# ON THE DISCRETE ORLICZ MINKOWSKI PROBLEM 

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#### Abstract

In this paper, we demonstrate the existence part of the discrete Orlicz Minkowski problem, which is a non-trivial extension of the discrete $L_{p}$ Minkowski problem for $0<p<1$.


## 1. Introduction

One of the cornerstones of the classical Brunn-Minkowski theory is the Minkowski problem. At the turn of the 19th into the 20th Century, Minkowski proposed this problem and solved the discrete case. The Minkowski problem was completely solved by Alexandrov [1], Fenchel and Jessen [12]. Analytic versions and algorithmic issues of this problem are still subject of current research and highly relevant (see, e.g., Chou and Wang [10], Jerison [26], Klain [27], and references therein).

In the middle of the last century, Firey (see [38] for references) extended Minkowski addition to $L_{p}$ Minkowski-Firey addtion. As a part of the $L_{p}$ Minkowski theorey, Lutwak [30] introduced the $L_{p}$ Minkowski problem. It asks for necessary and sufficient conditions on a Borel measure $\mu$ on $S^{n-1}$ to be the $L_{p}$ surface area measure of a convex body, i.e., is there a convex body $K$ such that

$$
h_{K}^{1-p} d S_{K}=d \mu ?
$$

[^0]Here, $h_{K}$ is the support function of $K$ and $S_{K}$ is the surface area measure of $K$. The solutions of the $L_{p}$ Minkowski problem have important applications to affine isoperimetric inequalities, see, e.g., Zhang [46], Lutwak, Yang and Zhang [33], Haberl and Schuster [18-20].

The even $L_{p}$ Minkowski problem for $p>1$ but $p \neq n$ was solved in [30]. An equivalent volume-normalized version of the $L_{p}$ Minkowksi problem was proposed in [34], and the even case was also solved for $p=$ $n$. A solution to the $L_{p}$ Minkowski problem for $p>n$ was given by Chou and Wang [11], in which they also solved the problem for polytopes for all $p>1$, while an alternate approach to this problem was presented by Hug et al [25]. Zhu [47-49], deal with the existence for the solution to the discrete $L_{p}$ Minkowski problem for $0 \leq p<1$ and $p=-n$. Other studies with respect to the $L_{p}$ Minkowski problem have also been extensively studied (see, e.g., $[5,8,9,22,35,39-41,43,50]$ ). Quite recently, Huang, Lutwak, Yang and Zhang [24] proposed the dual Minkowski problem and proved existence theorem. Since [24], a number of works on the dual Minkowski problem have appeared. Zhao [44], Böröczky, Henk and Pollehn [7] and Böröczky, Lutwak, Yang, Zhang, and Zhao [6] combined completely solved existence part of the even dual Minkowski problem when the index $q \in(1, n)$. Zhao [45] proved both the existence and the uniqueness of the solution to the dual Minkowski problem when $q<0$. Henk and Pollehn [21] showed a necessary condition for the even dual Minkowski problem when $q \geq$ $n+1$.

The Orlicz Brunn-Minkowski theory originated from the work of Lutwak, Yang, and Zhang in 2010, see [36,37], and the 2010 work of Ludwig [28] and Ludwig and Reitzner [29]. For the development of the Orlicz Brunn-Minkowski theory, see [14, 15,17, 28, 42]. Haberl, Lutwak, Yang and Zhang [17] first proposed the following Orlicz Minkowski problem: Given a suitable continuous function $\varphi:(0,+\infty) \rightarrow(0,+\infty)$ and a Borel measure $\mu$ on $S^{n-1}$, is there a convex body $K$ such that
for some $c>0$

$$
c \varphi\left(h_{K}\right) d S_{K}=d \mu ?
$$

Set $\varphi(t)=t^{1-p}(p \neq n)$, this problem reduces to the $L_{p}$ Minkowski problem.

The even Orlicz Minkowski problem was solved by Haberl, Lutwak, Yang and Zhang in [17] under some suitable conditions on $\varphi$. One of their results is:

Theorem 1.1. [17] Suppose $\varphi:(0, \infty) \rightarrow(0, \infty)$ is a continuous function such that $\phi(t)=\int_{o}^{t} \frac{1}{\varphi(s)} d s$ exists for every positive $t$ and is unbounded as $t \rightarrow \infty$, and $\mu$ is an even finite Borel measure on $S^{n-1}$ that is not concentrated on any great subsphere of $S^{n-1}$, then there exists an origin symmetric convex body $K \subset \mathbb{R}^{n}$ and $c>0$ such that $c \varphi\left(h_{K}\right) d S_{K}=d \mu$.

When $\varphi(t)=t^{1-p}, p>0$, we obtain the even $L_{p}$ Minkowski problem for $p>0$.

Later, the existence of the general Orlicz Minkowski problem without assuming that $\mu$ is an even measure was solved by Huang and He [23]. But besides the assumptions on $\varphi$ in [17], they assume that $\varphi(s)$ tends to infinity as $s \rightarrow 0^{+}$. As we can see, the $L_{p}$ Minkowski problem for $p>1$ is a special case of this result. However, the $L_{p}$ Minkowski problem for $0<p<1$ is not contained in this result.

In this paper, we aim to introduce a new version of Orlicz Minkowski problem for polytopes, which contains the discrete $L_{p}$ Minkowski problem for $0<p<1$.

Our main result can be formulated as follows:
Theorem 1.2. Suppose $\varphi:(0, \infty) \rightarrow(0, \infty)$ is continuously differentiable, strictly increasing and $\varphi(s)$ tends to 0 as $s \rightarrow 0^{+}$such that $\phi(t)=\int_{o}^{t} \frac{1}{\varphi(s)} d s$ exists for every positive $t$ and unbounded as $t \rightarrow$ $\infty$. If $\mu=\sum_{i=1}^{N} \alpha_{i} \delta_{u_{i}}$, where $\delta_{u_{i}}$ is Kronecker delta, $\alpha_{1}, \ldots, \alpha_{N}>$ 0 and $u_{1}, \ldots, u_{N} \in S^{n-1}$ are not contained in any closed hemisphere,
then there exists a polytope $P$ which contains the origin in its interior and $c>0$ such that

$$
\begin{equation*}
\mu=c \varphi(h(P, \cdot)) S(P, \cdot) . \tag{1.1}
\end{equation*}
$$

Let $\varphi(s)=s^{1-p}, 0<p<1$, we get Zhu's result in [47].
Corollary 1.3. Suppose vectors $u_{1}, \ldots, u_{N} \in S^{n-1}$ are not contained in any closed hemisphere, $\alpha_{1}, \ldots, \alpha_{N}>0$ and $\mu=\sum_{i=1}^{N} \alpha_{i} \delta_{u_{i}}$, where $\delta_{u_{i}}$ is Kronecker delta. If $0<p<1$, then there exists a polytope $P$ which contains the origin in its interior such that

$$
\mu=h(P, \cdot)^{1-p} S(P, \cdot)
$$

The work of Zhu [47] inspired us a lot. However, when it comes to the Orlicz case, the functional $\varphi$ may not be homogeneous, so it is difficult to show that the map $\xi_{\phi}\left(P_{r}\right)$ has a right derivative at $r=0$, which is needed to use the Lagrange multiplier rule. Thus, we need many new steps, for details, see section 4 . This paper is organized as follows: In section 2, we list some basic facts regarding convex bodies for quick reference. In section 3 , we give some properties about $\Phi_{P}(\xi)$. In section 4, we prove the differentiability of $\xi_{\phi}\left(P_{r}\right)$. The proof of Theorem 1.2 is presented in Section 5.

## 2. Preliminaries

In this section, we collect some terminologies and notations about convex bodies. We recommend the books of Gardner [13], Gruber [16], and Schneider [38] as excellent references on convex geometry.

For $x, y \in \mathbb{R}^{n}$, let $[x, y]=\{(1-\lambda) x+\lambda y: 0 \leq \lambda \leq 1\}$, and let $(x, y)=\{(1-\lambda) x+\lambda y: 0<\lambda<1\}$ when $x \neq y$. We also denote their inner product by $x \cdot y$ and the Euclidean norm of $x$ by $|x|=\sqrt{x \cdot x}$. The unit sphere $\left\{x \in \mathbb{R}^{n}:|x|=1\right\}$ is denoted by $S^{n-1}$. Let $V$ stand for $n$-dimensional Lebesgue measure, and $|\mu|=\mu\left(S^{n-1}\right)$ for a finite Borel measure $\mu$ on $S^{n-1}$.

A convex body is a compact convex set in $\mathbb{R}^{n}$ with nonempty interior. For a convex body $K$, the support function $h_{K}$ is defined by $h_{K}(u)=$ $h(K, u)=\max \{x \cdot u: x \in K\}$. We also denote $H_{u, t}=\left\{x \in \mathbb{R}^{n}:\right.$ $x \cdot u=t\}$ and $H_{u, t}^{-}=\left\{x \in \mathbb{R}^{n}: x \cdot u \leq t\right\}$. For $u \in S^{n-1}$, the support hyperplane $F(K, u)$ in direction $u$ is defined by

$$
F(K, u)=\left\{x \in \mathbb{R}^{n}: x \cdot u=h(K, u)\right\}
$$

the half-space $H^{-}(K, u)$ in direction $u$ is defined by

$$
H^{-}(K, u)=\left\{x \in \mathbb{R}^{n}: x \cdot u \leq h(K, u)\right\} .
$$

If the unit vectors $u_{1}, \ldots, u_{N}(N>n+1)$ are not contained in any closed hemisphere, we denote by $\mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$ a subset of polytopes, which satisfies

$$
P=\bigcap_{k=1}^{N} H^{-}\left(P, u_{k}\right), \forall P \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right) .
$$

It is easy to see that if $P \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$, then $P$ has at most $N$ facets, and the outer unit normals of $P$ are a subset of $\left\{u_{1}, \ldots, u_{N}\right\}$. Let $\mathcal{P}_{N}\left(u_{1}, \ldots, u_{N}\right)$ denote the subset of $\mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$ such that if $P \in \mathcal{P}_{N}\left(u_{1}, \ldots, u_{N}\right)$, then $P$ has exactly $N$ facets.

