# THE RATIONAL HOMOTOPY THEORY OF CERTAIN PATH SPACES WITH APPLICATIONS TO GEODESICS 

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It is well known that the topology of various path spaces on a complete riemannian manifold $M$ is closely related to the existence of various kinds of geodesics on $M$. Classical Morse theory and the theory of closed geodesics are beautiful examples of this sort.

The motivation for the present paper is the study of geodesics satisfying a very general boundary condition of which the above examples and the example of isometryinvariant geodesics are particular cases. In particular, we generalize a result of SullivanVigué [16].

Let $N \subset M \times M$ be a submanifold of the riemannian product $M \times M$. An $N$-geodesic on $M$ is a geodesic $c:[0,1] \rightarrow M$ which satisfies the boundary condition

$$
\begin{equation*}
(c(0), c(1)) \in N \quad \text { and } \quad(\dot{c}(0),-\dot{c}(1)) \in T N^{\perp} \tag{N}
\end{equation*}
$$

where $T^{\prime} N^{\perp}$ is the normal bundle of $N$ in $M \times M$. If $N=V_{1} \times V_{2}$, where $V_{i} \subset M, i=1,2$ are submanifolds of $M$ then an $N$-geodesic is simply a $V_{1}-V_{2}$ connecting geodesic (orthogonal to each $V_{i}$ ). If $N$ is the graph of an isometry, $A$, of $M$ then an $N$-geodesic is a geodesic which extends uniquely to an $A$-invariant geodesic $c: \mathbf{R} \rightarrow M$; i.e.

$$
c(t+1)=A(c(t)), \quad t \in \mathbf{R}
$$

When $A$ has finite order ( $A^{k}=\mathrm{id}$ ) then $c$ is in fact closed $(c(t+k)=c(t), t \in \mathbf{R})$.
The study of $N$-geodesics on $M$ proceeds via critical point theory for the energy integral on a suitable Hilbert manifold of curves with endpoints in $N$. This Hilbert manifold is homotopy equivalent to the space $M_{N}^{I}$ of continuous curves $f:[0,1] \rightarrow M$ satisfying $(f(0)$, $f(1)) \in N$, with the compact open topology (cf. Grove [4], [6]).
(1) Part of this work was done while the first named author visited the IHES at Bures-surYvette during May 1976.

In this paper we apply Sullivan's theory of minimal models to study the rational homotopy type of $M_{N}^{I}$, and hence to obtain information about $N$-geodesics.

Sullivan's theory (cf. [14], [15] and [8]) associates with each path connected space $S$ a certain differential algebra ( $\Lambda X_{S}, d_{S}$ ) over $\mathbf{Q}$ which describes its rational homotopy type. ( $\Lambda X_{S}, d_{S}$ ) is called the minimal model of $S$ and $H\left(\Lambda X_{S}\right)$ is the rational (singular) cohomology of $S$. As an algebra $\Lambda X_{S}$ is the free graded commutative algebra over the graded space $X_{S}$. If $S$ is nilpotent and its rational cohomology has finite type then $X_{S}$ is the (rational) dual of the graded space $\pi_{*}(S) \otimes \mathbb{Q}$. (See section 1 for more details.)

Our main result is an explicit construction of the minimal model for the space $M_{G(g)}^{t}$, where $G(g)$ is the graph of a so called I-rigid map and $M$ is any l-connected topological space whose rational cohomology has finite type (Theorem 3.17). This gives in particular a new proof of Sullivan's theorem for the space of closed curves $M^{S^{1}}$ [14]. Surprisingly enough the minimal model for $M_{G(g)}^{I}$ has exactly the same form as the minimal model for the space of closed curves on a space $M^{\prime}$. This space, however, is not obviously related to $M$ and it can be much bigger than $M$. For this reason the results of Sullivan-Vigué [16] do not carry over to our more general case in a completely satisfactory manner although some of the methods from [16] are important for us.

The minimal model for $M_{G(g)}^{I}$ contains all information about the rational homotopy theory of $M_{G(g)}^{I}$, in particular about the cohomology. An immediate consequence of the model is the following (Theorem 4.1).

Theorem. If the rational cohomology of $M_{G(g)}^{I}$ is non trivial and $g$ is rigid at 1 then $M_{G(g)}^{I}$ has non-zero cohomology in an infinite arithmetic sequence of dimensions.

The main application of the model is however (cf. Theorem 4.5).
Theorem. If $M$ is 1 -connected, $H^{*}(M)$ finite dimensional and $g: M \rightarrow M$ rigid at 1 , then $M_{G(g)}^{I}$ has a bounded sequence of Betti numbers if and only if

$$
\operatorname{dim} \pi_{*}^{\text {even }}(M)^{g_{*}} \otimes \mathbf{Q} \leqslant \operatorname{dim} \pi_{*}^{\text {odd }}(M)^{g_{*}} \otimes \mathbf{Q} \leqslant 1
$$

where $\pi_{*}(M)^{\sigma_{*}}$ is the homotopy of $M$ fixed by the induced map $g_{*}$.
When $g=$ id this specializes to the main theorem of Sullivan-Vigué [16]. If we combine this result with the main theorem of Grove-Tanaka [7] we obtain (generalizing the application by Sullivan-Vigué of Gromoll-Meyer [3]).

Theorem. Let $M$ be a compact 1-connected riemannian manifold and let $g$ be a finite order isometry of $M$. If $g$ has at most finitely many invariant geodesics then

$$
\operatorname{dim} \pi_{*}^{\text {even }}(M)^{g *} \otimes \mathbf{Q} \leqslant \operatorname{dim} \pi_{*}^{\text {odd }}(M)^{\sigma^{*}} \otimes \mathbf{Q} \leqslant 1 .
$$

As a consequence we obtain (cf. Cor. 4.10).
Corollary. Let $M$ be a l-connected, compact riemannian manifold whose cohomology is spherically generated (e.g. M formal) and let $g$ be a finite order isometry of $M$. If the induced map $g^{*}$ on cohomology fixes at least two generators then $g$ has infinitely many invariant geodesics.

The paper is divided into 4 sections. In section 1 we recall briefly the main results in the theory of (minimal) models and explain how they generalize when an action of a finite group is involved. Besides being of interest in itself we use these results in section 3 . In section 2 we translate the fibration

$$
\Omega M \longrightarrow M_{N}^{I} \xrightarrow{\pi_{N}} N
$$

to models. Here $M$ is any 1 -connected space, and $N$ a path connected subspace of $M \times M$. Furthermore, $\pi_{N}(f)=(f(0), f(1)), \Omega M$ is the ordinary loop space of $M$ and $M_{N}^{I}$ is defined as above. We exhibit a (not necessarily minimal) model for $M_{N}^{I}$ (Theorem 2.8). In particular (Cor. 2.11) we obtain explicitly the space of generators for the minimal model of $M_{N}^{I}$. We also apply results from the theory of models to our model of $M_{N}^{I}$ (Theorem 2.15 and Cor. 2.16).

In particular, suppose $N$ is a closed submanifold of $M \times M$ and $M$ is a complete riemannian manifold. Let $p_{i}: N \rightarrow M, i=0,1$ be the left and right projections and assume that either $p_{0}(N)$ or $p_{1}(N)$ is compact and that $V=N \cap \triangle(M)$ is a closed submanifold of $N$. Then according to Grove [5] if there are no $N$-geodesics on $M$ the inclusion $V \rightarrow M_{N}^{I}$ is a homotopy equivalence. Thus Theorem 2.15 yields:

Theorem. Suppose in addition to the above conditions $N$ is 1-connected and let

$$
\left(p_{i}\right)_{*}: \pi_{*}(N) \otimes \mathbf{Q} \rightarrow \pi_{*}(M) \otimes \mathbf{Q}, \quad i=0,1
$$

be the linear maps induced by $p_{i}, i=0,1$. If for some complete metric on $M$ there are no $N$ geodesics, then coker $\left(\left(p_{0}\right)_{*}-\left(p_{1}\right)_{*}\right)$ is spanned by elements of even degree and

$$
\operatorname{dim} \operatorname{coker}\left(\left(p_{0}\right)_{*}-\left(p_{1}\right)_{*}\right) \leqslant \operatorname{dim} V .
$$

As a second application we get from Example 2.21 the
Theorem. Let $\Sigma, \Sigma_{1}$ and $\Sigma_{2}$ be spheres (possibly exotic) and suppose $\Sigma_{1}$ and $\Sigma_{2}$ are imbedded in $\Sigma$ so that $\Sigma_{1} \cap \Sigma_{2}$ is a (collection of) closed submanifold(s) of $\Sigma$. Then for any riemannian metric on $\Sigma$ there are $\Sigma_{\mathbf{1}}-\Sigma_{\mathbf{2}}$ connecting geodesics.

Finally in section 3 and section 4 we specialize to the case $N=G(g)$ and get the results on isometry invariant geodesics.

## 1. Equivariant minimal models

Throughout the paper all vector spaces are defined over the rationals $\mathbf{Q}$ unless otherwise said. We begin by recalling some facts from Sullivan's theory of minimal models (see Sullivan [14], [15] and Halperin [8]).

A commutative graded differential algebra (c.g.d.a.) is a pair $\left(A, d_{A}\right)$ where $A=\oplus_{p=0}^{\infty} A^{p}$ is a non-negatively graded algebra (over $\mathbb{Q}$ ) with identity, such that $a b=(-1)^{p q} b a$ for $a \in A^{p}, b \in A^{q}$ and $d_{A}: A \rightarrow A$ is a derivation of degree 1 with $d_{A}^{2}=0$.
$\Lambda X$ will denote the free graded commutative algebra over a graded space $X$ i.e.

$$
\Lambda X=\text { exterior }\left(X^{\text {odd }}\right) \otimes \text { symmetric }\left(X^{\text {even }}\right)
$$

$\Lambda+X$ is the ideal of polynomials with no constant term i.e. $\Lambda^{+} X=\sum_{j>1} \Lambda^{j} X$.
A $K S$-complex is a c.g.d.a. $(\Lambda X, d)$ which satisfies:
$\left(\mathbf{k s}_{1}\right)$ There is a homogeneous basis $\left\{x_{\alpha}\right\}_{\alpha \in J}$ for $X$ indexed by a well ordered set $J$ such that $d x_{\alpha}$ is a polynomial in the $x_{\beta}$ with $\beta<\alpha$.

If ( $\Lambda X, d)$ in addition to $\left(\mathrm{ks}_{1}\right)$ satisfies
$\left(\mathrm{ks}_{2}\right) d X \subset \Lambda^{+} X \cdot \Lambda^{+} X$
then $(\Lambda X, d)$ is said to be minimal.
In the rest of the paper ( $\Lambda X, d$ ) is always assumed to be a connected KS-complex. Let $Q(\Lambda X)=\Lambda+X / \Lambda+X \cdot \Lambda+X$ be the indecomposables of $\Lambda X$ and $\zeta: \Lambda+X \rightarrow Q(\Lambda X)$ the projection. Define a differential $Q(d)$ on $Q(\Lambda X)$ by $Q(d) \zeta=\zeta d$. Then $(\Lambda X, d)$ is minimal if and only if $Q(d)=0$. If $\psi:(\Lambda X, d) \rightarrow\left(\Lambda X^{\prime}, d^{\prime}\right)$ is a c.g.d.a. map, we define $Q(\psi): Q(\Lambda X) \rightarrow Q\left(\Lambda X^{\prime}\right)$ by $Q(\psi) \zeta=\zeta^{\prime} \psi$. Note that $\zeta$ restricts to an isomorphism $X \rightarrow Q(\Lambda X)$ which allows us to identify these spaces.

