# The geometrical analysis of the path of free kick 

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#### Abstract

Free kicks play an important role in a modern soccer match. A skillful soccer player usually uses the opportunity of a free kick to score a goal. There are mainly two ways to give a free kick, falling ball and banana ball. The last thesis analyzes the path of falling soccer in two-dimensional plane. This thesis mainly focuses on using geometrical ways to generate a graph in three-dimensional coordinate system to analyze the path of banana ball and find out the most suitable distance to give a free kick.


Index Terms-soccer, free kick, path, geometry, calculus

## I. NOMENCLATURE

## Parameters

| T | Temperature during the match |
| :--- | :--- |
| $\mathrm{V}_{\text {wind }}$ | Velocity of wind during the match |
| $\mathrm{v}_{\infty}$ | Velocity of the soccer (ground as reference frame) |
| $\omega$ | Rotation speed of the soccer |
| $\mathrm{P}_{\mathrm{up}}$ | Pressure on the upper surface of the soccer |
| $\mathrm{P}_{\text {down }}$ | Pressure on the bottom surface of the soccer |
| t | Time of the soccer contact with foot |
| $\theta_{1}$ | Vertical angle of emergence |
| $\theta_{2}$ | Horizontal angle of emergence |
| F | Force on the soccer |
| c | The circumference of the soccer |
| H | Displacement of the soccer |

All of these parameters are in international unit

## II. Introduction

## A. Research Background

Free kicks play an important role in a modern soccer matches. A skillful soccer player usually uses the opportunity of a free kick to score a goal. There are mainly two ways to give a free kick, falling soccer and banana soccer. Banana soccer is a kind of free kick whose path is a curve. In a soccer
match, player usually applies banana soccer to bypass the wall of players to score a goal.
B. Basic Assumptions

The soccer is a perfect sphere, which the pressure inside is $60.8-11.5 \mathrm{kp}$ (as shown in Fig.1). Ignore both the loss and the addition of the weight of the soccer during the match.


Fig.1. 2012 UEFA European Championship Official Soccer.


Fig.2. Soccer Pitch.


Fig.3. Goal.
Because of the influence of the weather, we make these assumptions:

1. $\mathrm{T}=20^{\circ} \mathrm{C}$
2. Velocity of the wind is constantly $0 \mathrm{~m} / \mathrm{s}$
3. Moisture of the air does not influence the weight of the soccer
4. Characteristics of the soccer are constant
5. The soccer does not touch the ground before entering the goal
6. Shape of the soccer does not change
7. Diameter of the soccer is $\mathrm{d}=0.30 \mathrm{~m}$
8. Weight of the soccer is $\mathrm{M}=0.45 \mathrm{~kg}$

## III. MODEL AND ANALYSIS

## A. Basic Calculation

Assume the player kick the soccer with a force $\mathrm{F}=450 \mathrm{~N}$; analyze this force in a three-dimensional coordinate system as shown in Fig. 4.


Fig.4. Three-dimensional coordinate system.
In this three-dimensional coordinate system, F is in the XOY coordinate plane, the angle $\theta$ between $F$ and $y$-axis is $2^{\circ}$,
the angle between XOY coordinate plane and ground is $30^{\circ}$.

$$
\begin{align*}
& \left|\overrightarrow{F_{y}}\right|=|\vec{F}| \cos \theta \approx 450 N  \tag{1}\\
& \left|\overrightarrow{F_{x}}\right|=|\vec{F}| \sin \theta \approx 16 N  \tag{2}\\
& \overrightarrow{\left|F_{n e t}\right|}=m \frac{|\overrightarrow{\Delta v}|}{\Delta \mathrm{t}},  \tag{3}\\
& \overrightarrow{\left|v_{\infty}\right|}=\frac{\overline{|F| t}}{m}  \tag{4}\\
& \overrightarrow{|G|}=\sum_{m} m r^{2} \omega  \tag{5}\\
& \overrightarrow{|G|}=\int_{0}^{\pi} M_{\text {soccer }}(R \sin \theta)^{2} \omega d \theta  \tag{6}\\
& \overrightarrow{|F|} t=\frac{\pi}{2} M_{\text {soccer }} \omega R^{2} \tag{7}
\end{align*}
$$

Because the net force applied to an object is equal to the rate of change of momentum (3), the formula (3) can be written as (4). So the magnitude of $\mathrm{v}_{\infty}$ is approximately 20. This is the radial velocity of the soccer. Then according to the definition (5) of angular momentum, the angular momentum of the soccer during its movement can be presented by (6), which can be written as (7). So the magnitude of the angular velocity of the soccer during its movement is approximately 20.
B. Air Resistance

$$
\begin{align*}
& R e=\frac{\rho V d}{v}  \tag{8}\\
& \overrightarrow{\left|F_{1}\right|}=\frac{1}{2} \rho \overrightarrow{\left.V_{\infty}\right|^{2}} A C_{d} \tag{9}
\end{align*}
$$

When analyzing the path of banana ball, air resistance is an important factor to consider. Air is one kind of fluids. In fluid dynamics, there are mainly two kinds of air resistances, viscous drag and pressure drag. The number $\operatorname{Re}$ is a dimensionless parameter that determines the behavior and characteristics of viscous flow patterns. It is defined by (8), where $\rho$ is fluid density, $V$ is stream velocity, $d$ is a characteristic length scale (in this case is the diameter of the soccer), and v is fluid viscosity. For values of Re less than 2000, the dye streak remains smooth and undisturbed-that is, laminar flow resulted. The air resistance is mainly viscous drag. For Re greater than 3000, the dye streak seems to burst into turbulence and fill the whole tube with color.

| Temperature $\left({ }^{\circ} \mathrm{C}\right)$ | $\mathbf{v}^{*} \mathbf{1 0}^{\mathbf{5}}\left(\mathbf{m}^{\mathbf{2}} / \mathbf{s}\right)$ |
| :---: | :---: |
| 0 | 13.20 |
| $\mathbf{2 0}$ | $\mathbf{1 5 . 0 0}$ |
| 40 | 16.90 |
| 60 | 18.80 |
| 80 | 20.90 |
| 100 | 23.00 |
| 120 | 25.20 |
| 140 | 27.40 |

Fig.5. The relationship between temperature and the viscosity of air.