A point $z$ is said to be a vertex of a polytope $P$ if it can not be written in the form $z=(1-\lambda) x+\lambda y$ with $x, y \in P, x \neq y$, and $\lambda \in(0,1)$. The set of vertices of $P$ is denoted by vert $P$.

For a Borel set $\omega \subset S^{n-1}$, the surface area measure $S_{K}(\omega)$ of the convex body $K$ is the ( $n-1$ )-dimensional Hausdorff measure of the set of all boundary points of $K$ for which there exists a normal vector of $K$ belonging to $\omega$, i.e.,

$$
S_{K}(\omega)=\int_{x \in \nu_{K}^{-1}(\omega)} d \mathcal{H}^{n-1}(x)
$$

where $\nu_{K}: \partial^{\prime} K \rightarrow S^{n-1}$ is the Gauss map of $K$, defined on $\partial^{\prime} K$, the set of boundary points of K that have a unique outer unit normal, and $\mathcal{H}^{n-1}$ is $(n-1)$-dimensional Hausdorff measure. Observe that for the
surface area measure of $c K$ we have

$$
\begin{equation*}
S_{c K}=c^{n-1} S_{K}, c>0 \tag{2.1}
\end{equation*}
$$

Lemma 2.1. Suppose $\varphi:(0, \infty) \rightarrow(0, \infty)$ is differentiable, strictly increasing and $\varphi(s)$ tends to 0 as $s \rightarrow 0^{+}$such that $\phi(t)=\int_{o}^{t} \frac{1}{\varphi(s)} d s$ exists for every positive $t$. Let $\phi(0)=\lim _{t \rightarrow 0^{+}} \phi(t)$. Then

$$
\begin{equation*}
\phi^{\prime}(t)=\frac{1}{\varphi(t)} \text { for } t>0, \lim _{t \rightarrow 0^{+}} \frac{t}{\phi(t)-\phi(0)}=0 \tag{2.2}
\end{equation*}
$$

and $\phi$ is strictly concave on $[0, \infty)$.
Proof. The first equation of (2.2) is clear and the second follows from L'hopital's rule. Since $\varphi:(0, \infty) \rightarrow(0, \infty)$ is differentiable, strictly increasing, we have

$$
\begin{equation*}
\phi^{\prime \prime}=-\frac{\varphi^{\prime}}{\varphi^{2}}<0 . \tag{2.3}
\end{equation*}
$$

Thus $\phi$ is strictly concave on $(0, \infty)$. Then, for $\forall x, y \in(0, \infty)$,

$$
\begin{equation*}
\phi((1-\lambda) x+\lambda y)>(1-\lambda) \phi(x)+\lambda \phi(y), \forall \lambda \in(0,1) \tag{2.4}
\end{equation*}
$$

Let $x \rightarrow 0^{+}$, we have

$$
\begin{equation*}
\phi(\lambda y) \geq(1-\lambda) \phi(0)+\lambda \phi(y), \quad \forall \lambda \in(0,1) . \tag{2.5}
\end{equation*}
$$

These two inequalities (2.4) and (2.5) imply that $\phi$ is concave on $[0, \infty)$. We claim that $\phi$ is also strictly concave on $[0, \infty)$. If not, then there exist $\lambda^{\prime}, x^{\prime}$ with $0<\lambda^{\prime}<1, x^{\prime}>0$ such that

$$
\begin{equation*}
\phi\left(\lambda^{\prime} x^{\prime}\right)=\left(1-\lambda^{\prime}\right) \phi(0)+\lambda^{\prime} \phi\left(x^{\prime}\right) . \tag{2.6}
\end{equation*}
$$

Then for $\lambda^{\prime}<\mu<1$, by the concavity of $\phi$, we have

$$
\begin{equation*}
\phi\left(\lambda^{\prime} x^{\prime}\right)=\phi\left(\frac{\mu-\lambda^{\prime}}{\mu} \cdot 0+\frac{\lambda^{\prime}}{\mu} \mu x^{\prime}\right) \geq \frac{\mu-\lambda^{\prime}}{\mu} \phi(0)+\frac{\lambda^{\prime}}{\mu} \phi\left(\mu x^{\prime}\right) . \tag{2.7}
\end{equation*}
$$

Combining with (2.6), we have

$$
\phi\left(\mu x^{\prime}\right) \leq(1-\mu) \phi(0)+\mu \phi\left(x^{\prime}\right)
$$

Note that $\phi\left(\mu x^{\prime}\right)=\phi\left((1-\mu) \cdot 0+\mu x^{\prime}\right) \geq(1-\mu) \phi(0)+\mu \phi\left(x^{\prime}\right)$, thus,

$$
\begin{equation*}
\phi\left(\mu x^{\prime}\right)=(1-\mu) \phi(0)+\mu \phi\left(x^{\prime}\right) . \tag{2.8}
\end{equation*}
$$

From (2.6) and (2.8), it follows that

$$
\phi\left(\mu x^{\prime}\right)=\frac{1-\mu}{1-\lambda^{\prime}} \phi\left(\lambda^{\prime} x^{\prime}\right)+\frac{\mu-\lambda^{\prime}}{1-\lambda^{\prime}} \phi\left(x^{\prime}\right)
$$

which contradicts the fact that $\phi$ is strictly concave on $(0, \infty)$. Therefore, $\phi$ is strictly concave on $[0, \infty)$.

## 3. An extremal problem to the Orlicz Minkowski problem

Suppose that $\alpha_{1}, \ldots, \alpha_{N} \in \mathbb{R}^{+}$, the unit vectors $u_{1}, \ldots, u_{N}(N \geq n+$ 1) are not contained in any closed hemisphere and $P \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$. Now we define the function $\Phi_{P}: P \rightarrow \mathbb{R}$ by

$$
\begin{equation*}
\Phi_{P}(\xi)=\sum_{k=1}^{N} \alpha_{k} \phi\left(h\left(P, u_{k}\right)-\xi \cdot u_{k}\right) \tag{3.1}
\end{equation*}
$$

where $\phi$ is as described in Theorem 1.2 and $\phi(0):=\lim _{t \rightarrow 0^{+}} \phi(t)$.
In this section, we study the following extremal problem

$$
\begin{equation*}
\sup \left\{V(Q): \sup _{\xi \in Q} \Phi_{Q}(\xi)=1 \text { and } Q \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)\right\} \tag{3.2}
\end{equation*}
$$

Next, we will prove that $\Phi_{P}(\xi)$ is concave on $P$ and that there exists a unique $\xi_{\phi}(P) \in \operatorname{Int}(P)$ such that

$$
\Phi_{P}\left(\xi_{\phi}(P)\right)=\sup _{\xi \in P} \Phi_{P}(\xi)
$$

We want to prove that there exists a polytope with $u_{1}, \ldots, u_{N}$ as its outer unit normals and this polytope is a solution of problem (3.2). Now, we prove the concavity of $\Phi_{P}(\xi)$.

Lemma 3.1. If $\alpha_{1}, \ldots, \alpha_{N} \in \mathbb{R}^{+}$, the unit vectors $u_{1}, \ldots, u_{N}(N \geq$ $n+1)$ are not contained in any closed hemisphere, $\phi$ is strictly concave on $[0, \infty)$ and $P \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$, then $\Phi_{P}(\xi)$ is strictly concave on $P$.

Proof. Since $\phi$ is strictly concave on $[0, \infty)$. Then, for $0<\lambda<1$ and $\xi_{1}, \xi_{2} \in P$,

$$
\begin{aligned}
& \lambda \Phi_{P}\left(\xi_{1}\right)+(1-\lambda) \Phi_{P}\left(\xi_{2}\right) \\
= & \sum_{k=1}^{N} \alpha_{k}\left[\lambda \phi\left(h\left(P, u_{k}\right)-\xi_{1} \cdot u_{k}\right)+(1-\lambda) \phi\left(h\left(P, u_{k}\right)-\xi_{2} \cdot u_{k}\right)\right] \\
\leq & \sum_{k=1}^{N} \alpha_{k} \phi\left(h\left(P, u_{k}\right)-\left(\lambda \xi_{1}+(1-\lambda) \xi_{2}\right) \cdot u_{k}\right) \\
= & \Phi_{P}\left(\lambda \xi_{1}+(1-\lambda) \xi_{2}\right)
\end{aligned}
$$

with equality if and only if $\xi_{1} \cdot u_{k}=\xi_{2} \cdot u_{k}$ for all $k=1, \ldots, N$. Since $u_{1}, \ldots, u_{N}$ are not concentrated on any closed hemisphere, $\mathbb{R}^{n}=$ $\operatorname{Span}\left\{u_{1}, \ldots, u_{N}\right\}$. Thus, $\xi_{1}=\xi_{2}$. Therefore, $\Phi_{P}(\xi)$ is strictly concave on $P$.