We shall now recall the notation of homotopy due to Sullivan [15, §3] (see also [8; chap. 5]). Let ( $\Lambda X, d$ ) be a KS-complex with $X$ strictly positively graded (i.e. $\Lambda X$ is connected.)
$\left(\Lambda X^{I}, D\right)$ is the c.g.d.a. obtained by tensoring $(\Lambda X, d)$ with the "contractible" c.g.d.a. $(\Lambda \bar{X} \otimes \wedge D \bar{X}, D)$, where
$\left(c_{1}\right) \bar{X}$ is the suspension of $X$ i.e. $\bar{X}^{p}=X^{p+1}$
and
$\left(\mathrm{c}_{2}\right) D: \bar{X} \rightarrow D \bar{X}$ is an isomorphism.

The degree -1 isomorphism $\bar{X}=\bar{X}$ is written $x \mapsto \bar{x}$.
A derivation $i$ of degree -1 and a derivation $\theta$ of degree zero in $\Lambda X^{I}$ are defined by

$$
i x=\bar{x}, i \bar{x}=i D \bar{x}=0 \quad \text { for all } x \in X
$$

and

$$
\theta=D i+i D
$$

Let $\lambda_{0}: \Lambda X \rightarrow \Lambda X^{I}$ denote the standard inclusion and set $\lambda_{1}=e^{\theta}{ }^{\circ} \lambda_{0}$. Here $e^{\theta}$ is well defined because for any $\Phi \in \Lambda X^{I}$ there is an integer $n$ such that $\theta^{n} \Phi=0$ [8]. Note that if $\Pi: \Lambda X^{I} \rightarrow \Lambda X$ is the projection defined by

$$
\Pi x=x, \Pi \bar{x}=\Pi D \bar{x}=0 \quad \text { for all } x \in X
$$

then $\lambda_{0}$ and $\Pi$ induce inverse cohomology isomorphisms because $(\Lambda \bar{X} \otimes \Lambda D \bar{X}, D)$ is acyclic.
Definition 1.1. Two homomorphisms $\gamma_{0}, \gamma_{1}:(\Lambda X, d) \rightarrow\left(A, d_{A}\right)$ of c.g.d.a.'s are called homotopic (written $\gamma_{0} \sim \gamma_{1}$ ) if there is a c.g.d.a. map $\Gamma:\left(\Lambda X^{I}, D\right) \rightarrow\left(A, d_{A}\right)$ such that $\Gamma \circ \lambda_{i}=\gamma_{i}$ $i=0,1$.

If the c.g.d.a. $\left(A, d_{A}\right)$ is homology connected i.e. $H^{0}(A)=\mathbf{Q}$ a model for $\left(A, D_{A}\right)$ is a KS-complex $(\Lambda X, d)$ together with a homomorphism of c.g.d.a.'s

$$
\varphi:(\Lambda X, d) \rightarrow\left(A, d_{A}\right)
$$

which satisfies
(m) $\varphi$ induces an isomorphism $\varphi^{*}$ on cohomology.

If the KS-complex $(\Lambda X, d)$ is minimal we speak of the minimal model $\varphi:(\Lambda X, d) \rightarrow$ ( $A, d_{A}$ ).

We can now state the following important result (see [15, §5] and [8, chap. 6]).
Theorem 1.2. Let $\left(A, d_{A}\right)$ be a c.g.d.a. with $H^{0}(A)=\mathbf{Q}$. Then there is a minimal model

$$
\varphi:(\Lambda X, d) \rightarrow\left(A, d_{A}\right) .
$$

If $\varphi^{\prime}:\left(\Lambda X^{\prime}, d^{\prime}\right) \rightarrow\left(A, d_{A}\right)$ is another minimal model, then there is an isomorphism of c.g.d.a.'s $\alpha:(\Lambda X, d) \rightarrow\left(\Lambda X^{\prime}, d^{\prime}\right)$ such that $\varphi \sim \varphi^{\prime} \circ \alpha$. Finally, $\alpha$ is unique up to homotopy.

A number of choices are involved in the construction of $\varphi:(\Lambda X, d) \rightarrow\left(A, d_{A}\right)$. If a finite group $G$ acts on ( $A, d_{A}$ ), the flexibility in the construction enables us to obtain an induced action of $G$ on ( $\Lambda X, d)$ and to make $\varphi$ equivariant. In fact, one can carry out Sullivan's proof of Theorem 1.2 equivariantly using that any $G$-invariant subspace of a vector space has a $G$-invariant complement. Hence

Theorem 1.3. Let $\left(A, d_{A}\right)$ be a c.g.d.a. with $H^{0}(A)=\mathbf{Q}$ and let $G$ be a finite group acting on $A$ by c.g.d.a. maps. Then there is a minimal model

$$
\varphi:(\wedge X, d) \rightarrow\left(A, d_{A}\right)
$$

such that $G$ acts on $(\Lambda X, d)$ and $\varphi$ is equivariant. If $\varphi^{\prime}:\left(\Lambda X^{\prime}, d^{\prime}\right) \rightarrow\left(A, d_{A}\right)$ is another $G$ equivariant minimal model, then there is a $G$-isomorphism $\alpha:(\Lambda X, d) \rightarrow\left(\Lambda X^{\prime}, d^{\prime}\right)$ such that $\varphi \sim \varphi^{\prime} \circ \alpha$ and $\alpha$ is unique up to homotopy.

There is also an equivariant theorem for maps which again can be proved by making the corresponding non-equivariant proof (cf. e.g. [8, Theorem 5.19]) equivariant.

Theorem 1.4. Let $\left(A, d_{A}\right)$ and $\left(A^{\prime}, d_{A^{\prime}}\right)$ be a c.g.d.a.'s with $H^{0}(A)=H^{0}\left(A^{\prime}\right)=\mathbf{Q}$ and with actions of a finite group G. Furthermore, let

$$
\varphi:(\Lambda X, d) \rightarrow\left(A, d_{A}\right) \quad \text { and } \varphi^{\prime}:\left(\Lambda X^{\prime}, d^{\prime}\right) \rightarrow\left(A^{\prime}, d_{A}\right)
$$

be equivariant minimal models as in Theorem 1.3. Then for any equivariant c.g.d.a. map $\Omega$ : $\left(A, d_{A}\right) \rightarrow\left(A^{\prime}, d_{A^{\prime}}\right)$ there is an equivariant c.g.d.a. map $\omega:(\Lambda X, d) \rightarrow\left(\Lambda X^{\prime}, d^{\prime}\right)$ such that $\varphi^{\prime} \circ \omega \sim \Omega \circ \varphi$.

Now suppose $M$ is a topological space. Denote by $(A(M), d)$ the c.g.d.a. of rational differential (PL) forms on $M$.

A rational $p$-form $\Phi \in A^{p}(M)$ on $M$ is a function which assigns to each singular $q$ simplex $\sigma: \Delta^{q} \rightarrow M$ a $C^{\infty}$ differential $p$-form $\Phi_{\sigma}$ on the standard $q$-simplex $\Delta^{q}$ such that
$\left(d_{1}\right) \Phi_{\sigma}$ is in the c.g.d.a. generated (over $\left.\mathbf{Q}\right)$ by the barycentric coordinate functions. and
$\left(\mathrm{d}_{2}\right)$ The map $\sigma \mapsto \Phi_{\sigma}$ is compatible with face and degeneracy operations.
Multiplication and differentiation are defined in $A(M)$ by $(\Phi \wedge \Psi)_{\sigma}=\Phi_{\sigma} \wedge \Psi_{\sigma}$ and $(d \Phi)_{\sigma}=$ $d\left(\Phi_{\sigma}\right)$.

If $g: M \rightarrow M^{\prime}$ is a continuous map, there is an induced map $A(g): A\left(M^{\prime}\right) \rightarrow A(M)$ of c.g.d.a.'s given by $(A(g) \Phi)_{\sigma}=\Phi_{g o \sigma}$. One has the following important result.

Theorem 1.5. (Sullivan-Whitney-Thom). Integration yields a natural isomorphism of graded algebras

$$
\int^{*}: H^{*}(A(M)) \rightarrow H^{*}(M)
$$

where $H^{*}(M)$ denotes singular cohomology with coefficients in $\mathbf{Q}$.

When $M$ is path connected a (minimal) model for $(A(M), d)$ is called simply a ( minimal) model for $M$. The minimal model for $M$ will be denoted by

$$
\varphi_{M}:\left(\Lambda X_{M}, d_{M}\right) \rightarrow(A(M), d) .
$$

The space of indecomposable elements:

$$
\pi_{y}^{*}(M)=Q\left(\Lambda X_{M}\right) \cong X_{M}
$$

is called the pseudo dual homotopy of $M$. If $H^{*}(M)$ has finite type (i.e. finite dimensional in each degree) and $M$ is nilpotent then there is a natural isomorphism

$$
\pi_{\psi}^{*}(M) \rightarrow \operatorname{Hom}_{\mathbf{Z}}\left(\pi_{*}(M), \mathbf{Q}\right)
$$

(cf. [15] and [8]).

## 2. A model for the space $M_{N}^{I}$

Let $M$ be a simply connected space whose rational cohomology has finite type, and fix a path connected subspace $N \subset M \times M$.

Let $M^{I}$ be the space of continuous maps $f:[0,1] \rightarrow M$ with the compact open topology. In this section we shall determine a model for the subspace $M_{N}^{I} \subset M^{I}$ given by

$$
M_{N}^{I}=\left\{f \in M^{I} \mid(f(0), f(\mathbf{1})) \in N\right\} .
$$

We have the commutative diagram

where $\pi(f)=(f(0), f(1)), \pi_{N}$ is the restriction of $\pi$ and $\Omega M=\pi_{N}^{-1}\left(m_{0}, m_{\mathbf{1}}\right)=\left\{f \in M^{I} \mid f(0)=m_{0}\right.$ and $\left.f(1)=m_{1}\right\}$ for a chosen base point $\left(m_{0}, m_{1}\right) \in N$.

Both rows in (2.1) are Hurewicz fibrations which we denote respectively by $\mathcal{F}$ and $\mathcal{F}_{N}$. Note that $\mathfrak{F}_{N}=i_{N}^{*}(\mathcal{F})$.

We also have a homotopy equivalence $\eta: M \rightarrow M^{I}$ given by: $\eta(m)$ is the constant map $I \rightarrow m$. Clearly

$$
\begin{equation*}
\pi \circ \eta=\Delta: M \rightarrow M \times M \tag{2.2}
\end{equation*}
$$

is the diagonal of $M$.
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Now we begin the translation of (2.1) to models. Since $M$ is 1-connected and $H^{*}(M)$ has finite type it follows that $\wedge X_{M}$ is 1-connected; i.e. $X_{M}^{0}=X_{M}^{1}=0$, and has finite type (see [8; Cor. 3.11 and Cor. 3.15]).

Consider the diagram

where $\lambda_{0}$ and $\lambda_{1}$ are defined on page 281 and
and

$$
\begin{aligned}
& \lambda_{0} \otimes \lambda_{1}(\Phi \otimes \Psi)=\lambda_{0} \Phi \cdot \lambda_{1} \Psi \\
& \bar{\varrho} x=\bar{\varrho} D \bar{x}=0 \quad \text { and } \bar{\varrho} \bar{x}=\bar{x}
\end{aligned}
$$

$$
h\left(\Phi \otimes \Psi^{*} \otimes \bar{x}\right)=\lambda_{0} \Phi \cdot \lambda_{1} \Psi \cdot(\mathbf{l} \otimes \bar{x} \otimes \mathbf{1})
$$

By [8, Lemma 5.28] $h$ is an isomorphism of graded algebras (because $\Lambda X_{M}$ is minimal.) Since $\Lambda X_{M}$ is 1-connected, $d_{M} X_{M}^{p} \subset \Lambda\left(\oplus_{j=2}^{p-1} X_{M}^{j}\right)$. Hence (5.5) and (5.6) of [8] yield

$$
\begin{equation*}
\lambda_{1} x-\lambda_{0} x=D \bar{x}+\Omega(x), \quad x \in X_{M}^{p} \tag{2.4}
\end{equation*}
$$

where

$$
\Omega(x)=\sum_{n=1}^{\infty} \frac{(i D)^{n}}{n!} x \in\left\{\Lambda\left(X_{M}^{<p}\right) \otimes \Lambda\left(\bar{X}_{M}^{<p-1}\right) \otimes \Lambda\left(D \bar{X}_{M}^{<p}\right)\right\} \cap \text { ker } \Pi
$$

and $\Pi$ is defined on p. 281.
An easy calculation shows that $\bar{\varrho} D=\bar{\varrho} i D=0$, and it follows from (2.4) that (2.3) is commutative. Thus (cf. [8, chapers 1 and 5]) (2.3) exhibits $\Lambda X_{M} \otimes \Lambda X_{M} \rightarrow \Lambda X_{M}^{I} \rightarrow \Lambda \bar{X}_{M}$ as a minimal KS-extension.