From Fig. 5 we note that when the temperature is $20^{\circ} \mathrm{C}$ the viscosity of air is $15.00 * 10^{-5}$. V equals to $\mathrm{v}_{\infty}$. So in this case, the number Re is approximately $3 * 10^{5}$.


Fig.6. The curve of relationship between resistance constant $\left(C_{d}\right)$ of soccer and disk and Reynolds number.

From Fig. 6 we note that when the number Re is about $3 * 10^{5}$, the resistance constant $\left(\mathrm{C}_{\mathrm{d}}\right)$ is nearly 0.2 . A is the front face area of the soccer. So the pressure drag can be expressed as $F_{1} \approx 9.118 \times 10^{-3} \mathrm{~V}_{\infty}^{2}$, the relationship between the magnitudes of $F_{1}$ and $V_{\infty}^{2}$ is direct proportion. So the magnitude of acceleration $a_{1}$ is approximately $0.020 \mathrm{~V}_{\infty}^{2}$. Because the direction of acceleration $\mathrm{a}_{1}$ is opposite to the direction of its velocity, the velocity of the soccer tends to decrease.

## C. Vertical Force

The axis of the rotation of the soccer passes the center of the soccer and is perpendicular to the direction of the velocity of the soccer. When the soccer is rotating, due to the velocity of the surface of the soccer, the velocity of air around the soccer is different. According to the equation in Bernoulli's theorem, if velocity rises at a given elevation, pressure must fall. In this case, because the velocity of air is greater on the right side of the soccer, the pressure on the right side of the soccer is less than on the left side, so the path of the soccer tends to slightly move to right.

To analyze the vertical force acting on the soccer, we apply the idea of differentiation and divide the soccer into infinite small aspects as in Fig. 7.


Fig.7. Diagrammatic Sketch of the division of the soccer.
Establish grid in gambit as Fig.8. Each cell in the grid is the unit of iteration. Use Fluent to iteration from left of the grid to the right.


Fig.8. Gambit.
Define the boundary condition $\mathrm{v}=20 \mathrm{~m} / \mathrm{s}$, and the outcome of iteration is as Fig. 9 and Fig 10.


Fig.9. Distribution of static pressure around the soccer.


Fig.10. Distribution of velocity of the air around the soccer.


Fig.11. Magnified of distribution of the velocity of air around the soccer.

Find the relationship between V and $\theta$. Connect the dot that has a distinct velocity and the center of the ball. The angle between that line and the radius of the ball is $\theta$. It is shown in Fig. 12.


Fig.12. Diagrammatic sketch of angle $\theta$.
When the velocity of the soccer is $20 \mathrm{~m} / \mathrm{s}, \theta-\mathrm{v}_{\theta}$ data is in Appendix [A]. Then define $C_{p}=\frac{\mathrm{P}-\mathrm{P}_{\infty}}{\frac{1}{2} \mathrm{pv}_{\infty}^{2}}=1-\left(\frac{\mathrm{v}_{\theta}}{\mathrm{v}_{\infty}}\right)^{2}$, use $\mathrm{C}++$ to program and calculate. The code is in Appendix [B]. The outcome data is in Appendix [C]. Enter these data into Matlab; the graph generated is as Fig.13.


Fig.13. The graph of $\theta-C_{p \theta}$.

$$
\begin{align*}
& \overrightarrow{\left|v_{\theta}\right|}=\overrightarrow{\left|v_{\infty}\right|} \sqrt{1-C_{p \theta}},  \tag{10}\\
& P+\frac{1}{2} \rho \overrightarrow{|v|^{2}}=\text { constant },  \tag{11}\\
& P_{u p \theta}=P_{0}+\frac{1}{2} \rho\left(\overrightarrow{\left|v_{\theta}\right|}+\omega r\right)^{2},  \tag{12}\\
& P_{\text {down } \theta}=P_{0}+\frac{1}{2} \rho\left(\overrightarrow{\left|v_{\theta}\right|}-\omega r\right)^{2},  \tag{13}\\
& \Delta P_{\theta}=\frac{1}{2} \rho\left[\left(\overrightarrow{\left|v_{\theta}\right|}+\omega r\right)^{2}+\left(\overrightarrow{\left|v_{\theta}\right|}-\omega r\right)^{2}\right],  \tag{14}\\
& \Delta P_{\theta x}=\frac{1}{2} \rho\left[\left(\overrightarrow{\left|v_{\theta}\right|}+\omega r\right)^{2}+\left(\overrightarrow{\left|v_{\theta}\right|}-\omega r\right)^{2}\right] \sin \theta,  \tag{15}\\
& \overrightarrow{\left|F_{2}\right|}=2 S \iint_{D} 2 \rho \overrightarrow{\left|v_{\theta}\right|} \omega r \sin \theta d r d \theta  \tag{16}\\
& \overrightarrow{\left|F_{2}\right|}=4 \pi R^{2} \rho \omega \overrightarrow{\left|v_{\infty}\right|} \\
& 1500  \tag{17}\\
& \sum_{r=0}^{180} \sum_{\theta=0} \sqrt{1-C_{p \theta}} \frac{r}{10000} \sin \theta \Delta \frac{r}{10000} \Delta \theta
\end{align*}
$$

Because $C_{p \theta}$ and the radius of the soccer $r$ are not correlated, $\mathrm{v}_{\infty}$ is constant, so $\mathrm{v}_{\theta}$ can be expressed in terms of (10). Applying the Bernoulli's theorem, pressure on the top of the soccer can be expressed in terms of (12), and pressure on the bottom of the soccer can be expressed in terms of (13). Subtracting (13) from (12) gives the difference of pressure between two dots on the top and bottom surfaces of the soccer (14), so the difference of pressure on x-axis can be expressed in terms of (15). Apply the idea of integration to calculate the vertical force. In the domain $D: \theta \in(0, \pi), r \in$ $(0,0.15)$, integrate each difference of pressure between the dots on the top and bottom to get the whole difference of pressure between the top surface and bottom surface. So the vertical force can be expressed as (16), which can be written as (17). Because this equation is too complicated to calculate, we program by $\mathrm{C}++$ to calculate $\sum_{r=0}^{1500} \sum_{\theta=0}^{180} \sqrt{1-C_{p \theta}} \frac{r}{10000} \sin \theta \Delta \frac{r}{10000} \Delta \theta$.
Assume that $\Delta \frac{\mathrm{r}}{10000}=0.0001, \Delta \theta=1 \quad, \quad$ and

$$
\int_{a}^{b} f(x)=\sum_{i=1}^{n} f\left(\xi_{i}\right)\left(x_{i}-x_{i-1}\right),
$$

the code of C++ is in Appendix [D]. After we get the approximate magnitude of it, we substitute it into (17), and then we obtain vertical force $\overrightarrow{\left|\mathrm{F}_{2}\right|} \approx 0.284466438 \overrightarrow{\mathrm{v}_{\infty} \mid}$, so $\left|\overrightarrow{a_{2}}\right| \approx 0.632 \overrightarrow{\left|v_{\infty}\right|}$.

