

Discrete Curvature Flows For Surfaces and 3-Manifolds

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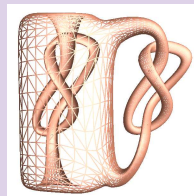
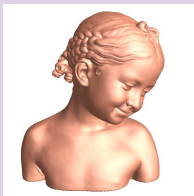
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Thanks for the invitation!



Curvature Flow

- A way to deform **metric** according to prescribed **curvature**;
- *intrinsic* curvature, *conformal* deformation;
- Solid results from *mathematics*, direct applications in *engineering*;
- *smooth vs discrete*.

Our Work

- Discrete Ricci flow and discrete Yamabe flow for surfaces
- Discrete curvature flow for 3-manifolds

Outline

- Curvature flow for surfaces
 - Theories
 - Discretization
 - Applications
- Curvature flow for 3-manifolds

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 - **Theories**
 - Discretization
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The Ricci Flow [Hamilton 1982, 1988]

The Riemannian metric \mathbf{g} is deformed proportional to the curvature K ,

$$\frac{d\mathbf{g}}{dt} = -2K\mathbf{g}$$

such that the curvature K evolves like heat diffusion:

$$\frac{dK}{dt} = -\Delta_{\mathbf{g}}K$$

Eventually, the curvature is constant everywhere.

Impact

A powerful tool to design Riemannian metrics by prescribed curvatures.

- In mathematics, it has been applied for proving Poincaré conjecture and Thurston's geometrization conjecture.
- In engineering, it has been applied in shape matching, registration, analysis, classification and etc.

Geometry

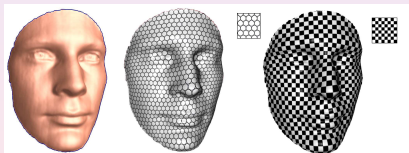
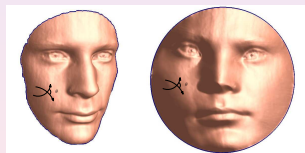
According to Klein, geometry studies the invariants under different transformation groups.

Surface Geometric Structures

- 1 Topology : orientability, genus, boundaries, ...
- 2 **Conformal Geometry** : measure angles between intersecting curves;
- 3 **Riemannian Geometry** : measure lengths of curves;
- 4 Euclidean Geometry : mean curvature $h : S \rightarrow \mathbb{R}$

Conformal Mapping

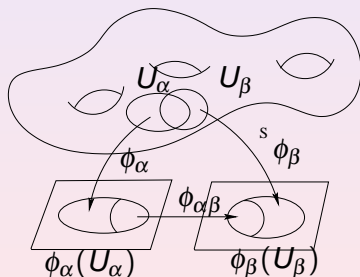
- Angle preserving, locally shape preserving.
- Map infinitesimal circles to infinitesimal circles.
- Möbius transformation group.



Conformal Structure

Definition (Conformal Structure)

An atlas is conformal, if all its transition maps are conformal (i.e., *biholomorphic*). A conformal structure is the maximal conformal atlas.



Fact

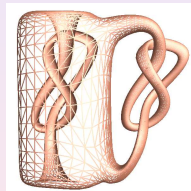
All metric surfaces are Riemann surfaces.



Spherical



Euclidean



Hyperbolic

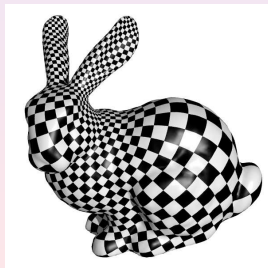
Connecting Conformal and Riemannian

Definition

Let Σ be a surface with a Riemannian metric $\mathbf{g} = \begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix}$.

Let $\lambda : \Sigma \rightarrow \mathbb{R}$ be a function defined on the surface. Then

- $e^{2\lambda} \mathbf{g}$ is another Riemannian metric **conformal** to \mathbf{g} ;
- $e^{2\lambda}$ is called the **conformal factor**.