We shall now define a commutative diagram of c.g.d.a.'s

in which all the vertical maps induce isomorphisms on cohomology.
First let $P_{L}, P_{R}: M \times M \rightarrow M$ be the left and right projections, and define

$$
\varphi_{M \times M}(\Phi \otimes \Psi)=A\left(P_{L}\right) \circ \varphi_{M} \Phi \cdot A\left(P_{R}\right) \circ \varphi_{M} \Psi
$$

Since $H^{*}(M)$ has finite type, the Künneth theorem holds and $\varphi_{M \times M}$ induces an isomorphism $\varphi_{M \times M}^{*}$ on cohomology. In particular $\varphi_{M \times M}: \wedge X_{M} \otimes \wedge X_{M} \rightarrow A(M \times M)$ is a minimal model for $M \times M$.

Next, note that the projection $\Pi$ : $\Lambda X_{M}^{I} \rightarrow \Lambda X_{M}$ satisfies $\Pi \circ \lambda_{0}=\Pi \circ \lambda_{1}=$ id. Hence $\Pi \circ\left(\lambda_{0} \otimes \lambda_{1}\right)=\mu$ is the multiplication homomorphism

$$
\mu: \wedge X_{M} \otimes \wedge X_{M} \rightarrow \Lambda X_{M}
$$

From this and (2.2) we see that the following diagram is commutative.


Since $\eta$ is a homotopy equivalence it induces an isomorphism $A(\eta)^{*}$ on cohomology. Therefore by Sullivan [15, §3] or Theorem 5.19 of [8] there is a homomorphism of c.g.d.a.'s

$$
\psi:\left(\Lambda X_{M}^{I}, D\right) \rightarrow\left(A\left(M^{l}\right), d\right)
$$

such that $\psi \circ\left(\lambda_{0} \otimes \lambda_{1}\right)=A(\pi) \circ \varphi_{M \times M}$ and $A(\eta) \circ \psi \sim \varphi_{M} \circ \Pi$. Because $A(\eta)^{*}, \varphi_{M}^{*}$ and $\Pi^{*}$ are all cohomology isomorphisms, so is $\psi^{*}$.

Finally (2.3) shows that ker $\varrho$ is generated by $\lambda_{0} \otimes \lambda_{1}\left(X_{M} \oplus X_{M}\right)$ and hence $\psi(\operatorname{ker} \bar{\varrho})$ is generated by $A(\pi) \circ \varphi_{M \times M}\left(X_{M} \oplus X_{M}\right)$. Since $A(j) \circ A(\pi)=0$ on elements of degree $>0$ it follows that $\psi$ factors to give a c.g.d.a. homomorphism

$$
\varphi_{\Omega}:\left(\Lambda \bar{X}_{M}, 0\right) \rightarrow(A(\Omega M), d)
$$

such that (2.5) commutes.
Now since $\mathcal{F}$ is a Hurewicz fibration, $M$ is 1 -connected and $H^{*}(M)$ has finite type, a theorem of Grivel [2] or [8, Th. 20.3] asserts that because $\varphi_{M \times M}^{*}$ and $\psi^{*}$ are isomorphisms so is $\varphi_{\Omega}^{*}$. In particular $\varphi_{\Omega}:\left(\Lambda \bar{X}_{M}, 0\right) \rightarrow A(\Omega M)$ is a minimal model for the loop space of $M$.

We now turn our attention to the fibration $\mathcal{F}_{N}$. Recall that $\varphi_{N}:\left(\Lambda X_{N}, d_{N}\right) \rightarrow(A(N), d)$ is a minimal model for the path connected space $N$.

Use (2.1) to obtain from (2.5) the commutative diagram


Using again Sullivan $[15, \S 5]$ or [8, Th. 5.19] we obtain unique (up to homotopy) c.g.d.a. maps
and

$$
\varphi_{0}:\left(\Lambda X_{M}, d_{M}\right) \rightarrow\left(\Lambda X_{N}, d_{N}\right)
$$

$$
\varphi_{1}:\left(\Lambda X_{M}, d_{M}\right) \rightarrow\left(\Lambda X_{N}, d_{N}\right)
$$

such that $\varphi_{N} \circ \varphi_{0} \sim A\left(P_{L} \circ i_{N}\right) \circ \varphi_{M}$ and $\varphi_{N} \circ \varphi_{1} \sim A\left(P_{R} \circ i_{N}\right) \circ \varphi_{M}$. Define a homomorphism of c.g.d.a.'s

$$
\mu_{N}: \wedge X_{M} \otimes \wedge X_{M} \rightarrow \wedge X_{N}
$$

by

$$
\mu_{N}(\Phi \otimes \Psi)=\varphi_{0}(\Phi) \cdot \varphi_{1}(\Psi) .
$$

Then

$$
\varphi_{N} \circ \mu_{N} \sim A\left(i_{N}\right) \circ \varphi_{M \times M}
$$

Therefore we can apply (9.15.4) of [8] to obtain from (2.6) another commutative diagram of c.g.d.a.'s

in which $\varphi_{\Omega}^{\prime} \sim \varphi_{\Omega}$. In particular $\varphi_{\Omega}^{*}$ is an isomorphism.
Finally, write $\Lambda X_{M}^{I}=\Lambda X_{M} \otimes \Lambda X_{M} \otimes \Lambda \bar{X}_{M}$ using the isomorphism $h$ of (2.3). The ideal ker $\mu_{N} \otimes \Lambda \bar{X}_{M}$ is $D$-stable, and so a c.g.d.a.

$$
\left(\Lambda X_{N} \otimes \wedge \bar{X}_{M}, D_{N}\right)
$$

is defined by

$$
D_{N}(\Phi \otimes \mathbf{1})=d_{N} \Phi \otimes \mathbf{1} \quad \text { and } \quad D_{N} \circ\left(\mu_{N} \otimes \mathbf{i d}\right)=\left(\mu_{N} \otimes \mathrm{id}\right) \circ D .
$$

Clearly $\psi_{N}$ factors through $\left(\Lambda X_{N} \otimes \Lambda \bar{X}_{M}, D_{N}\right)$ to produce the commutative diagram of c.g.d.a.'s


Because $\varphi_{N}^{*}$ and $\varphi_{\Omega}^{\prime *}$ are isomorphisms the comparison theorem, applied to the spectral
sequence of Grivel [2] or [8, Th. 20.5] for the fibration $\mathcal{F}_{N}$, shows that $\psi_{N}^{* *}$ is an isomorphism. Thus we have established

Theorem 2.8. A model for the space $M_{N}^{I}$ is given by

$$
\psi_{N}^{\prime}:\left(\Lambda X_{N} \otimes \wedge \bar{X}_{M}, D_{N}\right) \rightarrow\left(A\left(M_{N}^{I}\right), d\right)
$$

In particular (cf. Sullivan [15] or [8, Cor. 2.4]) the minimal model of $M_{N}^{I}$ is generated by $H\left(X_{N} \oplus \bar{X}_{M}, Q\left(D_{N}\right)\right)$, i.e.

$$
\pi_{\psi}^{*}\left(M_{N}^{I}\right)=H\left(X_{N} \oplus \bar{X}_{M}, Q\left(D_{N}\right)\right)
$$

Next recall that $\Lambda X_{N}$ is minimal and (cf. sec. 1) project the top row of (2.7) to the short exact sequence

$$
0 \rightarrow\left(X_{N}, 0\right) \rightarrow\left(X_{N} \oplus \bar{X}_{M}, Q\left(D_{N}\right)\right) \rightarrow\left(\bar{X}_{M}, 0\right) \rightarrow 0
$$

This leads to a long exact sequence

$$
\begin{equation*}
\ldots \xrightarrow{\partial^{*}} X_{N}^{p} \longrightarrow H^{p}\left(X_{N} \oplus \bar{X}_{M}, Q\left(D_{N}\right)\right) \longrightarrow \bar{X}_{N}^{p} \xrightarrow{\partial^{*}} X_{N}^{p+1} \longrightarrow \ldots \tag{2.9}
\end{equation*}
$$

in which clearly $\partial^{*}=Q\left(D_{N}\right)$.
A straightforward calculation using (2.4) shows that

$$
D_{N}(1 \otimes \bar{x})=\left(\varphi_{1}-\varphi_{0}\right) x-\left(\mu_{N} \otimes \mathrm{id}\right) \Omega(x), \quad x \in X_{M}
$$

Since $\Omega(x)$ is decomposable we conclude

$$
\partial^{*} \bar{x}=\left(Q\left(\varphi_{1}\right)-Q\left(\varphi_{0}\right)\right) x
$$

If $\partial_{M}^{*}: \bar{X}_{M} \rightarrow X_{M}$ is the canonical isomorphism we can write this as

$$
\begin{equation*}
\partial^{*}=\left[Q\left(\varphi_{1}\right)-Q\left(\varphi_{0}\right)\right] \circ \partial_{M}^{*} \tag{2.10}
\end{equation*}
$$

Now the sequence (2.9) allows us to identify $H\left(X_{N} \oplus \bar{X}_{M}, Q\left(D_{N}\right)\right)$ with coker $\partial^{*} \oplus \overline{\mathrm{ker} \partial^{*}}$, and so Theorem 2.8 has the following

Corollary 2.11. The space of generators for the minimal model of $M_{N}^{I}$ is given by

$$
\pi_{\psi}^{*}\left(M_{N}^{I}\right)=H\left(X_{N} \oplus \bar{X}_{M}, Q\left(D_{N}\right)\right)=\operatorname{coker}\left(Q\left(\varphi_{1}\right)-Q\left(\varphi_{0}\right)\right) \oplus \overline{\operatorname{ker}\left(Q\left(\varphi_{1}\right)-Q\left(\varphi_{0}\right)\right)}
$$

Next recall that we identify $X_{N}=\pi_{p}^{*}(N)$ etc. Since $\varphi_{0}$ and $\varphi_{1}$ correspond respectively to $p_{0}=P_{L} \circ i_{N}: N \rightarrow M$ and $p_{1}=P_{R} \circ i_{N}: N \rightarrow M$ we have $Q\left(\varphi_{i}\right)=p_{i}^{*}$, and (2.9) can be written in the form (cf. [10, sec. 4])

$$
\begin{equation*}
\ldots \longrightarrow \pi_{\psi}^{p}(N) \xrightarrow{\pi_{N}^{*}} \pi_{\psi}^{p}\left(M_{N}^{I}\right) \xrightarrow{j_{N}^{*}} \pi_{\psi}^{p}(\Omega M) \xrightarrow{\left(p_{1}^{*}-p_{0}^{*}\right) \partial_{M}^{*}} \pi_{\psi}^{p+1}(N) \longrightarrow \ldots \tag{2.12}
\end{equation*}
$$

Observe that (2.10) is analogous to a result of Grove [6] and that (2.12) is the $\psi$-analogue of a sequence in [6, Theorem 1.3]. However, unless $N$ is assumed nilpotent (2.12) cannot be obtained from [6] by dualizing; it may be a different sequence entirely!