## IV. TRAJECTORY OF THE SOCCER

A. Function \& Equations
$f(x, y, z, t)=0$,
$\vec{v}=\left(\frac{\partial x}{\partial t}, \frac{\partial y}{\partial t}, \frac{\partial z}{\partial t}\right)$,
$\overrightarrow{a_{1}}$
$=\frac{9.362 \times 10^{-3}\left(\frac{\partial^{2} x}{\partial t^{2}}+\frac{\partial^{2} y}{\partial t^{2}}+\frac{\partial^{2} z}{\partial t^{2}}\right)}{\sqrt{\frac{\partial^{2} x}{\partial t^{2}}+\frac{\partial^{2} y}{\partial t^{2}}+\frac{\partial^{2} z}{\partial t^{2}}}}\left(-\frac{\partial x}{\partial t},-\frac{\partial y}{\partial t},-\frac{\partial z}{\partial t}\right)$,
$\overrightarrow{a_{2}}=\frac{0.632 \sqrt{\frac{\partial^{2} x}{\partial t^{2}}+\frac{\partial^{2} y}{\partial t^{2}}+\frac{\partial^{2} z}{\partial t^{2}}}}{\sqrt{\frac{\partial^{2} x}{\partial t^{2}}+\frac{\partial^{2} y}{\partial t^{2}}}}\left(\frac{\partial y}{\partial t},-\frac{\partial x}{\partial t}, 0\right)$,
$\vec{g}=(0,0,-10)$,
$\vec{a}=\frac{\partial x}{\partial t^{2}}+\frac{\partial y}{\partial t^{2}}+\frac{\partial z}{\partial t^{2}}=\overrightarrow{a_{1}}+\overrightarrow{a_{2}}+\vec{g}$,
$\left\{\begin{array}{l}x=f(t) \\ y=g(t), \\ z=h(t)\end{array},\left\{\begin{array}{l}v_{x}=f^{\prime}(t) \\ v_{y}=g^{\prime}(t), \\ v_{z}=h^{\prime}(t)\end{array}\right)\left\{\begin{array}{l}a_{x}=f^{\prime \prime}(t) \\ a_{y}=g^{\prime \prime}(t), \\ a_{z}=h^{\prime \prime}(t)\end{array}\right.\right.$

$$
\begin{align*}
& \left\{\begin{array}{l}
f^{\prime \prime}(t)=\frac{0.632 g^{\prime}(t)}{\sqrt{\left(f^{\prime}(t)\right)^{2}+\left(g^{\prime}(t)\right)^{2}}}-\frac{9.362 \times 10^{-3}\left(f^{\prime}(t)\right)^{2}}{\sqrt{\left(f^{\prime}(t)\right)^{2}+\left(g^{\prime}(t)\right)^{2}+\left(h^{\prime}(t)\right)^{2}}} \\
g^{\prime \prime}(t)=-\frac{0.632 f^{\prime}(t)}{\sqrt{\left(f^{\prime}(t)\right)^{2}+\left(g^{\prime}(t)\right)^{2}}}-\frac{9.362 \times 10^{-3}\left(g^{\prime}(t)\right)^{2}}{\sqrt{\left(f^{\prime}(t)\right)^{2}+\left(g^{\prime}(t)\right)^{2}+\left(h^{\prime}(t)\right)^{2}}} \\
h^{\prime \prime}(t)=-\frac{9.362 \times 10^{-3}\left(h^{\prime}(t)\right)^{2}}{\sqrt{\left(f^{\prime}(t)\right)^{2}+\left(g^{\prime}(t)\right)^{2}+\left(h^{\prime}(t)\right)^{2}}-10,}
\end{array}\right. \\
& \left\{\begin{array}{l}
\lim _{\delta t \rightarrow 0} f(t+\delta t)=f(x)+f^{\prime}(t) \delta t, f(0)=0, \\
\lim _{\delta t \rightarrow 0} g(t+\delta t)=g(x)+g^{\prime}(t) \delta t, g(0)=0, \\
\lim _{\delta t \rightarrow 0} h(t+\delta t)=h(x)+h^{\prime}(t) \delta t, h(0)=0,
\end{array}\right. \\
& \left\{\begin{array}{l}
\lim _{\delta t \rightarrow 0} f^{\prime}(t+\delta t)=f^{\prime}(x)+f^{\prime \prime}(t) \delta t, f^{\prime}(0)=0, \\
\lim _{\delta t \rightarrow 0} g^{\prime}(t+\delta t)=g^{\prime}(x)+g^{\prime \prime}(t) \delta t, g^{\prime}(0)=10 \sqrt{3}, \\
\lim _{\delta t \rightarrow 0} h^{\prime}(t+\delta t)=h^{\prime}(x)+h^{\prime \prime}(t) \delta t, h^{\prime}(0)=10 .
\end{array}\right.
\end{align*}
$$

The movement of the soccer is a movement with velocity and accelerator affect each other continuously, so we need the idea of differentiation. Divide the time of this movement into infinite small parts, so during each of these instants, the change of velocity and accelerator is approximately zero. Appling basic rules of projectile motion, we can work out the instantaneous acceleration and instantaneous velocity of the soccer in every instant. Thus, a graph can be generated from all the data we get.

Apply differential-algebraic equation to express the relationship (18) between the position of the soccer and time. Use $x, y$, and $z$ to represent the location of the soccer in threedimensional coordinate system, and $t$ represents the time. Combination of (18)-(23) yields a system of partial differential equations. In order to reach the solution of this complicated system of equations, we transform this system of partial differential equations into parametric equations by substituting $x, y$, and $z$ through (24). The equations can be written as (25)(27). To solve the system of equations through $\mathrm{C}++$ programming, we assume that the change of time $\delta \mathrm{t}=0.01 \mathrm{~s}$, which means in $\delta t=0.01 \mathrm{~s}$, the soccer is in uniform rectilinear motion ( $\mathrm{C}++$ code is in Appendix [E]). Calculate by programming, there are many sets of solutions (solutions are in Appendix [F]), which represent the different locations the soccer is in during the movement. Enter these data into Matlab, and then a graph of the trajectory of the soccer is generated as Fig. 14.