Next we prove the existence and uniqueness of $\xi_{\phi}(P)$.
Lemma 3.2. Suppose $\alpha_{1}, \ldots, \alpha_{N} \in \mathbb{R}^{+}$, the unit vectors $u_{1}, \ldots, u_{N}(N \geq$ $n+1)$ are not concentrated on any closed hemisphere and $P \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$. If $\varphi:(0, \infty) \rightarrow(0, \infty)$ is differentiable, strictly increasing, $\varphi(s)$ tends to 0 as $s \rightarrow 0^{+}$such that $\phi(t)=\int_{o}^{t} \frac{1}{\varphi(s)} d s$ exists for every positive $t$ and unbounded as $t \rightarrow \infty$ and $\phi(0):=\lim _{t \rightarrow 0^{+}} \phi(t)$, then there exists a unique $\xi_{\phi}(P) \in \operatorname{Int}(P)$ such that

$$
\Phi_{P}\left(\xi_{\phi}(P)\right)=\max _{\xi \in P} \Phi_{P}(\xi)
$$

Proof. It follows from Lemma 2.1 and Lemma 3.1 that $\Phi_{P}(\xi)$ is strictly concave on $P$. Since $P$ is a compact convex set, there exists a unique $\xi_{\phi}(P) \in P$ such that

$$
\Phi_{P}\left(\xi_{\phi}(P)\right)=\max _{\xi \in P} \Phi_{P}(\xi)
$$

We next prove that $\xi_{\phi}(P) \in \operatorname{Int}(P)$. Otherwise, suppose $\xi_{\phi}(P) \in \partial P$ with

$$
h\left(P, u_{k}\right)-\xi_{\phi}(P) \cdot u_{k}=0
$$

for $k \in\left\{i_{1}, \ldots, i_{s}\right\}$ and

$$
h\left(P, u_{k}\right)-\xi_{\phi}(P) \cdot u_{k}>0
$$

for $k \in\{1, \ldots, N\} \backslash\left\{i_{1}, \ldots, i_{s}\right\}$, where $1 \leq i_{1} \leq \ldots \leq i_{s} \leq N$ and $1 \leq s \leq N-1$. Choose $x_{0} \in \operatorname{Int}(P)$. Let

$$
u_{0}=\frac{x_{0}-\xi_{\phi}(P)}{\left|x_{0}-\xi_{\phi}(P)\right|}
$$

and

$$
\begin{equation*}
\left[h\left(P, u_{k}\right)-\left(\xi_{\phi}(P)+\delta u_{0}\right) \cdot u_{k}\right]-\left[h\left(P, u_{k}\right)-\xi_{\phi}(P) \cdot u_{k}\right]=c_{k} \delta \tag{3.3}
\end{equation*}
$$

where $c_{k}=-u_{0} \cdot u_{k}$. Since $h\left(P, u_{k}\right)-\xi_{\phi}(P) \cdot u_{k}=0$ for $k \in\left\{i_{1}, \ldots, i_{s}\right\}$ and $x_{0}$ is an interior point of $P$, then $c_{k}=-u_{0} \cdot u_{k}>0$ for $k \in$ $\left\{i_{1}, \ldots, i_{s}\right\}$. Let

$$
c_{0}=\min \left\{h\left(P, u_{k}\right)-\xi_{\phi}(P) \cdot u_{k}: k \in\{1, \ldots, N\} \backslash\left\{i_{1}, \ldots, i_{s}\right\}\right\}>0,
$$

and choose $\delta>0$ small enough so that $\xi_{\phi}(P)+\delta u_{0} \in \operatorname{Int}(P)$ and

$$
\min \left\{h\left(P, u_{k}\right)-\left(\xi_{\phi}(P)+\delta u_{0}\right) \cdot u_{k}: k \in\{1, \ldots, N\} \backslash\left\{i_{1}, \ldots, i_{s}\right\}\right\}>\frac{c_{0}}{2}
$$

Since $\phi$ is differentiable, strictly increasing and concave (Lemma 2.1), for $x_{0}, x_{0}+\Delta x \in\left(\frac{c_{0}}{2}, \infty\right)$, we have

$$
\left|\phi\left(x_{0}+\Delta x\right)-\phi\left(x_{0}\right)\right|<\phi^{\prime}\left(\frac{c_{0}}{2}\right)|\Delta x| .
$$

From these two inequalities, $h\left(P, u_{k}\right)=\xi_{\phi}(P) \cdot u_{k}$ for $k \in\left\{i_{1}, \ldots, i_{s}\right\}$, $c_{k}>0$ for $k \in\left\{i_{1}, \ldots, i_{s}\right\}$ and equations (3.3), it follows that

$$
\begin{aligned}
& \Phi_{p}\left(\xi_{\phi}(P)+\delta u_{0}\right)-\Phi_{p}\left(\xi_{\phi}(P)\right) \\
= & \sum_{k=1}^{N} \alpha_{k}\left[\phi\left(h\left(P, u_{k}\right)-\left(\xi_{\phi}(P)+\delta u_{0}\right) \cdot u_{k}\right)-\phi\left(h\left(P, u_{k}\right)-\xi_{\phi}(P) \cdot u_{k}\right)\right] \\
\geq & -\sum_{k \in\{1, \ldots, N\} \backslash\left\{i_{1}, \ldots, i_{s}\right\}} \mid \phi\left(h\left(P, u_{k}\right)-\left(\xi_{\phi}(P)+\delta u_{0}\right) \cdot u_{k}\right) \\
& -\phi\left(h\left(P, u_{k}\right)-\xi_{\phi}(P) \cdot u_{k}\right) \mid+\sum_{k \in\left\{i_{1}, \ldots, i_{s}\right\}} \alpha_{k}\left(\phi\left(c_{k} \delta\right)-\phi(0)\right) \\
\geq & -\sum_{k \in\{1, \ldots, N\} \backslash\left\{i_{1}, \ldots, i_{s}\right\}} \alpha_{k} \phi^{\prime}\left(\frac{c_{0}}{2}\right)\left|c_{k} \delta\right|+\sum_{k \in\left\{i_{1}, \ldots, i_{s}\right\}} \alpha_{k}\left(\phi\left(c_{k} \delta\right)-\phi(0)\right) .
\end{aligned}
$$

Note that $\lim _{t \rightarrow 0^{+}} \frac{t}{\phi(t)-\phi(0)}=0$ (Lemma 2.1), then there exists a small enough $\delta_{0}>0$ such that $\xi_{\phi}(P)+\delta_{0} u_{0} \in \operatorname{Int}(P)$ and

$$
\Phi_{P}\left(\xi_{\phi}(P)+\delta_{0} u_{0}\right)>\Phi_{P}\left(\xi_{\phi}(P)\right)
$$

which contradicts the definition of $\xi_{\phi}(P)$. Therefore, the conclusion follows.

Note that, if $P_{i} \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$ and $P_{i}$ converges to a polytope $P$, then $P \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$. In order to use approximation, we need the following lemma.

Lemma 3.3. Suppose $\varphi:(0, \infty) \rightarrow(0, \infty)$ is differentiable, strictly increasing and $\varphi(s)$ tends to 0 as $s \rightarrow 0^{+}$such that $\phi(t)=\int_{o}^{t} \frac{1}{\varphi(s)} d s$ exists for every positive $t$ and unbounded as $t \rightarrow \infty$. If $\phi(0)=\lim _{t \rightarrow 0^{+}} \phi(t)$, $\alpha_{1}, \ldots, \alpha_{N} \in \mathbb{R}^{+}$, the unit vectors $u_{1}, \ldots, u_{N}(N \geq n+1)$ are not concentrated on any closed hemisphere, $P_{i} \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$ and $P_{i}$ converges to a polytope $P$, then $\lim _{i \rightarrow \infty} \xi_{\phi}\left(P_{i}\right)=\xi_{\phi}(P)$ and

$$
\lim _{i \rightarrow \infty} \Phi_{P_{i}}\left(\xi_{\phi}\left(P_{i}\right)\right)=\Phi_{P}\left(\xi_{\phi}(P)\right)
$$

Proof. By Lemma 3.2, $\xi_{\phi}\left(P_{i}\right)$ exists. Since $P_{i} \rightarrow P$ and $\xi_{\phi}\left(P_{i}\right) \in$ $\operatorname{Int}\left(P_{i}\right), \xi_{\phi}\left(P_{i}\right)$ is bounded. Suppose $\xi_{\phi}\left(P_{i}\right)$ does not converge to $\xi_{\phi}(P)$, then there exists a subsequence $P_{i_{j}}$ of $P_{i}$ such that $P_{i_{j}}$ converges to $P$, $\xi_{\phi}\left(P_{i_{j}}\right) \rightarrow \xi_{0}$ but $\xi_{0} \neq \xi_{\phi}(P)$. It follows from the continuity of $\phi$ that $\Phi_{P}(\xi)$ is continuous with respect to $P$ and $\xi$. Then by $\xi_{0} \in P$, we have

$$
\begin{aligned}
\lim _{j \rightarrow \infty} \Phi_{P_{i_{j}}}\left(\xi_{\phi}\left(P_{i_{j}}\right)\right) & =\Phi_{P}\left(\xi_{0}\right) \\
& <\Phi_{P}\left(\xi_{\phi}(P)\right) \\
& =\lim _{j \rightarrow \infty} \Phi_{P_{i_{j}}}\left(\xi_{\phi}(P)\right)
\end{aligned}
$$

which contradicts the fact that

$$
\Phi_{P_{i_{j}}}\left(\xi_{\phi}\left(P_{i_{j}}\right)\right) \geq \Phi_{P_{i_{j}}}\left(\xi_{\phi}(P)\right)
$$

Therefore, $\lim _{i \rightarrow \infty} \xi_{\phi}\left(P_{i}\right)=\xi_{\phi}(P)$. Thus,

$$
\lim _{i \rightarrow \infty} \Phi_{P_{i}}\left(\xi_{\phi}\left(P_{i}\right)\right)=\Phi_{P}\left(\xi_{\phi}(P)\right)
$$

For convex body $K$ in $\mathbb{R}^{n}$, we define

$$
R(K)=\max _{x \in K}|x| .
$$

The following lemma is needed to prove the boundness.

