# THE EXISTENCE OF SUPERSYMMETRIC STRING THEORY WITH TORSION 

JUN LI AND SHING-TUNG YAU

## 1. The system proposed by Strominger

In their proposed compactification of superstrings [4], Candelas, Horowitz, Strominger and Witten took the matric product of a maximal symmetric four dimensional spacetime $M$ with a six dimensional Calabi-Yau vacua $X$ as the ten dimensional spacetime; they identified the Yang-Mills connection with the $\mathrm{SU}(3)$ connection of the Calabi-Yau metric and set the dilaton to be a constant. To make this theory compatible with the standard grand unified field theory, Witten [28] and Horava-Witten [20] proposed to use higher rank bundles for strong coupled heterotic string theory so that the gauge groups can be $\mathrm{SU}(4)$ or $\mathrm{SU}(5)$. Mathematically, this approach relies on Uhlenbeck-Yau's theorem on constructing Hermitian-Yang-Mills connections on stable bundles [27. Many authors, including Friedman, Morgan and Witten [18; Donagi, Ovrat, Pantev and Reinbacher 12; Andreas 1], Kachru 21 and others, have worked on this subject since then.

In 24, A. Strominger analyzed heterotic superstring background with spacetime sypersymmetry and non-zero torsion by allowing a scalar "warp factor" to multiply the spacetime metric. He considered a ten dimensional spacetime that is the product $M \times X$ of a maximal symmetric four dimensional spacetime $M$ and an internal space $X$; the metric on $M \times X$ takes the form

$$
e^{2 D(y)}\left(\begin{array}{cc}
g_{i j}(y) & 0 \\
0 & g_{\mu \nu}(x)
\end{array}\right), \quad x \in X, \quad y \in M
$$

the connection on an auxiliary bundle is Hermitian-Yang-Mills over $X$ :

$$
F \wedge \omega^{2}=0, \quad F^{2,0}=F^{0,2}=0
$$

associated to the hermitian form $\omega=\frac{\sqrt{-1}}{2} g_{i \bar{j}} d z^{i} d \bar{z}^{j}$. In this system, following the convention that $d_{c}=\sqrt{-1}(\bar{\partial}-\partial)$, the physical relevant quantities are

$$
\begin{gathered}
h=\frac{1}{2} d_{c} \omega \\
\phi=\frac{1}{8} \log \|\Omega\|+\phi_{0}
\end{gathered}
$$

for a constant $\phi_{0}$ and

$$
g_{i j}^{0}=e^{2 \phi_{0}}\|\Omega\|^{\frac{1}{4}} g_{i j}
$$

The spacetime supersymmetry forces $D(y)$ to be the dilaton field.
In order for such ansatze to provide a supersymmetric configuration, one introduces a Majorana-Weyl spinor $\epsilon$ so that

$$
\delta \phi_{j}^{0}=\nabla_{j}^{0} \epsilon^{0}+\frac{1}{48} e^{2 \phi}\left(\gamma_{j}^{0} H^{0}-12 h_{j}^{0}\right) \epsilon^{0}=0
$$

[^0]$$
\delta \lambda^{0}=\nabla^{0} \phi \epsilon^{0}+\frac{1}{24} e^{2 \phi} h^{0} \epsilon^{0}=0
$$
and
$$
\delta \chi^{0}=e^{\phi} F_{i j} \Gamma^{0 i j} \epsilon^{0}=0
$$

Here $\psi^{0}$ is the gravitano, $\lambda^{0}$ is the dilatino, $\chi^{0}$ is the gluino, $\phi$ is the dilaton and $h$ is the Kalb-Ramond filed strength obeying

$$
d h=\operatorname{tr} R \wedge R-\operatorname{tr} F \wedge F
$$

(For details of this discussion, please consult [24 25].) By suitably transforming these quantities, Strominger showed that in order to achieve space-time supersymmetry the internal six manifold $X$ must be a complex manifold with a non-vanishing holomorphic three form $\Omega$; the Hermitian form $\omega$ must obey

$$
\partial \bar{\partial} \omega=\sqrt{-1} \operatorname{tr} F \wedge F-\sqrt{-1} \operatorname{tr} R \wedge R
$$

and

$$
d^{*} \omega=d_{c} \log \|\Omega\|
$$

Accordingly, he proposed to solve the system

$$
\begin{equation*}
F \wedge \omega^{2}=0 \tag{1.1}
\end{equation*}
$$

$$
\begin{equation*}
F^{2,0}=F^{0,2}=0 \tag{1.2}
\end{equation*}
$$

$$
\begin{equation*}
\partial \bar{\partial} \omega=\sqrt{-1} \operatorname{tr} F \wedge F-\sqrt{-1} \operatorname{tr} R \wedge R \tag{1.3}
\end{equation*}
$$

and

$$
\begin{equation*}
d^{*} \omega=d_{c} \log \|\Omega\| . \tag{1.4}
\end{equation*}
$$

These are solutions of superstrings with torsions that allows non-trivial dilaton fields and Yang-Mills fields ${ }^{1}$. Here $\Omega$ is a nowhere vanishing holomorphic three form on the complex threefold $X ; \omega$ is the Hermitian form and $R$ is the curvature tensor of the Hermitian metric $\omega ; F$ is the curvature of a vector bundle $E$; and $\operatorname{tr}$ is the trace of the endomorphism bundle of either $E$ or $T X$.

In [24], Strominger found some solutions to this system for $\mathrm{U}(1)$ principle bundles. In this paper we shall give the first irreducible non-singular solution of the supersymmetric system of Strominger for $\mathrm{U}(4)$ and $\mathrm{U}(5)$ principle bundles. We obtain our solutions by perturbing around the Calabi-Yau vacua paired with the gauge field on the tangent bundle of $X$.

In more concrete term, we take a smooth Calabi-Yau threefold $(X, \omega)$ and a reducible Yang-Mills connection (metric) $H$ on $T X \oplus \mathbb{C}_{X}^{\oplus r} ;(\omega, H)$ is a reducible solution to Strominger's system. For any small deformations $\bar{\partial}_{s}$ of the holomorphic structure of $T X \oplus \mathbb{C}_{X}^{\oplus r}$, we derive a sufficient condition for (1.1)-(1.4) being solvable for $\left(X, \bar{\partial}_{s}\right)$ : it is that the Kodaira-Spencer class of the family $\bar{\partial}_{s}$ at $s=0$ satisfies certain non-degeneracy condition (see Theorem 4.3). After that, we will construct examples of Calabi-Yau threefolds that admit small deformations of $T X \oplus \mathbb{C}_{X}^{\oplus r}$ satisfying this requirement. This provides the first example of regular irreducible solution to Strominger's system.

In the next paper, we would like to understand the non-perturbative theory and hope to formulate a global structure theorem of the moduli space of these fields.

[^1]It was speculated by M. Reid that all Calabi-Yau manifolds can be deformed to each other through conifold transition. To achieve this goal, it is inevitable that we must work with non-Kahler manifolds. We hope that such non-Kahler manifolds will adopt the Strominger structures. We shall come back to this in the second paper.

## 2. Solving Hermitian-Einstein equation by perturbation

In this section we will solve the usual Hermitian-Yang-Mills system using perturbation method. Let $\left(E, D_{s}^{\prime \prime}\right)$ be a smooth family of holomorphic vector bundles on an $n$-dimensional Kahler manifold $(X, \omega)$. Suppose $H_{0}$ is a Hermitian-Yang-Mills metric on $\left(E, D_{0}^{\prime \prime}\right)$; we ask under what condition can we extend $H_{0}$ to a smooth family of Hermitian-Yang-Mills metrics $H_{s}$ on $\left(E, D_{s}^{\prime \prime}\right)$ ? When $H_{0}$ is irreducible, the answer is affirmative. The case when $H_{0}$ is reducible is more subtle. Let $\left(E_{1}, D_{1}^{\prime \prime}\right)$ and $\left(E_{2}, D_{2}^{\prime \prime}\right)$ be two degree zero slope-stable vector bundles on $X$. By a theorem of Uhlenbeck-Yau, both $\left(E_{1}, D_{1}^{\prime \prime}\right)$ and $\left(E_{2}, D_{2}^{\prime \prime}\right)$ admit Hermitian-Yang-Mills metrics $H_{1}$ and $H_{2}$. The direct sum of their scalar multiples $H_{1} \oplus e^{t} H_{2}$ is a Hermitian-Yang-Mills metric on

$$
\left(E, D_{0}^{\prime \prime}\right) \triangleq\left(E_{1} \oplus E_{2}, D_{1}^{\prime \prime} \oplus D_{2}^{\prime \prime}\right)
$$

Suppose we are given a smooth deformation of holomorphic structures $D_{s}^{\prime \prime}$ of $D_{0}^{\prime \prime}$, then the Kodaira-Spensor class identifies the first order deformation of the family $D_{s}^{\prime \prime}$ at 0 to an element

$$
\kappa \in H_{\bar{\partial}}^{1}\left(X, E^{\vee} \otimes E\right)
$$

in the Dolbeault cohomology of the $\bar{\partial}$-operator $D_{0}^{\prime \prime}$. Because $D_{0}^{\prime \prime}=D_{1}^{\prime \prime} \oplus D_{2}^{\prime \prime}$, the above cohomology space decomposes into direct sum

$$
\oplus_{i, j=1}^{2} H_{\bar{\partial}}^{1}\left(X, E_{i}^{\vee} \otimes E_{j}\right)
$$

We let $\kappa_{i j} \in H_{\bar{\partial}}^{1}\left(X, E_{i}^{\vee} \otimes E_{j}\right)$ be its associated components under this decomposition.
Theorem 2.1. Suppose $\kappa_{12}$ and $\kappa_{21}$ are non-zero, then there is a unique $t$ so that for sufficiently small s the metric $H_{0}(t)=H_{1} \oplus e^{t} H_{2}$ extends to a family of Hermitian-Yang-Mills-metrics $H_{s}$ on $\left(E, D_{s}^{\prime \prime}\right)$.

We will prove this theorem by applying implicit function theorem to the elliptic system of the Hermitian-Yang-Mills metrics of $\left(E, D_{s}^{\prime \prime}\right)$.

To begin with, equation (1.2) holds for any hermitian connections of holomorphic vector bundles. Now let $H$ be a hermitian metric on $E$ and $F_{s, H}$ be its the hermitian curvature on $\left(E, D_{s}^{\prime \prime}\right)$. The Hermitian-Yang-Mills equation for $\left(E, D_{s}^{\prime \prime}\right)$, which has degree zero, then becomes

$$
\begin{equation*}
F_{s, H} \wedge \omega^{n-1}=0 \tag{2.1}
\end{equation*}
$$

The linearization of (2.1) is self-adjoint and has two-dimensional kernel and cokernel. In case $\wedge^{r}\left(E, D_{0}^{\prime \prime}\right) \cong \mathbb{C}_{X}$, we can normalize $H$ so that its induced metric on $\wedge^{r} E \cong \mathbb{C}_{X}$ is the constant one metric. Then the linearization of the restricted system has one dimensional kernel and cokernel. We suppose the cokernel is spanned by $J \cdot \omega^{n}$. Then for small $s$, the implicit function theorem supplies us a one dimensional family of solutions $H_{s, t}$, of determinant one, to the system (2.1) modulo the linear span of $J \cdot \omega^{n}$ :

$$
\begin{equation*}
F_{s, H_{s, t}} \wedge \omega^{n-1} \equiv 0 \quad \bmod J \cdot \omega^{n} \tag{2.2}
\end{equation*}
$$

To prove the theorem, it remains to show that we can find a function $t=\rho(s)$ so that

$$
\begin{equation*}
F_{s, H_{s, \rho(s)}} \wedge \omega^{n-1}=0 \tag{2.3}
\end{equation*}
$$

For this, we will look at the functional

$$
r(s, t)=\frac{\sqrt{-1}}{2} \int \operatorname{tr}\left(F_{s, H_{s, t}} \cdot J\right) \wedge \omega^{n-1}
$$

and investigate the derivatives $\dot{r}(0, t)=\left.\frac{d}{d s} r(s, t)\right|_{s=0}$. Since $r(0, t) \equiv 0$, the first order derivatives $\dot{r}(0, t)$ are independent of the parameterizations $(s, t)$. By a direct calculation, they all vanish. Thus we are forced to work at the second order derivatives $\ddot{r}(0, t)$; they are of the form

$$
\ddot{r}(0, t)=e^{-\alpha t} A-e^{\alpha t} B, \quad A, B \geq 0 .
$$

In case $\kappa_{12}$ and $\kappa_{21}$ are non-zero, $A$ and $B$ become positive; hence we can find a function $t=\rho(s)$ so that $\lim _{s \rightarrow 0} \rho(s)=\frac{1}{2 \alpha} \ln (A / B)$ and

$$
r(s, \rho(s))=0
$$

This shall prove the existence theorem. Since later we will adopt this approach to solve Strominger's system, we shall provide its detail here as a warm up.