Fig.14. The trajectory of the soccer.
V. CONCLUSION

| $\mathbf{X}$ | $\mathbf{Y}$ | $\mathbf{Z}$ |
| ---: | ---: | ---: |
| 8.46431 | 17.4701 | 2.65175 |
| 8.55762 | 17.535 | 2.59916 |
| 8.65114 | 17.5991 | 2.54573 |
| 8.74487 | 17.6624 | 2.49145 |
| $\mathbf{8 . 8 3 8 8 2}$ | $\mathbf{1 7 . 7 2 4 9}$ | $\mathbf{2 . 4 3 6 3 3}$ |
| 8.93296 | 17.7865 | 2.38037 |
| 9.02731 | 17.8474 | 2.32357 |
| 9.12185 | 17.9074 | 2.26593 |
| 9.21658 | 17.9666 | 2.20745 |

Fig.15. Part of data from Appendix [F].
The height of the goalpost is about 2.44 meters, from Fig. 15 we find the value of $x$ and $y$ when the value of $z$ is approximately 2.44 . The displacement of the soccer $\mathrm{H}=$ $\sqrt{x^{2}+y^{2}}$. So the displacement of the soccer is approximately 19.8 m . However, because the strides of different players are different, so players need to adjust their steps before shooting. After doing a research about the strides of players, we assume that the step of the player is 1 m . So the most suitable distance to shoot is about $19.8 \pm 1 \mathrm{~m}$. Assuming the top left corner is the center of a circle, 18.8 m and 20.8 m are radius draw two circles. Then assume the top right corner is the center of a circle, 18.8 m and 20.8 are radius draw two circles as in Fig. 16.


Fig.16. Diagrammatic sketch of the best area to shoot.
The white area in Fig. 16 is the area where the arcs cross. In this area, with right amount of force, player can score a goal by shooting towards either the top left corner or the top right corner of the goalpost. It is much more difficult for the goal keeper to stop the soccer. So the white area is the most suitable area to shoot.

In this thesis, we combine the theory of fluid dynamics and two fundamental operations of calculus, differentiation and integration. We also apply methods of modeling, partial differential equation, and iterated function. We analyze the motion and trajectory of soccer. The analysis of soccer's path is almost the same with the trajectory analysis of bullet and other projectile motions, which requires various mathematical and physical knowledge. This knowledge and analysis can be applied to both military affairs and criminal investigation.

## VI. VERIFICATION OF CONCLUSION



Fig. 17 Distribution of the ratio of goals.
To verify the result, we obtain data from the official website of UEFA. (Original data are in Appendix [G]) The data include all of the goals in the soccer matches in recent years and the distance of the goals. From the data we reach the rate of scoring goals in different distances from the goalpost. By using $\mathrm{C}++$, we processed the data ( $\mathrm{C}++$ code is in Appendix [H]), and generate a graph by Matlab as Fig. 17. From Fig. 17 we note that the area where the rate of scoring goals is the highest almost overlaps the white area in our conclusion, so our result is credible and applicable to real life.

## VII. Future research

In this thesis we assume that the force that a player kicks the soccer with is constant. However, in real life, the magnitude of that force should be a range. Thus the trajectory of the soccer should be a system of curves, and the displacement of the soccer should be an equation about the force. In the future research we will endeavor to solve this problem.

In fluid dynamics, a Kármán vortex street is a repeating pattern of swirling vortices caused by the unsteady separation of flow of a fluid around blunt bodies as shown in Fig.18.


Fig.18. Kármán vortex street.
A vortex street will only form at a certain range of flow velocities, specified by a range of Reynolds numbers. Vortex Street can be created by steady winds blowing past smokestacks, transmission line. The street gives rise to oscillating lateral forces on the shedding body. This will obviously influence the motion of the soccer. So in the future we will also do a research about it.

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## N11

APPENDIX
[A]

