while the third link $a b$ lies on the line which carries the two lower sides of $s_{1}^{2}$ and $s_{1}^{3}$.

On the link $a b$ we consider its Cantor middle-third set $\gamma$ and in particular its complementary set of intervals. On each of these intervals as side we construct a square, lying above $a b$, and denote by $\sigma$ the set of squares so obtained. We now form the union $[a, b] \cup \sigma$ which is evidently a continuum joining $a$ to $b$. We repeat


Fig. 1.
the same construction on each of the remaining two links placing the sets of squares as indicated in fig. l. This completes the construction of the continuum $J_{1}$. Observe that $J_{1}$ is composed of four corner squares, enumerably many intermediate squares and finally three Cantor sets. Leaving out the Cantor sets we have a collection of squares $s_{1}^{i}$ which we denote by $S_{1}$. We establish an order relation among the elements of $S_{1}=\left\{s_{1}^{i}\right\}$ obtained by traversing $J_{1}$ from $x=0$ to $x=1$. Each square $s_{1}$ has an entry point and an exit point defined in an obvious way.

The second step of our construction is as follows: In each square $s_{1}\left(s_{1} \in S_{1}\right)$ we join its entry point to its exit point by a continuum similar in structure to $J_{1}$, the only difference being that the sides of its four corner squares are now $=\theta_{2} \cdot$ side $s_{1}$. Replacing in $J_{1}$ each square $s_{1}$ by its sub-continuum so constructed we obtain our second continuum $J_{2}$. It is composed of a set $S_{2}$ of squares $s_{2}=s_{2}^{i}$ and enumerably many Cantor sets.

This construction is now repeated indefinitely by obtaining $J_{n}$ from $J_{n-1}$ by replacing each $s_{n-1}\left(\epsilon S_{n-1}\right)$ by a continuum similar in structure to $J_{1}$, having 4 corner squares of sides $=\theta_{n} \cdot$ side $s_{n-1}$. $S_{n}=\left\{s_{n}\right\}$ will denote the set of squares of $J_{n}$.

Evidently
$J_{1} \supset J_{2} \supset \ldots$
and

$$
\begin{equation*}
J=\bigcap_{v=1}^{\infty} J_{v} \tag{1.2}
\end{equation*}
$$

is easily shown to be a Jordan are joining the point $x=0$ to $x=1$.
Let us show that

$$
\begin{equation*}
m_{2} J>0 . \tag{1.3}
\end{equation*}
$$

To see this let $\sum_{n}(n=1,2, \ldots)$ denote the set of those $4^{n}$ elements of $S_{n}$ which are obtained by constructing, starting from $S_{0}$, only corner squares while omitting the
intermediate squares altogether. These $4^{n}$ elements of $\sum_{n}$ are squares of sides $=\theta_{1} \theta_{2} \ldots \theta_{n}$ and $J_{n} \supset \sum_{n}$. By (1.1) and (1.2) we therefore find

$$
m_{2} J=\lim _{n \rightarrow \infty} m_{2} J_{n} \geqslant \lim m_{2} \sum_{n}=\lim 4^{n}\left(\theta_{1} \theta_{2} \ldots \theta_{n}\right)^{2}=\prod_{y=1}^{\infty}\left(1-\frac{1}{8 v^{2}}\right)^{2}>0
$$

and (1.3) is established.
A similar discussion shows easily that every subare $J\left(v, v^{\prime}\right)$ of $J$ has positive $m_{2}$-measure and this already establishes the first inequality (3). We now turn to a proof of the second inequality (3).
1.2. Proof of Theorem 1. A proof of the second inequality (3) will require a closer discussion of the relation between a subare $J\left(v, v^{\prime}\right)$ and the squares $s_{n}$ of the continuum $J_{n}$. The inclusion relation $J\left(v, v^{\prime}\right) \subset s_{n}$ requires no explanation; if $s_{n} \cap J \subset J\left(v, v^{\prime}\right)$ then we shall say that $J\left(v, v^{\prime}\right)$ contains the square $s_{n}$, or that $s_{n}$ is contained in $J\left(v, v^{\prime}\right)$. The symbol $s_{n}$ will also be used to denote the area of the square $s_{n}$. The square $s_{n}$ contains four corner squares $s_{n+1}$; the least distance or the width of the corridor between two of these will be denoted by corr $s_{n}$, its value being

$$
\begin{equation*}
\operatorname{corr} s_{n}=\left(1-2 \theta_{n+1}\right) \text { side } s_{n}=\frac{1}{8(n+1)^{2}} \text { side } s_{n} \text {. } \tag{1.4}
\end{equation*}
$$

Our proof is based on the following preliminary remarks:

1. The distance between two complementary intervals of the Cantor set is at least equal to the length of the smaller interval. The distance between a complementary interval and an endpoint of the Cantor set is never less than the length of the interval.
2. Given $\varepsilon>0$ there is a constant $B_{\varepsilon}$ such that

$$
\begin{equation*}
\frac{s_{n}}{\left(\operatorname{corr} s_{n}\right)^{2-\varepsilon}}<B_{\varepsilon} \tag{1.5}
\end{equation*}
$$

for all $n$ and all squares $s_{n}$.
Omitting the simple proof of the first remark, we turn to the second. In view of (1.4) and the evident inequality side $s_{n}<2^{-n}$, we obtain

$$
\frac{s_{n}}{\left(\text { corr } s_{n}\right)^{2-\varepsilon}}<8^{2-\varepsilon}(n+1)^{2(2-\varepsilon)}\left(\text { side } s_{n}\right)^{\varepsilon}<8^{2}(n+1)^{4} 2^{-\varepsilon n},
$$

which is a bounded sequence and (1.5) is established.
Given the arc $J\left(v, v^{\prime}\right)$ we define the integer $n$ such that $J\left(v, v^{\prime}\right)$ is contained in a square $s_{n}$ but not in any $s_{n+1}$. We now distinguish three cases depending on the relation of $J\left(v, v^{\prime}\right)$ to the four corner squares of $s_{n}$.

1. $J\left(v, v^{\prime}\right)$ contains points of at least two corner squares of $s_{n}$. From the definition of corr $s_{n}$ and the inequality (1.5) we obtain that

$$
\begin{equation*}
\frac{m_{2} J\left(v, v^{\prime}\right)}{\left|v-v^{\prime}\right|^{2-\varepsilon}}<\frac{s_{n}}{\left(\operatorname{corr} s_{n}\right)^{2-\varepsilon}}<B_{\varepsilon} . \tag{1.6}
\end{equation*}
$$

2. $J\left(v, v^{\prime}\right)$ fully contains a corner square $s_{n+1}$, of $s_{n}$, but does not contain points of any of the other corner squares of $s_{n}$. A glance at fig. 1 (where the large square now represents $s_{n}$ ) shows that

$$
\begin{equation*}
\left|v-v^{\prime}\right|>\frac{1}{2} \text { side } s_{n+1}=\frac{1}{2} \theta_{n+1} \text { side } s_{n}>\frac{1}{8} \text { side } s_{n} . \tag{1.7}
\end{equation*}
$$

But then $\quad \frac{m_{2} J\left(v, v^{\prime}\right)}{\left|v-v^{\prime}\right|^{2-\varepsilon}}<\frac{s_{n}}{\left(8^{-1} \text { side } s_{n}\right)^{2-\varepsilon}}<8^{2}\left(\text { side } s_{n}\right)^{\varepsilon} \leqslant 8^{2}$.
3. In the remaining cases (see fig. 1) all the squares $s_{n+1}$ containing points of $J\left(v, v^{\prime}\right)$ are based on one and the same straight line. This will imply that the arc $J\left(v, v^{\prime}\right)$ is fairly stretched, in fact we shall prove the following: If
then

$$
\begin{gather*}
d=\operatorname{diam} J\left(v, v^{\prime}\right)  \tag{1.8}\\
\left|v-v^{\prime}\right| \geqslant \frac{1}{13} d \tag{1.9}
\end{gather*}
$$

Indeed, let $v \in s_{n+1}^{i}, v^{\prime} \in s_{n+1}^{j}$ and to fix the ideas we shall assume that the square $s_{n+1}^{i}$ does not exceed $s_{n+1}^{j}$ in size. Let $v_{0}$ be the orthogonal projection of $v$ on to the common base line of our squares. Let $v_{1}$ be the exit point of $s_{n+1}^{i}$ and $v_{2}$ the entry point of $s_{n+1}^{j}$.