We begin with the basic objects: the vector bundle, its holomorphic structure and its curvature. We let $(X, \omega)$ be a Kahler manifold of dimension $n$; we let $\left(E_{1}, D_{1}^{\prime \prime}\right)$ and $\left(E_{2}, D_{2}^{\prime \prime}\right)$ be two degree zero slope stable holomorphic vector bundles of ranks $r_{1}$ and $r_{2}$; we let $<,>_{1}$ and $<,>_{2}$ be the Hermitian-Yang-Mills metrics of $\left(E_{1}, D_{1}^{\prime \prime}\right)$ and $\left(E_{2}, D_{2}^{\prime \prime}\right)$. For simplicity, we assume $\wedge^{r_{i}}\left(E_{i}, D_{i}^{\prime \prime}\right) \cong \mathbb{C}_{X}$ and pick $<,>_{i}$ so that its induced metric on $\wedge^{r_{i}} E_{i} \cong \mathbb{C}_{X}$ is the constant 1 metric. Under this arrangement the $<,>_{i}$ are unique. We then let $E=E_{1} \oplus E_{2}$, of $\operatorname{rank} r=r_{1}+r_{2}$, and endow it with the holomorphic structure $D_{1}^{\prime \prime} \oplus D_{2}^{\prime \prime}$ and the reference hermitian metric $<,>=<,>_{1} \oplus<,>_{2}$.

Next we let $D_{s}^{\prime \prime}$ be a smooth family of holomorphic structures on $E$ so that $D_{0}^{\prime \prime}=D_{1}^{\prime \prime} \oplus D_{2}^{\prime \prime}$. $D_{s}^{\prime \prime}$ relates to $D_{0}^{\prime \prime}$ by a global section $A_{s} \in \Omega^{0,1}($ End $E)$ :

$$
D_{s}^{\prime \prime}=D_{0}^{\prime \prime}+A_{s}
$$

the hermitian connection $D_{s}=D_{s}^{\prime}+D_{s}^{\prime \prime}$ of $\left(E, D_{s}^{\prime \prime},<,>\right)$ relates to the hermitian connection $D_{0}$ of $\left(E, D_{0}^{\prime \prime},<,>\right)$ via

$$
D_{s}=\left(D_{0}^{\prime \prime}+A_{s}\right)+\left(D_{0}^{\prime}-A_{s}^{*}\right)
$$

the hermitian curvature of $D_{s}$ becomes

$$
\begin{equation*}
F_{s}=F_{0}+\left(D_{0}^{\prime \prime}+D_{0}^{\prime}\right)\left(A_{s}-A_{s}^{*}\right)-\left(A_{s}-A_{s}^{*}\right) \wedge\left(A_{s}-A_{s}^{*}\right) \tag{2.4}
\end{equation*}
$$

Here $A_{s}^{*}$ is the hermitian adjoint of $A_{s}$ under $<,>$.
It is instructive to express them in local coordinates. Let $e_{1}, \cdots, e_{n}$ be a (local) orthonormal basis of $(E,<,>)$. We define the connection form $\Gamma_{s, \alpha \beta}$ of $D_{s}^{\prime \prime}$ :

$$
D_{s}^{\prime \prime} e_{\alpha}=\Gamma_{s, \alpha \beta} e_{\beta}
$$

then the matrix

$$
A_{s}=\left(A_{s, \alpha \beta}\right)=\left(\Gamma_{s, \alpha \beta}-\Gamma_{0, \alpha \beta}\right)
$$

For any local section $v=\sum x_{\alpha} e_{\alpha}$, written in the matrix form $v=\mathbf{x e}^{t}$ with $\mathbf{x}=\left(x_{1}, \cdots, x_{n}\right)$ and $\mathbf{e}=\left(e_{1}, \cdots, e_{n}\right)$ being row vectors, the differentiation

$$
D_{s}^{\prime \prime} v=\left(\bar{\partial} \mathbf{x}+\mathbf{x}\left(\Gamma_{s, \alpha \beta}\right)\right) \mathbf{e}^{t}=\left(\bar{\partial} \mathbf{x}+\mathbf{x}\left(\Gamma_{0, \alpha \beta}\right)\right) \mathbf{e}^{t}+\left(\mathbf{x} A_{s}\right) \mathbf{e}^{t}=D_{0}^{\prime \prime} v+v A_{s}
$$

In case $\varphi$ is a section of $E^{\vee} \otimes E$, a local computation shows that

$$
D_{s}^{\prime \prime} \varphi=D_{0}^{\prime \prime} \varphi-\left[A_{s}, \varphi\right] \quad \text { and } \quad D_{s}^{\prime} \varphi=D_{0}^{\prime} \varphi+\left[A_{s}^{*}, \varphi\right] .
$$

This works for endomorphism-valued $p$ and $q$-forms $A$ and $B$ if we follow the convention $[A, B]=A \wedge B-(-1)^{p q} B \wedge A$.

Lemma 2.2. Let $\left(E, D_{s}^{\prime \prime}\right)$ be a family of holomorphic structures on a vector bundle $E$ over a Kahler manifold $(X, \omega)$. Then there is a family of gauge transformations $g_{s} \in \Omega^{0}(\operatorname{End} E)$, $g_{0}=i d$, so that the first order derivative $\frac{d}{d s} g_{s}^{*} D_{s}^{\prime \prime}$ is $D_{0}^{\prime \prime}$-harmonic.
Proof. First, we can find $\mu \in \Omega^{0}($ End $E)$ so that $\dot{D}_{0}^{\prime \prime}+D_{0}^{\prime \prime} \mu$ is $D_{0}^{\prime \prime}$-harmonic. We then choose a family of gauge transformation $g_{s}$ so that $\frac{d}{d s} g_{s}^{*} D_{s}^{\prime \prime}=\dot{D}_{0}^{\prime \prime}+D_{0}^{\prime \prime} \mu . g_{s}$ is the desired family of gauge transformations.

As a corollary, we can choose the family $D_{s}^{\prime \prime}=D_{0}^{\prime \prime}+A_{s}$ so that $\dot{A}_{0}$ is $D_{0}^{\prime \prime}$-harmonic with respect to the Kahler form $\omega$.

Solving Hermitian Yang-Mills connections involves working with other hermitian metrics of $E$. We let $\mathcal{H}(E)_{1}$ be the space of all hermitian metrics on $E$ whose induced metrics on $\wedge^{r} E \cong \mathbb{C}_{X}$ are the constant one metric. Once we have the reference metric $<,>$, the space $\mathcal{H}(E)_{1}$ is isomorphic to the space of determinant one pointwise positive definite $<,>$-hermitian symmetric endomorphisms of $E$ via

$$
<u, v>_{H}=<u H, v>
$$

In this paper, we shall use such $H$ to represent its associated hermitian metric.
Given a hermitian metric $H$, its hermitian connection $D_{s, H}$ is

$$
D_{s, H}=\left(D_{s}^{\prime}+D_{s}^{\prime} H \cdot H^{-1}\right)+D_{s}^{\prime \prime}
$$

its curvature is

$$
F_{s, H}=F_{s}+D_{s}^{\prime \prime}\left(D_{s}^{\prime} H \cdot H^{-1}\right)
$$

The Hermitian-Yang-Mills connections of $\left(E, D_{s}^{\prime \prime}\right)$ are hermitian metrics $H \in \mathcal{H}(E)_{1}$ making

$$
\tilde{L}_{s}(H)=\left(F_{s}+D_{s}^{\prime \prime}\left(D_{s}^{\prime} H \cdot H^{-1}\right)\right) \wedge \omega^{n-1}
$$

vanish. Because $H$ induces the constant one metric on $\wedge^{r} E, \operatorname{tr} F_{s, H}$, which is the curvature of $\left(\wedge^{r} E\right.$, $\left.\operatorname{det} H\right)$, is zero. Hence $\tilde{L}_{s}(H)$ is traceless $H$-hermitian antisymmetric. To make it $<,>$-hermitian anti-symmetric instead, we form the operator

$$
\begin{equation*}
L_{s}(H)=H^{-1 / 2} \cdot \tilde{L}_{s}(H) \cdot H^{1 / 2}: \mathcal{H}(E)_{1} \longrightarrow \Omega_{\mathbb{R}}^{2 n}(\mathfrak{s u} E) \tag{2.5}
\end{equation*}
$$

It takes value in the vector bundle $\mathfrak{s u E}$ of traceless hermitian anti-symmetric endomorphisms of $(E,<,>)$.

Next we let $I_{i}$ be the identity endomorphism of $E_{i}$, viewed as an endomorphism of $E$. Because both $E_{1}$ and $E_{2}$ are degree zero slope stable and $H_{1}$ and $H_{2}$ are their Hermitian-Yang-Mills metrics, the solutions to $L_{0}(H)=0$ are

$$
\begin{equation*}
H_{0, t}=e^{t / r_{2}} I_{1} \oplus e^{-t / r_{2}} I_{2}, \quad t \in \mathbb{R} \tag{2.6}
\end{equation*}
$$

Further, using $\delta H=H_{0, t}^{-1 / 2} \delta h H_{0, t}^{-1 / 2}$, which is an isomorphism of the tangent space of $\mathcal{H}(E)_{1}$ at $H_{0, t}$ with the space of sections of the vector bundle $\mathfrak{H e r}^{0} E$ of traceless hermitian symmetric endomorphisms of $(E,<,>)$, the linearization of $L_{0}$ at $H_{0, t}$ becomes

$$
\begin{equation*}
\delta L_{0}\left(H_{0, t}\right)(\delta h)=D_{0}^{\prime \prime} D_{0}^{\prime} \delta h \wedge \omega^{n-1}: \Omega^{0}\left(\mathfrak{H e r}^{0} E\right) \longrightarrow \Omega_{\mathbb{R}}^{2 n}(\mathfrak{s u} E) \tag{2.7}
\end{equation*}
$$

Because $\left(E, D_{0}^{\prime \prime}\right)$ is a direct sum of two distinct stable vector bundles, the kernel and the cokernel of $\delta L_{0}$ are both one-dimensional, of which the cokernel is spanned by

$$
J=\frac{\sqrt{-1}}{r_{2}} I_{1} \cdot \omega^{n} \oplus-\frac{\sqrt{-1}}{r_{1}} I_{2} \cdot \omega^{n}
$$

independent of $t$. To apply the implicit function theorem, we take the projection

$$
P: \Omega_{\mathbb{R}}^{2 n}(\mathfrak{s u} E) \longrightarrow \Omega_{\mathbb{R}}^{2 n}(\mathfrak{s u} E) / \mathbb{R} \cdot J
$$

and look at the composite

$$
P \circ L_{s}: \mathcal{H}(E)_{1} \longrightarrow \Omega_{\mathbb{R}}^{2 n}(\mathfrak{s u} E) / \mathbb{R} \cdot J
$$

Because the cokernel of $P \circ \delta L_{0}$ at $H_{0, t}$ is 0 , for small $s$ the operator $P \circ L_{s}$ is an open operator near $H_{0, t}$. Further because the linearization of $P \circ L_{s}$ has index one at $H_{0, t}$, the solution space $V_{s}$ of $P \circ L_{s}=0$ is a one-dimensional smooth manifold near $H_{0, t}$ and the union $\cup_{s} V_{s}$ is a smooth two dimensional manifold near $H_{0, t}$. Since $V_{0}$ is parameterized by the line $\mathbb{R}$ via the solutions (2.6), we can extend this parameterization to $V_{s}$ near $H_{0, t}$ so that $(s, t)$ provides a coordinate chart of $\cup_{s} V_{s}$. We let $H_{s, t}$ be the solution to $P \circ L_{s}=0$ associated to $(s, t) \in V_{s}$. This way, to solve $L_{s}(H)=0$ if suffices to find the vanishing loci of the function

$$
r(s, t)=\sqrt{-1} \int_{X} \operatorname{tr}\left(L_{s}\left(H_{s, t}\right) \cdot I_{1}\right) \in \mathbb{R}
$$

We will show that there is a function $t=\rho(s)$ so that $r(s, \rho(s))=0$. Because $r(0, t)=0$, the first step is to investigate the sign of the derivatives of $r(s, t)$ of $s$ at $s=0$. Recall that

$$
D_{s}^{\prime \prime} H_{s, t}=D_{0}^{\prime \prime} H_{s, t}-\left[A_{s}, H_{s, t}\right] \quad \text { and } \quad D_{s}^{\prime} H_{s, t}=D_{0}^{\prime \prime} H_{s, t}+\left[A_{s}^{*}, H_{s, t}\right]
$$

hence

$$
\frac{d}{d s} D_{s}^{\prime \prime} H_{s, t}=D_{s}^{\prime \prime} \dot{H}_{s, t}-\left[\dot{A}_{s}, H_{s, t}\right] \quad \text { and } \quad \frac{d}{d s} D_{s}^{\prime} H_{s, t}=D_{s}^{\prime} \dot{H}_{s, t}+\left[\dot{A}_{s}^{*}, H_{s, t}\right]
$$

Therefore, following the convention that $\dot{f}(s, t)=\frac{d}{d s} f(s, t)$ and $\dot{f}(0, t)=\left.\dot{f}(s, t)\right|_{s=0}$,

$$
\frac{d}{d s} L_{s}\left(H_{s, t}\right)=\dot{F}_{s}-\left[\dot{A}_{s}, D_{s} H_{s, t} \cdot H_{s, t}^{-1}\right]+D_{s}^{\prime \prime} \varphi_{s, t} \quad \text { with } \quad \varphi_{s, t}=\frac{d}{d s}\left(D_{s}^{\prime} H_{s, t} \cdot H_{s, t}^{-1}\right)
$$

We have the following useful easy observation:
Lemma 2.3. Let $\mu_{1} \in \Omega^{1,0}\left(E_{1}^{\vee} \otimes E_{2}\right)$, let $\mu_{2} \in \Omega^{0,1}\left(E_{1}^{\vee} \otimes E_{2}\right)$, and let $\psi \in \Omega^{0}\left(E_{2}^{\vee} \otimes E_{1}\right)$ be a smooth section.