| 0 | 7.52194 | 31 | 30.0877 | 62 | 45.1316 | 93 | 47.6389 | 124 | 32.5951 | 156 | 2.50731 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 7.52194 | 32 | 30.0877 | 63 | 45.1316 | 94 | 47.6389 | 125 | 30.0877 | 157 | 2.50731 |
| 2 | 7.52194 | 33 | 30.0877 | 64 | 45.1316 | 95 | 47.6389 | 126 | 30.0877 | 158 | 2.50731 |
| 3 | 7.52194 | 34 | 27.5804 | 65 | 45.1316 | 96 | 47.6389 | 127 | 27.5804 | 159 | 2.50731 |
| 4 | 7.52194 | 35 | 30.0877 | 66 | 45.1316 | 97 | 47.6389 | 128 | 27.5804 | 160 | 2.50731 |
| 5 | 7.52194 | 36 | 30.0877 | 67 | 45.1316 | 98 | 47.6389 | 129 | 25.0731 | 161 | 2.50731 |
| 6 | 7.52194 | 37 | 30.0877 | 68 | 45.1316 | 99 | 47.6389 | 130 | 25.0731 | 162 | 2.50731 |
| 7 | 7.52194 | 38 | 32.5951 | 69 | 47.6389 | 100 | 47.6389 | 131 | 22.5658 | 163 | 2.50731 |
| 8 | 10.0292 | 39 | 32.5951 | 70 | 47.6389 | 101 | 47.6389 | 132 | 22.5658 | 164 | 2.50731 |
| 9 | 10.0292 | 40 | 32.5951 | 71 | 47.6389 | 102 | 47.6389 | 133 | 20.0585 | 165 | 2.50731 |
| 10 | 10.0292 | 41 | 32.5951 | 72 | 47.6389 | 103 | 47.6389 | 134 | 20.0585 | 166 | 2.50731 |
| 11 | 12.5366 | 42 | 35.1024 | 73 | 47.6389 | 104 | 47.6389 | 135 | 17.5512 | 167 | 2.50731 |
| 12 | 12.5366 | 43 | 35.1024 | 74 | 47.6389 | 105 | 47.6389 | 136 | 17.5512 | 168 | 2.50731 |
| 13 | 15.0439 | 44 | 35.1024 | 75 | 47.6389 | 106 | 47.6389 | 137 | 15.0439 | 169 | 2.50731 |
| 14 | 15.0439 | 45 | 35.1024 | 76 | 47.6389 | 107 | 47.6389 | 138 | 15.0439 | 170 | 2.50731 |
| 15 | 15.0439 | 46 | 37.6097 | 77 | 47.6389 | 108 | 47.6389 | 140 | 5.01462 | 171 | 2.50731 |
| 16 | 17.5512 | 47 | 37.6097 | 78 | 47.6389 | 109 | 47.6389 | 141 | 5.01462 | 172 | 2.50731 |
| 17 | 17.5512 | 48 | 37.6097 | 79 | 47.6389 | 110 | 45.1316 | 142 | 5.01462 | 173 | 2.50731 |
| 18 | 17.5512 | 49 | 37.6097 | 80 | 47.6389 | 111 | 42.6243 | 143 | 5.01462 | 174 | 2.50731 |
| 19 | 17.5512 | 50 | 37.6097 | 81 | 47.6389 | 112 | 42.6243 | 144 | 5.01462 | 175 | 2.50731 |
| 20 | 17.5512 | 51 | 37.6097 | 82 | 47.6389 | 113 | 42.6243 | 145 | 5.01462 | 176 | 2.50731 |
| 21 | 17.5512 | 52 | 40.117 | 83 | 47.6389 | 114 | 42.6243 | 146 | 5.01462 | 177 | 2.50731 |
| 22 | 20.0585 | 53 | 40.117 | 84 | 47.6389 | 115 | 40.117 | 147 | 5.01462 | 178 | 2.50731 |
| 23 | 20.0585 | 54 | 40.117 | 85 | 47.6389 | 116 | 40.117 | 148 | 5.01462 | 179 | 2.50731 |
| 24 | 20.0585 | 55 | 40.117 | 86 | 47.6389 | 117 | 37.6097 | 149 | 5.01462 | 180 | 2.50731 |
| 25 | 22.5658 | 56 | 40.117 | 87 | 47.6389 | 118 | 37.6097 | 150 | 5.01462 |  |  |
| 26 | 22.5658 | 57 | 42.6243 | 88 | 47.6389 | 119 | 37.6097 | 151 | 5.01462 |  |  |
| 27 | 22.5658 | 58 | 42.6243 | 89 | 47.6389 | 120 | 37.6097 | 152 | 5.01462 |  |  |
| 28 | 25.0731 | 59 | 42.6243 | 90 | 47.6389 | 121 | 35.1024 | 153 | 2.50731 |  |  |
| 29 | 25.0731 | 60 | 42.6243 | 91 | 47.6389 | 122 | 35.1024 | 154 | 2.50731 |  |  |
| 30 | 25.0731 | 61 | 42.6243 | 92 | 47.6389 | 123 | 35.1024 | 155 | 2.50731 |  |  |

## [B]

\#include <cstdlib>
\#include <fstream>
using namespace std;
ifstream fin("v20-thea.in");
ofstream fout("Cp.out");
int main(int $\operatorname{argc}$, char $* \operatorname{argv}[])$
\{
double a[185][2];
int i,j;

```
for(i=0;i<=180;i++)
    {
        for(j=0;j<2;j++) fin>>a[i][j];
    }
for(i=0;i<180;i++)
    {
        a[i][1]=1-(a[i][1]/20)*(a[i][1]/20);
}
for(i=0;i<180;i++)
{
for(j=0;j<2;j++) fout<<a[i][j]<<" ";
fout <<endl;
}
```

return 0 ;
\}
[C]

| 0 | 0.858551 | 45 | -2.08044 | 90 | -4.67367 | 135 | 0.22989 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 0.858551 | 46 | -2.53622 | 91 | -4.67367 | 136 | 0.22989 |
| 2 | 0.858551 | 47 | -2.53622 | 92 | -4.67367 | 137 | 0.434205 |
| 3 | 0.858551 | 48 | -2.53622 | 93 | -4.67367 | 138 | 0.434205 |
| 4 | 0.858551 | 49 | -2.53622 | 94 | -4.67367 | 140 | 0.937134 |
| 5 | 0.858551 | 50 | -2.53622 | 95 | -4.67367 | 141 | 0.937134 |
| 6 | 0.858551 | 51 | -2.53622 | 96 | -4.67367 | 142 | 0.937134 |
| 7 | 0.858551 | 52 | -3.02343 | 97 | -4.67367 | 143 | 0.937134 |
| 8 | 0.748536 | 53 | -3.02343 | 98 | -4.67367 | 144 | 0.937134 |
| 9 | 0.748536 | 54 | -3.02343 | 99 | -4.67367 | 145 | 0.937134 |
| 10 | 0.748536 | 55 | -3.02343 | 100 | -4.67367 | 146 | 0.937134 |
| 11 | 0.607087 | 56 | -3.02343 | 101 | -4.67367 | 147 | 0.937134 |
| 12 | 0.607087 | 57 | -3.54208 | 102 | -4.67367 | 148 | 0.937134 |
| 13 | 0.434205 | 58 | -3.54208 | 103 | -4.67367 | 149 | 0.937134 |
| 14 | 0.434205 | 59 | -3.54208 | 104 | -4.67367 | 150 | 0.937134 |
| 15 | 0.434205 | 60 | -3.54208 | 105 | -4.67367 | 151 | 0.937134 |
| 16 | 0.22989 | 61 | -3.54208 | 106 | -4.67367 | 152 | 0.937134 |
| 17 | 0.22989 | 62 | -4.09216 | 107 | -4.67367 | 153 | 0.984283 |
| 18 | 0.22989 | 63 | -4.09216 | 108 | -4.67367 | 154 | 0.984283 |
| 19 | 0.22989 | 64 | -4.09216 | 109 | -4.67367 | 155 | 0.984283 |
| 20 | 0.22989 | 65 | -4.09216 | 110 | -4.09216 | 156 | 0.984283 |
| 21 | 0.22989 | 66 | -4.09216 | 111 | -3.54208 | 157 | 0.984283 |