We distinguish two cases depending on whether $\left|v_{2}-v_{1}\right|$ is $\geqslant d / 13$ or $<d / 13$. In the first case when $\left|v_{2}-v_{1}\right| \geqslant d / 13$ it is evident that also

$$
\begin{equation*}
\left|v-v^{\prime}\right| \geqslant \frac{1}{13} d \tag{1.10}
\end{equation*}
$$

Let us now assume

$$
\left|v_{2}-v_{1}\right|<\frac{1}{13} d
$$

The opening remark 1 of Section 1.2 implies that side $s_{n+1}^{i} \leqslant\left|v_{2}-v_{1}\right|<d / 13$ and $a$ fortiori

$$
\begin{equation*}
\left|v-v_{0}\right| \leqslant \frac{1}{13} d \tag{1.11}
\end{equation*}
$$

as well as
$\operatorname{diam} J\left(v, v_{2}\right) \leqslant \operatorname{diam} J\left(v, v_{1}\right)+\operatorname{diam} J\left(v_{1}, v_{2}\right)<\frac{\sqrt{2}}{13} d+\frac{\sqrt{2}}{13} d<\frac{3}{13} d$.

We now conclude from (1.8) that

$$
\begin{equation*}
\operatorname{diam} J\left(v_{2}, v^{\prime}\right)>\frac{10}{13} d \tag{1.12}
\end{equation*}
$$

Consider now the sequence of corner squares $s_{n+\nu} \subset s_{n+1}^{j}$ which have the common entry point $v_{2}\left(p=1,2, \ldots ; s_{n+1}=s_{n+1}^{5}\right)$ and let $p$ be such that

$$
v^{\prime} \in s_{n+p}, \quad v^{\prime} \notin s_{n+p+1} .
$$

By (1.12)

$$
\operatorname{diam} s_{n+p} \geqslant \operatorname{diam} J\left(v_{2}, v^{\prime}\right) \geqslant \frac{10}{13} d
$$

and therefore

$$
\left|v^{\prime}-v_{2}\right|>\text { side } s_{n+p+1}>\frac{1}{3 \sqrt{2}} \operatorname{diam} s_{n+p} \geqslant \frac{10}{3 \sqrt{2} \cdot 13} d>\frac{2}{13} d .
$$

But then a fortiori

$$
\left|v^{\prime}-v_{0}\right|>\frac{2}{13} d
$$

This and (1.11) imply (1.9) which has now been shown to hold in any case.
Returning to our proof of (3) we observe (1.8) implies that $m_{2} J\left(v, v^{\prime}\right)<d^{2}$ and now by (1.9)

$$
\begin{equation*}
\frac{m_{2} J\left(v, v^{\prime}\right)}{\left|v-v^{\prime}\right|^{2-\varepsilon}}<13^{2} d^{e} \leqslant 13^{2} \tag{1.13}
\end{equation*}
$$

The estimates (1.6), (1.7) and (1.13) establish (3) and our proof is completed.

## § 2. The lower quadratic length of plane ares

2.1. Proof of Theorem 2. The key to our discussion of quadratic length is Theorem 2 which we are now going to establish. Let $m_{2} J>0$. Denote by $E$ the set of points $v$ of $J$ to which corresponds some $v^{\prime}(\neq v)$ such that

$$
\begin{equation*}
\frac{m_{2} J\left(v, v^{\prime}\right)}{\left|v-v^{\prime}\right|^{2}}>A>8 \tag{2.1}
\end{equation*}
$$

where $A$ is a certain constant. $E$ is open. Let $E_{1}$ be the complement of $E$ on $J$. We shall show that, for any $A, m_{2} E_{1}=0$.

Suppose that for a certain $A$ this is not true, hence $m_{2} E_{1}>0$, and let an interior point $v_{0}$ of $J$ be a density point of $E_{1}$. Then to any $\eta>0$ corresponds an $r_{0}>0$ such that

$$
\begin{equation*}
m_{2}\left\{c\left(v_{0}, r\right)-E_{1}\right\}<\eta^{2} r^{2} \quad \text { if } \quad r<r_{0} \tag{2.2}
\end{equation*}
$$

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where $c\left(v_{0}, r\right)$ denotes the circle having center $v_{0}$ and radius $r$; this circle and all circles of the present discussion will be considered to be closed. At this point we select positive quantities $\delta, \eta, r$ subject to the inequalities

$$
\begin{equation*}
\delta<\frac{2}{A}, \quad \eta \sqrt{32 A}<\delta, \quad 4 A r<r_{0} \tag{2.3}
\end{equation*}
$$

and notice that the first two imply $\eta^{2} 32 A<\delta^{2}<\delta \cdot 2 / A$ hence

$$
\begin{equation*}
16 A^{2} \eta^{2}<\delta \tag{2.3'}
\end{equation*}
$$

We shall use the order relation among the points of $J$ using the symbol $\prec$, and shall speak of the first and last point of $J$ in a given closed set, denoting both as the extreme points of $J$. Let now $v_{1}$ and $v_{2}, v_{1} \prec v_{0} \prec v_{2}$ be the extreme points of $J$ belonging to the circle $c\left(v_{0}, r\right)$ so that no $v<v_{1}$, or $v \succ v_{2}$ belongs to the circle. Obviously $\left|v_{1}-v_{0}\right|=\left|v_{2}-v_{0}\right|=r$, while the arc $J\left(v_{1}, v_{2}\right)$ need not belong entirely to the circle $c\left(v_{0}, r\right)$. In fact the diameter of the arc $J\left(v_{1}, v_{2}\right)$ may well be large compared with $2 r$. As $v_{0}$ does not belong to $E$ we have

$$
\begin{gather*}
m_{2} J\left(v_{1}, v_{0}\right) \leqslant A\left|v_{1}-v_{0}\right|^{2}=A r^{2}, \\
m_{2} J\left(v_{0}, v_{2}\right) \leqslant A\left|v_{2}-v_{0}\right|^{2}=A r^{2}, \\
m_{2} J\left(v_{1}, v_{2}\right) \leqslant 2 A r^{2} .  \tag{2.4}\\
U=E_{1} J\left(v_{1}, v_{2}\right) \\
m_{2} U \leqslant 2 A r^{2} . \tag{2.5}
\end{gather*}
$$

and therefore
we have a fortiori
We denote by $d(p ; U)$ the distance from the point $p$ to the set $U$ and by $\{l, U\}$ the set of points $p$ of the plane such that $d(p, U) \leqslant l$ and not belonging to $U$. We shall now study the set

$$
V=\{\delta r, U\} \cdot c\left(v_{0}, 4 A r\right)
$$

in its relation to the arc $J$. First we add to $V$ such points of $U$ which lie in $c\left(v_{0}, 4 A r\right)$ to obtain the closure $\bar{V}$. Let now $v_{3}$ and $v_{4}$ be the extreme points of $J$ belonging to $\bar{V}$ and let us show that

$$
\begin{equation*}
v_{3} \prec v_{1}, v_{2} \prec v_{4} . \tag{2.6}
\end{equation*}
$$