Lemma 3.4. Suppose $\phi:[0, \infty) \rightarrow[0, \infty)$ is continuous, strictly increasing and $\phi(t)$ tends to infinity as $t \rightarrow \infty$. If $\alpha_{1}, \ldots, \alpha_{N} \in \mathbb{R}^{+}$, the unit vectors $u_{1}, \ldots, u_{N}(N \geq n+1)$ are not concentrated on any closed hemisphere, $P_{k} \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$, $o \in P_{k}$, and $R\left(P_{k}\right)$ is not bounded, then

$$
\sum_{i=1}^{N} \alpha_{i} \phi\left(h\left(P_{k}, u_{i}\right)\right)
$$

is not bounded.

Proof. By taking subsequences, we can assume

$$
\begin{equation*}
\lim _{k \rightarrow \infty} R\left(P_{k}\right)=\infty \tag{3.4}
\end{equation*}
$$

Let

$$
h_{+}(t)=\max \{0, t\}, f(u)=\sum_{i=1}^{N} \alpha_{i} \phi\left(h_{+}\left(u_{i} \cdot u\right)\right),
$$

where $t \in \mathbb{R}, u \in S^{n-1}$.
Since $u_{1}, \ldots, u_{N}$ are not contained in any closed hemisphere, $\mathbb{R}^{n}=$ $\operatorname{Span}\left\{u_{1}, \ldots, u_{N}\right\}$. Thus, for $u \in S^{n-1}$ there exists $i \in\{1, \ldots, N\}$ such that $h_{+}\left(u_{i} \cdot u\right)>0$, then we have $f(u)>0$ for all $u \in S^{n-1}$. Note that $\max \left\{h_{+}\left(u_{i} \cdot u\right): i \in\{1, \ldots, N\}\right\}$ is a continuous function on $S^{n-1}$. Thus, there exists a constant $a_{0}>0$ such that

$$
\begin{equation*}
\max \left\{h_{+}\left(u_{i} \cdot u\right): i \in\{1, \ldots, N\}\right\}>a_{0}, \text { for all } u \in S^{n-1} \tag{3.5}
\end{equation*}
$$

Suppose $\sum_{i=1}^{N} \alpha_{i} \phi\left(h\left(P_{k}, u_{i}\right)\right)$ is bounded, then there exists $M \in \mathbb{R}$ such that

$$
\phi\left(h\left(P_{k}, u_{i}\right)\right)<M, \text { for all } i \in\{1, \ldots, N\} .
$$

Since $\phi$ is continuous, strictly increasing and $\phi(t)$ tends to infinity as $t \rightarrow \infty$, there exists a unique $t_{0} \in \mathbb{R}^{+}$such that $\phi\left(t_{0}\right)=M$. Together with $\phi\left(h\left(P_{k}, u_{i}\right)\right)<M$, we have

$$
\begin{equation*}
t_{0}>h\left(P_{k}, u_{i}\right), \forall i \in\{1, \ldots, N\} \tag{3.6}
\end{equation*}
$$

Choose $v_{k} \in S^{n-1}$ such that $R\left(P_{k}\right) v_{k} \in P_{k}$. Since $o \in P_{k}$,

$$
\left.h\left(P_{k}, u_{i}\right)\right) \geq h_{+}\left(R\left(P_{k}\right) v_{k} \cdot u_{i}\right)=R\left(P_{K}\right) h\left(u_{i} \cdot v_{k}\right)
$$

Together with (3.6) and (3.5), we have

$$
t_{0}>R\left(P_{k}\right) \max _{i} h\left(u_{i} \cdot v_{k}\right)>R\left(P_{k}\right) a_{0},
$$

which contradicts (3.4). Thus $\sum_{i=1}^{N} \alpha_{i} \phi\left(h\left(P_{k}, u_{i}\right)\right)$ is unbounded.

## 4. THE DIFFERENTIABILITY OF $\xi_{\phi}\left(P_{r}\right)$

In fact, Lemma 3.4 guarantees that there exists a polytope $P$ that solves (3.2). See Lemma 4.9 for details. In this section, Let $\delta_{m}^{k}$ be Kronecker delta. This means if $k=m$, then $\delta_{m}^{k}=1$, otherwise, $\delta_{m}^{k}=0$. We want to prove that $P$ has exactly $N$ faces. If $P \in \mathcal{P}_{\mathcal{N}}\left(u_{1}, \ldots, u_{N}\right)$, then the differentiability of $\xi_{\phi}\left(P_{r}\right)$ is easy. See the following two lemmas.

Lemma 4.1. Suppose the unit vectors $u_{1}, \ldots, u_{N}(N \geq n+1)$ are not concentrated on any closed hemisphere. Let $P \in \mathcal{P}_{\mathcal{N}}\left(u_{1}, \ldots, u_{N}\right)$ and

$$
P_{r}=\bigcap_{k=1}^{N}\left\{x: x \cdot u_{k} \leq h\left(P, u_{k}\right)-r \delta_{m}^{k}\right\},
$$

where $m \in\{1,2, \ldots, N\}$. Then there exists a number $r_{0}>0$ such that $h\left(P_{r}, u_{k}\right)=h\left(P, u_{k}\right)-r \delta_{m}^{k}$ for every $|r|<r_{0}$.

Proof. Since $P \in \mathcal{P}_{\mathcal{N}}\left(u_{1}, \ldots, u_{N}\right)$, by Lemma 2.4.13 in [38], one can choose $r_{0}>0$, such that $P_{r}$ has exactly $N$ facets for $|r|<r_{0}$, which implies $h\left(P_{r}, u_{k}\right)=h\left(P, u_{k}\right)-r \delta_{m}^{k}$.

Lemma 4.2. Suppose $\varphi:(0, \infty) \rightarrow(0, \infty)$ is continuously differentiable, strictly increasing and $\varphi(s)$ tends to 0 as $s \rightarrow 0^{+}$such that $\phi(t)=$ $\int_{o}^{t} \frac{1}{\varphi(s)} d s$ exists for every positive $t$. If $\phi(0)=\lim _{t \rightarrow 0^{+}} \phi(t), \alpha_{1}, \ldots, \alpha_{N} \in$
$\mathbb{R}^{+}$, the unit vectors $u_{1}, \ldots, u_{N}(N \geq n+1)$ are not concentrated on any closed hemisphere, $P \in \mathcal{P}_{N}\left(u_{1}, \ldots, u_{N}\right)$ and $|r|$ small enough such that

$$
P_{r}=\bigcap_{k=1}^{N}\left\{x: x \cdot u_{k} \leq h\left(P, u_{k}\right)-r \delta_{m}^{k}\right\} \in \mathcal{P}_{N}\left(u_{1}, \ldots, u_{N}\right),
$$

where $m \in\{1,2, \ldots, N\}$. Then there exists a number $r_{0}>0$ such that $\xi(r)=\xi_{\phi}\left(P_{r}\right)$ is continuously differentiable with respect to $r$ in $\left(-r_{0}, r_{0}\right)$.

Proof. Let $\xi(r)=\xi_{\phi}\left(P_{r}\right)$ and

$$
\begin{aligned}
\Phi(r) & =\max _{\xi \in P_{r}} \sum_{k=1}^{N} \alpha_{k} \phi\left(h\left(P_{r}, u_{k}\right)-\xi \cdot u_{k}\right) \\
& =\sum_{k=1}^{N} \alpha_{k} \phi\left(h\left(P_{r}, u_{k}\right)-\xi(r) \cdot u_{k}\right) .
\end{aligned}
$$

From this and the fact $\xi(r)$ is an interior point of $P_{r}$, we have

$$
\begin{equation*}
\sum_{k=1}^{N} \alpha_{k} \phi^{\prime}\left(h\left(P_{r}, u_{k}\right)-\xi(r) \cdot u_{k}\right) u_{k, i}=0 \tag{4.1}
\end{equation*}
$$

for $i=1, \ldots, n$, where $u_{k}=\left(u_{k, 1}, \ldots, u_{k, n}\right)^{T}$.
Next, we use the inverse function theorem to prove the conclusion. Let $\xi_{0}=\xi(0)$ and

$$
F_{i}\left(r, \xi_{1}, \ldots, \xi_{n}\right)=\sum_{k=1}^{N} \alpha_{k} \phi^{\prime}\left(h\left(P_{r}, u_{k}\right)-\xi \cdot u_{k}\right) u_{k, i}
$$

where $i \in\{1, \ldots, n\}$ and $\xi=\left(\xi_{1}, \ldots, \xi_{n}\right)$. Since $P \in \mathcal{P}_{N}\left(u_{1}, \ldots, u_{N}\right)$, by Lemma 4.1, we have $h\left(P_{r}, u_{k}\right)=h\left(P, u_{k}\right)-r \delta_{m}^{k}$. Then,

$$
\begin{aligned}
\frac{\partial F_{i}}{\partial r} & =-\alpha_{m} \phi^{\prime \prime}\left(h\left(P, u_{m}\right)-r-\xi \cdot u_{m}\right) u_{m, i} \text { and } \\
\frac{\partial F_{i}}{\partial \xi_{j}} & =-\sum_{k=1}^{N} \alpha_{k} \phi^{\prime \prime}\left(h\left(P_{r}, u_{k}\right)-\xi \cdot u_{k}\right) u_{k, i} u_{k, j}
\end{aligned}
$$

are obviously continuous.