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| 22 | -0.00586 | 67 | -4.09216 | 112 | -3.54208 | 158 | 0.984283 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 23 | -0.00586 | 68 | -4.09216 | 113 | -3.54208 | 159 | 0.984283 |
| 24 | -0.00586 | 69 | -4.67367 | 114 | -3.54208 | 160 | 0.984283 |
| 25 | -0.27304 | 70 | -4.67367 | 115 | -3.02343 | 161 | 0.984283 |
| 26 | -0.27304 | 71 | -4.67367 | 116 | -3.02343 | 162 | 0.984283 |
| 27 | -0.27304 | 72 | -4.67367 | 117 | -2.53622 | 163 | 0.984283 |
| 28 | -0.57165 | 73 | -4.67367 | 118 | -2.53622 | 164 | 0.984283 |
| 29 | -0.57165 | 74 | -4.67367 | 119 | -2.53622 | 165 | 0.984283 |
| 30 | -0.57165 | 75 | -4.67367 | 120 | -2.53622 | 166 | 0.984283 |
| 31 | -1.26318 | 76 | -4.67367 | 121 | -2.08044 | 167 | 0.984283 |
| 32 | -1.26318 | 77 | -4.67367 | 122 | -2.08044 | 168 | 0.984283 |
| 33 | -1.26318 | 78 | -4.67367 | 123 | -2.08044 | 169 | 0.984283 |
| 34 | -0.9017 | 79 | -4.67367 | 124 | -1.65609 | 170 | 0.984283 |
| 35 | -1.26318 | 80 | -4.67367 | 125 | -1.26318 | 171 | 0.984283 |
| 36 | -1.26318 | 81 | -4.67367 | 126 | -1.26318 | 172 | 0.984283 |
| 37 | -1.26318 | 82 | -4.67367 | 127 | -0.9017 | 173 | 0.984283 |
| 38 | -1.65609 | 83 | -4.67367 | 128 | -0.9017 | 174 | 0.984283 |
| 39 | -1.65609 | 84 | -4.67367 | 129 | -0.57165 | 175 | 0.984283 |
| 40 | -1.65609 | 85 | -4.67367 | 130 | -0.57165 | 176 | 0.984283 |
| 41 | -1.65609 | 86 | -4.67367 | 131 | -0.27304 | 177 | 0.984283 |
| 42 | -2.08044 | 87 | -4.67367 | 132 | -0.27304 | 178 | 0.984283 |
| 43 | -2.08044 | 88 | -4.67367 | 133 | -0.00586 | 179 | 0.984283 |
| 44 | -2.08044 | 89 | -4.67367 | 134 | -0.00586 | 180 | 0.984283 |

## [D]

\#include <cstdlib>
\#include <fstream>
\#include <math.h>
using namespace std;
ifstream fin("Cp.in");
ofstream fout("sigema.out");
int main(int $\operatorname{argc}$, char $* \operatorname{argv}[])$
\{ long double a[181][2];
int $\mathrm{i}, \mathrm{j}$;
double r;
long double $\mathrm{s}=0$;
for $(\mathrm{i}=0 ; \mathrm{i}<180 ; \mathrm{i}++$ )
\{
for $(j=0 ; j<2 ; j++)$ fin $\gg a[i][j]$;

```
    }
    for(r=0;r<0.15;r=r+0.0001)
    {
    for(i=0;i<180;i++)
        {
s=s+\operatorname{sin}(\textrm{i}*3.1415926/180)*sqrt(1-a[i][1])*(3.1415926/180)*r*0.0001; }
        fout<<s<<endl;
        }
    return 0;
}
[E]
\#include <cstdlib>
\#include <fstream>
\#include <math.h>
using namespace std;
ofstream fout("x.out");
int main(int argc, char *argv[])
\{
int i,m;
double a,b;
double v[500][3];
double a1[500][3];
double a2[500][3];
double x[500][3];
double \(\mathrm{t}=0.01\);
\(\mathrm{v}[0][0]=0\);
\(\mathrm{v}[0][1]=17.32\);
\(\mathrm{v}[0][2]=10\);
\(x[0][0]=0\);
```

```
x[0][1]=0;
x[0][2]=0;
for(i=0;i<500;i++)
    {
    a=0.020*(v[i][0]*v[i][0]+v[i][1]*v[i][1]+v[i][2]*v[i][2]);
    a1[i][0]=a*(-v[i][0])/sqrt(v[i][0]*v[i][0]+v[i][1]*v[i][1]+v[i][2]*v[i][2]);
    a1[i][1]=a*(-v[i][1])/sqrt(v[i][0]*v[i][0]+v[i][1]*v[i][1]+v[i][2]*v[i][2]);
    a1[i][2]=a*(-v[i][2])/sqrt(v[i][0]*v[i][0]+v[i][1]*v[i][1]+v[i][2]*v[i][2]);
    b=0.632*sqrt(v[i][0]*v[i][0]+v[i][1]*v[i][1]+v[i][2]*v[i][2]);
    a2[i][0]=b*(v[i][1])/sqrt(v[i][0]*v[i][0]+v[i][1]*v[i][1]);
    a2[i][1]=b*(-v[i][0])/sqrt(v[i][0]*v[i][0]+v[i][1]*v[i][1]);
    a2[i][2]=0;
    v[i+1][0]=v[i][0]+(a2[i][0]+a1[i][0])*t;
    v[i+1][1]=v[i][1]+(a2[i][1]+a1[i][1])*t;
    v[i+1][2]=v[i][2]+(a2[i][2]+a1[i][2]-9.8)*t;
    x[i+1][0]=x[i][0]+v[i][0]*t;
    x[i+1][1]=x[i][1]+v[i][1]*t;
    x[i+1][2]=x[i][2]+v[i][2]*t;
    if(x[i+1][2]<0)//ensure z>0
        {
        m=i;
        break;
        }
    }
for(i=0;i<m;i++) fout<<x[i][0]<<" "<<x[i][1]<<" "<<x[i][2]<<" "<<endl;
    return 0;
}
```