To see this we have to show that $v_{1} \in \bar{V}$ and $v_{2} \in \bar{V}$. Suppose that $v_{1} \ddagger \bar{V}$ so that $E_{1} c\left(v_{1}, \delta r\right)=\varnothing$. But evidently

$$
m_{2}\left\{c\left(v_{0}, r\right) \cdot c\left(v_{1}, \delta r\right)\right\}>\delta^{2} r^{2}
$$

while the set of point of $c\left(v_{0}, r\right)$ which are not in $E_{1}$ is of measure $<\eta^{2} r^{2}$, which is $<\delta^{2} r^{2}$. A similar argument shows that $v_{2} \in \bar{V}$ and the relations (2.6) are established. We finally observe that $v_{3}$ and $v_{4}$ can not belong to $U=E_{1} J\left(v_{1}, v_{2}\right)$ and therefore $v_{3}$ and $v_{4}$ lie in $V$. Thus $v_{3}$ and $v_{4}$ are also the extreme points of $J$ belonging to $V$. Since $v_{3}$ and $v_{4}$ belong to $\{\delta r, U\}$, there are points $v_{1}^{\prime}, v_{2}^{\prime}$ of $U$ such that

$$
\begin{equation*}
\left|v_{3}-v_{1}^{\prime}\right| \leqslant \delta r,\left|v_{4}-v_{2}^{\prime}\right| \leqslant \delta r \tag{2.7}
\end{equation*}
$$

By (2.2) and the last condition (2.3)

$$
m_{2}\left\{c\left(v_{0}, 4 A r\right)-E_{1}\right\}<\eta^{2} 16 A^{2} r^{2}
$$

from which, in view of $V \subset c\left(v_{0}, 4 A r\right)$, we conclude that

$$
\begin{equation*}
m_{2}\left(V-V E_{1}\right)<\eta^{2} 16 A^{2} r^{2} . \tag{2.8}
\end{equation*}
$$

But the part of $E_{1}$ that belongs to $V$ lies on the arc $J\left(v_{3}, v_{4}\right)$, and again the points of $E_{1} J\left(v_{1}, v_{2}\right)=U$ do not belong to $V$. We conclude that

$$
\begin{equation*}
E_{1} V \subset J\left(v_{3}, v_{1}\right)+J\left(v_{2}, v_{4}\right) \tag{2.9}
\end{equation*}
$$

Now

$$
\begin{aligned}
V & =\left(V-E_{1} V\right)+E_{1} V, \\
m_{2} V & =m_{2}\left(V-V E_{1}\right)+m_{2} E_{1} V,
\end{aligned}
$$

and (2.8), (2.9) imply

$$
m_{2} V \leqslant \eta^{2} 16 A^{2} r^{2}+m_{2} J\left(v_{3}, v_{1}\right)+m_{2} J\left(v_{2}, v_{4}\right)
$$

and $a$ fortiori

$$
\begin{equation*}
m_{2} J\left(v_{3}, v_{1}^{\prime}\right)+m_{2} J\left(v_{2}^{\prime}, v_{4}\right)>m_{2} V-\eta^{2} 16 A^{2} r^{2} \tag{2.10}
\end{equation*}
$$

To estimate $m_{2} V$ from below we shall introduce polar coordinates $(\varrho, \theta)$ with the origin at $v_{0}$, and we write

$$
l(\theta)=\bigcup_{\varrho \geqslant 0}(\varrho, \theta), \quad\left(r_{1}, r_{2}, \theta\right)=\bigcup_{r_{1} \leqslant \varrho \leqslant r_{2}}(\varrho, \theta) .
$$

We consider the set of directions

$$
\Theta_{1}[\theta \mid U \cdot((1-\eta) r, r, \theta)=\varnothing] .
$$

Observing that all points of $E_{1} c\left(v_{0}, r\right)$ lie on the arc $J\left(v_{1}, v_{2}\right)$, we have

$$
E_{1} c\left(v_{0}, r\right)=E_{1} J\left(v_{1}, v_{2}\right) c\left(v_{0}, r\right)=U c\left(v_{0}, r\right)
$$

and thus

$$
c\left(v_{0}, r\right)-E_{1}=c\left(v_{0}, r\right)-U .
$$

By (2.2)

$$
m_{2}\left\{c\left(v_{0}, r\right)-U\right\}<\eta^{2} r^{2}
$$

from which it follows at once that

$$
\begin{equation*}
m \Theta_{1}<2 \eta \tag{2.11}
\end{equation*}
$$

Consider now the set

$$
\Theta_{2}[\theta \mid m\{U \cdot(r, 4 A r, \theta)\}>(4 A-\mathbf{l}-\delta) r] .
$$

By (2.5) and writing $S_{\theta}=(r, 4 A r, \theta)$ we have

$$
\begin{align*}
& 2 A r^{2}>m_{2} U \geqslant m_{2} U \cdot \bigcup_{\theta \in \Theta_{2}}(r, 4 A r, \theta) \\
& =\iint \varrho d \varrho d \theta=\int_{\Theta_{2}} d \theta \int_{U \cdot s_{\theta}} \varrho d \varrho>r \int_{\Theta_{2}} d \theta \int_{U \cdot s_{\theta}} d \varrho>r^{2}(4 A-1-\delta) m \Theta_{2} . \\
& m \Theta_{2}<\frac{2 A}{4 A-1-\delta}<\frac{8}{15} . \tag{2.12}
\end{align*}
$$

Hence
Consider finally the set $\Theta_{3}$ which is the complement of $\Theta_{1}+\Theta_{2}$.
By (2.11) and (2.12)

$$
\begin{equation*}
m \Theta_{3}>2 \pi-1 \tag{2.13}
\end{equation*}
$$

Let $C U$ denote the complement of $U$. For any $\theta \in \Theta_{3}$ the segment $((1-\eta) r, r, \theta)$ contains points of $U$ while $m\{(r, 4 A r, \theta) U\} \leqslant(4 A-1-\delta) r$ and therefore

$$
\begin{equation*}
m\{(r, 4 A r, \theta) \cdot C U\}>\delta r \tag{2.14}
\end{equation*}
$$