Let $r=0$, then, the Jacobian matrix of $F:=\left(F_{1}, \ldots, F_{N}\right)$ at $\xi_{0}$ equals

$$
\left(\left.\frac{\partial F}{\partial \xi_{j}}\right|_{\xi_{0}}\right)_{n \times n}=-\sum_{k=1}^{N} \alpha_{k} \phi^{\prime \prime}\left(h\left(P, u_{k}\right)-\xi_{0} \cdot u_{k}\right) u_{k} \cdot u_{k}^{T},
$$

where $u_{k} u_{k}^{T}$ is an $n \times n$ matrix.
Since $u_{1}, \ldots, u_{N}$ are not contained in any closed hemisphere, $\mathbb{R}^{n}=$ $\operatorname{Span}\left\{u_{1}, \ldots, u_{N}\right\}$. Thus, for any $x \in \mathbb{R}^{n}$ with $x \neq 0$, there exists a $u_{i_{m}} \in\left\{u_{1}, \ldots, u_{N}\right\}$ such that $u_{i_{m}} \cdot x \neq 0$. Together with the fact that $\phi$ is twice differentiable and strictly concave, we have

$$
\begin{aligned}
& x^{T} \cdot\left(-\sum_{k=1}^{N} \alpha_{k} \phi^{\prime \prime}\left(h\left(P, u_{k}\right)-\xi_{0} \cdot u_{k}\right) u_{k} \cdot u_{k}^{T}\right) \cdot x \\
= & -\sum_{k=1}^{N} \alpha_{k} \phi^{\prime \prime}\left(h\left(P, u_{k}\right)-\xi_{0} \cdot u_{k}\right)\left(x \cdot u_{k}\right)^{2} \\
\geq & -\alpha_{i_{m}} \phi^{\prime \prime}\left(h\left(P, u_{i_{m}}\right)-\xi_{0} \cdot u_{k}\right)\left(x \cdot u_{i_{m}}\right)^{2}>0 .
\end{aligned}
$$

Thus, $\left(\left.\frac{\partial F}{\partial \xi_{j}}\right|_{\left(0, \xi_{0}\right)}\right)$ is positive definite. From this, equation (4.1), the inverse function theorem and the fact that $F_{i}$ has continuous partial derivative for $\xi$ and $r$, the conclusion follows.

Remark 4.1. For $t>0$, by a similar method in Lemma 4.2, we have $\xi_{\phi}(t P)$ is continuously differentiable in a small neighborhood of $t$. Thus, $\xi_{\phi}(t P)$ is continuous for every $t>0$. Therefore, $\Phi_{t P}\left(\xi_{\phi}(t P)\right)$ is continuous for $t>0$.

In order to prove that every polytope which solves (3.2) has exactly $N$ faces, we need one-sided differentiability of $\xi_{\phi}\left(P_{r}\right)$ for $P \in$ $\mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$. First, we study the property of $h\left(P_{r}, u_{k}\right)$, for which the following three lemmas are prepared.

Lemma 4.3. Let $P$ be a polytope, then for every $u \in \mathbb{S}^{n-1}, F(P, u)$ is the convex hull of the set $\operatorname{vert} P \cap F(P, u)$, where $\operatorname{vert} P$ denotes the vertices of $P$.

Proof. If $y \in F(P, u)$, then it can be expressed by

$$
y=\sum_{i=1}^{m} a_{i} y_{i}, \text { where } y_{i} \in \operatorname{vert} P
$$

where $0<a_{i} \leq 1$ and $\sum a_{i}=1$.
Note that $y \cdot u=h(P, u)$ and $y_{i} \cdot u \leq h(P, u)$. We have $y_{i} \cdot u=h(P, u)$ for $1 \leq i \leq m$. Thus, the conclusion follows.

Lemma 4.4. Let $P$ be a polytope, $u \in \mathbb{S}^{n-1}$. Then there exists a real number $r^{\prime}>0$ such that

$$
P \cap H_{u, h(P, u)-r} \subset \operatorname{conv}\left\{F(P, u) \cup\left(P \cap H_{u, h(P, u)-r^{\prime}}\right)\right\}, \forall r \in\left(0, r^{\prime}\right) .
$$

Proof. We can choose $r^{\prime}>0$ small enough such that

$$
z \cdot u<h(P, u)-r^{\prime}, \forall z \in \operatorname{vert} P / F(P, u)
$$

Let $0<r<r^{\prime}$ and $x \in P \cap H_{u, h(P, u)-r}$, then $x$ has the following representation

$$
x=\sum_{i=1}^{p} a_{i} y_{i}+\sum_{j=1}^{q} b_{j} z_{j}, \sum_{i=1}^{p} a_{i}+\sum_{j=1}^{q} b_{j}=1,
$$

where $0<a_{i}, b_{j}<1, p, q \in \mathbb{N}, y_{i} \in F(P, u), z_{j} \in \operatorname{vert} P / F(P, u)$ and $z_{j} \cdot u<h(P, u)-r^{\prime}$.

We may write

$$
x=\lambda \sum_{i=1}^{p} \frac{a_{i}}{\lambda} y_{i}+(1-\lambda) \sum_{j=1}^{q} \frac{b_{j}}{1-\lambda} z_{j}, \lambda:=\sum_{i=1}^{p} a_{i} .
$$

Note that

$$
\left(\sum_{i=1}^{p} \frac{a_{i}}{\lambda} y_{i}\right) \cdot u=h(P, u),\left(\sum_{j=1}^{q} \frac{b_{j}}{1-\lambda} z_{j}\right) \cdot u<h(P, u)-r^{\prime} .
$$

Thus, we can choose a point

$$
z \in\left(\sum_{i=1}^{p} \frac{a_{i}}{\lambda} y_{i}, \sum_{j=1}^{q} \frac{b_{j}}{1-\lambda} z_{j}\right) \subset P
$$

such that

$$
z \cdot u=h(P, u)-r^{\prime} .
$$

Combining with $x \in P \cap H_{u, h(P, u)-r}$, we have $x \in\left[\sum_{i=1}^{p} \frac{a_{i}}{\lambda} y_{i}, z\right]$, which is equivalent to the assertion of the lemma.

Lemma 4.5. Suppose the unit vectors $u_{1}, \ldots, u_{N}(N \geq n+1)$ are not concentrated on any closed hemisphere. Let $P \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right), r^{\prime}>0$ and

$$
P_{r}=\bigcap_{k=1}^{N}\left\{x: x \cdot u_{k} \leq h\left(P, u_{m}\right)-r \delta_{m}^{k}\right\}
$$

such that $h\left(P_{r}, u_{m}\right)=h\left(P, u_{m}\right)-r$ for $0 \leq r \leq r^{\prime}$, where $m \in$ $\{1,2, \ldots, N\}$. Then there exists a number $r_{m}$ with $0<r_{m}<r^{\prime}$ such that
i) $\operatorname{vert} P_{r} \cap F\left(P_{r}, u_{m}\right) \subset\left\{(1-\lambda) y+\lambda z: y \in \operatorname{vert} P \cap F\left(P, u_{m}\right), z \in\right.$ $\left.\operatorname{vert} P_{r_{m}} \cap F\left(P_{r_{m}}, u_{m}\right)\right\}$, where $r \in\left(0, r_{m}\right)$ and $\lambda=\frac{r}{r_{m}}$.
ii) $F\left(P_{r}, u_{m}\right)=\left\{(1-\lambda) y+\lambda z: y \in \operatorname{vert} P \cap F\left(P, u_{m}\right), z \in \operatorname{vert} P_{r_{m}} \cap\right.$ $\left.F\left(P_{r_{m}}, u_{m}\right)\right\}$, where $r \in\left(0, r_{m}\right)$ and $\lambda=\frac{r}{r_{m}}$.

Proof. Since $h\left(P_{r}, u_{m}\right)=h\left(P, u_{m}\right)-r$ for $0 \leq r \leq r^{\prime}$, then $F\left(P_{r}, u_{m}\right)=$ $P \cap H_{u_{m}, h\left(P, u_{m}\right)-r}$ for $0 \leq r \leq r^{\prime}$. Thus, by Lemma 4.4, there exists a number $r_{m}$ with $0<r_{m}<r^{\prime}$ such that

$$
\begin{equation*}
F\left(P_{r}, u_{m}\right) \subset \operatorname{conv}\left\{F\left(P, u_{m}\right) \cup\left(F\left(P_{r_{m}}, u_{m}\right)\right)\right\}, \forall r \in\left(0, r_{m}\right) \tag{4.2}
\end{equation*}
$$

For i), let $x \in \operatorname{vert} P_{r} \cap F\left(P_{r}, u_{m}\right)$, by (4.2) and Lemma 4.3, it can be expressed as

$$
x=\sum_{i=1}^{p} b_{i} y_{i}+\sum_{j=1}^{q} c_{j} z_{j}
$$

where $p, q \in \mathbb{N}, 0<b_{i}, c_{j}<1, \sum b_{i}=1-\lambda, \sum c_{j}=\lambda, \lambda=\frac{r}{r_{m}}$ and $y_{i} \in \operatorname{vert} P \cap F\left(P, u_{m}\right), z_{j} \in \operatorname{vert} P_{r_{m}} \cap F\left(P_{r_{m}}, u_{m}\right)$. If $p=q=1$, the assertion is clear. Otherwise, we can rewrite $x$ as

$$
\begin{aligned}
x & =\sum_{i=1}^{p} \frac{b_{i}}{1-\lambda}(1-\lambda) y_{i}+\sum_{j=1}^{q} \frac{c_{j}}{\lambda} \lambda z_{j} \\
& =\sum_{i, j} \frac{b_{i} c_{j}}{(1-\lambda) \lambda}\left((1-\lambda) y_{i}+\lambda z_{j}\right),
\end{aligned}
$$

where $\sum_{i, j} \frac{b_{i} c_{j}}{(1-\lambda) \lambda}=1$. This contradicts the fact $x \in \operatorname{vert} P_{r}$, since $(1-\lambda) y_{i}+\lambda z_{j} \in F\left(P_{r}, u_{m}\right) \subset P_{r}$.