## N11

[F]

| X | Y | Z | X | Y | Z |
| ---: | ---: | ---: | ---: | ---: | ---: |
| 0 | 0 | 0 | 4.03179 | 13.0121 | 4.16217 |
| 0 | 0.1732 | 0.1 | 4.10715 | 13.1173 | 4.15677 |
| 0.001264 | 0.345707 | 0.19862 | 4.18299 | 13.2218 | 4.1504 |
| 0.003779 | 0.51752 | 0.295868 | 4.25929 | 13.3255 | 4.14306 |
| 0.007531 | 0.688635 | 0.391752 | 4.33604 | 13.4285 | 4.13477 |
| 0.012509 | 0.859052 | 0.48628 | 4.41326 | 13.5307 | 4.12552 |
| 0.018698 | 1.02877 | 0.579459 | 4.49092 | 13.6322 | 4.11531 |
| 0.026087 | 1.19778 | 0.671298 | 4.56902 | 13.7329 | 4.10414 |
| 0.034663 | 1.36609 | 0.761802 | 4.64757 | 13.8328 | 4.09203 |
| 0.044414 | 1.5337 | 0.850981 | 4.72655 | 13.932 | 4.07897 |
| 0.055327 | 1.7006 | 0.93884 | 4.80596 | 14.0305 | 4.06496 |
| 0.06739 | 1.86679 | 1.02539 | 4.88579 | 14.1282 | 4.05 |
| 0.080591 | 2.03227 | 1.11063 | 4.96604 | 14.2251 | 4.0341 |
| 0.094919 | 2.19704 | 1.19457 | 5.0467 | 14.3213 | 4.01727 |
| 0.110361 | 2.36109 | 1.27723 | 5.12778 | 14.4167 | 3.99949 |
| 0.126907 | 2.52443 | 1.3586 | 5.20926 | 14.5114 | 3.98079 |
| 0.144544 | 2.68706 | 1.43869 | 5.29113 | 14.6053 | 3.96114 |
| 0.163261 | 2.84897 | 1.5175 | 5.3734 | 14.6984 | 3.94057 |
| 0.183047 | 3.01016 | 1.59506 | 5.45606 | 14.7908 | 3.91907 |
| 0.20389 | 3.17063 | 1.67135 | 5.53911 | 14.8824 | 3.89665 |
| 0.22578 | 3.33039 | 1.74639 | 5.62253 | 14.9733 | 3.8733 |
| 0.248707 | 3.48942 | 1.82018 | 5.70633 | 15.0634 | 3.84903 |
| 0.272658 | 3.64773 | 1.89274 | 5.7905 | 15.1527 | 3.82384 |
| 0.297623 | 3.80532 | 1.96405 | 5.87504 | 15.2413 | 3.79773 |
| 0.323592 | 3.96218 | 2.03414 | 5.95994 | 15.329 | 3.77071 |
| 0.350554 | 4.11832 | 2.10301 | 6.04519 | 15.4161 | 3.74277 |
| 0.378499 | 4.27374 | 2.17066 | 6.13079 | 15.5023 | 3.71393 |
| 0.407416 | 4.42843 | 2.23709 | 6.21674 | 15.5878 | 3.68418 |
| 0.437296 | 4.58239 | 2.30232 | 6.30303 | 15.6725 | 3.65352 |
| 0.468128 | 4.73562 | 2.36634 | 6.38966 | 15.7564 | 3.62196 |
| 0.499903 | 4.88813 | 2.42917 | 6.47662 | 15.8396 | 3.58949 |
| 0.53261 | 5.03991 | 2.49081 | 6.56391 | 15.922 | 3.55613 |
| 0.56624 | 5.19095 | 2.55126 | 6.65152 | 16.0036 | 3.52187 |
| 0.600783 | 5.34127 | 2.61054 | 6.73945 | 16.0844 | 3.48672 |
| 0.636229 | 5.49086 | 2.66863 | 6.82769 | 16.1644 | 3.45068 |
| 0.67257 | 5.63971 | 2.72556 | 6.91624 | 16.2437 | 3.41374 |
| 0.709796 | 5.78784 | 2.78132 | 7.0051 | 16.3222 | 3.37591 |
| 0.747897 | 5.93523 | 2.83591 | 7.09425 | 16.3999 | 3.3372 |
| 0.786864 | 6.08189 | 2.88935 | 7.1837 | 16.4768 | 3.29761 |
| 0.826689 | 6.22781 | 2.94164 | 7.27344 | 16.5529 | 3.25714 |
| 0.867362 | 6.37301 | 2.99278 | 7.36347 | 16.6282 | 3.21578 |
|  |  |  |  |  |  |