Consider now, for a fixed $\theta \in \Theta_{3}$, the intersections of the sets $U$ and $C U$ with the closed segment $((1-\eta) r, 4 A r, \theta)$ : Its intersection with $U$ is a closed non-void set while its intersection with $C U$ is an open set, i.e. a collection of non-overlapping open intervals of total measure $>\delta r$ by (2.14). If none of these intervals exceeds $\delta r$ in length then they belong to $\{\delta r, U\}$ by the definition of this set. If one of these intervals, $I$ say, exceeds $\delta r$ in length then obviously the two sub-intervals of length $\delta r$, co-terminal with $I$, must belong to $\{\delta r, U\}$. In any case we have shown that

$$
m(((1-\eta) r, 4 A r, \theta)\{\delta r, U\}) \geqslant \delta r
$$

Now by (2.13)

$$
m_{2} \bigcup_{\theta \in \Theta_{3}}[((1-\eta) r, 4 A r, \theta)\{\delta r, U\}]>(1-\eta) r \delta r m \Theta_{3}>5 r^{2} \delta
$$

and $a$ fortiori, by the definition of $V$,

$$
m_{2} V>5 r^{2} \delta
$$

By (2.10) and (2.3')

$$
m_{2} J\left(v_{3}, v_{1}^{\prime}\right)+m_{2} J\left(v_{3}^{\prime}, v_{4}\right)>4 r^{2} \delta
$$

and at least one of the terms on the left side, say the first one, satisfies the inequality

$$
m_{2} J\left(v_{3}, v_{1}^{\prime}\right)>2 r^{2} \delta
$$

Now by (2.7) and (2.3)

$$
\frac{m_{2} J\left(v_{3}\right.}{\left|v_{3}-v_{1}^{\prime}\right|^{2}}, \frac{v_{1}^{\prime}}{2}>\frac{2 r^{2} \delta}{\delta^{2} r^{2}}=\frac{2}{\delta}>A
$$

which is impossible because $v_{1}^{\prime} \in E_{1}$. This contradiction establishes Theorem 2.
2.2. Proof of Theorem 3 when $B$ is a Jordan arc. Let $J=J(0,1)$ be a Jordan arc. Given $\varepsilon$ we are to show that we can inscribe a polygon of vertices
such that

$$
\begin{equation*}
0=u_{0} \prec u_{1} \prec \ldots \prec u_{s}=1, \tag{2.15}
\end{equation*}
$$

$$
\begin{equation*}
\sum_{i=1}^{s}\left|u_{i}-u_{i-1}\right|^{2}<\varepsilon \tag{2.16}
\end{equation*}
$$

Suppose this to be already established; the additional requirement of the theorem, that (2.16) can be achieved while $\max \left|u_{i}-u_{i-1}\right|$ is as small as we please, can now be satisfied in an obvious way. Indeed, we can first subdivide $J$ into a finite sequence of arcs of sufficiently small diameters and then apply the result (2.16) to each of these ares.

We may ignore the simple case when $m_{2} J=0$ for two reasons:
(1) It is easily disposed of by the second part of our proof which uses coverings $U$ of small $\sum d^{2} ;(2)$ It is covered by A . Ville's theorem of 1936. We may therefore assume that $m_{2} J>0$.

Let $\varepsilon>0$ be given. For $\delta_{1}>0$ denote by $E_{\delta_{1}}$, the set of those points $v$, of $J$, to which correspond points $v^{\prime}$ with $\left|v-v^{\prime}\right|>\delta_{1}$ and satisfying the condition

$$
\begin{equation*}
\frac{m_{2} J\left(v, v^{\prime}\right)}{\left|v-v^{\prime}\right|^{2}}>\frac{2 m_{2} J}{\varepsilon} . \tag{2.17}
\end{equation*}
$$

By Theorem 2

$$
\lim _{\delta_{1} \rightarrow 0} m_{2} E_{\delta_{1}}=m_{2} J
$$

We assume $\delta_{1}$ so chosen that

$$
m_{2} E_{\delta_{1}}>\frac{2}{3} m_{2} J
$$

Denote by $E_{\delta_{1}}^{+}$and $E_{\overline{\delta_{1}}}$ the disjoint sets of those points of $E_{\delta_{1}}$ to which correspond points $v^{\prime} \succ v$ or $v^{\prime} \prec v$ respectively: $E_{\delta_{1}}=E_{\delta_{1}}^{+}+E_{\delta_{1}}^{-}$. Let $E_{\delta_{1}}^{\prime}$ be one of the sets on the right hand side whose measure is $>\frac{1}{3} m_{2} J$. Suppose it is $E_{\delta_{1}}^{+}$.

We can obviously select a sequence of disjoint arcs

$$
J\left(v_{11}, v_{11}^{\prime}\right), \quad J\left(v_{12}, v_{12}^{\prime}\right), \ldots, \quad J\left(v_{1, n_{1}}, v_{1, n_{1}}^{\prime}\right),
$$

in natural order along $J$, where $v_{11}, v_{12}, \ldots, v_{1, n_{1}}$ are points of $E_{\delta_{1}}^{\prime}=E_{\delta_{1}}^{+}$and $v_{11}^{\prime}, v_{12}^{\prime}, \ldots, v_{1, n_{2}}^{\prime}$ the corresponding points satisfying (2.17), so that the measure of $E_{\delta_{1}}^{\prime}$ outside these $n_{1}$ arcs be as small as we please. These arcs are picked successively along $J$ and their number $n_{1}$ is necessarily finite because the $m_{2}$-measure of each arc exceeds $2 \delta_{1}^{2} m_{2} J / \varepsilon$. Writing

$$
\Gamma_{1}=J\left(v_{11}, v_{11}^{\prime}\right)+J\left(v_{12}, v_{12}^{\prime}\right)+\ldots+J\left(v_{1, n_{1}}, v_{1, n_{1}}^{\prime}\right)
$$

we may therefore assume that

$$
m_{2} \Gamma_{1}>\frac{1}{3} m_{2} J
$$

Let now $\delta_{2}>0$ and denote by $E_{\delta_{2}}$ the set of those $v$ of $J-\Gamma_{1}$ to which correspond points $v^{\prime}$ satisfying (2.17), $v^{\prime}$ belonging to the same arc of $J-\Gamma_{1}$ as $v$, and such that $\left|v-v^{\prime}\right|>\delta_{2}$. As before $m_{2} E_{\delta_{2}} \rightarrow m_{2}\left(J-\Gamma_{1}\right)$ as $\delta_{2} \rightarrow 0$. Assume $\delta_{2}$ so chosen that

$$
m_{2} E_{\delta_{2}}>\frac{2}{3} m_{2}\left(J-\Gamma_{1}\right)
$$

We now define the set $E_{\delta_{2}}^{\prime}$ as $E_{\delta_{1}}^{\prime}$ was defined before and a set $\Gamma_{2}$ of disjoint arcs in $J-\Gamma_{1}$, such that for each arc $J\left(v, v^{\prime}\right)$ of $\Gamma_{2}(2.17)$ holds, while

$$
m_{2} \Gamma_{2}>\frac{1}{3} m_{2}\left(J-\Gamma_{1}\right)
$$

Similarly sets $\Gamma_{3}, \Gamma_{4}, \ldots, \Gamma_{k}$ are defined successively such that

$$
m_{2} \Gamma_{i}>\frac{1}{3} m_{2}\left(J-\Gamma_{1}-\ldots-\Gamma_{i-1}\right) \quad(i=2, \ldots, k)
$$

Since the measure of each $\Gamma_{1}$ exceeds a third of the remaining measure, we can reach a value $k$ such that

$$
\begin{equation*}
m_{2}\left(J-\Gamma_{1}-\ldots-\Gamma_{k}\right)<\frac{\varepsilon}{2} \tag{2.18}
\end{equation*}
$$