1. Suppose $D_{0}^{\prime \prime} \psi=0$, then $\int_{X} \operatorname{tr}\left(D_{0}^{\prime \prime} \mu \cdot \psi\right) \wedge \omega^{n-1}=0$.
2. Suppose $D_{0}^{\prime * *} \mu_{2}=0$, then $\int_{X} \operatorname{tr}\left(\mu_{2} \cdot D_{0}^{\prime} \psi\right) \wedge \omega^{n-1}=0$.

Proof. The two identities follow directly from the Stokes' formula. First, because $D_{0}^{\prime \prime} \psi=0$, because $\mu$ is a $(1,0)$-form and because $\omega$ is a Kahler form on $X$,

$$
\int_{X} \operatorname{tr}\left(D_{0}^{\prime \prime} \mu_{1} \cdot \psi\right) \wedge \omega^{n-1}=\int_{X} \bar{\partial}\left(\operatorname{tr}\left(\mu_{1} \cdot \psi\right) \wedge \omega^{n-1}\right)=\int_{X} d\left(\operatorname{tr}\left(\mu_{1} \cdot \psi\right) \wedge \omega^{n-1}\right)=0
$$

This proves the first part. As to the second part, a direct computation shows that

$$
0=\operatorname{tr}\left(D_{0}^{\prime * *} \mu_{2} \cdot \phi\right) \cdot \omega^{n}=-2 n \operatorname{tr}\left(D_{0}^{\prime} \mu_{2} \cdot \phi\right) \cdot \omega^{n-1}
$$

The identity follows immediately.
We now evaluate $\dot{r}(0, t)$ and $\ddot{r}(0, t)$. First, we show that

$$
\begin{equation*}
\left.\frac{d}{d s} L_{s}\left(H_{s, t}\right)\right|_{s=0}=\left.\frac{d}{d s} \tilde{L}_{s}\left(H_{s, t}\right)\right|_{s=0}=0 \tag{2.8}
\end{equation*}
$$

Because $F_{0, H_{0, t}} \wedge \omega^{n-1}=0$, the first identity holds automatically. We now look at the second identity. By definition, there is a function $c(s, t)$ with $c(0, t)=0$ so that

$$
c(s, t) J=L_{s}\left(H_{s, t}\right)=H_{s, t}^{-1 / 2} F_{s, H_{s, t}} H_{s, t}^{1 / 2}
$$

Taking derivative of $s$ at $s=0$ gives us

$$
\dot{c}(0, t) J=\left.\frac{d}{d s}\left(H_{s, t}^{-1 / 2} F_{s, H_{s, t}} H_{s, t}^{1 / 2} \wedge \omega^{n-1}\right)\right|_{s=0}=H_{0, t}^{-1 / 2} \dot{F}_{0, H_{0, t}} H_{0, t}^{1 / 2} \wedge \omega^{n-1} .
$$

Using the explicit form of $H_{0, t}, A_{0}=0, \dot{F}_{0}=D_{0}^{\prime} \dot{A}_{0}-D_{0}^{\prime \prime} \dot{A}_{0}^{*}$ and $D H_{0, t}=0$, we obtain

$$
\left.\frac{d}{d s} \int_{X} \operatorname{tr}\left(H_{s, t}^{-1 / 2} F_{s, H_{s, t}} H_{s, t}^{1 / 2} \wedge \omega^{n-1} \cdot I_{1}\right)\right|_{s=0}=\int_{X} \operatorname{tr}\left(\left(D_{0}^{\prime} \varphi+D_{0}^{\prime \prime} \varphi^{\prime}\right) \cdot I_{1}\right) \wedge \omega^{n-1}
$$

for some smooth sections $\varphi$ and $\varphi^{\prime}$. The right hand side of the above identity is zero by Lemma 2.3 thus

$$
\int_{X} \dot{c}(0, t) \operatorname{tr}\left(J \cdot I_{1}\right)=0
$$

which forces $\dot{c}(0, t)=0$. This proves (2.8), and $\dot{r}(0, t)=0$ for all $t$.
We next compute $\ddot{r}(0, t)$. Because of (2.8),

$$
\left.\frac{d^{2}}{d s^{2}} L_{s}\left(H_{s, t}\right)\right|_{s=0}=\left.H_{0, t}^{-1 / 2} \frac{d^{2}}{d s^{2}} \tilde{L}_{s}\left(H_{s, t}\right)\right|_{s=0} H_{0, t}^{1 / 2}
$$

A direct computation shows that

$$
\begin{equation*}
\left.\frac{d^{2}}{d s^{2}} \tilde{L}_{s}\left(H_{s, t}\right)\right|_{s=0}=\ddot{F}_{0}-2\left[\dot{A}_{0},\left[\dot{A}_{0}^{*}, H_{0, t}\right] H_{0, t}^{-1}\right]-2\left[\dot{A}_{0}, D_{0}^{\prime} \dot{H}_{0, t} \cdot H_{0, t}^{-1}\right]+D_{0}^{\prime \prime} \dot{\varphi}_{0, t} \tag{2.9}
\end{equation*}
$$

with

$$
\begin{equation*}
\varphi_{s, t}=\frac{d}{d s}\left(D_{s}^{\prime} H_{s, t} \cdot H_{s, t}^{-1}\right)=\left(\dot{D}_{s}^{\prime} H_{s, t}+D_{s}^{\prime} \dot{H}_{s, t}\right) H_{s, t}^{-1}=\left[\dot{A}_{s}^{*}, H_{s, t}\right] H_{s, t}^{-1}+D_{s}^{\prime} \dot{H}_{s, t} \cdot H_{s, t}^{-1} \tag{2.10}
\end{equation*}
$$

Because $H_{0, t}$ commutes with $I_{1}$,

$$
\begin{aligned}
\ddot{r}(0, t)=\sqrt{-1}( & \int_{X} \operatorname{tr}\left(\ddot{F}_{0} \cdot I_{1}\right) \wedge \omega^{n-1}-2 \int_{X} \operatorname{tr}\left(\left[\dot{A}_{0},\left[\dot{A}_{0}^{*}, H_{0, t}\right] H_{0, t}^{-1}\right] \cdot I_{1}\right) \wedge \omega^{n-1}- \\
& \left.-2 \int_{X} \operatorname{tr}\left(\left[\dot{A}_{0}, D_{0}^{\prime} \dot{H}_{0, t} \cdot H_{0, t}^{-1}\right] \cdot I_{1}\right) \wedge \omega^{n-1}+\int_{X} \operatorname{tr}\left(D_{0}^{\prime \prime} \dot{\varphi}_{0, t} \cdot I_{1}\right) \wedge \omega^{n-1}\right)
\end{aligned}
$$

To analyze the sign of the above integration, we use the splitting $E=E_{1} \oplus E_{2}$ to express

$$
\dot{A}_{0}=\left(\begin{array}{cc}
C_{11} & C_{12} \\
C_{21} & C_{22}
\end{array}\right)
$$

Because

$$
H_{0, t}=\left(\begin{array}{cc}
\exp \left(\frac{t}{r_{2}}\right) \cdot I_{1} & 0 \\
0 & \exp \left(\frac{-t}{r_{1}}\right) \cdot I_{2}
\end{array}\right)
$$

the second term

$$
-2 \sqrt{-1} \int_{X} \operatorname{tr}\left(\left[\dot{A}_{0},\left[\dot{A}_{0}^{*}, H_{0, t}\right] H_{0, t}^{-1}\right] \cdot I_{1}\right) \wedge \omega^{n-1}
$$

in $\ddot{r}(0, t)$ is, for $\alpha=\frac{1}{n_{1}}+\frac{1}{n_{2}}$,

$$
-2 \sqrt{-1}\left(1-e^{-\alpha t}\right) \int_{X} \operatorname{tr}\left(C_{12} \wedge C_{12}^{*}\right) \wedge \omega^{n-1}-2 \sqrt{-1}\left(1-e^{\alpha t}\right) \int_{X} \operatorname{tr}\left(C_{21}^{*} \wedge C_{21}\right) \wedge \omega^{n-1}
$$

Similarly, because of (2.4) and $F_{s}^{2,0}=F_{s}^{0,2}=0$,

$$
\sqrt{-1} \int_{X} \operatorname{tr}\left(\ddot{F}_{0} \cdot I_{1}\right) \wedge \omega^{n-1}=2 \sqrt{-1} \int_{X} \operatorname{tr}\left(C_{12} \wedge C_{12}^{*}\right) \wedge \omega^{n-1}+2 \sqrt{-1} \int_{X} \operatorname{tr}\left(C_{21}^{*} \wedge C_{21}\right) \wedge \omega^{n-1}
$$

The last term in $\ddot{r}(0, t)$ is zero because of Lemma 2.3] the next-to-last term is

$$
-2 \sqrt{-1} \int_{X} \operatorname{tr}\left(\dot{A}_{0} \cdot D^{\prime} \dot{H}_{0, t} \cdot H_{0, t}^{-1} \cdot I_{1}\right) \wedge \omega^{n-1}+2 \sqrt{-1} \int_{X} \operatorname{tr}\left(D_{0}^{\prime} \dot{H}_{0, t} \cdot H_{0, t}^{-1} \cdot \dot{A}_{0} \cdot I_{1}\right) \wedge \omega^{n-1}
$$

which vanishes because $D_{0}^{\prime \prime *} \dot{A}_{0}=0$ and Lemma 2.3. Therefore,

$$
\ddot{r}(0, t)=\sqrt{-1} e^{-\alpha t} \int_{X} \operatorname{tr}\left(C_{12} \wedge C_{12}^{*}\right) \wedge \omega^{n-1}+\sqrt{-1} e^{\alpha t} \int_{X} \operatorname{tr}\left(C_{21}^{*} \wedge C_{21}\right) \wedge \omega^{n-1}
$$

Because the associated cohomology class $\left[C_{i j}\right]=\kappa_{i j}$ and $\kappa_{21}$ and $\kappa_{12}$ are both non-zero,

$$
A=\sqrt{-1} \int_{X} \operatorname{tr}\left(C_{12} \wedge C_{12}^{*}\right) \wedge \omega^{n-1} \quad \text { and } \quad B=-\sqrt{-1} \int_{X} \operatorname{tr}\left(C_{21}^{*} \wedge C_{21}\right) \wedge \omega^{n-1}
$$

are positive. Hence for sufficiently small $s$, the value $r(s, t)>0$ for $t<\frac{1}{2 \alpha} \ln \frac{A}{B}$ and $r(s, t)>0$ for $t>\frac{1}{2 \alpha} \ln \frac{A}{B}$. Hence there is a function $t=\rho(s)$ so that $r(s, \rho(s))=0$. This proves that the system $L_{s}(H)=0$ is solvable for small $s$. Here the function $\rho(s)$ is not necessarily continuous, but $\lim _{s \rightarrow 0} \rho(s)=\frac{1}{2 \alpha} \ln \frac{A}{B}$.

## 3. Linearization of Strominger's system

In this section we will study the linearization of Strominger's system. Before we do this, we will first rephrase the system (1.1)-(1.4) in the form that is easier to handle.