Conformal Structure: Reinterpretation

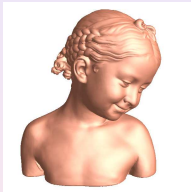
Consider all the Riemannian metrics on a topological surface S . Two Riemannian metrics $\mathbf{g}_1, \mathbf{g}_2$ are **conformally equivalent** $\mathbf{g}_1 \sim \mathbf{g}_2$, if they differ by a scalar function (i.e. conformal factor), $\mathbf{g}_2 = e^{2u}\mathbf{g}_1, u: S \rightarrow \mathbb{R}$. Each **conformal equivalence class** of Riemannian metrics on S is a *conformal structure* of S .

Theorem (Poincaré Uniformization Theorem)

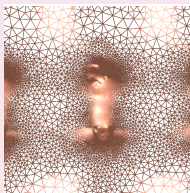
Let (S, \mathbf{g}) be a compact 2-dimensional Riemannian manifold. Then there is a metric $\tilde{\mathbf{g}} = e^{2u}\mathbf{g}$ conformal to \mathbf{g} which has constant Gauss curvature.

Uniformization

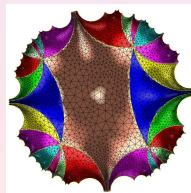
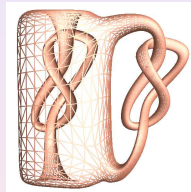
- All surfaces admit one of three canonical geometries: Spherical, Euclidean or Hyperbolic geometry.
- For any case, Ricci flow can deform metric conformally to be with constant curvature everywhere!



Spherical



Euclidean



Hyperbolic



Theorem (Hamilton 1988)

For a closed surface of non-positive Euler characteristic, if the total area of the surface is preserved during the flow, the Ricci flow will converge to a metric such that the Gaussian curvature is constant (equals to \bar{K}) every where.

Theorem (Chow 1991)

For a closed surface of positive Euler characteristic, if the total area of the surface is preserved during the flow, the Ricci flow will converge to a metric such that the Gaussian curvature is constant (equals to \bar{K}) every where.

Yamabe Equation

Suppose $\bar{g} = e^{2u}g$ is a conformal metric on the surface, then the Gaussian curvature on interior points are

$$\bar{K} = e^{-2u}(-\Delta_g u + K),$$

geodesic curvature on the boundary

$$\bar{k}_g = e^{-u}(-\partial_n u + k_g).$$

Yamabe Flow

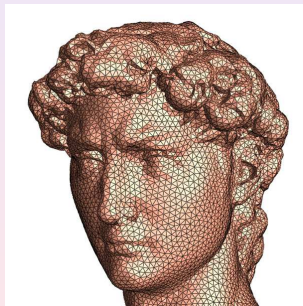
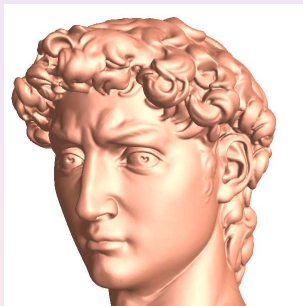
Lead to the solution to the Yamabe equation. Has essentially the same computational power as the Ricci flow for surfaces.

Outline

- Curvature flow for surfaces
 - Theories
 - **Discretization**
 - Applications
- Curvature flow for 3-manifolds

Discrete Representation of Surfaces

- Surfaces are represented as triangular meshes.
- Discrete model can be acquired using 3D scanner in real time.



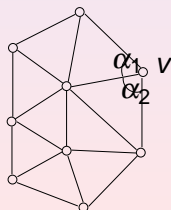
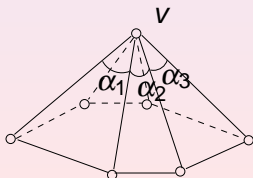
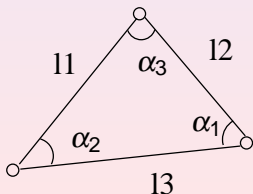
Discrete Metrics and Curvatures

- **Discrete Metric:** A function defined over edges,
 $l : E = \{\text{edges}\} \rightarrow \mathbb{R}^+$, satisfying triangular inequality.
- **Discrete Curvature:** A function defined over vertices,
 $K : V = \{\text{vertices}\} \rightarrow \mathbb{R}^1$,

$$K(v) = 2\pi - \sum_i \alpha_i, v \notin \partial M; K(v) = \pi - \sum_i \alpha_i, v \in \partial M$$

satisfying the discrete Gauss-Bonnet theorem:

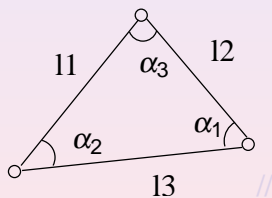
$$\sum_{v \notin \partial M} K(v) + \sum_{v \in \partial M} K(v) = 2\pi\chi(M).$$



Discrete Metrics and Curvatures

Discrete metric determines discrete curvature by cosine law:

$$\cos \alpha_i = \frac{l_j^2 + l_k^2 - l_i^2}{2l_j l_k}, l \neq j \neq k \neq i$$



Conformal metric deformation by curvature flow

$$\mathbf{g} \rightarrow e^{2u} \mathbf{g}, u: S \rightarrow \mathbb{R}$$

- **analytical approach**: discrete Yamabe flow, using typical discrete notations (l_{ij} per edge, u_i per vertex).
- **geometric approach**: discrete Ricci flow, using so called circle packing metric (γ_i per vertex, Φ_{ij} per edge).

Discrete Yamabe Flow - Analytic Approach

Smooth Conformal Metric Deformation

$$\mathbf{g} \rightarrow e^{2u} \mathbf{g}, u : S \rightarrow \mathbb{R}$$

Discrete Conformal Metric Deformation

$$l_{ij} \rightarrow e^{u_i} e^{u_j} l_{ij}, u : V \rightarrow \mathbb{R}$$

Discrete Yamabe flow

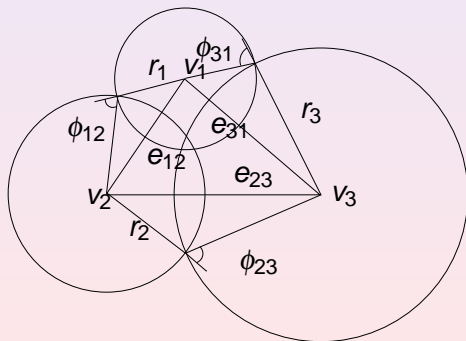
$$\frac{du_i}{dt} = -u_i K_i$$

Discrete Ricci Flow - Geometric Approach

Circle Packing Metric [Thurston 1978]

We associate each vertex v_i with a circle with radius γ_i . On edge e_{ij} , the two circles intersect at the angle of Φ_{ij} . The edge lengths are

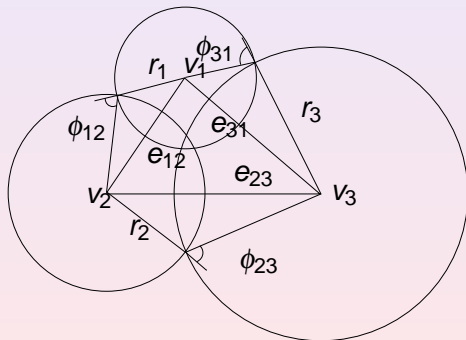
$$l_{ij}^2 = \gamma_i^2 + \gamma_j^2 + 2\gamma_i\gamma_j \cos \Phi_{ij}$$



Discrete Ricci Flow - Geometric Approach

Discrete Ricci flow

$$\frac{d\gamma_i}{dt} = -\gamma_i K_i$$



Definition

Let $u_i = \ln \gamma_i$, the **Entropy Energy** is defined as

$$f(\mathbf{u}) = \int_{\mathbf{u}_0}^{\mathbf{u}} \sum_{i=1}^n (K_i - \bar{K}_i) du_i,$$

where $\mathbf{u} = (u_1, u_2, \dots, u_n)$, $\mathbf{u}_0 = (0, 0, \dots, 0)$.

Theorem (Chow and Luo 2002)

Euclidean Ricci energy is Well defined and convex, namely, there exists a unique global minimum. And the discrete Euclidean Ricci flow converges to the global minimum.

Gradient descent Method

Ricci flow is the gradient descent method for minimizing Ricci energy,

$$\nabla f = (K_1 - \bar{K}_1, K_2 - \bar{K}_2, \dots, K_n - \bar{K}_n).$$

Newton's method

The Hessian matrix of Ricci energy is

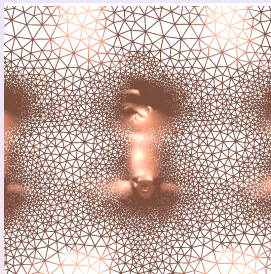
$$\frac{\partial^2 f}{\partial u_i \partial u_j} = \frac{\partial K_i}{\partial u_j}.$$

Newton's method can be applied directly.