Let $J\left(v_{i}, v_{i}^{\prime}\right), \quad(i=1, \ldots, N)$, be all the arcs of $\Gamma_{1}+\ldots+\Gamma_{k}$ is ascending order. By (2.17)

$$
\begin{equation*}
\sum_{1}^{N}\left|v_{i}-v_{i}^{\prime}\right|^{2}<\frac{\varepsilon}{2 m_{2} J} \sum_{1}^{N} m_{2} J\left(v_{i}, v_{i}^{\prime}\right) \leqslant \frac{\varepsilon}{2} . \tag{2.19}
\end{equation*}
$$

The distance between any pair of arcs of $J-\Gamma_{1}-\ldots-\Gamma_{k}$ being positive, let it be greater than $2 \alpha(>0)$. Denote by $U=U\left(\alpha, \overline{J-\Gamma_{1}-\ldots-\Gamma_{k}}\right)$ a collection of closed convex sets (e.g. squares with sides parallel to fixed directions), each set of diameter $<\alpha$ and such that every point of the closure $\overline{J-\Gamma_{1}-\ldots-\Gamma_{k}}$ is an interior point of at least one of the sets. $U$ may always be assumed to consist of a finite number of sets. If we denote by $d$ the diameter of the general set of $U$ then, by (2.18), we can choose $U$ so that

$$
\begin{equation*}
\sum_{U} d^{2}<\frac{\varepsilon}{2} . \tag{2.20}
\end{equation*}
$$

We may write

$$
J-\Gamma_{1}-\ldots-\Gamma_{k}=\sum_{i=0}^{N} J\left(v_{i}^{\prime}, v_{i+1}\right),
$$

where $v_{0}^{\prime}=0$ and $v_{N+1}=1$, while the first and the last arc of this sum may not exist. Any element of $U$ can cover points of one arc only. Thus we can write

$$
U=\sum_{i=0}^{N} U_{i}
$$

where $U_{i}$ consists of those sets of $U$ which cover points of the arc $J\left(v_{i}^{\prime}, v_{i+1}\right)$. Clearly, by (2.20),

$$
\begin{equation*}
\sum_{i=0}^{N} \sum_{U_{i}} d^{2}=\sum_{U} d^{2}<\frac{\varepsilon}{2} \tag{2.21}
\end{equation*}
$$

Take the general are $J\left(v_{i}^{\prime}, v_{i+1}\right)$ and define on it a finite sequence of points

$$
\begin{equation*}
v_{i}^{\prime}=w_{i, 0}, w_{i, 1}, \ldots, w_{i, p_{i}}=v_{i+1} \tag{2.22}
\end{equation*}
$$

in the following way: Let $w_{i, 0}$ be interior to the set $U_{i}^{(1)}$. If also $v_{i+1}$ is in $U_{1}^{(i)}$ then $p_{i}=1$ and we are through. If not, let $w_{i, 1}$ be the last point of the arc $J\left(v_{i}^{\prime}, v_{i+1}\right)$ which belongs to $U_{i}^{(1)}$. Clearly $w_{i, 1}$ is on the boundary of $U_{i}^{(1)}$; let $w_{i, 1}$ be interior to $U_{i}^{(2)}$. If also $v_{i+1}$ belongs to $U_{i}^{(2)}$ then $p_{i}=2$ and we stop the process. If not, let $w_{i, 2}$ be the last point of $J\left(w_{i, 1}, v_{i+1}\right)$ belonging to $U_{i}^{(2)}$. Continuing in this way, we obtain the sequence of points (2.22) such that the points $w_{i, j-1}$ and $w_{i, j}$ belong to the same set $U_{i}^{(j)}\left(j=1, \ldots, p_{i}\right)$, where the $p_{i}$ sets $U_{i}^{(i)}$ are distinct elements of the collection $U_{i}$. We conclude that

$$
\sum_{j=1}^{p_{i}}\left|w_{i, j-1}-w_{i, j}\right|^{2} \leqslant \sum_{U_{i}} d^{2}
$$

and therefore

$$
\begin{equation*}
\sum_{i=0}^{N} \sum_{j=1}^{p_{i}}\left|w_{i, j-1}-w_{i, j}\right|^{2} \leqslant \sum_{U} d^{2}<\frac{\varepsilon}{2} . \tag{2.23}
\end{equation*}
$$

We have thus obtained the following monotone sequence of points along $J$ :

$$
\begin{aligned}
0 & =w_{0.0}, w_{0.1}, \ldots, \quad w_{0, p_{0}}=v_{1}, \quad v_{1}^{\prime}=w_{1.0}, \quad w_{1,1}, \ldots, \quad w_{1, p_{1}}=v_{2}, \\
v_{2}^{\prime} & =w_{2.0}, \ldots, \quad w_{N, p_{N}}=1 .
\end{aligned}
$$

Denoting them in order by $0=u_{0}, u_{1}, \ldots, u_{s}=1$, we have

$$
\sum\left|u_{i-1}-u_{i}\right|^{2}=\sum\left|v_{i}-v_{i}^{\prime}\right|^{2}+\sum_{i=0}^{N} \sum_{j=1}^{p_{i}}\left|w_{i, j-1}-w_{i, j}\right|^{2}<\frac{\varepsilon}{2}+\frac{\varepsilon}{2}=\varepsilon
$$

by (2.19) and (2.23), and the desired inequality (2.16) is established and therefore also the theorem for the case when $B$ is a Jordan arc.
2.3. A lemma on continuous arcs and proof of Theorem 3. Let $B$ be a non-closed continuous are in the plane. By omitting from $B$ subares with coincident endpoints (loops) we may reduce $B$ to become a Jordan are $J$ joining the original endpoints of $B$. A precise description of this intuitive idea is given by ( ${ }^{1}$ )

Lemma 1. Let $x=f(t)$ be an continuous complex-valued function of $t \in I=[0,1]$ such that $f(0) \neq f(1)$. We can find in $I$ a perfect set $F$ such that the image $f(F)$ is a Jordan arc $J$, having as endpoints $f(0)$ and $f(\mathbf{1})$, in the sense that the relations

$$
\begin{equation*}
a \in F, a^{\prime} \in F, a<a^{\prime} \quad f(a)=f\left(a^{\prime}\right) \tag{2.24}
\end{equation*}
$$

hold if and only if the open interval ( $a, a^{\prime}$ ) is contiguous to $F$.
Remark 1. The set $F$ is by no means always uniquely defined. An arc $B$ in the shape of a pretzel, with its ends slightly extended, admits three distinct sets $F$ obtained by removing from $I$ appropriate single open intervals.

Remark 2. The lemma and its proof require nothing beyond the continuity of $f(t)$. The lemma therefore holds as stated if the values of $f(t)$ are in a Hausdorff space.

[^1]Proof: We call the open interval $S=\left(t, t^{\prime}\right)$ a loopsegment provided that $f(t)=f\left(t^{\prime}\right)$. Let $L$ denote the totality of loopsegments. Since $L$ is evidently compact, there exists a longest loopsegment which we denote by $S_{1}=\left(t_{1}, t_{1}^{\prime}\right)$ and define $F_{1}=I-S_{1}$. Observe that if $S \in L, S \subset F_{1}$, then $S$ can not abut on $S_{1}$ since their union would give a longer loopsegment. Let $S_{2}$ be the longest among the $S \subset F_{1}$ and consider $F_{2}=I-S_{1}-S_{2}$. We repeat this operation successively obtaining the loopsegments $S_{1}, S_{2}, \ldots$ such that the closed segments $\bar{S}_{1}, \bar{S}_{2}, \ldots$ are pairwise disjoint and $l\left(S_{1}\right) \geqslant l\left(S_{2}\right) \geqslant \ldots$. Either the process terminates when $F_{n}=I-S_{1}-\ldots-S_{n}$ contains no further loopsegment, or else it continues indefinitely when evidently $l\left(S_{n}\right) \rightarrow 0$. In either case let $\Omega=\sum_{i} S_{i}$ and consider the perfect set $F=I-\Omega$.