The assertion ii) follows from i), Lemma 4.3 and $((1-\lambda) y+\lambda z) \cdot u_{m}=$ $h\left(P, u_{m}\right)-r, \forall y \in \operatorname{vert} P \cap F\left(P, u_{m}\right), \forall z \in \operatorname{vert} P_{r_{m}} \cap F\left(P_{r_{m}}, u_{m}\right)$, where $\lambda=\frac{r}{r_{m}}$.

Now, we prove the property of $h\left(P_{r}, u_{k}\right)$ for $P \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$.
Lemma 4.6. Suppose the unit vectors $u_{1}, \ldots, u_{N}(N \geq n+1)$ are not concentrated on any closed hemisphere. Let $P \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$ and

$$
P_{r}=\bigcap_{k=1}^{N}\left\{x: x \cdot u_{k} \leq h\left(P, u_{k}\right)-r \delta_{m}^{k}\right\},
$$

where $m \in\{1,2, \ldots, N\}$. Then there exists a number $r_{0}>0$ such that for $0 \leq r \leq r_{0}$,

$$
h\left(P_{r}, u_{k}\right)=\left\{\begin{array}{l}
h\left(P, u_{k}\right)-r, \text { if } k=m \\
h\left(P, u_{k}\right)-a_{k} r, \text { if } k \neq m
\end{array}\right.
$$

where $a_{k}$ is a constant with $a_{k} \geq 0$.
Proof. We first prove $h\left(P_{r}, u_{m}\right)=h\left(P, u_{m}\right)-r$ for small enough $r$. Let $x \in \operatorname{vert} P \cap F\left(P, u_{m}\right)$. Suppose that

$$
h\left(P, u_{k}\right)=x \cdot u_{k}
$$

for $k \in\left\{m, i_{1}, \ldots, i_{s}\right\}$ and

$$
\begin{equation*}
h\left(P, u_{k}\right)>x \cdot u_{k} \tag{4.3}
\end{equation*}
$$

for $k \in\{1, \ldots, N\} \backslash\left\{m, i_{1}, \ldots, i_{s}\right\}$, where $1 \leq i_{1} \leq \ldots \leq i_{s} \leq N$ and $1 \leq s \leq N-1$.

Note that the set $\left\{u_{k}: k \in\left\{m, i_{1}, i_{2} \ldots, i_{s}\right\}\right\}$ is contained in an open hemisphere. Thus, we can choose a unit vector $u_{0}$ such that

$$
\begin{equation*}
u_{0} \cdot u_{k}>0, \forall k \in\left\{m, i_{1}, i_{2} \ldots, i_{s}\right\} . \tag{4.4}
\end{equation*}
$$

By (4.3), there exists a number $r^{\prime}>0$ such that

$$
\begin{equation*}
h\left(P, u_{k}\right)>\left(x-\frac{r}{u_{0} \cdot u_{m}} u_{0}\right) \cdot u_{k} \tag{4.5}
\end{equation*}
$$

for $\forall 0 \leq r \leq r^{\prime}$ and $\forall k \in\{1, \ldots, N\} \backslash\left\{m, i_{1}, \ldots, i_{s}\right\}$. It follows from (4.4) and (4.5) that

$$
\left(x-\frac{r}{u_{0} \cdot u_{m}} u_{0}\right) \cdot u_{k} \leq h\left(P, u_{k}\right)-r \delta_{m}^{k}, \forall k \in\{1, \ldots, N\} .
$$

Hence

$$
x-\frac{r}{u_{0} \cdot u_{m}} u_{0} \in P_{r} \text { and }\left(x-\frac{r}{u_{0} \cdot u_{m}} u_{0}\right) \cdot u_{m}=h\left(P, u_{m}\right)-r \text {. }
$$

This implies

$$
\begin{equation*}
h\left(P_{r}, u_{m}\right)=h\left(P, u_{m}\right)-r \text { for } \forall 0 \leq r \leq r^{\prime} . \tag{4.6}
\end{equation*}
$$

Now, we turn to deal with the case $k \neq m$. If $F\left(P, u_{k}\right) \not \subset F\left(P, u_{m}\right)$, then there exists $x_{k} \in F\left(P, u_{k}\right)$ such that

$$
x_{k} \cdot u_{k}=h\left(P, u_{k}\right) \text { but } x_{k} \cdot u_{m}<h\left(P, u_{m}\right) .
$$

Then there exists a number $r_{k}$ such that $x_{k} \cdot u_{m}<h\left(P, u_{m}\right)-r$ for $r<r_{k}$. This implies $x_{k} \in P_{r}$ for $r<r_{k}$ and

$$
\begin{equation*}
h\left(P_{r}, u_{k}\right)=x_{k} \cdot u_{k}=h\left(P, u_{k}\right) \tag{4.7}
\end{equation*}
$$

If $F\left(P, u_{k}\right) \subset F\left(P, u_{m}\right)$, we claim that $F\left(P_{r}, u_{k}\right) \subset F\left(P_{r}, u_{m}\right)$ for small enough $r$. In fact, let $x \in P_{r} \backslash F\left(P_{r}, u_{m}\right)$. By (4.6), we have

$$
h\left(P, u_{m}\right)-r=h\left(P_{r}, u_{m}\right)>x \cdot u_{m}
$$

which implies $x \notin F\left(P, u_{m}\right)$. Thus, $x \notin F\left(P, u_{k}\right)$, that is, $x \cdot u_{k}<$ $h\left(P, u_{k}\right)$.

Let $y \in F\left(P, u_{k}\right) \subset F\left(P, u_{m}\right)$, then

$$
y \cdot u_{m}-r>x \cdot u_{m}, \quad \text { and } \quad y \cdot u_{k}>x \cdot u_{k} .
$$

Then, there exists a point $z_{r} \in(x, y)$, such that

$$
y \cdot u_{m}-r>z_{r} \cdot u_{m}, \quad \text { and } \quad z_{r} \cdot u_{k}>x \cdot u_{k} .
$$

Thus, $z_{r} \in P_{r}$ and $h\left(P_{r}, u_{k}\right) \geq z_{r} \cdot u_{k}>x \cdot u_{k}$. This implies $x \notin F\left(P_{r}, u_{k}\right)$, and hence the claim is clear.

Using the claim, and Lemma 4.5 with (4.6), we can choose an $0<$ $r_{0}<r^{\prime}$ such that

$$
\begin{array}{r}
F\left(P_{r}, u_{m}\right)=\left\{(1-\lambda) y+\lambda z: y \in \operatorname{vert} P \cap F\left(P, u_{m}\right),\right. \\
\left.z \in \operatorname{vert} P_{r_{0}} \cap F\left(P_{r_{0}}, u_{m}\right)\right\}, \tag{4.8}
\end{array}
$$

and

$$
\begin{equation*}
F\left(P_{r}, u_{k}\right) \subset F\left(P_{r}, u_{m}\right) \text { if } F\left(P, u_{k}\right) \subset F\left(P, u_{m}\right) \tag{4.9}
\end{equation*}
$$

where $r \in\left(0, r_{0}\right)$ and $\lambda=\frac{r}{r_{0}}$.
For any $r \in\left(0, r_{0}\right)$, by (4.9), there exists $x_{k} \in \operatorname{vert} P_{r} \cap F\left(P_{r}, u_{m}\right)$ such that $h\left(P_{r}, u_{k}\right)=x_{k} \cdot u_{k}$. By the definition of support function, $h\left(P_{r}, u_{k}\right)=$ $\sup \left\{x \cdot u_{k}: x \in F\left(P_{r}, u_{m}\right)\right.$. By (4.8), we have $h\left(P_{r}, u_{k}\right)=\{((1-\lambda) y+$ $\left.\lambda z) \cdot u_{k}: y \in \operatorname{vert} P \cap F\left(P, u_{m}\right), z \in \operatorname{vert} P_{r_{0}} \cap F\left(P_{r_{0}}, u_{m}\right)\right\}$.

Together with $F\left(P, u_{k}\right) \subset F\left(P, u_{m}\right)$ and $F\left(P_{r_{0}}, u_{k}\right) \subset F\left(P_{r_{0}}, u_{m}\right)$, it follows that

$$
h\left(P_{r}, u_{k}\right)=(1-\lambda) h\left(P, u_{k}\right)+\lambda h\left(P_{r_{0}}, u_{k}\right),
$$

which is equivalent to

$$
\begin{equation*}
h\left(P_{r}, u_{k}\right)=h\left(P, u_{k}\right)-a_{k} r, \tag{4.10}
\end{equation*}
$$

where $a_{k}=\frac{h\left(P, u_{k}\right)-h\left(P_{r_{0}}, u_{k}\right)}{r_{0}} \geq 0$.
The conclusion follows from (4.6), (4.7) and (4.10).
With tackle in hand, now, we aim to prove that $\xi_{\phi}\left(P_{r}\right)$ has one-sided derivative at 0 for $P \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$.

Lemma 4.7. Suppose $\varphi:(0, \infty) \rightarrow(0, \infty)$ is continuously differentiable, strictly increasing and $\varphi(s)$ tends to 0 as $s \rightarrow 0^{+}$such that $\phi(t)=$ $\int_{o}^{t} \frac{1}{\varphi(s)} d s$ exists for every positive $t$. Assume that $\phi(0)=\lim _{t \rightarrow 0^{+}} \phi(t)$, $\alpha_{1}, \ldots, \alpha_{N} \in \mathbb{R}^{+}$, the unit vectors $u_{1}, \ldots, u_{N}(N \geq n+1)$ are not concentrated on any closed hemisphere, $P \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$ and $r \geq 0$ small enough such that

$$
P_{r}=\bigcap_{k=1}^{N}\left\{x: x \cdot u_{k} \leq h\left(P, u_{k}\right)-r \delta_{m}^{k}\right\} \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right),
$$

where $m \in\{1,2, \ldots, N\}$. If the continuous function $\lambda:[0, \infty) \rightarrow$ $(0, \infty)$ is continuously differentiable on $(0, \infty)$ and $\lim _{r \rightarrow 0} \lambda^{\prime}(r)$ exists, then $\xi_{\phi}\left(\lambda(r) P_{r}\right)$ has right derivative at 0 .