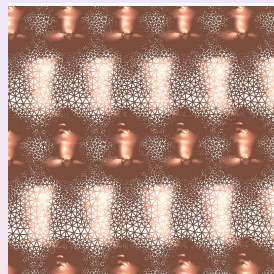
Euclidean Uniform Flat Metric



original surface

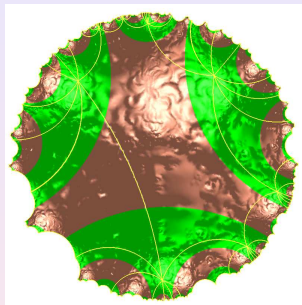
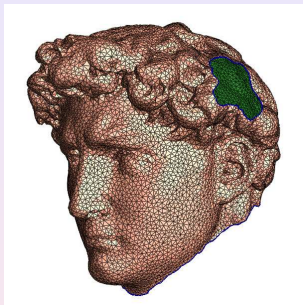


fundamental domain



universal cover

Hyperbolic Uniformization Metric



Genus 0 surface with 3 boundaries. The double covered surface is of genus 2. The boundaries are mapped to hyperbolic lines.

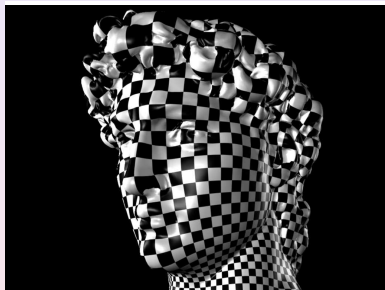
Outline

- Curvature flow for surfaces
 - Theories
 - Discretization
 - **Applications**
- Curvature flow for 3-manifolds

Many practical problems can be formulated as finding a special metric with certain curvature constraints.

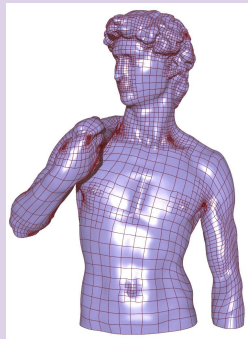
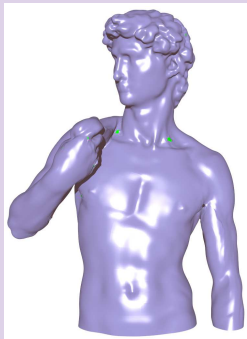
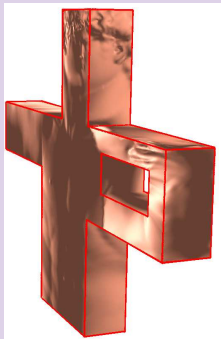
- Parameterization - finding a flat metric
- Polycube map - a flat metric with curvatures concentrated on corners
- Vector Field Design - a flat metric with cone singularities with special holonomy.
- Manifold Spline - constructing affine atlas utilizing flat metrics
- Shape Matching - register and compare two surfaces.
-

Surface Parameterization

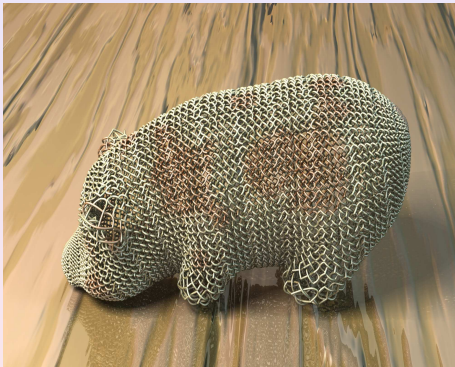
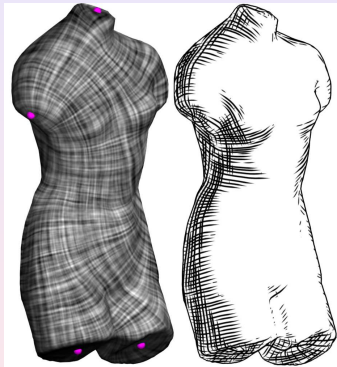