We fix a Calabi-Yau threefold $\left(X, \omega_{0}\right)$ and a (3, 0)-holomorphic form $\Omega$ so that $\Omega \wedge \bar{\Omega}=$ $\omega_{0}^{3}$. We let $\left(E, D^{\prime \prime}\right)$ be a rank $r$ holomorphic bundle over $X$ such that $c_{1}(E)=0$ and $c_{2}(E)=c_{2}(X)$. We then choose a hermitian metric $H$ on $E$ and let $D_{H}=D_{H}^{\prime} \oplus D^{\prime \prime}$ be the hermitian connection of $\left(E, D^{\prime \prime}, H\right)$; its curvature $F_{H}=D_{H} \circ D_{H}$ satisfies

$$
F_{H}^{2,0}=F_{H}^{0,2}=0
$$

Thus the second equation of the Strominger's system follows automatically.
The fourth equation of the system is a non-linear equation of a hermitian form $\omega$ involving the adjoint $d_{\omega}^{*}$ of $\omega$. It turns out that this equation is equivalent to

$$
d\left(\|\Omega\|_{\omega} \omega^{2}\right)=0
$$

We now prove this equivalence. We let $\mathcal{H}(X)$ and $\mathcal{K}(X)$ be the cones of positive definite hermitian forms and Kahler forms on $X$ respectively. Given an $\omega \in \mathcal{H}(X)$, we let $*_{\omega}$ be the (hermitian) star operator of $\omega$; and let $d_{\omega}^{*}$ be the adjoint of $d$ with respect to the metric $\omega$.

The hermitian star operator has an explicit local expression. Given a hermitian form $\omega$ on $X$ it induces canonical hermitian metrics on $T_{X, \mathbb{C}}$ and on $\wedge^{k} T_{X, \mathbb{C}}^{\vee}$. Let $(\cdot, \cdot)_{\omega}$ be the hermitian metric on $\wedge^{k} T_{X, \mathbb{C}}^{\vee}$ and $\frac{1}{3!} \omega^{3}$ its associated volume form on $X$. The star operator $*_{\omega}$ is the $\mathbb{C}$-linear operator defined via

$$
(\varphi, \psi)_{\omega} \cdot \frac{\omega^{3}}{3!}=\varphi \wedge *_{\omega} \bar{\psi}
$$

Let $p \in X$ be any point and let $\varphi_{1}, \varphi_{2}, \varphi_{2}$ be an $(\cdot, \cdot)_{\omega}$-orthonormal basis (a moving frame) of the ( 1,0 )-forms near $p$ obeying $\left(\varphi_{i}, \varphi_{j}\right)_{\omega}=2 \delta_{i j}$. Then the hermitian form

$$
\omega=\frac{\sqrt{-1}}{2} \sum_{i=1}^{3} \varphi_{i} \wedge \bar{\varphi}_{i} .
$$

For any subset $I=\left\{i_{1}, \cdots, i_{k}\right\} \subset\{1,2,3\}$, we denote by $\varphi_{I}=\varphi_{i_{1}} \wedge \cdots \wedge \varphi_{i_{k}}$, and denote by $I^{\circ}$ the complement $\{1,2,3\}-I$. Following this convention,

$$
\begin{equation*}
*_{\omega}\left(c \bar{\varphi}_{I} \wedge \varphi_{J}\right)=\epsilon_{I J} \sqrt{-1} 2^{|I|+|J|-3} c \varphi_{I^{\circ}} \wedge \bar{\varphi}_{J^{\circ}}, \quad c \in \mathbb{C}, \tag{3.1}
\end{equation*}
$$

where $\epsilon_{I J}$ is the parity of permuting $\left(I, J ; I^{\circ}, J^{\circ}\right) \mapsto\left(1,2,3 ; 1^{\prime}, 2^{\prime}, 3^{\prime}\right)$.
We now re-state and prove the mentioned equivalence.

Lemma 3.1. Let $\omega_{0}$ be the reference Kahler form as before. Then the equation (1.4) is equivalent to

$$
\begin{equation*}
*_{\omega_{0}} d\left(\|\Omega\|_{\omega} \omega^{2}\right)=0 \tag{3.2}
\end{equation*}
$$

Proof. Let $f$ be a positive real valued function, then

$$
d\left(f \omega^{2}\right)=f d \omega^{2}+d f \wedge \omega^{2}=2 f d *_{\omega} \omega+d f \wedge \omega^{2}
$$

Thus

$$
*_{\omega} d\left(f \omega^{2}\right)=2 f *_{\omega} d *_{\omega} \omega+*_{\omega}\left(d f \wedge \omega^{2}\right)=-2 f d_{\omega}^{*} \omega+2 d_{c} f
$$

Here we have used the identity

$$
*_{\omega}\left(d f \wedge \omega^{2}\right)=2 d_{c} f
$$

which holds for all hermitian form $\omega$. Replacing $f$ by $\|\Omega\|$, we obtain

$$
*_{\omega} d\left(\|\Omega\|_{\omega} \omega^{2}\right)=2\|\Omega\|_{\omega}\left(-d_{\omega}^{*} \omega+d_{c} \log \|\Omega\|_{\omega}\right)
$$

which vanishes if and only if

$$
d_{\omega}^{*} \omega=d_{c} \log \|\Omega\|_{\omega}
$$

Finally, since $*_{\omega}$ and $*_{\omega_{0}}$ are both isomorphisms, $*_{\omega} d\left(\|\Omega\|_{\omega}^{-1} \omega^{2}\right)=0$ if and only if

$$
*_{\omega_{0}} d\left(\|\Omega\|_{\omega} \omega^{2}\right)=0
$$

This proves the lemma.
To apply the implicit function theorem, we need to specify the range of the operators associated to Strominger's system. For that, noting that $2 d d_{c}=\sqrt{-1} \partial \bar{\partial}$, we let $R\left(d d_{c}\right) \subset$ $\Omega_{\mathbb{R}}^{2,2}(X)$ and $R\left(d_{\omega_{0}}^{*}\right) \subset \Omega_{\mathbb{R}}^{1}(X)$ be the range of

$$
d d_{c}: \Omega_{\mathbb{R}}^{1,1}(X) \rightarrow \Omega_{\mathbb{R}}^{2,2}(X) \quad \text { and } \quad d_{\omega_{0}}^{*}: \Omega_{\mathbb{R}}^{1,1}(X) \rightarrow \Omega_{\mathbb{R}}^{1}(X)
$$

Because $\left(X, \omega_{0}\right)$ is a Kahler manifold, by $\partial \bar{\partial}$-lemma, a real form $\alpha \in R\left(d d_{c}\right)$ if and only if $d \alpha=0$. Hence, after picking a usual Banach norm on $\Omega_{\mathbb{R}}^{2,2}(X), R\left(d d_{c}\right)$ is closed in it. As to $R\left(d_{\omega_{0}}^{*}\right)$, since $d_{\omega_{0}}^{*}$ is part of an elliptic complex, it is also closed. This way, after replacing (1.4) by (3.2) and omitting the equation (1.2), the Strominger's system is equivalent to the vanishing of the operator

$$
\begin{equation*}
\mathbf{L}=\mathbf{L}_{1} \oplus \mathbf{L}_{2} \oplus \mathbf{L}_{3}: \mathcal{H}(E)_{1} \times \mathcal{H}(X) \longrightarrow \Omega_{\mathbb{R}}^{6}(\mathfrak{s u} E) \oplus R\left(d d_{c}\right) \oplus R\left(d_{\omega_{0}}^{*}\right) \tag{3.3}
\end{equation*}
$$

defined by

$$
\begin{gather*}
\mathbf{L}_{1}(H, \omega)=H^{-1 / 2} F_{H} H^{1 / 2} \wedge \omega^{2} \in \Omega_{\mathbb{R}}^{6}(\mathfrak{s u} E)  \tag{3.4}\\
\mathbf{L}_{2}(H, \omega)=\frac{1}{2} d d_{c} \omega+\left(\operatorname{tr}\left(F_{H} \wedge F_{H}\right)-\operatorname{tr}\left(R_{\omega} \wedge R_{\omega}\right)\right) \in \Omega_{\mathbb{R}}^{2,2}(X) ;  \tag{3.5}\\
\mathbf{L}_{3}(H, \omega)=*_{\omega_{0}} d\left(\|\Omega\|_{\omega} \omega^{2}\right) \in \Omega_{\mathbb{R}}^{1}(X) \tag{3.6}
\end{gather*}
$$

Because $c_{2}(E)=c_{2}(T X)$ and $X$ is a Kahler manifold, by $\partial \bar{\partial}$-lemma the image of $\mathbf{L}_{2}$ lies in $R(P)$. As to $\mathbf{L}_{3}$, because

$$
*_{\omega_{0}} d= \pm *_{\omega_{0}} d *_{\omega_{0}} *_{\omega_{0}}^{-1}=\mp d_{\omega_{0}}^{*} *_{\omega_{0}}^{-1}
$$

its image lies in the range of $d_{\omega_{0}}^{*}$ as well. Therefore the operator $\mathbf{L}$ is well-defined.

Proposition 3.2. Suppose $\mathbf{L}\left(H, \omega_{0}\right)=0$. Then the three summands of the linearization of $\mathbf{L}$ at $\left(H, \omega_{0}\right)$ are

$$
\begin{aligned}
\delta \mathbf{L}_{1}\left(H, \omega_{0}\right)(\delta h, \delta \omega) & =D^{\prime \prime} D_{H}^{\prime} \delta h \wedge \omega_{0}^{2}+2 H^{-1 / 2} F_{H} H^{1 / 2} \wedge \omega_{0} \wedge \delta \omega \\
\delta \mathbf{L}_{2}\left(H, \omega_{0}\right)(\delta h, \delta \omega) & =\frac{1}{2} d d_{c} \delta \omega+2\left(\operatorname{tr}\left(\delta F_{H}(\delta h) \wedge F_{H}\right)-\operatorname{tr}\left(\delta R_{\omega_{0}}(\delta \omega) \wedge R_{\omega_{0}}\right)\right) \\
\delta \mathbf{L}_{3}\left(H, \omega_{0}\right)(\delta h, \delta \omega) & =2 d_{\omega_{0}}^{*} \delta \omega-d_{\omega_{0}}^{*}\left(\left(\delta \omega, \omega_{0}\right)_{\omega_{0}} \omega_{0}\right)
\end{aligned}
$$

Here as before we follow the convention $\delta H=H^{-1 / 2} \delta h H^{-1 / 2}$.
Proof. The formula for $\delta \mathbf{L}_{1}$ is well-known [27]; the formula for $\delta \mathbf{L}_{2}$ in the written form is a tautology; we stop short of finding an explicit form of $\delta R$ since the current form is sufficient for our purposes.

We now prove the formula for $\delta \mathbf{L}_{3}$. Let $\omega_{t}$ be a smooth variation of the hermitian form $\omega_{0}$; let $\varphi_{1}(t), \varphi_{2}(t), \varphi_{3}(t)$ be an orthonormal basis of (1,0)-forms, smooth in $t$, expressed in a holomorphic coordinate $\left(z_{1}, z_{2}, z_{3}\right)$ near $p \in X$ by

$$
\varphi_{i}(t)=\sum_{j} b_{i j}(t) d z_{j}, \quad b_{i j}(0)(p)=\delta_{i j} \quad \text { and } \quad\left(\varphi_{i}(t), \varphi_{j}(t)\right)_{\omega_{t}}=2 \delta_{i j}
$$

We can compute explicitly $\left.\frac{d}{d t}\left(\omega_{t}^{2}\right)\right|_{t=0}$. First,

$$
\omega_{t}^{2}=\frac{1}{2} \sum \varphi_{i^{\circ}}(t) \wedge \bar{\varphi}_{i^{\circ}}(t)=\frac{1}{2} \sum_{i, l, k} c_{i k}(t) \bar{c}_{i l}(t) d z_{k^{\circ}} \wedge d \bar{z}_{l^{\circ}},
$$

where $c_{i j}(t)$ is the $i j$-th minor of the matrix $\left(b_{i j}(t)\right)_{3 \times 3}$; namely

$$
\begin{equation*}
\left(c_{i j}(t)\right)^{t}=\operatorname{det}\left(b_{i j}(t)\right) \cdot\left(b_{i j}(t)\right)^{-1} \tag{3.7}
\end{equation*}
$$

Hence at $p$,

$$
\left.\frac{d}{d t} \omega_{t}^{2}\right|_{t=0}=\frac{1}{2} \sum\left(\dot{c}_{l k}(0)+\dot{\bar{c}}_{k l}(0)\right) d z_{k^{\circ}} \wedge d \bar{z}_{l^{\circ}}
$$

Using the identity (3.7) above,

$$
\dot{c}_{l k}(0)+\dot{\bar{c}}_{k l}(0)=-\dot{b}_{k l}(0)-\dot{\bar{b}}_{l k}(0)+c_{l k}(0) \sum \dot{b}_{i i}(0)+\bar{c}_{k l}(0) \sum_{i} \dot{\bar{b}}_{i i}(0)
$$