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| 0.908874 | 6.51747 | 3.04278 | 7.45378 | 16.7028 | 3.17355 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0.951218 | 6.66119 | 3.09164 | 7.54436 | 16.7765 | 3.13044 |
| 0.994383 | 6.80418 | 3.13937 | 7.63521 | 16.8495 | 3.08646 |
| 1.03836 | 6.94644 | 3.18597 | 7.72633 | 16.9216 | 3.04162 |
| 1.08314 | 7.08796 | 3.23144 | 7.81771 | 16.993 | 2.9959 |
| 1.12872 | 7.22874 | 3.27579 | 7.90935 | 17.0636 | 2.94931 |
| 1.17509 | 7.36879 | 3.31902 | 8.00124 | 17.1333 | 2.90187 |
| 1.22224 | 7.50811 | 3.36114 | 8.09338 | 17.2023 | 2.85356 |
| 1.27016 | 7.64668 | 3.40215 | 8.18576 | 17.2704 | 2.80439 |
| 1.31884 | 7.78452 | 3.44206 | 8.27838 | 17.3378 | 2.75436 |
| 1.36828 | 7.92163 | 3.48086 | 8.37123 | 17.4043 | 2.70348 |
| 1.41846 | 8.058 | 3.51857 | 8.46431 | 17.4701 | 2.65175 |
| 1.46939 | 8.19363 | 3.55519 | 8.55762 | 17.535 | 2.59916 |
| 1.52105 | 8.32852 | 3.59071 | 8.65114 | 17.5991 | 2.54573 |
| 1.57343 | 8.46267 | 3.62515 | 8.74487 | 17.6624 | 2.49145 |
| 1.62653 | 8.59609 | 3.65851 | 8.83882 | 17.7249 | 2.43633 |
| 1.68033 | 8.72877 | 3.69079 | 8.93296 | 17.7865 | 2.38037 |
| 1.73484 | 8.86071 | 3.722 | 9.02731 | 17.8474 | 2.32357 |
| 1.79005 | 8.99192 | 3.75213 | 9.12185 | 17.9074 | 2.26593 |
| 1.84594 | 9.12238 | 3.7812 | 9.21658 | 17.9666 | 2.20745 |
| 1.90251 | 9.25211 | 3.8092 | 9.31149 | 18.025 | 2.14814 |
| 1.95975 | 9.38109 | 3.83614 | 9.40658 | 18.0825 | 2.08801 |
| 2.01766 | 9.50934 | 3.86202 | 9.50184 | 18.1393 | 2.02704 |
| 2.07622 | 9.63685 | 3.88685 | 9.59727 | 18.1951 | 1.96525 |
| 2.13544 | 9.76362 | 3.91063 | 9.69287 | 18.2502 | 1.90263 |
| 2.1953 | 9.88965 | 3.93336 | 9.78862 | 18.3044 | 1.8392 |
| 2.2558 | 10.0149 | 3.95505 | 9.88452 | 18.3578 | 1.77494 |
| 2.31693 | 10.1395 | 3.9757 | 9.98057 | 18.4104 | 1.70987 |
| 2.37869 | 10.2633 | 3.9953 | 10.0768 | 18.4621 | 1.64399 |
| 2.44106 | 10.3864 | 4.01388 | 10.1731 | 18.5129 | 1.57729 |
| 2.50405 | 10.5087 | 4.03142 | 10.2696 | 18.5629 | 1.50978 |
| 2.56763 | 10.6303 | 4.04793 | 10.3661 | 18.6121 | 1.44147 |
| 2.63182 | 10.7511 | 4.06342 | 10.4628 | 18.6605 | 1.37235 |
| 2.6966 | 10.8713 | 4.07788 | 10.5597 | 18.7079 | 1.30242 |
| 2.76197 | 10.9906 | 4.09133 | 10.6566 | 18.7546 | 1.2317 |
| 2.82791 | 11.1092 | 4.10376 | 10.7536 | 18.8003 | 1.16018 |
| 2.89443 | 11.2271 | 4.11517 | 10.8507 | 18.8453 | 1.08787 |
| 2.96151 | 11.3443 | 4.12557 | 10.948 | 18.8893 | 1.01476 |
| 3.02915 | 11.4607 | 4.13497 | 11.0453 | 18.9325 | 0.940857 |
| 3.09735 | 11.5763 | 4.14336 | 11.1427 | 18.9749 | 0.866168 |
| 3.1661 | 11.6912 | 4.15075 | 11.2401 | 19.0163 | 0.790694 |
| 3.23539 | 11.8054 | 4.15713 | 11.3377 | 19.057 | 0.714436 |
| 3.30522 | 11.9188 | 4.16252 | 11.4352 | 19.0967 | 0.637396 |

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| 3.37558 | 12.0315 | 4.16692 | 11.5329 | 19.1356 | 0.559578 |
| ---: | ---: | ---: | ---: | ---: | ---: |
| 3.44647 | 12.1435 | 4.17032 | 11.6306 | 19.1736 | 0.480983 |
| 3.51787 | 12.2546 | 4.17274 | 11.7283 | 19.2108 | 0.401615 |
| 3.58979 | 12.3651 | 4.17417 | 11.8261 | 19.247 | 0.321474 |
| 3.66222 | 12.4748 | 4.17461 | 11.9239 | 19.2824 | 0.240565 |
| 3.73515 | 12.5838 | 4.17408 | 12.0218 | 19.3169 | 0.158888 |
| 3.80858 | 12.692 | 4.17256 |  |  |  |
| 3.8825 | 12.7994 | 4.17007 |  |  |  |
| 3.9569 | 12.9061 | 4.16661 |  |  |  |

[G]

| 17.0 | 52.4 | 17.4 | 44.8 |
| :--- | :--- | :--- | :--- |
| 16.6 | 53.6 | 17.2 | 44.5 |
| 15.8 | 55.8 | 17.5 | 44.3 |
| 14.7 | 57.1 | 17.1 | 44.2 |
| 17.1 | 51.7 | 17.5 | 43.9 |
| 17.4 | 51.5 | 17.2 | 43.8 |
| 17.4 | 50.9 | 17.1 | 43.4 |
| 17.6 | 49.9 | 17.4 | 43.5 |
| 17.6 | 48.8 | 17.5 | 43.2 |
| 14.7 | 46.9 | 17.4 | 42.7 |
| 15.6 | 46.3 | 17.1 | 42.7 |
| 15.3 | 45.3 | 17.3 | 41.9 |
| 14.6 | 44.5 | 17.3 | 41.6 |
| 14.7 | 43.7 | 17.7 | 39.4 |
| 14.5 | 42.7 | 17.6 | 38.0 |
| 14.8 | 41.7 | 17.5 | 36.4 |
| 14.8 | 40.4 | 17.2 | 35.6 |
| 14.5 | 39.2 | 17.1 | 34.3 |
| 15.4 | 40.1 | 16.7 | 33.8 |
| 15.7 | 41.9 | 16.5 | 32.8 |
| 16.3 | 42.7 | 16.4 | 32.2 |
| 15.2 | 43.3 | 16.0 | 32.0 |
| 15.7 | 43.8 | 15.9 | 31.3 |
| 16.3 | 44.3 | 15.6 | 31.1 |
| 17.2 | 45.0 | 17.8 | 47.6 |

## [H]

\#include <cstdlib>

```
#include <fstream>
#include <math.h>
using namespace std;
ifstream fin("02.in");
ofstream fout("02.out");
int main(int argc, char *argv[])
{
    double a[50],b[50];
    int c[60][90];
    int i,j,k,n;
    for(i=0;i<50;i++)
        {
        fin>>a[i];
        fin>>b[i];
        }
        for(i=0;i<60;i++)
        {
        for(j=0;j<90;j++)
            {
        n=0;
            for(k=0;k<50;k++)
                {
                if(a[k]>i&&a[k]<=(i+1)&&b[k]>j&&b[k]<=(j+1)) n++;
                }
            c[i][j]=n;
            }
        }
            for(i=0;i<60;i++) fout<<i+0.5<<" ";
    fout<<endl<<endl;
    for(j=0;j<90;j++) fout<<j+0.5<<" ";
```

```
fout<<endl<<endl;
for(j=0;j<90;j++)
    {
    for(i=0;i<60;i++)
        {
        fout<<c[i][j]/50.0<<" ";
        }
        fout<<";";
        }
        return EXIT_SUCCESS;
```

\}