Now let $V=N \cap \Delta(M)$ and let $\sigma: V \rightarrow M_{N}^{I}$ be the inclusion defined by

$$
\sigma(x, x): I \rightarrow x, \quad(x, x) \in N \cap \Delta(M)
$$

Because of applications to geodesics we consider the following conditions:

$$
\begin{equation*}
\sigma \text { is a homotopy equivalence } \tag{2.13}
\end{equation*}
$$

$$
\begin{equation*}
H^{p}(V)=0, \quad p>r \tag{2.14}
\end{equation*}
$$

Note that (2.13) implies that $V$ is path connected, and that $\sigma$ induces an isomorphism $\pi_{\psi}^{*}\left(M_{N}^{I}\right) \rightarrow \pi_{\psi}^{*}(V)$. Moreover if $\gamma: V \rightarrow N$ is the inclusion then $\pi_{N} \circ \sigma=\gamma$, and so we can identify $\pi_{N}^{*}$ with $\gamma^{*}$ 。

Theorem 2.15. Suppose (2.13) and (2.14) hold. Then
(i) $\operatorname{ker}\left(p_{1}^{*}-p_{0}^{*}\right)$ has finite dimension $\leqslant r$, and is spanned by elements of even degree.
(ii) The sequence
$0 \longrightarrow \pi_{\psi}^{\text {odd }}(M) \xrightarrow{p_{1}^{*}-p_{0}^{*}} \pi_{\psi}^{\text {odd }}(N) \xrightarrow{\gamma^{*}} \pi_{\psi}^{\text {odd }}(V)$

$$
\mathcal{\pi}_{\psi}^{\text {even }}(M) \underset{p_{1}^{*}-p_{0}^{*}}{\partial_{M}^{*} \circ j_{N}^{*} \circ\left(\sigma^{*}\right)^{-1}} \pi_{\psi}^{\text {even }}(N) \xrightarrow[\gamma^{*}]{\longrightarrow} \pi_{\psi}^{\text {even }}(V) \longrightarrow 0
$$

is exact.
Proof. (i) follows from Lemma 2.18 below, applied to ( $\wedge X_{N} \otimes \Lambda \bar{X}_{M}, D_{N}$ ). (ii) follows from (i) and the exactness of (2.12).

Corollary 2.16. The following are equivalent when (2.13) and (2.14) hold
(i) $\operatorname{dim} \pi_{\psi}^{*}(N)<\infty$
and
(ii) $\operatorname{dim} \pi_{\varphi}^{*}(V)<\infty$ and $\operatorname{dim} \pi_{\varphi}^{*}(M)<\infty$.

Furthermore, if (i) and (ii) hold then

$$
\chi_{\pi}(N)=\chi_{\pi}(M)+\chi_{\pi}(V)
$$

where $\chi_{\pi}=\operatorname{dim} \pi_{\psi}^{\text {even }}-\operatorname{dim} \pi_{\psi}^{\text {odd }}$ is the homotopy Euler characteristic.

Proof. If (i) holds then $\operatorname{dim} \pi_{\varphi}^{\text {odd }}(M)<\infty$; then $\pi_{\psi}^{2 p-1}(M)=0$, if $2 p-1 \geqslant m$, some $m$. Apply Theorem 5.9 of [10] to the projection $\left.\left(\Lambda X_{M}, d\right) \rightarrow \Lambda\left(\sum_{j>m} X_{M}^{j}\right), 0\right)$ to obtain $X_{M}^{j}=0$, $j>m$. Hence $\operatorname{dim} \pi_{\psi}^{*}(M)<\infty$ and so (i) implies (ii).

Consider in general (cf. top row of (2.7)) a sequence of connected KS complexes of the form

$$
(\Lambda Y, d) \xrightarrow{i}(\Lambda Y \otimes \Lambda X, D) \xrightarrow{\varrho}(\Lambda X, 0)
$$

in which $(\Lambda Y, d)$ is minimal. As above we obtain a long exact sequence

$$
\begin{equation*}
\ldots \longrightarrow Y^{p} \xrightarrow{Q(i)^{*}} H^{p}(Y \oplus X, Q(D)) \xrightarrow{Q(\varrho)^{*}} X^{p} \xrightarrow{\partial^{*}} Y^{p+1} \longrightarrow \ldots \tag{2.17}
\end{equation*}
$$

Lemma 2.18. If $H^{i}(\Lambda Y \otimes \Lambda X, D)=0$ for $i>r$ then every homogeneous element in ker $\partial^{*}$ has odd degree and $\operatorname{dim}$ ker $\partial^{*} \leqslant r$.

Proof. Choose a graded subspace $X_{1} \subset X$ so that

$$
X=X_{1} \oplus \operatorname{ker} \partial^{*}
$$

This decomposition defines a linear projection $X \rightarrow$ ker $\partial^{*}$ which extends to a homorphism

$$
\varrho_{1}: \Lambda X \rightarrow \Lambda \operatorname{ker} \partial^{*}
$$

Composing with $\varrho$ we obtain

$$
\varrho_{2}=\varrho_{1} \circ \varrho:(\wedge Y \otimes \wedge X, D) \rightarrow\left(\Lambda \operatorname{ker} \partial^{*}, 0\right)
$$

Moreover, by exactness $\operatorname{ker} \partial^{*}=\operatorname{im} Q(\varrho)^{*}$ and since $Q\left(\varrho_{1}\right)$ is the identity in ker $\partial^{*}$ we obtain that $Q\left(\varrho_{2}\right)^{*}$ is surjective. Thus Theorem 5.9 of [10] applies and shows that the product of any $r+1$ elements of positive degree in $H\left(\Lambda \operatorname{ker} \partial^{*}\right)$ is zero. Since $H\left(\Lambda \operatorname{ker} \partial^{*}\right)=\Lambda$ ker $\partial^{*}$ this implies the lemma.

We close this section with two examples in which $N=V_{0} \times V_{1}$ and $V_{i} \subset M, i=0,1$. Note by the way that it would be no real restriction to consider only the case $N=V_{0} \times V_{1}$ since in fact $M_{N}^{I}=M \times M_{N \times \Delta(M)}^{I}$.

If $N=V_{0} \times V_{1}$ and $i_{j}: V_{j} \rightarrow M, j=0,1$ are the inclusions then $p_{1}^{* *}-p_{0}^{*}: \pi_{\psi}^{*}(M) \rightarrow \pi_{\psi}^{*}(N)$ can be written as

$$
\begin{equation*}
i_{1}^{*}-i_{0}^{*}: \pi_{\psi}^{*}(M) \rightarrow \pi_{\psi}^{*}\left(V_{0}\right) \oplus \pi_{\psi}^{*}\left(V_{1}\right) \tag{2.19}
\end{equation*}
$$

and if (2.13) and (2.14) hold this can be substituted in the sequence of Theorem 2.15 (ii).
Example 2.20. Suppose $V_{0}$ and $V_{1}$ are even spheres of dimensions $2 l$ and $2 m$, and $V=V_{0} \cap V_{1}$ is properly contained in each. Assume (2.13) and (2.14) hold and $\operatorname{dim} H^{*}(M)<\infty$. Then

$$
H^{*}(V)=H^{*}(p t)
$$

and

$$
\begin{equation*}
\sum_{p} \operatorname{dim} H^{p}(M) t^{p}=\left(1+t^{2 l}\right)\left(1+t^{2 m}\right) \tag{2.21}
\end{equation*}
$$

Indeed, since $V$ is contractible in each of $V_{0}$ and $V_{1}, \gamma^{*}=0$. From (ii) of Theorem 2.15 we then deduce that

$$
i_{1}^{*}-i_{0}^{\nRightarrow}: \pi_{\psi}^{\text {odd }}(M) \rightarrow \pi_{\psi}^{\text {odd }}\left(V_{0} \times V_{1}\right)
$$

is an isomorphism and

$$
i_{1}^{\neq}-i_{0}^{*}: \pi_{\psi}^{\text {even }}(M) \rightarrow \pi_{\psi}^{\text {even }}\left(V_{0} \times V_{1}\right)
$$

is surjective. Since $\operatorname{dim} \pi_{\psi}^{\text {odd }}\left(V_{0} \times V_{1}\right)=\operatorname{dim} \pi_{\varphi}^{\text {even }}\left(V_{0} \times V_{1}\right)=2$ on the one hand, and since by Theorem 1' of [9]

$$
\operatorname{dim} \pi_{\psi}^{\text {odd }}(M) \geqslant \operatorname{dim} \pi_{\psi}^{\text {even }}(M)
$$

on the other, we must have equality above and hence

$$
i_{1}^{*}-i_{0}^{*}: \pi_{\psi}^{*}(M) \rightarrow \pi_{\varphi}^{*}\left(V_{0} \times V_{1}\right)
$$

is an isomorphism. Again by Theorem 2.15 (ii), this implies $\pi_{\psi}^{*}(V)=0$ and so $H^{*}(V)=H^{*}(p t)$. It also allows us to apply Corollary 2 to Theorem 5 of [9] which gives (2.21).

Example 2.22. Let $M, V_{0}$ and $V_{1}$ all be spheres and suppose $V_{0} \cap V_{1}$ is properly contained in each $V_{i}, i=0,1$. Then (2.13) and (2.14) cannot hold. Otherwise as in the above example

$$
i_{1}^{*}-i_{0}^{*}: \pi_{\psi}^{\text {odd }}(M) \rightarrow \pi_{\psi}^{\text {odd }}\left(V_{0} \times V_{1}\right)
$$

would be an isomorphism, but $\operatorname{dim} \pi_{\psi}^{\text {odd }}(M)=1$ and $\operatorname{dim} \pi_{\psi}^{\text {odd }}\left(V_{0} \times V_{1}\right)=2$.

## 3. The minimal model for the space of $\boldsymbol{g}$-invariant curves

Let $M$ continue to denote a l-connected space whose rational cohomology has finite type, and fix a continuous map $g: M \rightarrow M$. We shall apply the results of section 2 to the case $N$ is the graph of $g$ :

$$
N=G(g)=\{(x, g(x)) \mid x \in M\} .
$$

When $g$ satisfies a condition we call rigidity at 1 (this is always true if $g^{t}=i d$, some $k$ ) then we give an explicit form of the minimal model of $M_{G(g)}^{I}$.

Since $M_{G(g)}^{I}$ consists of paths $f: I \rightarrow M$ such that $f(1)=g(f(0))$ we can identify it with the space of paths

$$
f: \mathbf{R} \rightarrow M \quad \text { satisfying } f(t+1)=g(f(t))
$$

i.e. the space of $g$-invariant curves. Similarly if $g^{k}=$ id we can identify $M_{G(g)}^{I}$ with the space of continuous maps

$$
f: S^{1} \rightarrow M \quad \text { such that } f\left(e^{2 \pi I / k} e^{i \theta}\right)=g\left(f\left(e^{i \theta}\right)\right)
$$

i.e. $M_{G(g)}^{I}$ is then the space of $g$-invariant circles on $M$.