Let ( $a, a^{\prime}$ ) satisfy the conditions (2.24). We cannot have $\left[a, a^{\prime}\right] \subset F$. Indeed, $\left(a, a^{\prime}\right) \in L$ and should have been removed before $l\left(S_{n}\right)$ has become $<a^{\prime}-a$. Hence $\left[a, a^{\prime}\right] \nsubseteq F$ and therefore $\left(a, a^{\prime}\right) \supset S_{i}=\left(t_{i}, t_{i}^{\prime}\right)$ for some $i$ and where we choose for $i$ the least value which will do. Now we must have $\left(a, a^{\prime}\right)=S_{i}=\left(t_{i}, t_{i}^{\prime}\right)$ for if $\left(a, a^{\prime}\right) \neq S_{i}$ then $a^{\prime}-a>l\left(S_{i}\right)$ and $\left(a, a^{\prime}\right)$ should have been removed before $S_{i}$. This proves our lemma except, perhaps, the main point that $J$ is a Jordan arc. To see this, let $\tau=\tau(t)$ be a continuous non-decreasing function in the range $I, \tau(0)=0, \tau(1)=1$ and such that $\tau(t)=\tau\left(t^{\prime}\right)$ for $t<t^{\prime}$ if and only if the interval $\left(t, t^{\prime}\right)$ is contained in $\Omega=\Sigma S_{i}$. If we now identify the two endpoints $t_{i}$ and $t_{i}^{\prime}$ of $S_{i}$ for all $i$, we obtain a set $F_{1}$ which by $\tau=\tau(t)$ is homeomorphic with the range $0 \leqslant \tau \leqslant 1$. On the other hand, we have shown that $J=f\left(\boldsymbol{F}^{\prime}\right)=f\left(\boldsymbol{F}_{1}\right)$ is a homeomorph of $\boldsymbol{F}_{1}$. It therefore follows that $J$ is a homeomorph of the interval $0 \leqslant \tau \leqslant 1$ and our lemma is established.

A general proof of Theorem 3 now becomes obvious. Given $\varepsilon>0$ and applying Theorem 3 to the Jordan are $J$ just constructed we can find a division

$$
0=t^{(0)}<t^{(1)}<\cdots<t^{(n)}=1
$$

where all $t^{(i)} \in F$ and such that

$$
\sum_{i=1}^{n}\left|f\left(t^{(i)}\right)-f\left(t^{(i-1)}\right)\right|^{2}<\varepsilon
$$

and this already establishes the theorem.

## § 3. On plane Jordan arcs of finite and positive $\boldsymbol{\Lambda}^{\alpha}$-measure

3.1. Proof of Theorem 4. To obtain an are $J$ having the properties required by Theorem 4 we repeat with some simplifications the construction of § 1.1: We now choose $\theta_{n}=0$, independent of $n$, satisfying the equation

$$
4 \theta^{\alpha}=1 \quad(1<\alpha<2)
$$

Starting as in § 1.1 with the unit square $S_{0}$, let the continuum $J_{1}$ consist of four corner squares of sides $=\theta$ and of three rectilinear links (fig. 1). $J_{2}$ is obtained from $J_{1}$, by replacing each square $s_{1}$ by a continuum geometrically similar to $J_{1}$ (because $\theta_{2}=\theta_{1}=\theta$ ) which joins its entry point to its exit point and so forth. Now $J=\cap J_{n}$ is our present Jordan arc. If we observe that $J$ is covered by collection $\sum_{n}$ of $4^{n}$ squares having diameters $\theta^{n} \sqrt{2}$, we see that

$$
\Lambda^{\alpha} J \leqslant(\sqrt{2})^{\alpha}
$$

and we leave it to the reader to show that $\Lambda^{\alpha} J>0$. In terms of the notations of § l we can say that $J$ consists of the set

$$
\Sigma=\lim _{n \rightarrow \infty} \sum_{n}=\bigcap \sum_{n}
$$

plus an enumerable set of links whose $\Lambda^{\alpha}$-measure is 0 . To any are $J\left(v, v^{\prime}\right)$, which is not a rectilinear segment, corresponds a value $n$ such that $J\left(v, v^{\prime}\right) \cap \sum$ belongs to one square of $\sum_{n}$ but to more than one square of $\sum_{n+1}$. From this it follows that

$$
\Lambda^{\alpha} J\left(v, v^{\prime}\right)<\theta^{n \alpha} 2^{\frac{1}{\alpha} \alpha}
$$

On the other hand $\left|v-v^{\prime}\right|$ is surely greater than or equal to the width of the corridors of $s_{n}$. Since corr $s_{n}=\theta^{n}(\mathbf{1}-2 \theta)$ we obtain

$$
\left|v-v^{\prime}\right| \geqslant \theta^{n}(1-2 \theta) .
$$

Hence

$$
\frac{\Lambda^{\alpha} J\left(v, v^{\prime}\right)}{\left|v-v^{\prime}\right|^{\alpha}}<\left(\frac{\sqrt{2}}{1-2 \theta}\right)^{\alpha}=K
$$

which proves Theorem 4.
We might remark that there are plane Jordan arcs $J$ of finite $\Lambda^{\alpha}$-measure, $1<\alpha<2$, such that

$$
\varlimsup_{v^{\prime} \rightarrow v} \frac{\Lambda^{\alpha} J\left(v, v^{\prime}\right)}{\left|v-v^{\prime}\right|^{\alpha}}=+\infty
$$

at almost all points $v$ in the sense of $\Lambda^{\alpha}$-measure, but we do not dwell on giving an exemple here.
3.2. Proof of Theorem 5. We pick $\delta>0$ and $A$ such that $0<A<1$ and denote by $E$ the set of those points $v$ of $J$, to which correspond $v^{\prime}$ satisfying the inequalities

$$
\begin{equation*}
\frac{\Lambda^{\alpha} J\left(v, v^{\prime}\right)}{\left|v-v^{\prime}\right|^{\alpha}}>A, \quad\left|v-v^{\prime}\right|<\delta \tag{3.1}
\end{equation*}
$$