Polycube Map

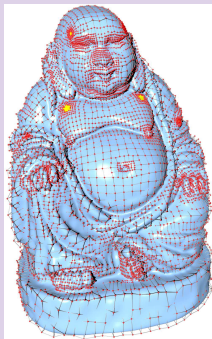
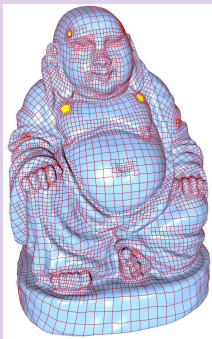
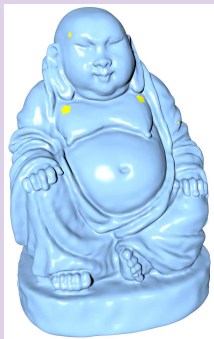
Polycube Map



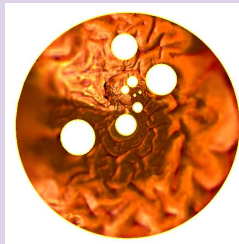
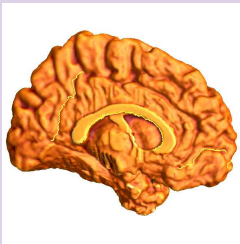
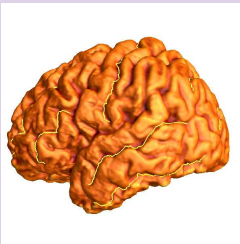
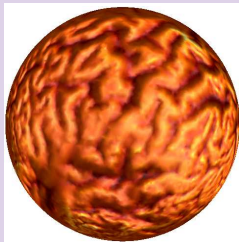
Vector Field Design



Manifold Spline

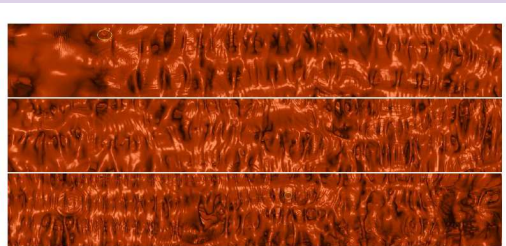
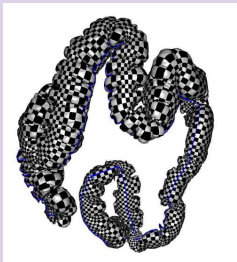


Brain Mapping

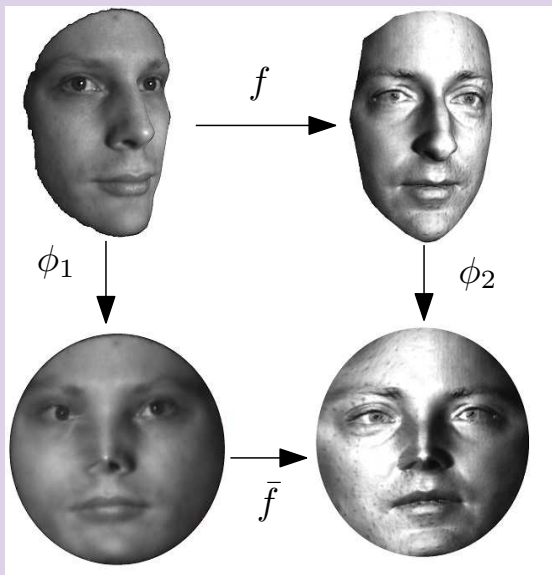


Colon Flattening

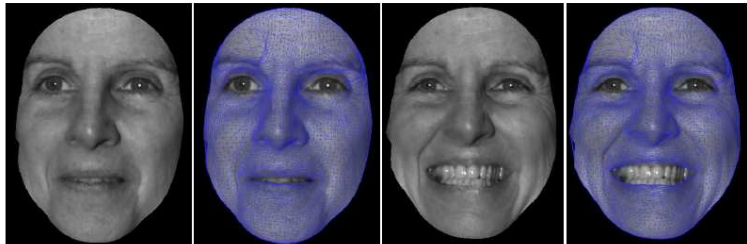
Virtual Colonoscopy



Surface Matching



Surface Tracking



Conformal Invariants

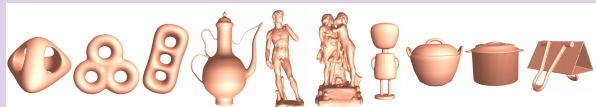


Teichmüller Shape Space

Genus 2 Shapes



Genus 3 Shapes



Teichmüller Space

- In Teichmüller shape space, each point represents a conformal equivalent class of surfaces.
- In Teichmüller shape space, a curve connecting two points represents a deformation from one shape to the other.