Therefore at $p$,

$$
\left.\frac{d}{d t} \omega_{t}^{2}\right|_{t=0}=\frac{-1}{2} \sum_{l, k}\left(\dot{b}_{k l}(0)+\dot{\bar{b}}_{l k}(0)\right) d z_{k^{\circ}} \wedge d \bar{z}_{l^{\circ}}+\frac{1}{2}\left(\sum_{k} d z_{k^{\circ}} \wedge d \bar{z}_{k^{\circ}}\right) \cdot\left(\sum \dot{b}_{i i}(0)+\dot{\bar{b}}_{i i}(0)\right)
$$

On the other hand, $\omega_{0}^{2}=\frac{1}{2} \sum d z_{k} \circ \wedge d \bar{z}_{k^{\circ}}$. Hence

$$
\begin{equation*}
\left.\frac{d}{d t} \omega_{t}^{2}\right|_{t=0}=\frac{-1}{2} \sum_{l, k}\left(\dot{b}_{k l}(0)+\dot{\bar{b}}_{l k}(0)\right) d z_{k^{\circ}} \wedge d \bar{z}_{l^{\circ}}+\omega_{0}^{2}\left(\sum \dot{b}_{i i}(0)+\dot{\bar{b}}_{i i}(0)\right) \tag{3.8}
\end{equation*}
$$

Next we compute

$$
\left.\frac{d}{d t} \log \|\Omega\|_{\omega_{t}}^{2}\right|_{t=0}=-\left.\frac{d}{d t} \frac{\omega_{t}^{3}}{\omega_{0}^{3}}\right|_{t=0}=-\sum \dot{b}_{i i}(0)+\dot{\bar{b}}_{i i}(0)
$$

Adding $\|\Omega\|_{\omega_{0}} \equiv 1$, we get

$$
\begin{aligned}
\left.\frac{d}{d t}\left(\|\Omega\|_{\omega_{t}} \omega_{t}^{2}\right)\right|_{t=0} & =\left.\left(\frac{1}{2} \omega_{0}^{2} \frac{d}{d t} \log \|\Omega\|_{\omega_{t}}^{2}+\frac{d}{d t} \omega_{t}^{2}\right)\right|_{t=0} \\
& =-\frac{1}{2} \sum_{l, k}\left(\dot{b}_{k l}(0)+\dot{b}_{l k}(0)\right) d z_{k^{\circ}} \wedge d \bar{z}_{l^{\circ}}+\frac{1}{2}\left(\sum \dot{b}_{i i}(0)+\dot{\bar{b}}_{i i}(0)\right) \omega_{0}^{2}
\end{aligned}
$$

On the other hand, at $p$

$$
\left.\frac{d}{d t} \omega_{t}\right|_{t=0}=\frac{\sqrt{-1}}{2} \sum_{i} \dot{\varphi}_{i} \wedge \bar{\varphi}_{i}+\varphi_{i} \wedge \dot{\bar{\varphi}}_{i}=\frac{\sqrt{-1}}{2} \sum_{i, j}\left(\dot{b}_{j i}(0)+\dot{\bar{b}}_{i j}(0)\right) d z_{i} \wedge d \bar{z}_{j}
$$

Hence

$$
*_{\omega_{0}} \dot{\omega}_{0}=\frac{1}{4} \sum_{i, j}\left(\dot{\bar{b}}_{j i}(0)+\dot{b}_{i j}(0)\right) d z_{i^{\circ}} \wedge d \bar{z}_{j^{\circ}}
$$

Combined, we obtain

$$
\left.\frac{d}{d t}\left(\|\Omega\|_{\omega_{t}} \omega_{t}^{2}\right)\right|_{t=0}=-2 *_{\omega_{0}} \dot{\omega}_{0}+\left(\sum \dot{b}_{i i}(0)+\dot{\bar{b}}_{i i}(0)\right) \frac{\omega_{0}^{2}}{2}
$$

It remains to treat the term $\sum \dot{b}_{i i}(0)+\dot{\bar{b}}_{i i}(0)$. From

$$
\left(\dot{\omega}_{0}, \omega_{0}\right)_{\omega_{0}} \frac{\omega_{0}^{3}}{3!}=\dot{\omega}_{0} \wedge *_{\omega_{0}} \omega_{0} \quad \text { and } \quad *_{\omega_{0}} \omega_{0}=\frac{1}{4} \sum d z_{k^{\circ}} \wedge d \bar{z}_{k^{\circ}}
$$

we get

$$
\begin{aligned}
\dot{\omega}_{0} \wedge *_{\omega_{0}} \omega_{0} & =\frac{\sqrt{-1}}{8} \sum\left(\dot{b}_{i j}(0)+\dot{\bar{b}}_{j i}(0)\right) d z_{i} \wedge d \bar{z}_{j} \wedge d z_{k^{\circ}} \wedge d \bar{z}_{k^{\circ}} \\
& =-\frac{\sqrt{-1}}{8} \sum\left(\dot{b}_{i i}(0)+\dot{\bar{b}}_{i i}(0)\right) d z_{1} \wedge d \bar{z}_{1} \wedge d z_{2} \wedge d \bar{z}_{2} \wedge d z_{3} \wedge d \bar{z}_{3}
\end{aligned}
$$

hence

$$
\left(\dot{\omega}_{0}, \omega_{0}\right)_{\omega_{0}}=\frac{\dot{\omega}_{0} \wedge *_{\omega_{0}} \omega_{0}}{\omega_{0}^{3} / 3!}=\sum \dot{b}_{i i}(0)+\dot{\bar{b}}_{i i}(0)
$$

This proves that

$$
\left.\frac{d}{d t}\left(\|\Omega\|_{\omega_{t}} \omega_{t}^{2}\right)\right|_{t=0}=-2 *_{\omega_{0}} \dot{\omega}_{0}+\left(\sum \dot{b}_{i i}(0)+\dot{\bar{b}}_{i i}(0)\right) \omega_{0}^{2}=-2 *_{\omega_{0}} \dot{\omega}_{0}+*_{\omega_{0}}\left(\dot{\omega}_{0}, \omega_{0}\right)_{\omega_{0}} \omega_{0}
$$

Finally, Applying $*_{\omega_{0}} d$ to both sides of this identity, we obtain

$$
\left.\frac{d}{d t} *_{\omega_{0}} d\left(\|\Omega\|_{\omega_{t}} \omega_{t}^{2}\right)\right|_{t=0}=2 d_{\omega_{0}}^{*} \dot{\omega}_{0}-d_{\omega_{0}}^{*}\left(\left(\dot{\omega}_{0}, \omega_{0}\right)_{\omega_{0}} \omega_{0}\right)
$$

This proves the Proposition.
Strominger's system admits a class of reducible solutions. Let

$$
\left(E, D_{0}^{\prime \prime}\right)=\mathbb{C}_{X}^{\oplus r} \oplus T X
$$

be the direct sum of the trivial holomorphic bundle $\mathbb{C}_{X}^{\oplus r}$ and the tangent bundle $T X$. We fix an isomorphism $\wedge^{r+3} E \cong \mathbb{C}_{X}$; we endow $E$ with the hermitian metric $<,>$ that is a direct sum of a constant metric on $\mathbb{C}_{X}^{\oplus r}$ and the Calabi-Yau metric $\omega_{0}$ on $T X$. We normalize $<,>$ so that its induced metric on $\wedge^{r+3} E \cong \mathbb{C}_{X}$ is the constant one metric. As before, the metric $<,>$ is identified with the identity endomorphism $I: E \rightarrow E$.

Now let $\mathcal{H}_{r \times r}^{+}$be the space of positive definite hermitian symmetric $r \times r$ metrics; let $I_{1}$ and $I_{2}$ be the identity endomorphisms of $\mathbb{C}_{X}^{\oplus r}$ and $T X$ respectively. By abuse of notation, for $T \in \mathcal{H}_{r \times r}^{+}$we also view it as the constant endomorphism of $\mathbb{C}_{X}^{\oplus r}$ induced by $T$, viewed as an endomorphism of $E$. Then the assignment

$$
T \in \mathcal{H}_{r \times r}^{+} \longmapsto H_{T}=T \oplus|T|^{-1 / 3} I_{2} \in \mathcal{H}(E)_{1},|T|=\operatorname{det} T
$$

associates each $T \in \mathcal{H}_{r \times r}^{+}$to a hermitian metric of $E$.

Obviously, the hermitian curvature $F_{H_{T}}$ of $\left(E,<,>_{H_{T}}\right)$ is $0 \oplus R_{\omega_{0}}$; hence $F_{H_{T}} \wedge F_{H_{T}}=$ $R_{\omega_{0}} \wedge R_{\omega_{0}}$. Because $\omega_{0}$ is $d$-closed,

$$
\mathbf{L}_{2}\left(H_{T}, \omega_{0}\right)=\frac{1}{2} d d_{c} \omega_{0}+\operatorname{tr}\left(F_{H_{T}} \wedge F_{H_{T}}\right)-\operatorname{tr}\left(R_{\omega_{0}} \wedge R_{\omega_{0}}\right)=0
$$

Further, because $<,>_{H_{T}}$ is Hermitian-Yang-Mills, and because $d_{\omega_{0}}^{*} \omega_{0}=0$ and $\Omega \wedge \bar{\Omega}=\omega_{0}^{3}$, $\mathbf{L}_{1}\left(H_{T}, \omega_{0}\right)=\mathbf{L}_{3}\left(H_{T}, \omega_{0}\right)=0$. Therefore $\left(H_{T}, \omega_{0}\right)$ is a solution to $\mathbf{L}(H, \omega)=0$. Indeed, for any constant $c>0$, the pair $\left(H_{T}, c \omega_{0}\right)$ is a solution to $\mathbf{L}=0$. These solutions are reducible because the vector bundle $E$ splits under the hermitian connection $D_{H_{T}}$. In this paper, we will call such solutions the trivial solutions to Strominger's system.

To construct irreducible solutions to Strominger's system, we will first form a family of holomorphic structures $D_{s}^{\prime \prime}$ on $E$ that is a smooth deformation of $D_{0}^{\prime \prime}$; we then show that certain trivial solutions to Strominger's system on ( $E, D_{0}^{\prime \prime}$ ) can be extended to (irreducible) solutions on $\left(E, D_{s}^{\prime \prime}\right)$. We shall prove this by applying implicit function theorem to the operator $\mathbf{L}$ of (3.3).

To this end, we pick an integer $k$ and a large $p$ and endow the domain and the target of $\mathbf{L}$ the Banach space structures as indicated:

$$
\mathcal{H}(E)_{1, L_{k}^{p}} \times \mathcal{H}(X)_{L_{k}^{p}} \longrightarrow \Omega_{\mathbb{R}}^{6}(\mathfrak{s u} E)_{L_{k-2}^{p}} \oplus R\left(d d_{c}\right)_{L_{k-2}^{p}} \oplus R\left(d_{\omega_{0}}^{*}\right)_{L_{k-1}^{p}}
$$

$\mathbf{L}$ becomes a smooth operator and its linearized operator $\delta \mathbf{L}$ at a solution $(H, \omega)$ becomes a linear map

$$
\Omega^{0}\left(\mathfrak{H e r}^{0} E\right)_{L_{k}^{p}} \oplus \Omega_{\mathbb{R}}^{1,1}(X)_{L_{k}^{p}} \longrightarrow \Omega_{\mathbb{R}}^{6}(\mathfrak{s u} E)_{L_{k-2}^{p}} \oplus R\left(d d_{c}\right)_{L_{k-2}^{p}} \oplus R\left(d_{\omega_{0}}^{*}\right)_{L_{k-1}^{p}}
$$

Here we used the canonical isomorphisms $T_{H} \mathcal{H}(E)_{1, L_{k}^{p}} \cong \Omega^{0}\left(\mathfrak{H e r}^{0} E\right)_{L_{k}^{p}}$ and $T_{\omega} \mathcal{H}(X)_{L_{k}^{p}} \cong$ $\Omega_{\mathbb{R}}^{1,1}(X)_{L_{k}^{p}}$. For simplicity, in the following we will abbreviate

$$
\mathcal{W}_{1}=\Omega_{\mathbb{R}}^{6}(\mathfrak{s u} E)_{L_{k-2}^{p}} \quad \text { and } \quad \mathcal{W}_{2}=R\left(d d_{c}\right)_{L_{k-2}^{p}} \oplus R\left(d_{\omega_{0}}^{*}\right)_{L_{k-1}^{p}}
$$

Thus $\delta \mathbf{L}(H, \omega)$ is a linear map

$$
\begin{equation*}
\delta \mathbf{L}(H, \omega): \Omega^{0}\left(\mathfrak{H e r}^{0} E\right)_{L_{k}^{p}} \oplus \Omega_{\mathbb{R}}^{1,1}(X)_{L_{k}^{p}} \longrightarrow \mathcal{W}_{1} \oplus \mathcal{W}_{2} \tag{3.9}
\end{equation*}
$$