The set $E$ is either void or open; in any case its complement $E_{1}=J-E$ is closed. Let us now show that if

$$
\begin{equation*}
\Lambda^{\alpha} E_{1}=0 \tag{3.2}
\end{equation*}
$$

for every fractional $A$ and every $\delta$ then our theorem follows. Indeed, let $A_{n}, 0<A_{n}<1$, and $\delta_{n}(n=1,2, \ldots)$ be such that

$$
\lim A_{n}=1, \quad \lim \delta_{n}=0,
$$

and let $E^{(n)}, E_{1}^{(n)}$ be the corresponding sets defined above. We assume that $\Lambda^{\alpha} E_{1}^{(n)}=0$ for every $n$ and therefore $F=\bigcap_{1}^{\infty} E_{1}^{(n)}$ also has the property $\Lambda^{\alpha} F=0$. If $v \in J-F$ then

$$
\frac{\Lambda^{\alpha} J\left(v, v_{n}^{\prime}\right)}{\left|v-v_{n}^{\prime}\right|^{\alpha}}>A_{n}, \quad\left|v-v_{n}^{\prime}\right|<\delta_{n}
$$

for appropriate points $v_{n}^{\prime}$, and the inequality (7) follows on letting $n \rightarrow \infty$.
To establish (3.2) let us assume that $\Lambda^{\alpha} E_{1}>0$ and see that we get a contradiction. By the definition of $\Lambda^{\alpha}$-measure, for every $\varepsilon>0$ we can find a closed convex set $U$ of diameter $d U$ as small as we please, in particular $d U<\delta$, and such that

$$
\Lambda^{\alpha}\left(E_{1} U\right)>(1-\varepsilon)(d U)^{\alpha}
$$

and in particular such that

$$
\begin{equation*}
\Lambda^{\alpha}\left(E_{1} U\right)>A(d U)^{\alpha} . \tag{3.3}
\end{equation*}
$$

Let $v_{1}, v_{2}$ be the extreme points of $J$ belonging to the closed set $E_{1} U$. In particular $J\left(v_{1}, v_{2}\right) \supset E_{1} U$. But then $\Lambda^{\alpha} J\left(v_{1}, v_{2}\right) \geqslant \Lambda^{\alpha}\left(E_{1} U\right)$ and (3.3) implies

$$
\frac{\Lambda^{\alpha} J\left(v_{1}, v_{2}\right)}{(d U)^{\alpha}}>A
$$

and a fortiori

$$
\frac{\Lambda^{\alpha} J\left(v_{1}, v_{2}\right)}{\left|v_{1}-v_{2}\right|^{\alpha}}>A, \quad\left|v_{1}-v_{2}\right| \leqslant d U<\delta .
$$

However, these inequalities imply that $v_{1}$ and $v_{2}$ belong to $E$ while they actually belong to $E_{1}$ by construction. This contradiction establishes the theorem.

## § 4. On Lipschitz classes of functions defined on Jordan ares

4.1. Proof of Theorem 7. It follows from the assumptions of Theorem 7, namely $G(v) \in \operatorname{Lip}_{J} \phi(x)$ and (9) that to any $a>0$, however small, corresponds a function $\delta(v)>0$ such that

$$
\left|G(v)-G\left(v^{\prime}\right)\right| \leqslant a\left|v-v^{\prime}\right|^{\alpha} \quad \text { if } \quad\left|v-v^{\prime}\right| \leqslant \delta(v) .
$$

Let $E_{n}$ be the set of points $v$ of $J$, for which

$$
\left|G(v)-G\left(v^{\prime}\right)\right| \leqslant a\left|v-v^{\prime}\right|^{\alpha} \quad \text { if } \quad\left|v-v^{\prime}\right| \leqslant 2^{-n} .
$$

The set $E_{n}$ is closed and $\lim E_{n}=J$. Take a sequence $\left\{\varepsilon_{n}\right\}, \varepsilon_{n}>\varepsilon_{n+1}, \varepsilon_{n} \rightarrow 0$, and such that $\sum_{\varepsilon_{n}}<\Lambda^{\alpha} J$. Here we assume that $\Lambda^{\alpha} J>0$, the proof for the case when $\Lambda^{\alpha} J=0$ being a simplified version of the present one. For every $n$ we can find a set $P_{n}=P_{n}\left(E_{n}-E_{n-1}, 2^{-n}\right)$ of convex sets, each of diameter $<2^{-n}$, and such that every point of $E_{n}-E_{n-1}$ is an interior point of at least one of the sets. We shall also assume that

$$
\sum_{P_{n}} d^{\alpha}<\Lambda^{\alpha}\left(E_{n}-E_{n-1}\right)+\varepsilon_{n},
$$

where $d$ denotes the diameter of a general set of the collection $P_{n}$. Every point of $J$ is an interior point of at least one convex set of the collection $\sum P_{n}$ and by the Heine-Borel theorem there is a finite subcollection $P$ of $\Sigma P_{n}$ with the same property. We obviously have

$$
\begin{equation*}
\sum_{P} d^{\alpha}<\Lambda^{\alpha} J+\sum \varepsilon_{n}<2 \Lambda^{\alpha} J \tag{4.1}
\end{equation*}
$$

Let $p^{(1)}, p^{(2)}, \ldots, p^{(k)}$ denote all the convex sets which are elements of $P$. If $p^{(i)} \in P_{n}$, then let $v^{(i)}$ be a point of $\left(E_{n}-E_{n-1}\right) \cap p^{(i)}$. Writing $r^{(i)}=d p^{(i)}<2^{-n}$, we construct the circle $c^{(i)}=c\left(v^{(i)}, r^{(i)}\right)$ which clearly contains $p^{(i)}$.

Thus

$$
J \subset C=c^{(1)}+c^{(2)}+\ldots+e^{(k)}
$$

$$
\begin{equation*}
\sum_{i=1}^{k}\left(r^{(i)}\right)^{\alpha}<2 \Lambda^{\alpha} J \tag{4.2}
\end{equation*}
$$

By the definition of $E_{n}$ we see that for any $v \in c^{(i)} \cap J$

$$
\left|G(v)-G\left(v^{(i)}\right)\right|<a\left|v-v^{(i)}\right|^{\alpha}<a\left(r^{(i)}\right)^{\alpha}
$$

and therefore for any pair $v^{\prime}, v^{\prime \prime}$ of points of $c^{(i)} \cap J$

$$
\left|G\left(v^{\prime}\right)-G\left(v^{\prime \prime}\right)\right|<2 a\left(r^{(i)}\right)^{x}
$$

Let $\mathrm{v}_{0} \prec v^{*}$ by any pair of points of $J$ and let $v_{0}$ be an interior point of $c^{\left(i_{0}\right)}$. Denote by $v_{1}$ the last point $v \succ v_{0}, v \preceq v^{*}$, such that $v \in c^{\left({ }_{0}\right)}$. We have

$$
\left|G\left(v_{0}\right)-G\left(v_{1}\right)\right|<2 a\left(r^{\left(i_{1}\right)}\right)^{\alpha} .
$$

Now $v_{1}$ is an interior point of one of the circles of $C$, say of $c^{\left(i_{1}\right)}, i_{1} \neq i_{0}$, and let $v_{2}$ be the last point $v \succ v_{1}, v \leq v^{*}$, such that $v \in c^{\left(i_{1}\right)}$. As before

$$
\left|G\left(v_{1}\right)-G\left(v_{2}\right)\right|<2 a\left(r^{\left(i_{1}\right)}\right)^{\alpha}
$$

and so forth. After a finite number of steps, in fact after $k^{\prime} \leqslant k$ steps, we shall reach the point $v^{*}$. By (4.2) we find

$$
\begin{aligned}
\left|G\left(v_{0}\right)-G\left(v^{*}\right)\right| & \leqslant\left|G\left(v_{0}\right)-G\left(v_{1}\right)\right|+\left|G\left(v_{1}\right)-G\left(v_{2}\right)\right|+\ldots+\left|G\left(v_{k^{\prime}}\right)-G\left(v^{*}\right)\right| \\
& <2 a\left(\left(r^{\left(i_{0}\right)}\right)^{\alpha}+\left(r^{\left(i_{j}\right)}\right)^{\alpha}+\ldots+\left(r^{\left(i_{k^{\prime}}\right)}\right)^{\alpha}\right)<4 a \Lambda^{\alpha} J .
\end{aligned}
$$