Proof. Let $F=\left(F_{1}, \ldots, F_{n}\right)$ and

$$
\begin{equation*}
F_{i}\left(r, \xi_{1}, \ldots, \xi_{n}\right)=\sum_{k=1}^{N} \alpha_{k} \phi^{\prime}\left(h\left(\lambda(r) P_{r}, u_{k}\right)-\xi \cdot u_{k}\right) u_{k, i}, \tag{4.11}
\end{equation*}
$$

where $i \in\{1, \ldots, n\}$ and $\xi=\left(\xi_{1}, \ldots, \xi_{n}\right)$. Since $P \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$, by Lemma 4.6, for small enough $r \geq 0$, we have

$$
h\left(\lambda(r) P_{r}, u_{k}\right)=\left\{\begin{array}{c}
\lambda(r) h\left(P, u_{k}\right)-\lambda(r) r, \text { if } k=m  \tag{4.12}\\
\lambda(r) h\left(P, u_{k}\right)-a_{k} \lambda(r) r, \text { if } k \neq m
\end{array}\right.
$$

where $a_{k}$ is a constant with $a_{k} \geq 0$.
By a similar method in Lemma 4.2 and the inverse function theorem, $\xi(r):=\xi_{\phi}\left(\lambda(r) P_{r}\right)$ is continuously differentiable for every $r>0$ and

$$
\left(\begin{array}{c}
\frac{d \xi_{1}}{d r} \\
\frac{d \xi_{2}}{d r} \\
\vdots \\
\frac{d \xi_{n}}{d r}
\end{array}\right)=\left(\begin{array}{cc}
\frac{\partial F_{1}}{\partial \xi_{1}} & \frac{\partial F_{1}}{\partial \xi_{2}} \cdots \frac{\partial F_{1}}{\partial \xi_{n}} \\
\frac{\partial F_{2}}{\partial \xi_{1}} & \frac{\partial F_{2}}{\partial \xi_{2}} \cdots \frac{\partial F_{2}}{\partial \xi_{n}} \\
\vdots \\
\frac{\partial F_{n}}{\partial \xi_{1}} & \frac{\partial F_{n}}{\partial \xi_{2}} \cdots \frac{\partial F_{n}}{\partial \xi_{n}}
\end{array}\right)^{-1}\left(\begin{array}{c}
\frac{\partial F_{1}}{\partial r} \\
\frac{\partial F_{2}}{\partial r} \\
\vdots \\
\frac{\partial F_{n}}{\partial r}
\end{array}\right) .
$$

Letting $a_{m}=1$, then by (4.11) and (4.12), we have

$$
\begin{aligned}
\frac{\partial F_{i}}{\partial \xi_{j}}= & -\sum_{k=1}^{N} \alpha_{k} \phi^{\prime \prime}\left(h\left(\lambda(r) P_{r}, u_{k}\right)-\xi \cdot u_{k}\right) u_{k, i} u_{k, j} \text { and } \\
\frac{\partial F_{i}}{\partial r}= & \sum_{k=1}^{N} \alpha_{k} \phi^{\prime \prime}\left(\lambda(r) h\left(P, u_{k}\right)-a_{k} \lambda(r) r-\xi \cdot u_{k}\right) \\
& \cdot\left(\lambda^{\prime}(r) h\left(P, u_{k}\right)-a_{k} \lambda^{\prime}(r) r-a_{k} \lambda(r)\right) u_{k, i}
\end{aligned}
$$

By a similar proof in Lemma 4.2, the matrix $\left(\frac{\partial F_{i}}{\partial \xi_{j}}\right)$ is positive definite. Thus, $\lim _{r \rightarrow 0+} \xi^{\prime}(r)$ exists.

It follows from the Lagrange mean value theorem that for every $r>0$ and $1 \leq i \leq n$, there exists a $\varepsilon_{i}(r)$ with $0<\varepsilon_{i}(r)<r$ such that

$$
\frac{\xi_{i}(r)-\xi_{i}(0)}{r}=\xi_{i}^{\prime}\left(\varepsilon_{i}(r)\right) .
$$

Let $r \rightarrow 0+$, then the conclusion follows.
Now, we turn to prove that there exists a polytope with $u_{1}, \ldots, u_{N}$ as its outer unit normals and this polytope is a solution of problem (3.2). Before this, we need the following lemma.

Lemma 4.8. [47, Lemma 3.5] If $P$ is a polytope in $\mathbb{R}^{n}$ and $v_{0} \in S^{n-1}$ with $V_{n-1}\left(F\left(P, v_{0}\right)\right)=0$, then there exists a $\delta_{0}>0$ such that for $0 \leq$ $\delta<\delta_{0}$,

$$
V\left(P \cap\left\{x: x \cdot v_{0} \geq h\left(P, v_{0}\right)-\delta\right\}\right)=c_{n} \delta^{n}+\ldots+c_{2} \delta^{2},
$$

where $c_{n}, \ldots, c_{2}$ are constants that depend on $P$ and $v_{0}$.
Next, we prove the existence of a solution in (3.2).
Lemma 4.9. Suppose $\varphi:(0, \infty) \rightarrow(0, \infty)$ is continuously differentiable, strictly increasing and $\varphi(s)$ tends to 0 as $s \rightarrow 0^{+}$such that $\phi(t)=$ $\int_{o}^{t} \frac{1}{\varphi(s)} d s$ exists for every positive $t$ and unbounded as $t \rightarrow \infty$. If $\phi(0)=$ $\lim _{t \rightarrow 0^{+}} \phi(t), \alpha_{1}, \ldots, \alpha_{N} \in \mathbb{R}^{+}$, the unit vectors $u_{1}, \ldots, u_{N}(N \geq n+1)$ are not concentrated on any closed hemisphere, then there exists a $P \in \mathcal{P}_{N}\left(u_{1}, \ldots, u_{N}\right)$ such that $\xi_{\phi}(P)=o$ and

$$
V(P)=\sup \left\{V(Q): \max _{\xi \in Q} \Phi_{Q}(\xi)=1 \text { and } Q \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)\right\}
$$

Proof. Note that, for $P, Q \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$, if $Q$ is a translate of $P$, then

$$
\Phi_{P}\left(\xi_{\phi}(P)\right)=\Phi_{Q}\left(\xi_{\phi}(Q)\right)
$$

Thus, we can choose a sequence $P_{i} \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)$ with $\xi_{\phi}\left(P_{i}\right)=o$ such that $V\left(P_{i}\right)$ converges to

$$
\sup \left\{V(Q): \max _{\xi \in Q} \Phi_{Q}(\xi)=1 \text { and } Q \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)\right\}
$$

We claim that $P_{i}$ is bounded. Otherwise, from Lemma 3.4, $\Phi_{P_{i}}\left(\xi_{\phi}\left(P_{i}\right)\right)$ converges to $+\infty$. This contradicts $\Phi_{P_{i}}\left(\xi_{\phi}\left(P_{i}\right)\right)=1$. Therefore, $P_{i}$ is bounded.

From Lemma 3.3 and the Blaschke selection theorem, there exists a subsequence of $P_{i}$ that converges to a polytope $P$ such that $P \in$ $P\left(u_{1}, \ldots, u_{N}\right), \xi_{\phi}(P)=o$ and

$$
\begin{equation*}
V(P)=\sup \left\{V(Q): \max _{\xi \in Q} \Phi_{Q}(\xi)=1 \text { and } Q \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)\right\} \tag{4.13}
\end{equation*}
$$

We next prove that $F\left(P, u_{i}\right)$ are facets for all $i=1, \ldots, N$. Otherwise, there exists a $i_{0} \in\{1, \ldots, N\}$ such that $F\left(P, u_{i_{0}}\right)$ is not a facet of P .