To study the kernel and the cokernel of $\delta \mathbf{L}$ at a trivial solution $\left(H_{T}, c \omega_{0}\right)$ we will first look at the linear map

$$
\begin{equation*}
\mathbf{F}(\delta h)=D_{0}^{\prime \prime} D_{0, H_{T}}^{\prime}(\delta h) \wedge \omega_{0}^{2}: \Omega^{0}\left(\mathfrak{H e r}^{0} E\right)_{L_{k}^{p}} \longrightarrow \Omega_{\mathbb{R}}^{6}(\mathfrak{s u} E)_{L_{k-2}^{p}} \tag{3.10}
\end{equation*}
$$

Here according to our convention, $D_{H_{T}}=D_{0, H_{T}}^{\prime} \oplus D_{0}^{\prime \prime}$ is the hermitian connection of $\left(E, D_{0}^{\prime \prime}, H_{T}\right)$ for a $T \in \mathcal{H}_{r \times r}^{+}$. Since $\left(E, D_{0}^{\prime \prime}\right)=\mathbb{C}_{X}^{\oplus r} \oplus T X$, the above is a linear elliptic operator of index 0 whose kernel is

$$
V_{0}=\left\{M \oplus a I_{2} \mid M \in \operatorname{End}\left(\mathbb{C}^{\oplus r}\right), M=M^{*}, \operatorname{tr} M+3 a=0\right\}
$$

and cokernel is

$$
\begin{equation*}
V_{1}=\omega_{0}^{3} \cdot V_{0} \subset \mathcal{W}_{1}=\Omega_{\mathbb{R}}^{6}(\mathfrak{s u} E)_{L_{k-2}^{p}} \tag{3.11}
\end{equation*}
$$

We let $\mathbf{P}$ be the obvious projection

$$
\mathbf{P}: \mathcal{W}_{1} \longrightarrow \mathcal{W}_{1} / V_{1}
$$

Proposition 3.3. Let $\left(X, \omega_{0}\right), \Omega,<,>$ and $T \in \mathcal{H}_{r \times r}^{+}$be as before. Then there is a constant $C$ so that for any $c>C$, the linear operator

$$
\mathbf{P} \circ \delta \mathcal{L}_{1}\left(H_{T}, c \omega_{0}\right) \oplus \delta \mathcal{L}_{2}\left(H_{T}, c \omega_{0}\right) \oplus \delta \mathcal{L}_{3}\left(H_{T}, c \omega_{0}\right)
$$

from $\Omega^{0}\left(\mathfrak{H e r}^{0} E\right)_{L_{k}^{p}} \oplus \Omega_{\mathbb{R}}^{1,1}(X)_{L_{k}^{p}}$ to $\mathcal{W}_{1} / V_{1} \oplus \mathcal{W}_{2}$ is surjective.

Proof. As we shall see, the proof of the Proposition relies on the understanding of the operator

$$
T: \Omega_{\mathbb{R}}^{1,1}(X)_{L_{k}^{p}} \longrightarrow \mathcal{W}_{2}
$$

defined by, after setting $P=\frac{1}{2} d d_{c}=\sqrt{-1} \partial \bar{\partial}$,

$$
T \mu=\left(P \mu, 2 d_{\omega_{0}}^{*} \mu-d_{\omega_{0}}^{*}\left(\left(\mu, \omega_{0}\right)_{\omega_{0}} \omega_{0}\right)\right)
$$

Before we go on, we remark that since in the proof of this Proposition we will solely work with the Kahler form $\omega_{0}$, for convenience we will abbreviate $*_{\omega_{0}}$ and $d_{\omega_{0}}^{*}$ to $*$ and $d^{*}$.

For the starter, we form the linear operator $S$ :

$$
S \mu=2 \mu-\left(\mu, \omega_{0}\right)_{\omega_{0}} \omega_{0}: \Omega_{\mathbb{R}}^{1,1} \longrightarrow \Omega_{\mathbb{R}}^{1,1}
$$

and its inverse

$$
S^{-1} \phi=\frac{1}{2}\left(\phi-\left(\phi, \omega_{0}\right)_{\omega_{0}} \omega_{0}\right)
$$

Then by setting $\phi=S \mu, T \mu$ can be expressed as

$$
T \mu=T \circ S^{-1} \phi=\left(P \circ S^{-1} \phi, d^{*} \phi\right)
$$

Then applying the Hodge decomposition to $\phi \in \Omega_{\mathbb{R}}^{1,1}(X)$,

$$
\phi=d d^{*} \psi+d^{*} d \psi+h
$$

for a real $(1,1)$-form $\psi$ and harmonic $h$. By the $\partial \bar{\partial}$-lemma, we can rewrite $d^{*} d \psi=* P \alpha$ for a real form $\alpha$.

As to the harmonic $h$, we check that the pairing $\left(h, \omega_{0}\right)_{\omega_{0}}$ is constant. Since $\left(X, \omega_{0}\right)$ is Kahler,

$$
d_{c} * h=d^{*} * h \wedge \omega_{0}-d^{*}\left(* h \wedge \omega_{0}\right)
$$

and since $d^{*} * h=d_{c} * h=0, d^{*}\left(* h \wedge \omega_{0}\right)=0$. Hence the defining identity

$$
\begin{equation*}
\left(h, \omega_{0}\right) * 1=* h \wedge \omega_{0} \tag{3.12}
\end{equation*}
$$

forces $\left(h, \omega_{0}\right)_{\omega_{0}}$ to be a constant. Therefore the space of harmonic forms $\mathbb{H} \subset \Omega_{\mathbb{R}}^{1,1}(X)$ lies in the kernel of both $T$ and $T \circ S^{-1}$.

With this said, to study the surjectivity of $T$ we only need to look at those $\phi$ that are orthogonal to $\mathbb{H}$ under the $L^{2}$-intersection pairing

$$
<u, v>=\int_{X}(u, v)_{\omega_{0}} * 1 .
$$

In particular, such $\phi$ has decomposition

$$
\phi=* P \alpha+d^{*} d \psi
$$

and

$$
T \circ S^{-1} \phi=\left(P \circ S^{-1}(* P \alpha)+P \circ S^{-1}\left(d d^{*} \psi\right), d^{*} d\left(d^{*} \psi\right)\right)
$$

To proceed, we look at the operator $U$ :

$$
\begin{equation*}
U \alpha=2 * P \circ S^{-1}(* P \alpha)=* P\left(* P \alpha-\left(* P \alpha, \omega_{0}\right)_{\omega_{0}} \omega_{0}\right) \tag{3.13}
\end{equation*}
$$

Because

$$
P^{*}=(\sqrt{-1} \partial \bar{\partial})^{*}=-\sqrt{-1} \bar{\partial}^{*} \partial^{*}=* \sqrt{-1} \partial \bar{\partial} *=* P *
$$

$U \alpha$ can be re-written as

$$
\begin{equation*}
U \alpha=P^{*} P \alpha-* P\left(\left(* P(\alpha), \omega_{0}\right)_{\omega_{0}} \omega_{0}\right) \tag{3.14}
\end{equation*}
$$

To proceed, we need to simplify the operator $U$. We first use the identities

$$
\begin{equation*}
\partial^{*} \mu \wedge \omega_{0}-\partial^{*}\left(\mu \wedge \omega_{0}\right)=\sqrt{-1} \bar{\partial} \mu \quad \text { and } \quad \bar{\partial}^{*} \mu \wedge \omega_{0}-\bar{\partial}^{*}\left(\mu \wedge \omega_{0}\right)=-\sqrt{-1} \partial \mu \tag{3.15}
\end{equation*}
$$

which hold for all Kahler manifolds, to derive

$$
\partial^{*}\left(f \omega_{0}^{2}\right)=-2 \sqrt{-1} \bar{\partial} f \wedge \omega_{0}
$$

Using $\left(* P \alpha, \omega_{0}\right)_{\omega_{0}}=*\left(P \alpha \wedge \omega_{0}\right)$, which follows from (3.12), we have

$$
P\left(\left(* P \alpha, \omega_{0}\right)_{\omega_{0}} \omega_{0}\right)=P\left(*\left(P \alpha \wedge \omega_{0}\right) \wedge \omega_{0}\right)=-\sqrt{-1} * \bar{\partial}^{*} \partial^{*}\left(P \alpha \wedge \omega_{0}\right) \wedge \omega_{0}
$$

Applying the identities (3.15) further, we obtain

$$
\partial^{*}\left(P \alpha \wedge \omega_{0}\right)=\partial^{*} P \alpha \wedge \omega-\sqrt{-1} \bar{\partial} P \alpha=\partial^{*} P \alpha \wedge \omega
$$

and

$$
\bar{\partial}^{*} \partial^{*}\left(P \alpha \wedge \omega_{0}\right)=\bar{\partial}^{*}\left(\partial^{*} P \alpha \wedge \omega_{0}\right)=\bar{\partial}^{*} \partial^{*} P \alpha \wedge \omega_{0}+\sqrt{-1} \partial \partial^{*} P \alpha \wedge \omega_{0}
$$

Put together, we obtain

$$
\begin{aligned}
P\left(\left(* P \alpha, \omega_{0}\right)_{\omega_{0}} \omega_{0}\right) & =-\sqrt{-1} * \bar{\partial}^{*} \partial^{*}\left(P \alpha \wedge \omega_{0}\right) \wedge \omega_{0} \\
& =-\sqrt{-1} *\left(\bar{\partial}^{*} \partial^{*} P \alpha \wedge \omega_{0}+\sqrt{-1} \partial \partial^{*} P \alpha \wedge \omega_{0}\right) \wedge \omega_{0} \\
& =*\left(P^{*} P \alpha \wedge \omega_{0}\right) \wedge \omega_{0}+*\left(\partial \partial^{*} P \alpha \wedge \omega_{0}\right) \wedge \omega_{0}
\end{aligned}
$$

Because $\partial \partial^{*} P \alpha=\square_{\partial} P \alpha$ since $\partial P \alpha=0$, the operator $U$ becomes

$$
\begin{equation*}
U(\alpha)=P^{*} P \alpha-*\left(*\left(P^{*} P \alpha \wedge \omega\right) \wedge \omega_{0}\right)-*\left(*\left(\square_{\partial} P \alpha \wedge \omega_{0}\right) \wedge \omega_{0}\right) \tag{3.16}
\end{equation*}
$$

To continue, recall that for $\nu \in \Omega_{\mathbb{R}}^{1,1}(X)$ such that $\left(\nu, \omega_{0}\right)_{\omega_{0}}=0, *\left(\nu \wedge \omega_{0}\right)=-\nu$. Hence

$$
*\left(\nu \wedge \omega_{0}\right)=*\left(\left(\nu-\frac{1}{3}\left(\nu, \omega_{0}\right)_{\omega_{0}} \omega_{0}\right) \wedge \omega_{0}\right)+\frac{1}{3} *\left(\left(\nu, \omega_{0}\right)_{\omega_{0}} \omega_{0}^{2}\right)=-\nu+\left(\nu, \omega_{0}\right)_{\omega_{0}} \omega_{0}
$$

and

$$
*\left(*\left(\nu \wedge \omega_{0}\right) \wedge \omega_{0}\right)=*\left(-\nu \wedge \omega_{0}+\left(\nu, \omega_{0}\right)_{\omega_{0}} * \omega_{0}^{2}\right)=\mu+\left(\nu, \omega_{0}\right)_{\omega_{0}} \omega_{0}
$$

Therefore by (3.16),

$$
\begin{aligned}
U \alpha & =P^{*} P \alpha-\left(P^{*} P \alpha+\left(P^{*} P \alpha, \omega_{0}\right)_{\omega_{0}} \omega_{0}\right)-*\left(* \square_{\partial} P \alpha \wedge \omega_{0}\right) \\
& =-*\left(* \square_{\partial} P \alpha \wedge \omega_{0}\right)-\left(P^{*} P \alpha, \omega_{0}\right)_{\omega_{0}} \omega_{0}
\end{aligned}
$$

Now we are ready to derive the estimate that for a universal constant $C$ (in the sense that it only depends on $\left.\left(X, \omega_{0}\right)\right)$,

$$
\begin{equation*}
C^{-1}\left\|T \circ S^{-1} \phi\right\| \leq\|P \alpha\|_{L_{k}^{p}}+\left\|d d^{*} \psi\right\|_{L_{k}^{p}} \leq C\left\|T \circ S^{-1} \phi\right\|, \quad \forall \phi \perp \mathbb{H} . \tag{3.17}
\end{equation*}
$$