For the moment let $g: M \rightarrow M$ be any continuous map. We translate from section 2 with $N=G(g)$. Note that $p_{0}: G(g) \rightarrow M$ is a homeomorphism, and so $\varphi_{0}$ (which represents it) is an isomorphism. Moreover if

$$
\psi_{g}:\left(\Lambda X_{M}, d_{M}\right) \rightarrow\left(\Lambda X_{M}, d_{M}\right)
$$

represents $g\left(\varphi_{M} \circ \psi_{g} \sim A(g) \circ \varphi_{M}\right)$ then $p_{1}$ is represented by $\varphi_{1}=\varphi_{0} \circ \psi_{g}$.
Next recall (Theorem 2.8) the model $\left(\Lambda X_{G(g)} \otimes \Lambda \bar{X}_{M}, D_{G(g)}\right)$ for $M_{G(g)}^{I}$. Define a c.g.d.a. $\left(\Lambda X_{M} \otimes \Lambda \bar{X}_{M}, D_{g}\right)$ by requiring that

$$
\varphi_{0} \otimes \mathrm{id}:\left(\Lambda X_{M} \otimes \wedge \bar{X}_{M}, D_{g}\right) \rightarrow\left(\Lambda X_{G(g)} \otimes \wedge \bar{X}_{M}, D_{G(g)}\right)
$$

be an isomorphism. Set $\varphi_{g}^{\prime}=\boldsymbol{\psi}_{G(g)}^{\prime} \circ\left(\varphi_{0} \otimes \mathrm{id}\right)$, then Theorem 2.8 reads:
Corollary 3.1. A model for $M_{G(g)}^{I}$ is given by

$$
\varphi_{g}^{\prime}:\left(\Lambda X_{M} \otimes \Lambda \bar{X}_{M}, D_{g}\right) \rightarrow\left(A\left(M_{G(g)}^{I}\right), d\right)
$$

where $D_{g}$ is determined by

$$
D_{g} \circ\left(\mu_{g} \otimes \mathrm{id}\right)=\left(\mu_{g} \otimes \mathrm{id}\right) \circ D
$$

and $\mu_{g}: \wedge X_{M} \otimes \Lambda X_{M} \rightarrow \Lambda X_{M}$ is given by

$$
\mu_{g}(\Phi \otimes \Psi)=\Phi \cdot \psi_{g}\left(\Psi^{\prime}\right)
$$

For the induced differential $Q\left(D_{g}\right)$ we have

$$
\begin{gather*}
Q\left(D_{g}\right) X_{M}=0 \quad \text { and via }(2.10) \\
Q\left(D_{g}\right) \bar{x}=\left(Q\left(\psi_{g}\right)-i d\right) x, \quad \bar{x} \in \bar{X}_{M} \tag{3.2}
\end{gather*}
$$

which translates Lemma 1.5 of [6].
Remark 3.3. In view of our hypotheses on $M$ there is a canonical isomorphism as mentioned at the end of section 1 ,

$$
Q\left(\Lambda X_{M}\right) \xrightarrow{\cong} \operatorname{Hom}_{\mathbf{Z}}\left(\pi_{*}(M) ; \mathbf{Q}\right) .
$$

Because $M$ is simply connected $g$ induces a well defined homomorphism of homotopy groups

$$
g_{*}: \pi_{*}(M) \rightarrow \pi_{*}(M)
$$

even though $g$ may not preserve base points. Moreover if

$$
g^{*}: \operatorname{Hom}\left(\pi_{*}(M) ; \mathbf{Q}\right) \rightarrow \operatorname{Hom}\left(\pi_{*}(M) ; \mathbf{Q}\right)
$$

is the dual of $g_{*}$, then the isomorphism above identifies $Q\left(\psi_{g}\right)$ with $g^{*}$. In particular the generators for the minimal model of $M_{G(g)}^{I}$ are determined by $g_{\neq}$.

Now let $\left(\Lambda X_{M}\right)_{0}$ be the subalgebra of $\Lambda X_{M}$ of elements $\Phi$ satisfying

$$
\psi_{s} \Phi=\Phi
$$

and let $Q\left(\Lambda X_{M}\right)_{0}$ be the subspace of elements $a \in Q\left(\Lambda X_{M}\right)$ satisfying

$$
Q\left(\psi_{g}\right) a=a
$$

Definition 3.4. A map $g: M \rightarrow M$ will be called rigid at 1 if

$$
\begin{equation*}
Q\left(\Lambda X_{M}\right)=Q\left(\Lambda X_{M}\right)_{0} \oplus \operatorname{im}\left(Q\left(\psi_{g}\right)-\mathrm{id}\right) \tag{3.5}
\end{equation*}
$$

and if for a suitable choice of $\psi_{g}$ the projection

$$
\begin{equation*}
\zeta:\left(\Lambda+X_{M}\right)_{0} \rightarrow Q\left(\Lambda X_{M}\right)_{0} \tag{3.6}
\end{equation*}
$$

is surjective.
Remark 3.7. Since $Q\left(\Lambda X_{M}\right) \cong X_{M}$ is a graded space of finite type, condition (3.5) simply says that if $\left(Q\left(\psi_{g}\right)-\mathrm{id}\right)^{n} a=0$ then $Q\left(\psi_{g}\right) a=a$. Equivalently, $Q\left(\psi_{g}\right)$-id restricts to an isomorphism of the subspace im $\left(Q\left(\psi_{g}\right)-\mathrm{id}\right)$.

Condition (3.6) says that any $Q\left(\psi_{g}\right)$-invariant vector can be represented by a $\psi_{g}$ invariant element in $\Lambda X_{M}$.

Thus while (3.5) can be interpreted as a condition on $g_{\#},(3.6)$ is more subtle. Note that if $\psi_{g}$ and $X_{M}$ can be chosen so that $X_{M}$ is stable under $\psi_{g}$ then (3.6) is automatic.

Example 3.8. Suppose $g: M \rightarrow M$ is a continuous map such that $g^{k}=$ id for some $k \in \mathbf{Z}$. Thus $g$ makes $M$ into a $G$-space, where $G=\mathbf{Z}_{k}$. In this case by Theorem 1.3 we can choose $\psi_{g}$ so that $\psi_{g}^{k}=$ id, which allows us to choose $X_{M}$ to be stable under $\psi_{g}$. (In fact the constructions in the proof of 1.3 already make $\psi_{g}$ act on $X_{M}$ with order $k$.) According to the remark above $g$ is rigid at 1 .

Using another approach we have more generally

## Theorem 3.9. Let $M$ be 1-connected and suppose $g$ : $M \rightarrow M$ satisfies

$$
g^{k} \sim \mathrm{jd}
$$

Then $g$ is rigid at 1 .

Proof. Let $\varphi_{M}: \Lambda X \rightarrow A(M)$ be the minimal model and choose $\psi_{1}: \Lambda X \rightarrow \Lambda X$ so that

$$
\varphi_{M} \psi_{1} \sim A(g) \varphi_{M}
$$

Then $\psi_{1}^{k} \sim$ id.
By a result of Sullivan [15; Prop. 6.5] or [8, Th. 11.21], this implies

$$
\psi_{1}^{k}=e^{\theta}=\sum_{0}^{\infty} \frac{\theta^{m}}{m!}
$$

where $\theta=s d+d s$ and $s$ is a derivation of degree -1 in $\Lambda X$. Moreover

$$
\theta=\ln \left(\psi_{1}^{k}\right)=\sum_{n \geqslant 1}(-1)^{n-1} \frac{\left(\psi_{1}^{k}-\mathrm{id}\right)^{n}}{n}
$$

In particular

$$
\theta \psi_{1}=\psi_{1} \theta
$$

Set $\theta_{1}=-\theta / k=-\left(\frac{s}{k} d+d \frac{s}{k}\right)$; then $e^{\theta_{1}} \sim$ id (cf. Sullivan [15, Prop. A.3]) or [8,
Th. 11.21]. Also $\theta_{1} \psi_{1}=\psi_{1} \theta_{1}$, whence

$$
e^{\theta_{1}} \psi_{1}=\psi_{1} e^{\theta_{1}}
$$

Hence

$$
\left(e^{\theta_{1}} \psi_{1}\right)^{k}=e^{k \theta_{3}} \psi_{1}^{k}=e^{-\theta} \psi_{1}^{k}=\mathrm{id}
$$

and

$$
e^{\theta_{1}} \psi_{1} \sim \psi_{1} .
$$

Put $\psi=e^{\theta_{1}} \psi_{1}$. Then

$$
\psi \sim \psi_{1} \Rightarrow \varphi_{M} \psi \sim A(g) \varphi_{M}
$$

and so $\psi$ represents $g$. On the other hand

$$
\psi^{k}=\mathrm{id} \quad \text { in } \Lambda X
$$

and so by the argument above $\psi$ is rigid at $l$.
Remark 3.10. Without proof we mention that there are many more 1 -rigid maps e.g. retractions and more generally maps $g$ satisfying $g^{k+s}=g^{k}$ for some $k$ and $s$.

Henceforth we assume $g$ to be rigid at 1 and determine the minimal model of $M_{G(g)}^{I}$.
It is immediate from definition 3.4 that we can choose $X_{M}$ and $\psi_{g}$ so that $X_{M}=Y \oplus U$, where

$$
\psi_{g} y=y, \quad y \in Y
$$

and

$$
U \subset \mathrm{im}\left(\psi_{g}-\mathrm{id}\right)
$$

Lemma 3.11. With the choices above
(i) $\operatorname{im}\left(\psi_{g}-\mathrm{id}\right) \subset \Lambda Y \otimes \Lambda+U$, and
(ii) $\Lambda Y \otimes \Lambda+U$ is $d_{M}$-stable.

Proof. (i): Choose a graded subspace $V \subset \Lambda^{+} X_{M}$ so that $\zeta(V) \subset U$ and $\left(\psi_{g}-\mathrm{id}\right): V \rightarrow U$ is an isomorphism. If we regard $U$ as a subspace of $Q\left(\Lambda X_{M}\right)$, then clearly

$$
\left(\psi_{g}-\mathrm{id}\right)=\left(Q\left(\psi_{o}\right)-\mathrm{id}\right) \circ \zeta: V \rightarrow U
$$

Since $\psi_{g}-\mathrm{id}: V \rightarrow U$ is an isomorphism it follows that $\zeta: V \rightarrow U$ is an isomorphism. Therefore

$$
\Lambda+X_{M}=\Lambda+X_{M} \cdot \Lambda+X_{M} \oplus Y \oplus V
$$

and so

$$
\left(\psi_{g}-\mathrm{id}\right) \Lambda+X_{M}=\left(\psi_{g}-\mathrm{id}\right)\left(\Lambda+X_{M} \cdot \Lambda+X_{M}\right)+U \subset\left[\left(\psi_{g}-\mathrm{id}\right) \Lambda^{+} X_{M}\right] \cdot \Lambda+X_{M}+\Lambda Y \otimes \Lambda+U
$$

An easy degree argument completes the proof.
(ii): Since $\Lambda Y \otimes \Lambda+U$ is the ideal generated by $U$, (ii) follows from the relation

$$
d_{M} U \subset d_{M} \operatorname{im}\left(\psi_{g}-\mathrm{id}\right) \subset \operatorname{im}\left(\psi_{g}-\mathrm{id}\right) \subset \Lambda Y \otimes \Lambda+U
$$

Since the ideal $\Lambda Y \otimes \Lambda^{+} U$ is $d_{M^{-}}$-stable we may divide out by it to obtain a c.g.d.a. $(\Lambda Y, \delta)$ such that the projection

$$
\begin{equation*}
P: \wedge X_{M} \rightarrow \wedge Y \tag{3.12}
\end{equation*}
$$

is a homomorphism of c.g.d.a.'s.
We now associate to ( $\Lambda Y, \delta$ ) the corresponding c.g.d.a. $\left(\Lambda Y^{I}, D\right)(p .280)$, with $\Lambda Y^{I}=$ $\Lambda Y \otimes \Lambda \bar{Y} \otimes \Lambda D \bar{Y}$, and derivations $i$ and $\theta$ in $\Lambda Y^{I}$, and c.g.d.a. maps $\lambda_{0}, \lambda_{1}: \Lambda Y \rightarrow \Lambda Y^{I}$. Moreover $\lambda_{0}$ and $\lambda_{1}$ determine an isomorphism

$$
\lambda_{0} \otimes \lambda_{1} \otimes \mathrm{id}: \Lambda Y \otimes \Lambda Y \otimes \Lambda \bar{Y} \rightarrow \Lambda Y^{1}
$$

(compare (2.3)). Thus a homomorphism of graded algebras

$$
\mu \otimes \operatorname{id}: \Lambda Y^{\prime} \rightarrow \Lambda Y \otimes \Lambda \bar{Y}
$$

is defined by

$$
(\mu \otimes \mathrm{id}) \lambda_{0} \Phi=(\mu \otimes \mathrm{id}) \lambda_{1} \Phi=\Phi \quad \text { and }(\mu \otimes \mathrm{id}) \bar{y}=\bar{y}
$$

for all $\Phi \in \Lambda Y$ and $\bar{y} \in \bar{Y}$. As in section 2 a differential $\bar{D}$ in $\Lambda Y \otimes \Lambda \bar{Y}$ is defined by requiring $\mu \otimes i d$ to be a map of c.g.d.a.'s.