Since $a$ was arbitrary we conclude that

$$
G\left(v_{0}\right)-G\left(v^{*}\right)=0
$$

which was to be proved.
4.2. Proof of Theorem 8. There remains as our last task to furnish a proof of Theorem 8. Let the positive monotone function $\phi(x)$ of that theorem be given. We select a function $\psi(x)$ which is convex and continuously differentiable in the range $[0,1]$ and such that

$$
\begin{equation*}
0<\psi(x)<\phi(\sqrt{x}) \quad(0<x \leqslant 1) \quad \psi(0)=0 . \tag{4.3}
\end{equation*}
$$

Let

$$
\begin{equation*}
t=A \psi(x), \quad A=\pi / \psi(\mathbf{1}) \tag{4.4}
\end{equation*}
$$

This is a relation which maps the range $0 \leqslant x \leqslant 1$ onto $0 \leqslant t \leqslant \pi$. We now invert (4.4) obtaining the concave increasing function

$$
\begin{equation*}
x=\left(F^{\prime}(t)\right)^{2} \quad(0 \leqslant t \leqslant \pi, \quad F(t) \geqslant 0) . \tag{4.5}
\end{equation*}
$$

We now consider the function

$$
\begin{equation*}
h(t)=1-(F(t))^{2} \quad(0 \leqslant t \leqslant \pi), \tag{4.6}
\end{equation*}
$$

which has the following properties: $h(0)=1, h(\pi)=0, h(t)$ is convex in [0, $\pi$ ] and continuously differentiable in $(0, \pi)$. Notice in particular that in the range $(0, \pi)$, $h^{\prime}(x)<0$ and non-decreasing. We now extend the definition of $h(t)$ to the range $[-\pi, \pi]$
so as to be even, and expand it in cosine series

$$
\begin{equation*}
h(t)=\sum_{0}^{\infty} A_{\nu} \cos v t \tag{4.7}
\end{equation*}
$$

Clearly $A_{0}>0$. But also all $A_{v}>0$. Indeed

$$
\frac{\pi}{2} A_{v}=\int_{0}^{\pi} h(t) \cos \nu t d t=\frac{1}{v} \int_{0}^{\pi}\left(-h^{\prime}(t)\right) \sin \nu t d t>0 .
$$

the last integral being positive, because $-h^{\prime}(t)$ is positive and decreasing. (Compare Bochner [1], 76-77.)

We may therefore write the expression (4.7) as

$$
h(t)=\sum_{0}^{\infty} 2 a_{\nu}^{2} \cos v t, \quad\left(a_{\nu}>0\right),
$$

and in particular, for $t=0$

$$
1=\sum_{0}^{\infty} 2 a_{v}^{2} .
$$

Now (4.6) gives

$$
\begin{equation*}
F^{2}(t)=\sum_{1}^{\infty} 2 a_{v}^{2}(1-\cos v t)=\sum_{1}^{\infty} 4 a_{v}^{2} \sin ^{2} \frac{v t}{2} \tag{4.8}
\end{equation*}
$$

This expansion implies that $F(t)$ is a screw function in Hilbert space which corresponds to a closed screw line of that space. We refer to von Neumann and Schoenberg [5] for further information on this subject; we, however, need none whatever, because what we need is perfectly elementary and explained in a few words: We mean that there is in the Hilbert space $H$ a closed curve

$$
\begin{equation*}
C: x=f(t), \quad(0 \leqslant t \leqslant 2 \pi ; f(t) \text { of period } 2 \pi), \tag{4.9}
\end{equation*}
$$

such that for all real $t$ and $t^{\prime}$

$$
\begin{equation*}
F\left(t-t^{\prime}\right)=\left\|f(t)-f\left(t^{\prime}\right)\right\| . \tag{4.10}
\end{equation*}
$$

This curve is immediately constructed, for (4.8) gives

$$
\begin{align*}
F^{2}\left(t-t^{\prime}\right) & =\sum 4 a_{\nu}^{2} \sin ^{2} \frac{1}{2} \nu\left(t-t^{\prime}\right) \\
& =\sum_{\nu=1}^{\infty}\left\{\left(a_{\nu} \cos \nu t-a_{\nu} \cos \nu t^{\prime}\right)^{2}+\left(a_{\nu} \sin \nu t-a_{\nu} \sin \nu t^{\prime}\right)^{2}\right\} \tag{4.11}
\end{align*}
$$

In the space $H$ of real sequences $\left\{x_{n}\right\}_{0}^{\infty}$ with $\sum x_{n}^{2}<\infty$ and the usual norm $\|x\|=\left(\sum x_{n}^{2}\right)^{\frac{1}{2}}$ we indeed see by (4.11) that the closed curve $C$ traced out by

$$
f(t)=\left\{a_{1} \cos t, a_{1} \sin t, a_{2} \cos 2 t, a_{2} \sin 2 t, \ldots\right\} \quad(0 \leqslant t \leqslant 2 \pi)
$$

enjoys the property (4.10).
Along the Jordan are

$$
\begin{equation*}
\Gamma: x=f(t) \quad(0 \leqslant t \leqslant \pi) \tag{4.12}
\end{equation*}
$$

we now define the function

$$
\begin{equation*}
g(t)=t \tag{4.13}
\end{equation*}
$$

For any two values $t, t^{\prime}$ such that $0 \leqslant t<t^{\prime} \leqslant \pi$

$$
\frac{g\left(t^{\prime}\right)-g(t)}{\phi\left(\left\|f\left(t^{\prime}\right)-f(t)\right\|\right)}=\frac{t^{\prime}-t}{\phi\left(F\left(t^{\prime}-t\right)\right)}
$$

and by (4.3) this is $\quad<\frac{t^{\prime}-t}{\psi\left(F^{2}\left(t^{\prime}-t\right)\right)}=A$,
the last equality relation holding because the relation (4.5) is the inverse of (4.4). We have therefore shown that

$$
g\left(t^{\prime}\right)-g(t)<A \phi\left(\left\|f\left(t^{\prime}\right)-f(t)\right\|\right) \quad\left(0 \leqslant t<t^{\prime} \leqslant \pi\right) .
$$

Returning to our old notation $v=f(t), G(v)=g(t)$, this is precisely the relation

$$
\left|G\left(v^{\prime}\right)-G(v)\right|<A \phi\left(\left\|v^{\prime}-v\right\|\right)
$$

which was to be established and which shows that $G(v) \in U \operatorname{Lip}_{J} \phi(x)$. Since $G(v)=g(t)=t$ ist not a constant our Theorem 8 is thereby established.

## References

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[^0]:    (1) The main results of the present paper were announced in the note: Sur les arcs ascendants à pente partout nulle et des problèmes qui s'y rattachent, C. R. Acad. Paris, 249 (1959), 1079-1080. Subsequently M. G. Glaeser kindly brought to our attention the references [3] and [8] which helped us to shorten and improve our paper.

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[^1]:    ${ }^{(1)}$ Lemma 1 is a special case of the following Arcwise Connectedness Theorem: Every two points $a$ and $b$ of a locally connected continuum $M$ can be joined in $M$ by a simple continuous arc. (See [9], p. 36.) However, a simple proof of Lemma 1 is here included for the reader's convenience.