First note that the first inequality holds because $T \circ S^{-1}$ is a bounded operator. As to the second, because $d^{*} d\left(d^{*} \psi\right)=\square_{\partial} d^{*} \psi$ and that $d^{*} \psi$ is orthogonal to the harmonic forms, the elliptic estimate ensures that for a universal constant $C_{1}$,

$$
\left\|d^{*} \psi\right\|_{L_{k+1}^{p}} \leq C_{1}\left\|\square_{\partial} d^{*} \psi\right\|_{L_{k-1}^{p}} \leq C_{1}\left\|T \circ S^{-1} \phi\right\|
$$

Then because

$$
P \circ S^{-1}\left(d d^{*} \psi\right)=-\frac{1}{2} P\left(d d^{*} \psi, \omega_{0}\right)_{\omega_{0}} \omega_{0}
$$

and because the right hand side involves the third differentiation of $d^{*} \psi$,

$$
\left\|P \circ S^{-1}\left(d d^{*} \psi\right)\right\|_{L_{k-2}^{p}} \leq C_{2}\left\|d^{*} \psi\right\|_{L_{k+1}^{p}} \leq C_{1} C_{2}\left\|T \circ S^{-1} \phi\right\|
$$

holds for a universal constant $C_{2}$. On the other hand,

$$
\begin{equation*}
\frac{1}{2} * U \alpha=T \circ S^{-1} \phi+\frac{1}{2} P \circ S^{-1}\left(d d^{*} \psi, \omega_{0}\right)-d^{*} d\left(d^{*} \psi\right) \tag{3.18}
\end{equation*}
$$

the previous estimates ensure that there is a universal constant $C_{3}$ so that

$$
\begin{equation*}
\|U \alpha\|_{L_{k-2}^{p}} \leq C_{3}\left\|T \circ S^{-1} \phi\right\| \tag{3.19}
\end{equation*}
$$

Because

$$
d *\left(* \square_{\partial} P \alpha \wedge \omega_{0}\right)=0
$$

the formula of $U \alpha$ before (3.17) gives

$$
\begin{equation*}
d\left(P^{*} P \alpha, \omega_{0}\right)_{\omega_{0}} \wedge \omega_{0}=d(U \alpha) \tag{3.20}
\end{equation*}
$$

Combined with

$$
\int_{X}\left(P^{*} P \alpha, \omega_{0}\right)_{\omega_{0}} * 1=\int_{X}\left(P \alpha, P \omega_{0}\right)_{\omega_{0}} * 1=0
$$

and that wedging $\omega$ forms an isomorphism from $\Omega_{\mathbb{R}}^{1,1}(X)$ to $\Omega_{\mathbb{R}}^{2,2}(X)$ whose inverse has bounded norm, (3.20) and (3.19) implies that

$$
\left\|\left(P^{*} P \alpha, \omega_{0}\right)_{\omega_{0}}\right\|_{L_{k-2}^{p}} \leq C_{4}\|U \alpha\|_{L_{k-2}^{p}} \leq C_{3} C_{4}\left\|T \circ S^{-1} \phi\right\|
$$

Thus for a universal constant $C_{5}$,

$$
\left\|\square_{\partial} P \alpha\right\|_{L_{k-2}^{p}} \leq C_{5}\left\|T \circ S^{-1} \phi\right\| .
$$

Finally, because $\square_{\partial}$ is elliptic,

$$
\|P \alpha\|_{L_{k}^{p}} \leq C_{6}\left\|T \circ S^{-1} \phi\right\|
$$

This proves that the second inequality in (3.17) holds for a universal constant $C$.
It remains to show that $T \circ S^{-1}$ is surjective. Because $d^{*}$ surjects onto $R\left(d^{*}\right)$, we only need to verify that restricting to $\operatorname{ker} d^{*} \cap \Omega_{\mathbb{R}}^{1,1}(X)_{L_{k}^{p}}$ the operator $T \circ S^{-1}$ surjects onto $R\left(d d_{c}\right)_{L_{k-2}^{p}}$. Because

$$
R\left(* d d_{c}\right)_{L_{k}^{p}} \subset \operatorname{ker} d^{*} \cap \Omega_{\mathbb{R}}^{1,1}(X)_{L_{k}^{p}}
$$

it suffices to show that

$$
\begin{equation*}
* T \circ S^{-1}(* P(\cdot))=\frac{1}{2} U(\cdot): R\left(* d d_{c}\right)_{L_{k}^{p}} \longrightarrow R\left(* d d_{c}\right)_{L_{k-4}^{p}} \tag{3.21}
\end{equation*}
$$

is surjective. For this we note that the estimates derived so far show that (3.21) is injective and has closed range. Hence if we can show that it is self-adjoint, it must be surjective as well. We now show that $U$ is self-adjoint. Obviously, the first term $P^{*} P$ appeared in $U$ in (3.14) is self-adjoint. As to the second term, we observe that the $L^{2}$-intersection

$$
<* P\left(\left(* P \alpha, \omega_{0}\right)_{\omega_{0}} \omega_{0}\right), \beta>=<\left(* P \alpha, \omega_{0}\right)_{\omega_{0}} * \omega_{0}, P \beta>=\int_{X}\left(* P \alpha, \omega_{0}\right)_{\omega_{0}}\left(* P \beta, \omega_{0}\right)_{\omega_{0}} * 1
$$

Because both $\alpha$ and $\beta$ are real, the above expression is symmetrical in $\alpha$ and $\beta$. Therefore the operator $U$ is self-adjoint, and hence is surjective.

We are ready to prove the Proposition now. By a change of trivialization of $\mathbb{C}_{X}^{\oplus r}$, we can assume without lose of generality that $T=I_{r \times r}$; thus $H_{T}=I$. We next let $\mathfrak{H e r}^{0} E$ be the $\mathbb{R}$-sub-vector bundle of End $E$ consisting of traceless pointwise $<,>$-hermitian symmetric endomorphisms of $E$. Clearly, $T_{I} \mathcal{H}(E)_{1, L_{k}^{p}}=\Omega^{0}\left(\mathfrak{H e r}^{0} E\right)_{L_{k}^{p}}$. We now define linear operators

$$
\mathbf{T}_{1}, \mathbf{T}_{2}: \Omega\left(\mathfrak{H e r}^{0} E\right)_{L_{k}^{p}} \oplus \Omega_{\mathbb{R}}^{1,1}(X)_{L_{k}^{p}} \longrightarrow \mathcal{W}_{2}
$$

that are

$$
\mathbf{T}_{1}(\delta h, \delta \omega)=\left(P \delta \omega, 2 d_{\omega_{0}}^{*} \delta \omega-d_{\omega_{0}}^{*}\left(\left(\delta \omega, \omega_{0}\right)_{\omega_{0}} \omega_{0}\right)\right)
$$

and

$$
\mathbf{T}_{2}(\delta h, \delta \omega)=2 \operatorname{tr}\left(\delta F_{I}(\delta h) \wedge F_{I}\right)-2 \operatorname{tr}\left(\delta R_{\omega_{0}}(\delta g) \wedge R_{\omega_{0}}\right)
$$

Because

$$
\begin{aligned}
\delta \mathrm{Ł}_{1}\left(I, c \omega_{0}\right)(\delta h, c \delta \omega) & =c^{2} \delta \mathrm{Ł}_{1}\left(I, \omega_{0}\right)(\delta h, \delta \omega) ; \\
\delta \mathrm{Ł}_{2}\left(I, c \omega_{0}\right)(\delta h, c \delta \omega) & =\sqrt{-1} \partial \bar{\partial} c \delta \omega+2 \operatorname{tr}\left(\delta F_{I}(\delta h) \wedge F_{I}\right)-2 \operatorname{tr}\left(\delta R_{c \omega_{0}}(c \delta \omega) \wedge R_{c \omega_{0}}\right) \\
& =c P \delta \omega+2 \operatorname{tr}\left(\delta F_{I}(\delta h) \wedge F_{I}\right)-2 \operatorname{tr}\left(\delta R_{\omega_{0}}(\delta \omega) \wedge R_{\omega_{0}}\right),
\end{aligned}
$$

and

$$
\delta \mathrm{Ł}_{3}\left(I, c \omega_{0}\right)(\delta h, c \delta \omega)=2 d^{*} c \delta \omega-d^{*}\left(\left(c \delta \omega, \omega_{0}\right)_{\omega_{0}} \omega_{0}\right)
$$

$$
\begin{equation*}
\mathbf{P} \circ \delta \mathrm{Ł}_{1}\left(I, c \omega_{0}\right) \oplus \delta \mathrm{Ł}_{2}\left(I, c \omega_{0}\right) \oplus \delta \mathrm{Ł}_{3}\left(I, c \omega_{0}\right)=c^{2} \mathbf{P} \circ \delta \mathrm{Ł}_{1}\left(I, \omega_{0}\right) \oplus c\left(\mathbf{T}_{1}+c^{-1} \mathbf{T}_{2}\right) \tag{3.22}
\end{equation*}
$$

Hence to prove the Proposition we need to show that the right hand side is surjective. Based on the discussion before,

$$
\mathbf{P} \circ \delta \mathrm{Ł}_{1}\left(I, \omega_{0}\right)(\delta h, 0)=\mathbf{P} \circ \mathbf{F}(\delta h): \Omega^{0}\left(\mathfrak{H e r}^{0} E\right)_{L_{k}^{p}} \longrightarrow \mathcal{W}_{1} / V_{1}
$$

is surjective and its kernel is $V_{0}$. Also, we proved that

$$
\mathbf{T}_{1}: \Omega_{\mathbb{R}}^{1,1}(X)_{L_{k}^{p}} \longrightarrow \mathcal{W}_{2}
$$

which is the operator $T$ discussed before, is surjective with kernel $\mathbb{H} \subset \Omega_{\mathbb{R}}^{1,1}(X)$.
Now let $\mathcal{V} \subset \Omega^{0}\left(\mathfrak{H e r}^{0} E\right)_{L_{k}^{p}} \oplus \Omega_{\mathbb{R}}^{1,1}(X)_{L_{k}^{p}}$ be the orthogonal complement of $V_{1} \oplus \mathbb{H}$. For simplicity, we abbreviate $\mathbf{T}_{0}=\mathbf{P} \circ \delta \mathbf{L}_{1}\left(I, \omega_{0}\right)$. The discussion before shows that

$$
\left(\mathbf{T}_{0} \oplus \mathbf{T}_{1}\right) \mid \mathcal{V}: \mathcal{V} \longrightarrow \mathcal{W}_{1} / V_{1} \oplus \mathcal{W}_{2}
$$

is surjective and that there is a constant $C$ so that

$$
\begin{equation*}
C^{-1}\left\|\left(u_{1}, u_{2}\right)\right\| \leq\left\|\left(\mathbf{T}_{0}\left(u_{1}, u_{2}\right), \mathbf{T}_{1}\left(u_{1}, u_{2}\right)\right)\right\| \leq C\left\|\left(u_{1}, u_{2}\right)\right\|, \quad\left(u_{1}, u_{2}\right) \in \mathcal{V} \tag{3.23}
\end{equation*}
$$

Because $\mathbf{T}_{2}$ is a bounded operator, for sufficiently large $c$,

$$
\mathbf{T}_{0} \oplus\left(\mathbf{T}_{1}+c^{-1} \mathbf{T}_{2}\right): \Gamma\left(\operatorname{End}_{\mathrm{h}}^{0} E\right)_{L_{k}^{p}} \times \Omega_{\mathbb{R}}^{1,1}(X) \longrightarrow \mathcal{W}_{1} / V_{1} \oplus \mathcal{W}_{2}
$$

is surjective. In particular, the left hand side of (3.22) is surjective. This proves the Proposition.

## 4. Irreducible solutions to Strominger's system

In section two, assuming the existence of a non-degenerate deformation of holomorphic structures of the vector bundle $E_{1} \oplus E_{2}$ we showed how to use perturbation method to prove the existence of the Hermitian-Yang-Mills connections. In this section, we will construct solutions to Strominger's system using similar method. We will find an initial trivial solution to the Strominger's system and show that it can be extended to a family of irreducible solutions.