In order to identify $\bar{D}$, we define a degree -1 derivation $i_{Y}$ in $\Lambda Y \otimes \Lambda \bar{Y}$ by

$$
i_{Y} y=\bar{y} \quad \text { and } \quad i_{Y} \bar{y}=0
$$

and a degree +1 derivation $d_{g}$ in $\Lambda Y \otimes \Lambda \bar{Y}$ by

$$
d_{g} y=\delta y \quad \text { and } \quad d_{g} \bar{y}=-i_{Y} \delta y, \quad y \in Y
$$

Since obviously $i_{Y}^{2}=0$ we get

$$
\begin{equation*}
d_{g} \circ i_{Y}+i_{Y} \circ d_{g}=0 \tag{3.13}
\end{equation*}
$$

and therefore $d_{g}^{2}=0$; i.e. $\left(\Lambda Y \otimes \Lambda \bar{Y}, d_{g}\right)$ is a c.g.d.a.
Remark. $\left(\Lambda Y \otimes \Lambda \bar{Y}, d_{g}\right)$ is obviously a minimal KS complex. If $Y$ is the minimal model for a space $S$, then $\left(\Lambda Y \otimes \Lambda \bar{Y}, d_{g}\right)$ is Sullivan's model for the space of maps $S^{1} \rightarrow S([14],[16])$.

Lemma 3.14. The differentials $\bar{D}$ and $d_{g}$ agree, i.e.

$$
\mu \otimes \mathrm{id}:\left(\Lambda Y^{I}, D\right) \rightarrow\left(\Lambda Y \otimes \Lambda \bar{Y}, d_{g}\right)
$$

is a homomorphism of c.g.d.a.'s.
Proof. Note that $\bar{D}=\delta$ in $\Lambda Y$. Hence we need only show

$$
\bar{D} \bar{y}=-i_{Y} \delta y, \quad y \in Y .
$$

which we do by induction on the degree of $y$.
First recall that the derivation $i$ in $\Lambda Y^{I}$ (p.281) satisfies $i^{2}=0$, whence by (2.4) $i\left(\lambda_{1} y\right)=i\left(\lambda_{0} y\right)=\bar{y}$ for all $y \in Y$. If follows that

$$
(\mu \otimes \mathrm{id}) \circ i=i_{Y} \circ(\mu \otimes \mathrm{id})
$$

and using (2.4) we conclude

$$
\begin{aligned}
\bar{D} \bar{y} & =-\sum_{n=1}^{\infty} \frac{\left(i_{Y} \bar{D}\right)^{n}}{n!} y=-\sum_{n=0}^{\infty} \frac{\left(i_{Y} \bar{D}\right)^{n}}{(n+1)!} i_{Y} \delta y \\
& =-i_{Y} \delta y-\sum_{n=1}^{\infty} \frac{\left(i_{Y} \bar{D}\right)^{n}}{(n+1)!} i_{Y} \delta y
\end{aligned}
$$

If $\operatorname{deg} y=p$ then $\delta y$ is a polynomial in the $y_{j}$ 's with $\operatorname{deg} y_{j}<p((\Lambda Y, \delta)$ is a 1-connected KS-complex) and it follows from (3.13) and our induction hypothesis that

$$
\bar{D} i_{\mathrm{Y}} \delta y=d_{g} i_{\mathrm{Y}} \delta y=i_{\mathrm{Y}} \delta^{2} y=0 .
$$

Hence the equation above reads $\bar{D} \bar{y}=-i_{Y} \delta y$ and we are done.
Now extend the c.g.d.a. map $P$ of (3.12) to a c.g.d.a. map $P^{I}:\left(\Lambda X_{M}^{I}, D\right) \rightarrow\left(\Lambda Y^{l}, D\right)$ by setting

$$
P^{I} \bar{x}=\widehat{P x} \quad \text { and } \quad P^{I} D \bar{x}=D \overline{P x}, \quad x \in Y
$$

and

$$
P^{I} \bar{x}=P^{I} D \bar{x}=0, \quad x \in U
$$

Then $P^{I}$ commutes with $i$ and $\theta$ so that

$$
\begin{equation*}
P^{I} \circ \lambda_{0}=\lambda_{0} \circ P \quad \text { and } \quad P^{I} \circ \lambda_{1}=\lambda_{1} \circ P \tag{3.15}
\end{equation*}
$$

Also, extend $P$ to an algebra homomorphism

$$
P_{g}: \wedge X_{M} \otimes \Lambda \bar{X}_{M} \rightarrow \Lambda Y \otimes \wedge \bar{Y}
$$

by setting $P_{g} \bar{x}=\overline{P x}$ for all $x \in X_{M}$ (i.e. $P_{g} \bar{x}=0, x \in U$ ).
For these extensions we have
Lemma 3.16. The diagram

commutes. In particular $P_{g} \circ D_{g}=d_{g} \circ P_{g}$, i.e. $P_{g}$ is a homomorphism of c.g.d.a.'s.
Proof. If $x \in X_{M}$ then $(\mu \otimes \mathrm{id}) \circ P^{I} \bar{x}=P_{g} \circ\left(\mu_{g} \otimes \mathrm{id}\right) \bar{x}$ is immediate from the definitions. Moreover by (3.15)

$$
(\mu \otimes \mathrm{id}) \circ P^{I} \lambda_{0} x=(\mu \otimes \mathrm{id}) \circ \lambda_{0} \circ P x=P x=P_{g} \circ\left(\mu_{g} \otimes \mathrm{id}\right) \lambda_{0} x .
$$

Finally recall that $\operatorname{im}\left(\psi_{q}-\mathrm{id}\right) \subset \Lambda Y \otimes \Lambda+U$ by Lemma 3.11. It follows that
and hence by (3.15)

$$
(\mu \otimes \mathrm{id}) \circ P^{I} \circ \lambda_{1} x=(\mu \otimes \mathrm{id}) \circ \lambda_{1} \circ P x=P x=P \circ \psi_{g} x=P_{g} \circ \psi_{g} x=P_{g} \circ\left(\mu_{g} \otimes \mathrm{id}\right) \circ \lambda_{1} x
$$

i.e. the diagram commutes. Since $\mu_{g} \otimes i d, P^{I}$ and $\mu \otimes i d$ are all morphisms of c.g.d.a.'s and $\mu_{g} \otimes$ id is surjective, it follows that $P_{g}$ is also a c.g.d.a. homomorphism.

Theorem 3.17. The homomorphism $P_{g}$ induces an isomorphism

$$
H\left(\Lambda X_{M} \otimes \wedge \bar{X}_{M}, D_{g}\right) \rightarrow H\left(\Lambda Y \otimes \wedge \bar{Y}, d_{g}\right)
$$

of cohomology. In particular $\left(\Lambda Y \otimes \Lambda \bar{Y}, d_{g}\right)$ is the minimal model of $M_{G(g)}^{\prime}$.
Proof. According to Theorem 7.1 in [8] we need only check that

$$
Q\left(P_{\jmath}\right)^{*}: H\left(X_{M} \oplus \bar{X}_{M}, Q\left(D_{g}\right)\right) \rightarrow Y \oplus \bar{Y}
$$

is an isomorphism. But it follows from 3.2 that $Q\left(D_{g}\right)$ is zero on $X_{M}$ and on $\bar{Y}$ and restricts to an isomorphism $\bar{U} \rightarrow U$. Hence $Q\left(P_{g}\right)^{*}$ identifies $H\left(X_{M} \oplus \bar{X}_{M}, Q\left(D_{g}\right)\right)$ with $Y \oplus \bar{Y}$.

Finally, consider the commutative diagram


Since $P_{g}^{*}$ is an isomorphism Sullivan [15] or Theorem 5.19 of [8] implies there is a homomorphism $\varphi:\left(\Lambda Y \otimes \Lambda \bar{Y}, d_{g}\right) \rightarrow\left(\Lambda X_{M} \otimes \Lambda \bar{X}_{M}, D_{g}\right)$ of c.g.d.a.'s such that $\varphi^{*}$ is the isomorphism inverse to $P_{g}$.

Thus

$$
\varphi_{g}:\left(\Lambda Y \otimes \Lambda \bar{Y}, d_{g}\right) \rightarrow\left(A\left(M_{G(g)}^{I}\right), d\right)
$$

is a minimal model for $A\left(M_{G(g)}^{I}\right)$, where $\varphi_{\theta}=\varphi_{g}^{\prime} \circ \varphi$.
Remark. As mentioned earlier the c.g.d.a. $\left(\Lambda Y \otimes \Lambda \bar{Y}, d_{g}\right)$ is exactly Sullivan's construction applied to ( $\Lambda Y, \delta$ ). Moreover if $g=\mathrm{id}_{M}$ then $\psi_{g}=\mathrm{id}, X_{M}=Y$ and $P_{g}=\mathrm{id}$. Hence we recover Sullivan's theorem [14] (with a different proof) as a special case of Theorem 3.15.

Remark 3.18. The fact that the minimal model of $M_{G(g)}^{I}$ appears to be the minimal model for a space of closed curves can be explained as follows:

Let $A(p)$ be the rational c.g.d.a. $\subset A\left(\Delta^{p}\right)$ generated by the barycentric coordinate functions. In [15, §8] Sullivan constructs the function adjoint to "differential forms" which associates with each c.g.d.a. $\left(R, d_{R}\right)$ the simplicial set $\langle R\rangle$ given by

$$
\left.\langle R\rangle_{p}=\left\{\text { all homomorphisms }\left(R, d_{R}\right) \rightarrow(A(p), d)\right)\right\} .
$$

Now suppose $g$ is rigid at 1 . The homomorphism $\psi_{g}$ yields a map of simplicial sets

$$
\left\langle\psi_{g}\right\rangle:\left\langle\Lambda X_{M}\right\rangle \rightarrow\left\langle\Lambda X_{M}\right\rangle
$$

The fixed point set of $\left\langle\psi_{g}\right\rangle$ is the sub-simplicial set $\left\langle\Lambda X_{M}\right\rangle^{g}$ defined by

$$
\left\langle\Lambda X_{M}\right\rangle_{p}^{g}=\left\{\text { all homomorphisms }\left(\Lambda X_{M}, d_{M}\right) \xrightarrow{\eta}(A(p), d) \quad \text { such that } \eta \circ \psi_{g}=\eta\right\} \text {. }
$$

On the other hand, since $g$ is rigid at 1 we have that the ideal generated by im ( $\psi_{g}-\mathrm{id}$ ) is exactly $\Lambda Y_{\otimes} \Lambda+U$. Hence we obtain $\left\langle\Lambda X_{M}\right\rangle_{p}^{g}=\langle\Lambda Y\rangle_{p}$ i.e.

$$
\left\langle\Lambda X_{M}\right\rangle^{g}=\langle\Lambda Y\rangle
$$

Let $\left|\left\langle\Lambda X_{M}\right\rangle\right|$ and $|\langle\Lambda Y\rangle|$ be the geometric realizations (cf. Milnor [13]). $\left\langle\psi_{g}\right\rangle$ defines a continuous map $\bar{g}$ of $\left|\left\langle\Lambda X_{M}\right\rangle\right|$ and we have that the fixed point set of $\bar{g}$ is given by

$$
\left|\left\langle\Lambda X_{\mu}\right\rangle\right\rangle^{\bar{\sigma}}=|\langle\Lambda Y\rangle| .
$$

Finally note that $\left|\left\langle\Lambda X_{M}\right\rangle\right|$ is the "rationalization of $M$ " and $\bar{g}$ is the rationalization of $g$; thus $\Lambda Y$ is the minimal model of the fixed point set of the rationalization of $g$. Moreover the model of the $g$-invariant paths on $M$ coincides with the model of the space of all closed paths in the fixed point set of the rationalization of $g, \bar{g}$.