Challenges

- Computing the coordinates of a shape in the Teichmüller space.
- Computing the geodesics (i.e. the extremal quasi-conformal map) in the space.

Outline

- Curvature flow for surfaces
 - Theories
 - Discretization
 - Applications
- **Curvature flow for 3-manifolds**

From surfaces to 3-manifolds

Similar idea

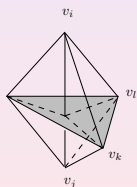
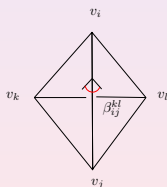
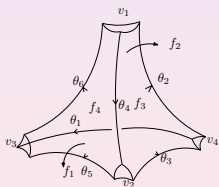
Conformal deformation of metrics driven by intrinsic curvature.

Yet quite different ...

- For 2-manifolds, topology and conformal structure determine a metric; for 3-manifolds: topology determines a metric.
- Surface Ricci flow has no singularities, 3-Manifold Ricci flow has.

Some Other Difference

- Primitive blocks: truncated tetrahedra (instead of triangles)
- Discrete curvature: edge curvature (instead of vertex curvature)
- Flow equation: $\frac{dx_{ij}}{dt} = -u_i K_{ij}$, x_{ij} edge length, K_{ij} edge curvature.



3-Manifold Curvature Flow

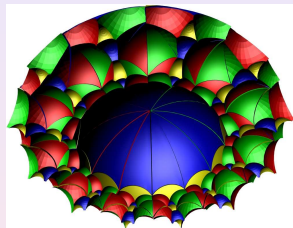
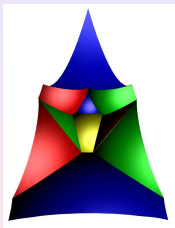
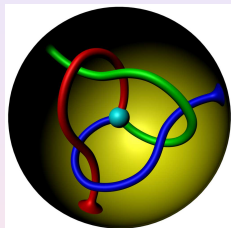
Uniformization

- Thurston's geometrization conjectured all 3-manifolds admit one of eight canonical geometries.
- Poincaré conjecture considers one special case: closed, compact, simply connected 3-manifolds are 3-spheres; proved using the Ricci flow.

Our Work

- A discrete curvature flow [Luo 2005] for hyperbolic 3-manifolds with boundaries.
- Discrete algorithms [Yin et al 2008] to compute this flow and visualize the constant curvature metric.

Discrete curvature flow for hyperbolic 3-manifolds

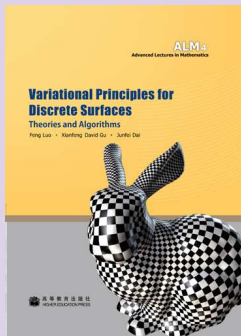
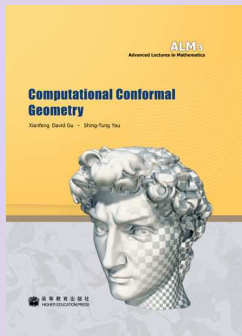


- Would help the study of 3-manifold geometry.
- Expect applications in volumetric parameterization.
- To be generalized to other types of 3-manifolds

Conclusion

- Curvature flow is a fundamental tool to discover the intrinsic nature of geometry; it can be discretized properly to solve practical problems in engineering fields.
- For surfaces, the discrete curvature flow algorithms are available for all three geometries (spherical, Euclidean and hyperbolic).
- For 3-manifolds, the discrete curvature flow algorithm has been studied for certain class of 3-manifolds; much more to be explored.

- More details in *Computational Conformal Geometry* and *Variational Principles of Discrete Surfaces*.
- All the data sets and source codes are available at <http://www.cs.sunysb.edu/~gu> .



Acknowledgement

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- Thanks to our collaborators: Arie Kaufman, Hong Qin, Dimitris Samaras, Paul M. Thompson, Tony F. Chan, Shing-Tung Yau and many more ...
- Thanks to all the audience