Choose $\delta \geq 0$ small enough so that the polytope

$$
P_{\delta}=P \bigcap\left\{x: x \cdot u_{i_{0}} \leq h\left(P, u_{i_{0}}\right)-\delta\right\} \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)
$$

and (by Lemma 4.8)

$$
V\left(P_{\delta}\right)=V(P)-\left(c_{n} \delta^{n}+\ldots+c_{2} \delta^{2}\right),
$$

where $c_{n}, \ldots, c_{2}$ are constants that depend on $P$ and direction $u_{i_{0}}$. By Lemma 4.6, we can assume $\delta \geq 0$ is small enough so that

$$
\begin{equation*}
h\left(P_{\delta}, u_{k}\right)=h\left(P, u_{k}\right)-a_{k} \delta, \tag{4.14}
\end{equation*}
$$

where $a_{k}$ is a constant with $a_{k} \geq 0$ and $a_{i_{0}}=1$.
From Lemma 3.3, for any $\delta_{i} \rightarrow 0$, it is always true that $\xi_{\phi}\left(P_{\delta_{i}}\right) \rightarrow o$. We have

$$
\lim _{\delta \rightarrow 0} \xi_{\phi}\left(P_{\delta}\right)=o
$$

Let

$$
\lambda(\delta)=\left(\frac{V\left(P_{\delta}\right)}{V(P)}\right)^{-\frac{1}{n}}=\left(1-\frac{\left(c_{n} \delta^{n}+\ldots+c_{2} \delta^{2}\right)}{V(P)}\right)^{-\frac{1}{n}} .
$$

then we have $V\left(\lambda(\delta) P_{\delta}\right)=V(P)$ and $\lambda^{\prime}(0)=0$.
Let $\xi(\delta)=\xi_{\phi}\left(\lambda(\delta) P_{\delta}\right)$ and

$$
\begin{align*}
\Phi(\delta) & =\max _{\xi \in \lambda(\delta) P_{\delta}} \sum_{k=1}^{N} \alpha_{k} \phi\left(h\left(\lambda(\delta) P_{\delta}, u_{k}\right)-\xi \cdot u_{k}\right)  \tag{4.15}\\
& =\sum_{k=1}^{N} \alpha_{k} \phi\left(h\left(\lambda(\delta) P_{\delta}, u_{k}\right)-\xi(\delta) \cdot u_{k}\right) .
\end{align*}
$$

From this and the fact $\xi(\delta)$ is an interior point of $\lambda(\delta) P_{\delta}$, we get

$$
\begin{equation*}
\sum_{k=1}^{N} \alpha_{k} \phi^{\prime}\left(h\left(P, u_{k}\right)\right) u_{k}=0 \tag{4.16}
\end{equation*}
$$

It follows from Lemma 4.7 that $\xi_{\phi}\left(\lambda(\delta) P_{\delta}\right)$ has right derivative at 0 . Together with (4.14), (4.15), (4.16), $\lambda^{\prime}(0)=0$ and the definition of $\phi$, we have the right derivative

$$
\begin{aligned}
\left.\frac{d}{d \delta}\right|_{\delta=0^{+}} \Phi(\delta) & =-\sum_{k=1}^{N} \alpha_{k} a_{k} \phi^{\prime}\left(h\left(P, u_{i_{0}}\right)\right)+\sum_{k=1}^{N} \alpha_{k} \phi^{\prime}\left(h\left(P, u_{k}\right)\right)\left(\xi_{r}^{\prime}(0) \cdot u_{k}\right) \\
& =-\sum_{k=1}^{N} \alpha_{k} a_{k} \phi^{\prime}\left(h\left(P, u_{i_{0}}\right)\right)+\xi_{r}^{\prime}(0) \cdot \sum_{k=1}^{N} \alpha_{k} \phi^{\prime}\left(h\left(P, u_{k}\right)\right) u_{k} \\
& =-\sum_{k=1}^{N} \alpha_{k} a_{k} \phi^{\prime}\left(h\left(P, u_{i_{0}}\right)\right)<0
\end{aligned}
$$

Note that $o=\xi_{\phi}(P) \in \operatorname{Int} P$, there exists a $\delta_{0}>0$ such that $P_{\delta_{0}} \in$ $\mathcal{P}\left(u_{1}, \ldots, u_{N}\right), o \in P_{\delta_{0}}$ and

$$
\Phi_{\lambda_{0} P_{\delta_{0}}}\left(\xi_{\phi}\left(\lambda_{0} P_{\delta_{0}}\right)\right)<\Phi_{P}\left(\xi_{\phi}(P)\right)=1
$$

where $\lambda_{0}=\left(\frac{V\left(P_{\delta_{0}}\right)}{V(P)}\right)^{-\frac{1}{n}}$. Let $P_{0}:=\lambda_{0} P_{\delta_{0}}$, then $P_{0} \in P\left(u_{1}, \ldots, u_{N}\right)$, $o \in P_{0}, V\left(P_{0}\right)=V(P)$, and

$$
\sup _{\xi \in P_{0}} \Phi_{P_{0}}(\xi)<1
$$

Then by Lemma 3.4 and Remark 4.1, there exists a real number $\beta>1$ such that

$$
\sup _{\xi \in \beta P_{0}} \Phi_{\beta P_{0}}(\xi)=1
$$

But $V\left(\beta P_{0}\right)>V\left(P_{0}\right)=V(P)$, which contradicts equation (4.13). Therefore, $P \in P_{N}\left(u_{1}, \ldots, u_{N}\right)$.

## 5. The Orlicz Minkowski problem for polytopes

This section is devoted to the proof of our main theorem by using the Lagrange multiplier rule. In the following, we denote by $\mathbb{R}_{+}^{N}$ the
set of all $x=\left(x_{1}, \ldots, x_{N}\right) \in \mathbb{R}^{N}$ with positive components. To use the Lagrange multiplier rule, we need the following lemma.

Lemma 5.1. [25, Lemma 3.2] Let $u_{1}, \ldots, u_{N} \in S^{n-1}$ be pairwise distinct vectors which are not contained in any closed hemisphere. For $x \in$ $\mathbb{R}_{+}^{N}$, let $P(x)=\bigcap_{i=1}^{N} H_{u_{i}, x_{i}}^{-}$. Then $V(P(x))$ is continuously differentiable and $\partial_{i} V(P(x))=S\left(P(x),\left\{u_{i}\right\}\right)$ for $i=1, \ldots, N$.

Now, we turn to prove Theorem 1.2.
Proof. Let $P(x)=\bigcap_{i=1}^{N} H_{u_{i}, x_{i}}^{-}$, where $x \in \mathbb{R}_{+}^{N}$, such that

$$
\max _{\xi \in P(x)} \Phi_{P(x)}(\xi)=1
$$

Then (3.2) becomes

$$
\sup \left\{V(P(x)): \Phi_{P(x)}\left(\xi_{\phi}(P(x))=1\right\}\right.
$$

From this restriction condition and the fact $\xi_{\phi}(P(x))$ is an interior point of $P(x)$, we have

$$
\begin{equation*}
\sum_{k=1}^{N} \alpha_{k} \phi^{\prime}\left(h\left(P(x), u_{k}\right)-\xi_{\phi}(P(x)) \cdot u_{k}\right) u_{k}=o \tag{5.1}
\end{equation*}
$$

From Lemma 4.9, there exists a polytope $P \in P_{N}\left(u_{1}, \cdots, u_{N}\right)$ with $\xi_{\phi}(P)=o$ such that

$$
V(P)=\sup \left\{V(Q): \max _{\xi \in Q} \Phi_{Q}(\xi)=1: Q \in \mathcal{P}\left(u_{1}, \ldots, u_{N}\right)\right\}
$$

Let $z=\left(h\left(P, u_{1}\right), h\left(P, u_{2}\right), \ldots, h\left(P, u_{N}\right)\right)=\left(z_{1}, \ldots, z_{N}\right)$, then

$$
\begin{gathered}
\Phi_{P(z)}\left(\xi_{\phi}(P(z))\right)=1 \\
V(P(z))=\sup \left\{V(P(x)): \Phi_{P(x)}\left(\xi_{\phi}(P(x))\right)=1\right\}
\end{gathered}
$$

and (5.1) becomes

$$
\begin{equation*}
\sum_{k=1}^{N} \alpha_{k} \phi^{\prime}\left(z_{k}\right) u_{k}=o . \tag{5.2}
\end{equation*}
$$

Since $P \in P_{N}\left(u_{1}, \cdots, u_{N}\right)$, by Lemma 2.4.13 in [38] and Lemma 4.2 , we can choose a small neighborhood $D(z)$ of $z$, such that $\forall x \in$
$D(z), h\left(P(x), u_{i}\right)=x_{i}$ and the partial differential $\partial_{i} \xi_{\phi}(P(x))$ exists , where $i \in\{1, \ldots, N\}$.

By the Lagrange multiplier rule there is some $\lambda \in \mathbb{R}$ such that

$$
\nabla V(P(z))=\lambda \nabla\left(\sum_{k=1}^{m} \alpha_{k} \phi\left(z_{k}-\xi_{\phi}(P(z)) \cdot u_{k}\right)\right)
$$

where $V(P(z))$ is differentiable by Lemma 5.1, $\phi^{\prime}\left(z_{i}\right)$ exists since $z_{i}>$ 0 for all $i=1, \ldots, m$. Therefore, by (5.2)

$$
\begin{aligned}
S_{i} & :=S\left(P(z), u_{i}\right) \\
& =\lambda \alpha_{i} \phi^{\prime}\left(z_{i}\right)-\lambda \sum_{k=1}^{N} \alpha_{k} \phi^{\prime}\left(z_{k}\right) \partial_{i} \xi_{\phi}(P(z)) \cdot u_{k} \\
& =\lambda \alpha_{i} \phi^{\prime}\left(z_{i}\right)-\lambda \partial_{i} \xi_{\phi}(P(z)) \cdot \sum_{k=1}^{N} \alpha_{k} \phi^{\prime}\left(z_{k}\right) u_{k} \\
& =\lambda \alpha_{i} \phi^{\prime}\left(z_{i}\right),
\end{aligned}
$$

where $i \in\{1, \ldots, N\}$.
Then, we have

$$
n V(P(z))=\sum_{i=1}^{N} S_{i} z_{i}=\lambda \sum_{i=1}^{N} \alpha_{i} \phi^{\prime}\left(z_{i}\right) z_{i} .
$$

Therefore, for $i=1, \ldots, N$,

$$
S\left(P(z), u_{i}\right)=S_{i}=\frac{1}{c} \alpha_{i} \phi^{\prime}\left(z_{i}\right),
$$

where $\left.c=\frac{1}{n V(P(z))} \sum_{i=1}^{N} \alpha_{i} \phi^{\prime}\left(z_{i}\right)\right) z_{i}$. Indeed, from the definition of $\phi$, it follows that

$$
\mu=\sum_{i=1}^{N} \alpha_{i} \delta_{u_{i}}=c \varphi(h(P, \cdot)) S(P, \cdot) .
$$

Corollary 1.3 follows from this theorem and (2.1).

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