Remark 3.19. Note that if $g: M \rightarrow M$ is periodic i.e. $g^{k}=\mathrm{id}_{M}$ then we can prove Theorem 3.17 directly via Sullivan's theorem by studying the inclusion of $M_{G(g)}^{I}$ into the space of all circles on $M$ (cf. the beginning of sec. 3) and using (3.3) and the remarks concluding section 1.

## 4. On the cohomology of $M_{G(\mathrm{~s})}^{( }$

Throughout this section $M$ is a l-connected space whose rational cohomology has finite type and $g: M \rightarrow M$ is a l-rigid map. In particular we have a minimal model for the space $M_{G(g)}^{I}$ of $g$-invariant curves as in Theorem 3.17.

We show how one can use the minimal model for $M_{G(g)}^{I}$ in order to obtain information about the cohomology $H^{*}\left(M_{G(g)}^{I}\right)$. In particular we are interested in the Betti-numbers of $M_{G(g)}^{I}$, because of their significance in applications to geodesics.

As a first application we have the following immediate generalization of a theorem due to Sullivan [14].

Theorem 4.1. If the rational cohomology of $M_{G(g)}^{I}$ is not trivial, then $M_{G(g)}^{I}$ has nonzero Betti numbers in an infinite arithmetic sequence of dimensions.

Proof. First suppose ( $\wedge Y, \delta)((3.12))$ has no odd dimensional generators; i.e. $\Lambda Y$ is a polynomial algebra in even dimensional generators (which exist for otherwise $Y=\bar{Y}=\{0\}$ and consequently $H^{*}\left(M_{G(g)}^{I}\right)$ would be trivial) and $\delta=0$. Then $d_{g}=0$ and the $d_{g}$-closed elements $\left\{x^{\prime}\right\}_{j \in \mathbb{N}}$ in $\Lambda Y \otimes \Lambda \bar{Y}$ provides us with an infinite sequence of non-zero cohomology classes.

Secondly, if $\Lambda Y$ has odd dimensional generators we proceed exactly as in Sullivan [14, p. 46].

We are now interested in finding necessary and sufficient conditions in order for $M_{G(g)}^{I}$ to have an unbounded sequence of Betti numbers. Note that as a consequence of Theorem 4.1 we have

Corollary 4.2. Suppose the rational cohomology of the spaces $\left(M_{i}\right)_{G\left(g_{i}\right)}^{I}, i=1,2$ is nontrivial. Then $\left(M_{1} \times M_{2}\right)_{G\left(\theta_{1} \times g_{2}\right)}^{I}$ has an unbounded sequence Betti numbers.

We return to the general case corresponding to the direct sum decomposition $Y=$ $Y^{\text {odd }} \oplus Y^{\text {even }}$

$$
\chi_{0}=\operatorname{dim} Y^{\mathrm{odd}}
$$

and

$$
\chi_{e}=\operatorname{dim} Y^{\text {even }}
$$

if both $\chi_{0}$ and $\chi_{e}$ are finite

$$
\chi_{\pi}=\chi_{e}-\chi_{0}
$$

is the homotopy Euler characteristic of ( $\Lambda Y, \delta$ ).
Proposition 4.3. The sequence of Betti numbers for $M_{G(g)}^{I}$ is unbounded if and only if one of the following conditions is fulfilled:
(i) $\chi_{0} \geqslant 2$
(ii) $\chi_{0}=0$ and $\chi_{e} \geqslant 2$
(iii) $\chi_{0}=1, \delta Y^{\text {odd }}=\{0\}$ and $\chi_{e} \geqslant 1$
(iv) $\chi_{0}=1, \delta Y^{\text {odd }} \neq\{0\}$ and $\chi_{e} \geqslant 3$
(v) $\chi_{0}=1, \delta Y^{\text {odd }} \neq\{0\}, \chi_{e}=2$ and $\operatorname{dim} \mathbf{Q}\left[x_{1}, x_{2}\right] /\left(\partial P / \partial x_{1}, \partial P / \partial x_{2}\right)=\infty$, where $Y^{\text {even }}=$ $\operatorname{span}\left\{x_{1} ; x_{2}\right\}$ and $\delta y=P\left(x_{1}, x_{2}\right), y \in Y^{\text {odd }}$.

Proof. In [16] it has in particular been proved that $\chi_{0} \geqslant 2$ implies that $H\left(\Lambda Y \otimes \Lambda \bar{Y}, d_{g}\right)$ has an unbounded sequence $\left\{b_{i}\right\}_{i \in \mathbf{N}}$ of Betti numbers.

If $\chi_{0}=0$ then $d_{g}=0$ and $\left\{b_{i}\right\}_{i \in \mathbb{N}}$ is clearly unbounded if and only if $\chi_{e} \geqslant 2$.
Assume in the following that $\chi_{0}=1$. First let $\delta Y^{\text {odd }}=\{0\}$. If $\chi_{e}=0$ then $\Lambda Y=\mathbf{Q}(y, \tilde{y})$ and $d_{g}=0$. Thus $\left\{b_{i}\right\}$ is bounded. Suppose now on the other hand that $\chi_{e} \geqslant 1$. Then clearly the ideal im $d_{g}$ in ker $d_{g}$ is contained in the ideal generated by $y$ and $\bar{y}$, where $y \in Y^{\text {oda }}$. Hence $\operatorname{dim} \operatorname{ker} \delta \cap Y^{\text {even }} \geqslant 2$ implies that $\left\{b_{i}\right\}_{t \in N}$ is unbounded. If there are not two even closed generators of $Y$ we range the generators of $Y^{\text {even }}$ by increasing degrees $x_{1}, x_{2}, \ldots, x_{n}, \ldots$ so that $\delta x_{1}=0, \delta x_{2}=x_{1}^{\alpha} y, \ldots, \delta x_{n}=P_{n}\left(x_{1}, \ldots, x_{n-1}\right) y, \ldots$ and $P_{n}, n \geqslant 3$, belongs to the ideal generated by $x_{2}, \ldots, x_{n-1}$. Then we have
and

$$
\begin{gathered}
d_{g} \bar{x}_{2}=\alpha x_{1}^{\alpha-1} \bar{x}_{1} y+x_{1}^{\alpha} \bar{y} \\
d_{g} \bar{x}_{n}=\sum_{k=1}^{n-1} \frac{\partial P_{n}}{\partial x_{k}} \bar{x}_{k} y+P_{n} \cdot \bar{y}
\end{gathered}
$$

for $n \geqslant 3$. Hence in $\Lambda Y \otimes \Lambda \bar{Y}$, im $d_{g}$ is contained in the ideal

$$
\left(d_{g} x_{2}, d_{g} \bar{x}_{2}, x_{2} \bar{y}, \ldots, x_{n} \bar{y}, \ldots, \bar{x}_{2} y, \ldots, \bar{x}_{n} y, \ldots, x_{2} y, \ldots, x_{n} y, \ldots\right)
$$

so the family of closed elements $\left\{x_{1}^{a} \bar{y}^{b}\right\},(a, b) \in \mathbf{N} \times \mathbf{N}$ are homologically independent, in particular $\left\{b_{i}\right\}_{i \in \mathrm{~N}}$ is unbounded.

In the rest of the proof we assume besides $\chi_{0}=1$ that $\delta Y^{\text {odd }} \neq\{0\}$. Then $\delta Y^{\text {even }}=0$ since $\delta^{2}=0$.

If $\chi_{e}=1$ we have $\Lambda Y=\boldsymbol{Q}(x, y)$ with $\delta x=0$ and $\delta y=x^{h}$. It is then easy to prove that $\left\{b_{i}\right\}_{i \in \mathbf{N}}$ are bounded (see Addendum in [16]). If $\chi_{e}=\infty$ we obviously have $\left\{b_{i}\right\}_{i \in \mathbf{N}}$ unbounded.

We shall now show that $3 \leqslant \chi_{e}<\infty$ implies $\left\{b_{i}\right\}_{i \in \mathrm{~N}}$ unbounded. Let $x_{1}, \ldots, x_{p}, p \geqslant 3$, be a basis for $Y^{\text {even }}$. An element of the polynomial ring $\mathbf{Q}\left[x_{1}, \ldots, x_{p}\right]$ is easily seen to be a boundary in $\left(\Lambda Y \otimes \Lambda \bar{Y}, d_{g}\right)$ if and only if it is in the ideal generated by $d_{g} y, y \in Y^{\text {oda }}$. Now, consider the graded ring $A=\mathbf{Q}\left[x_{1}, \ldots, x_{p}\right] /\left(d_{g} y\right)$ of Krull dimension $q=p-1 \geqslant 2$. By lemme 1 of [12] there are positive integers $N$ and $\alpha$ and a polynomial $P$ with $\operatorname{deg} P=$ $q-1 \geqslant 1$, such that for all $n \geqslant N$ and $n \equiv 0(\bmod \alpha)$ we have $\operatorname{dim} A_{n}=P(n)$, where $A_{n}$ is the subspace of $A$ of elements of degree $n$.

Finally assume $\chi_{e}=2$ and let $x_{1}, x_{2}$ be a basis for $Y^{\text {even }}$. If $y \in Y^{\text {odd }} \delta y=P\left(x_{1}, x_{2}\right)$ and hence im $d_{g}$ is contained in the ideal generated by $\partial P / \partial x_{1}$ and $\partial P / \partial x_{2}$. If $A=\mathbf{Q}\left[x_{1}, x_{2}\right] /$ $\left(\partial P / \partial x_{1}, \partial P / \partial x_{2}\right)$ is not finite dimensional, then $A$ has Krull dimension $\geqslant 1$ and the ring $B=A \otimes \mathbf{Q}(\bar{y})$ has therefore Krull dimension $\geqslant 2$. Again by Lemma 1 of [12] we conclude that $\left\{\operatorname{dim} B_{n}\right\}_{n \in \mathbb{N}}$ is unbounded. But for any non-zero element $\bar{\beta} \in B$ the element $\bar{x}_{1} \bar{x}_{2} \bar{\beta}$ is a cocycle in $\left(\Lambda Y \otimes \Lambda \bar{Y}, d_{g}\right)$ and not a boundary i.e. $\left\{b_{i}\right\}_{i \in \mathrm{~N}}$ is unbounded. If $\operatorname{dim} A<\infty$ a direct but lengthy computation of $H\left(\Lambda Y \otimes \wedge \bar{Y}, d_{g}\right)$ in even and odd degrees shows that $\left\{b_{i}\right\}_{i \in \mathbf{N}}$ is bounded.

From Proposition 1 in [16] and the above proposition we get
Corollary 4.4. The sequence of Betti numbers for $M_{G(g)}^{I}$ is bounded if and only if the cohomology ring $H(\Lambda Y, \delta)$ has one of the following types:
(i) $H(\Lambda Y, \delta)=\mathbf{Q}$
(ii) $H(\Lambda Y, \delta)$ is generated by one element
(iii) $H(\Lambda Y, \delta)$ is a polynomial algebra in two variables $x_{1}, x_{2}$ truncated by an ideal generated by one element $P$ such that $\operatorname{dim} \mathbf{Q}\left[x_{1}, x_{2}\right] /\left(\partial P / \partial x_{1}, \partial P / \partial x_{2}\right)<\infty$.

In Proposition 4.3 and Corollary 4.4 the cohomology of $M$ was only supposed to be of finite type. If we assume $H^{*}(M)$ to be finite dimensional (e.g. $M$ a finite complex) we can apply some recent results of Halperin [9] and [10] to obtain:

Theorem 4.5. Let $M$ be a l-connected space with finite dimensional cohomology $H^{*}(M)$ and let $g: M \rightarrow M$ be a 1-rigid map. Then exactly one of the following holds:
(I) $\chi_{0}=\chi_{e}=0$. In this case $\Lambda Y=\mathbf{Q}$ and $H^{*}\left(M_{G}^{I}(g)\right)=\mathbf{Q}$.
(II) $\chi_{0}=1, \chi_{e}=0$. In this case $\Lambda Y=\Lambda(y)$ and $H^{*}\left(M_{G(g)}^{I}\right)=\Lambda(y, \bar{y})$ is the exterior algebra on $y$ tensor the polynomial algebra on $\bar{y}$.
(III) $\chi_{0}=\chi_{e}=1$. In this case $\Lambda Y=\Lambda(y, x)$ with $\delta x=0, \delta y=x^{n+1}$ and $H^{*}\left(M_{G(O)}^{I}\right)=$ $\Lambda^{+}(x, \bar{x}) /\left(x^{n+1}, x^{n} \bar{x}\right) \otimes \Lambda(\bar{y})$. In particular $\left\{b_{i}\left(M_{G(\theta)}^{I}\right)\right\}$ is bounded.
(IV) $\left\{b_{i}\left(M_{G(g)}^{I}\right)\right\}_{i \in \mathbf{N}}$ is unbounded.

In particular $\left\{b_{i}\right\}$ is bounded if and only if $\chi_{e} \leqslant \chi_{0} \leqslant 1$.

Proof. If $\operatorname{dim} Y=\infty$ we see from Proposition 4.3 that $\left\{b_{i}\right\}_{i \in \mathbb{N}}$ is unbounded.
Suppose now that $\operatorname{dim} Y<\infty$. Since $\operatorname{dim} H^{*}(M)=\operatorname{dim} H\left(\Lambda X_{M}, d_{m}\right)<\infty$ Corollary 5.13 of Halperin [10] implies that $\operatorname{dim} H(\Lambda Y, \delta)<\infty$. We can therefore apply the finiteness results of Halperin [9]. In particular $\chi_{\pi}=\chi_{e}-\chi_{0} \leqslant 0$ by Theorem 1 in [9].

If $\chi_{0} \geqslant 2$ we know from Proposition 4.3 that $\left\{b_{i}\right\}_{i \in \mathbf{N}}$ is unbounded.
If $\chi_{0}=1$ we must have $\chi_{e} \leqslant 1$. Suppose $\chi_{e}=1$. Then $\delta x=0$ and $\delta y=x^{n+1}$ for some $n$ because $H(\Lambda Y, \delta)$ is finite dimensional. The actual computation of $H^{*}\left(M_{G(g)}^{I}\right)$ is then contained in the Addendum of [16].

The case $\chi_{0}=1$ and $\chi_{e}=0$ is clear.
Finally $\chi_{0}=\chi_{e}=0$ if and only if $H^{*}\left(M_{G(g)}^{I}\right)$ is trivial.
Note that if $\operatorname{dim} H^{*}(M)<\infty$ then (iii) in Corollary 4.4 is impossible. If $g=\mathrm{id}_{M}$ then $Y=X_{M}$; i.e. (i) is also impossible and Corollary 4.4 is nothing but the main theorem of Sullivan and Vigué [16].

Theorem 4.5 gives a necessary and sufficient condition on the action of $g$ on $\pi_{*}(M) \otimes \mathbf{Q}$ in order for $H^{*}\left(M_{G(g)}^{I}\right)$ to have an unbounded sequence of Betti numbers. As in the case $g=\mathrm{id}_{M}$ it would be interesting also to have a (necessary and sufficient) condition on the action of $g$ on $H^{*}(M)$ in order for $H^{*}\left(M_{G(g)}^{I}\right)$ to have an unbounded sequence of Betti numbers. We can illustrate the subtlety of this problem with the following examples.

Example 4.6. Let $M=S^{2 p} \times S^{2 q}$ with $p \neq q$ and $p, q \geqslant 1$. Then $\Lambda X_{S^{2 p}}=\Lambda\left(x_{1}, y_{1}\right)$ with $\operatorname{deg} x_{1}=2 p$, deg $y_{1}=4 p-1, d x_{1}=0$ and $d y_{1}=x_{1}^{2}$ and similarly for $\Lambda X_{S^{2 q}}=\Lambda\left(x_{2}, y_{2}\right)$. Thus any 1 -rigid homotopy equivalence $g$ of $M$ will fix at least the generators $y_{i}, i=1,2$ and by Theorem 4.5 $M_{G(g)}^{T}$ will have an unbounded sequence of Betti numbers. However, $g$ may $\operatorname{map} x_{i}$ to $-x_{i}, i=1,2$ and hence not fix any generators in the cohomology $H^{*}(M)$.

Example 4.7. Take $M=\mathbf{C} P^{2 p+1} \times \mathbf{C} P^{2 q+1}$ with $p \neq q$ and $p, q \geqslant 0$. Then $\Lambda X_{C^{p 2 p+1}}=$ $\Lambda\left(x_{1}, y_{1}\right)$ with $\operatorname{deg} x_{1}=2, \operatorname{deg} y_{1}=2(2 p+1)+1, d x_{1}=0$ and $d y_{1}=x_{1}^{2 p+2}$ and similarly for $\Lambda X_{\mathbf{C P}^{2 q+1}}=\Lambda\left(x_{2}, y_{2}\right)$. We can therefore draw exactly the same conclusions as above.

Example 4.8. Endow $S^{2 p}$ and $\mathbf{C} P^{2 q}$ with their standard riemannian metrics and $S^{2 p} \times$ C $P^{2 q}$ with the product metric. Let $q_{1}=-\mathrm{id}_{S^{2 p}}$ be the antipodal map on $S^{2 p}$ and $g_{2}$ the conjugate map on $\mathbf{C} P^{2 q}$ i.e. in homogeneous coordinates $g_{2}\left(z_{1}, \ldots, z_{2 q+1}\right)=\left(\bar{z}_{1}, \ldots, \bar{z}_{2 q+1}\right)$. If $M=T_{1}\left(S^{2 p} \times \mathbf{C} P^{2 q}\right)$ is the unit tangent bundle of $S^{2 p} \times \mathbf{C} P^{2 q}$ then the differential of the involutive isometry $g_{1} \times g_{2}$ restricts to an involution $g$ on $M$.

Note that $M$ is the total space of the fibre bundle $M \rightarrow S^{2 p} \times \mathbf{C} P^{2 q}$ with fiber $S^{2 p+4 q-1}$. Therefore $\Lambda X_{M}=\Lambda X_{S^{2 p}} \otimes \Lambda X_{\mathbf{C P}^{2 q}} \otimes \Lambda X_{S^{2 p+4 q-1}}=\Lambda\left(x_{1}, x_{2}, y_{1}, y_{2}, y_{3}\right)$ with $\operatorname{deg} x_{1}=2 p$, $\operatorname{deg} x_{2}=2, \operatorname{deg} y_{1}=4 p-1, \operatorname{deg} y_{2}=4 q+1, \operatorname{deg} y_{3}=2 p+4 q-1$ and $d x_{1}=d x_{2}=0, d y_{1}=x_{1}^{2}, d y_{2}=$ $x_{2}^{2 q+1}$ and $d y_{3}=(4 q+2) x_{1} x_{2}^{2 q}\left(x_{1} x_{2}^{2 q}=\right.$ orientation class of $S^{2 p} \times \mathbf{C} P^{2 q}$ and Euler class of bundle $=(4 q+2) \cdot$ orientation class). Furthermore $g$ induces an involution on $\Lambda X_{M}$ which is given on generators by $x_{1} \rightarrow-x_{1}, x_{2} \rightarrow-x_{2}$ and hence $y_{1} \rightarrow y_{1}, y_{2} \rightarrow-y_{2}$ and $y_{3} \rightarrow-y_{3}$; i.e. $\chi_{0}=1$ and $\chi_{e}=0$. According to Theorem 4.5 the Betti numbers for $M_{G(g)}^{T}$ are uniformly bounded, in fact $H^{*}\left(M_{G(\theta)}^{I}\right)=\Lambda\left(y_{1}, \bar{y}_{1}\right)$.

On the other hand, let $u_{1}=(4 q+2) x_{2}^{2 q} y_{1}-x_{1} y_{3}$ and $u_{2}=(4 q+2) x_{1} y_{2}-x_{2} y_{3}$. Then a family of generators for $H\left(\Lambda X_{M}, d\right)$ contains $x_{1}, x_{2}, u_{1}$ and $u_{2}$ (or linear combinations of these), and on cohomology $g^{*}\left(u_{i}\right)=u_{i}, i=1,2$ i.e. $g$ fixes two generators of $H^{*}(M)$ but the sequence of Betti numbers for $M_{G(g)}^{I}$ is bounded.

We finally restrict our attention to spaces whose cohomology (over $\mathbf{Q}$ ) is spherically generated.

Definition 4.9. Let $M$ be a 1 -connected space whose cohomology is of finite type. We say that $H^{*}(M)$ is spherically generated if

$$
\operatorname{ker} \zeta^{*}=H^{+}\left(\Lambda X_{M}\right) \cdot H^{+}\left(\Lambda X_{M}\right)
$$

where $\zeta^{*}$ is the induced map on cohomology by the projection $\zeta: \Lambda+X_{M} \rightarrow Q\left(\Lambda X_{M}\right)(p .280)$.
Note that $\zeta^{*}$ is the dual of the Hurewicz map. The above definition is therefore equivalent to saying that $\zeta^{*}$ imbeds the generators of $H^{*}(M)$ into Hom ( $\left.\pi^{*}(M), \mathbf{Q}\right)$.

Corollary 4.10. Let $M$ be a 1-connected space whose cohomology is finite dimensional and spherically generated, and let $g$ be a 1 -rigid map of $M$. Then $M_{G(g)}^{I}$ has an unbounded sequence of Betti numbers if the induced map $g^{*}$ on cohomology $H^{*}(M)$ fixes at least two generators. (1)

Proof. By hypothesis, $H^{*}(M)$ is spherically generated, so $\zeta^{*}$ induces an embedding

$$
H^{+}(M) / H^{+}(M) \cdot H^{+}(M) \rightarrow Q\left(\Lambda X_{M}\right)
$$

${ }^{(1)}$ i.e. the subspace fixed by the linear map induced by $g^{*}$ on $H^{+}(M) / H^{+}(M) \cdot H^{+}(M)$ has dimension $\geqslant 2$.
commuting with the induced actions by $g$. Hence we can choose the generators of $\Lambda X_{M}$ so that we have two closed generators fixed by $\psi_{g}$. They give two closed generators of $\Lambda Y$, and we conclude using Theorem 4.5.

Remark 4.11. According to example 8.13 of [11] any formal space (its minimal model is a formal consequence of its cohomology) has spherically generated cohomology. Thus Corollary 4.10 applies in particular to formal spaces. Among formal spaces are riemannian symmetric spaces [14] and Kähler manifolds [1] (and [11, Cor. 6.9]).

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