We continue to work with a Calabi-Yau threefold $\left(X, \omega_{0}\right)$ and the vector bundle

$$
\left(E, D_{0}^{\prime \prime}\right)=\mathbb{C}_{X}^{\oplus r} \oplus T X ;
$$

we fix a smooth isomorphism $\wedge^{r+3} E \cong \mathbb{C}_{X}$ so that the $D_{0}^{\prime \prime}$ induces the standard holomorphic structure on $\mathbb{C}_{X}$; we let $D_{s}^{\prime \prime}$ be a smooth deformation of the holomorphic structure $D_{0}^{\prime \prime}$. As in section two, we write

$$
D_{s}^{\prime \prime}=D_{0}^{\prime \prime}+A_{s}, \quad A_{s} \in \Omega^{0,1}(\text { End } E)
$$

and write

$$
\dot{A}_{0}=\left(\begin{array}{ll}
C_{11} & C_{12} \\
C_{21} & C_{22}
\end{array}\right) \in \Omega^{0,1}(\text { End } E)
$$

according to the decomposition $E=\mathbb{C}_{X}^{\oplus r} \oplus T X$. Because of Lemma 2.2 we can assume without lose of generality that $C_{i j}$ are $D_{0}^{\prime \prime}$-harmonic. Since $E_{1}=\mathbb{C}_{x}^{\oplus r}$ and $H_{\bar{\partial}}^{1}\left(X, \mathbb{C}_{X}\right)=0$,

$$
\begin{equation*}
C_{11}=0 \tag{4.1}
\end{equation*}
$$

Because Pic $X$ is discrete, we can assume further that $\operatorname{tr} A_{s}=0$ for all $s$. This means that under given smooth isomorphism $\wedge^{r+3} E \cong \mathbb{C}_{X}$, the induced holomorphic structure on $\wedge^{r+3} E$ is the standard holomorphic structure on $\mathbb{C}_{X}$.

Next, we let $H_{1}$ be the standard constant metric on $\mathbb{C}_{X}^{\oplus r}$ and let $H_{2}$ be induced by the Calabi-Yau metric $\omega_{0}$ normalized so that $\operatorname{det}\left(H_{1} \oplus H_{2}\right)$ is the constant one metric on $\wedge^{r+3} E \cong \mathbb{C}_{X}$. The pair of $<,>=H_{1} \oplus H_{2}$ and $\omega_{0}$ is a trivial solution of the Strominger's system on $\left(E, D_{0}^{\prime \prime}\right)$. We fix such $<,>$ as a reference hermitian metric on $E$. Following the convention in the previous section, all other determinant one hermitian metrics on $E$ are of the forms $<\cdot, \cdot>_{H}=<\cdot H, \cdot>$ for some determinant one pointwise positive definite $<,>$-hermitian symmetric endomorphisms of $E$.

Following this convention, the space of all trivial solutions to Strominger's system on ( $E, D_{0}^{\prime \prime}$ ) with Kahler form $\omega_{0}$ is isomorphic to the space of determinant one positive definite $r \times r$ hermitian symmetric matrices $T$ with the correspondence

$$
T \in \mathcal{H}_{r \times r}^{+} \longmapsto H_{T}=T \oplus|T|^{-1 / 3} I_{2} \in \mathcal{H}(E)_{1}
$$

With the chosen Kahler form $\omega_{0}$ and a hermitian metric $H_{T}$, the proposition 3.3 says that for $V_{1}$ the cokernel defined in (3.11) and for large enough $c$, the linearized operator $\delta \mathbf{L}$ at $\left(H_{T}, c \omega_{0}\right)$ surjects onto

$$
\begin{equation*}
\Omega_{\mathbb{R}}^{6}(\mathfrak{s} u E)_{L_{k-2}^{p}} / V_{1} \oplus R\left(d d_{c}\right)_{L_{k-2}^{p}} \oplus R\left(d_{\omega_{0}}^{*}\right)_{L_{k-1}^{p}} \tag{4.2}
\end{equation*}
$$

With the connection forms $A_{s}$, the metric $<,>$ and the Kahler form $\omega_{0}$ so chosen, we can now define operators

$$
\mathbf{L}_{s}=\mathbf{L}_{s, 1} \oplus \mathbf{L}_{s, 2} \oplus \mathbf{L}_{s, 3}
$$

between

$$
\mathcal{H}(E)_{1, L_{k}^{p}} \times \mathcal{H}(X)_{L_{k}^{p}} \longrightarrow \Omega_{\mathbb{R}}^{6}(\mathfrak{s} u E)_{L_{k-2}^{p}} \oplus R\left(d d_{c}\right)_{L_{k-2}^{p}} \oplus R\left(d_{\omega_{0}}^{*}\right)_{L_{k-1}^{p}}
$$

with $\mathbf{L}_{s, i}$ defined as in (3.4)-(3.6) of which the curvature form $F_{H}$ is replaced by the hermitian curvature of $\left(E, D_{s}^{\prime \prime}, H\right)$ :

$$
F_{s, H}=D_{s, H} \circ D_{s, H}
$$

Let $\mathbf{P}$ be the projection from

$$
\Omega_{\mathbb{R}}^{6}(X)(\mathfrak{s} u E)_{L_{k-2}^{p}} \oplus R\left(d d_{c}\right)_{L_{k-2}^{p}} \oplus R\left(d_{\omega_{0}}^{*}\right)_{L_{k-1}^{p}}
$$

to (4.2) and let $\mathcal{H}_{\omega}(X)_{L_{k}^{p}}$ be the space of those $L_{k}^{p}$-hermitian forms whose $\omega_{0}$-harmonic parts are $\omega$.

Lemma 4.1. For any $T_{0} \in \mathcal{H}_{r \times r}^{+}$, there are constants $a>0$ and $C>0$ such that for any $c>C$ there is a neighborhood $\mathcal{U}_{c}$ of $\left(H_{T_{0}}, c \omega_{0}\right) \in \mathcal{H}(E)_{1, L_{k}^{p}} \times \mathcal{H}_{c \omega_{0}}(X)_{L_{k}^{p}}$ such that for each $s \in[0, a)$ the set $\mathcal{S}_{s}=\left(\mathbf{P} \circ \mathbf{L}_{s}\right)^{-1}(0) \cap \mathcal{U}_{c}$ is a smooth $r^{2}$-dimensional manifold and that the union

$$
\begin{equation*}
\mathcal{S}=\coprod_{s \in[0, a)} \mathcal{S}_{s} \times s \subset \mathcal{U}_{c} \times[0, a) \tag{4.3}
\end{equation*}
$$

is a smooth $\left(r^{2}+1\right)$-dimensional manifold.

Proof. By proposition 3.3 there is a $C>0$ such that the linearized operator of $\mathbf{P} \circ \mathbf{L}_{0}$ is surjective at $\left(H_{T_{0}}, c \omega_{0}\right)$. Hence by the implicit theorem, for sufficiently small $s$ the solution set to $\mathbf{P} \circ \mathbf{L}_{s}=0$ is smooth near $\left(H_{T_{0}}, c \omega_{0}\right)$ and has dimension equal to the index of the linear operator $\mathbf{P} \circ \delta \mathbf{L}_{0}$, which is $r^{2}+\operatorname{dim} H^{1,1}(X, \mathbb{R})$. By restricting to the slice

$$
\mathcal{H}(E)_{1, L_{k}^{p}} \times \mathcal{H}_{c \omega_{0}}(X)_{L_{k}^{p}} \subset \mathcal{H}(E)_{1, L_{k}^{p}} \times \mathcal{H}(X)_{L_{k}^{p}}
$$

that is transversal to the kernel of $\mathbf{P} \circ \delta \mathbf{L}_{0}$, the solution set $\mathcal{S}_{s}$ will have the property as stated in the Lemma. This proves the Lemma.

Following our convention, $\mathcal{S}_{0}$ consists of all pairs

$$
\begin{equation*}
\left(H_{0, T}, \omega_{0, T}\right) ; \quad H_{0, T}=T \oplus|T|^{-1 / 3} I_{2}, \quad \omega_{0, T}=c \omega_{0} \tag{4.4}
\end{equation*}
$$

Since $\mathcal{S}_{s}$ and $\mathcal{S}$ are smooth, by shrinking $\mathcal{U}_{c}$ if necessary, we can parameterize $\mathcal{S}$ smoothly by $(s, T)$ so that $(s, T)$ parameterizes the set $\mathcal{S}$ that is consistent with the projection $\mathcal{S} \rightarrow[0, a)$ and the parameterization (4.4). By shrinking $\mathcal{U}_{c}$ if necessary, we can assume that under this parameterization, $\mathcal{S} \cong[0, a) \times B_{\epsilon}\left(T_{0}\right)$, where $B_{\epsilon}\left(T_{0}\right)$ is the ball of radius $\epsilon$ centered at $T_{0}$ in $\mathcal{H}_{r \times r}^{+}$. In the following, we denote by

$$
\left(H_{s, T}, \omega_{s, T}\right) \in \mathcal{S}_{s}, \quad T \in B_{\epsilon}\left(T_{0}\right)
$$

the solutions with parameters $(s, T)$. For simplicity, we denote by $F_{s, T}$ the curvature of the hermitian vector bundle $\left(E, D_{s}^{\prime \prime}, H_{s, T}\right)$. By our construction, it satisfies

$$
\mathbf{L}_{s, 1}\left(H_{s, T}, \omega_{s, T}\right) \equiv 0 \quad \bmod V_{1}, \quad \mathbf{L}_{s, 2}\left(H_{s, T}, \omega_{s, T}\right)=0 \quad \text { and } \quad \mathbf{L}_{s, 3}\left(H_{s, T}, \omega_{s, T}\right)=0
$$

Hence to find solutions to $\mathbf{L}_{s}=0$ it suffices to investigate the vanishing loci of the functional $\mathbf{r}(s, \cdot)$ from $B_{\epsilon}\left(T_{0}\right)$ to the Lie algebra $\mathfrak{u}(r)$ defined by

$$
\begin{equation*}
\mathbf{r}(s, T)=\int_{X}\left[\mathbf{L}_{s, 1}\left(H_{s, T}, \omega_{s, T}\right)\right]_{1} \tag{4.5}
\end{equation*}
$$

where $[\cdot]_{1}$ is the projection from $\Omega_{\mathbb{R}}(\mathfrak{s u E})$ to $\Omega_{\mathbb{R}}^{\bullet}\left(\mathfrak{u}\left(\mathbb{C}_{X}^{\oplus r}\right)\right)$. Here $\mathfrak{u}\left(\mathbb{C}_{X}^{\oplus r}\right)$ is the bundle of $<,>$-hermitian antisymmetric endomorphisms of $\mathbb{C}_{X}^{\oplus r}$.

As in section two, we shall first prove $\dot{\mathbf{r}}(0, T)=0$ for all $T$. Indeed,

$$
\begin{equation*}
\dot{\mathbf{r}}(0, T)=\int_{X} T^{-1 / 2}\left[\dot{F}_{0, T}\right]_{1} T^{1 / 2} \wedge \omega_{0, T}^{2}+2 \int_{X} T^{-1 / 2}\left[F_{0, T}\right]_{1} T^{1 / 2} \wedge \omega_{0, T} \wedge \dot{\omega}_{0, T} \tag{4.6}
\end{equation*}
$$

Because $H_{0, T}$ is a direct sum of a flat metric on $\mathbb{C}_{X}^{\oplus r}$ and a metric on $T X$, under the decomposition $E=\mathbb{C}_{X}^{\oplus}{ }^{2} \oplus T X$,

$$
F_{0, T}=\left(\begin{array}{cc}
0 & 0  \tag{4.7}\\
0 & *
\end{array}\right) \in \Omega_{\mathbb{R}}^{1,1}(\mathfrak{s} u E)
$$

What we will actually show is that

$$
\dot{F}_{0, T} \wedge \omega_{0, T}^{2}=\left(\begin{array}{cc}
0 & 0 \\
0 & *
\end{array}\right) \in \Omega_{\mathbb{R}}^{6}(\mathfrak{s} u E)
$$

Since $\left(H_{s, T}, \omega_{s, T}\right)$ are solutions to $\mathbf{L}_{s}=0 \bmod V_{1}$, there is a function $\mathbf{c}(s, T)$ taking values in $V_{1}$ with $\mathbf{c}(0, T)=0$ so that

$$
F_{s, T} \wedge \omega_{s, T}^{2}=H_{s, T}^{1 / 2} \mathbf{c}(s, T) H_{s, T}^{-1 / 2}
$$

Taking derivative of $s$ at $s=0$, and coupled with $\mathbf{c}(0, T)=0$, we obtain

$$
\begin{equation*}
\dot{F}_{0, T} \wedge \omega_{0, T}^{2}+2 F_{0, T} \wedge \omega_{0, T} \wedge \dot{\omega}_{0, T}=H_{0, T}^{1 / 2} \dot{\mathbf{c}}(0, T) H_{0, T}^{-1 / 2} \tag{4.8}
\end{equation*}
$$

which, after projecting to $\Omega_{\mathbb{R}}^{6}\left(\mathfrak{u}\left(\mathbb{C}_{X}^{\oplus r}\right)\right)$, becomes

$$
\begin{equation*}
\left[\dot{F}_{0, T} \wedge \omega_{0, T}^{2}\right]_{1}=T^{1 / 2} \dot{\mathbf{c}}(0, T) T^{-1 / 2} \tag{4.9}
\end{equation*}
$$

Next, we let $F_{s}$ as in (2.4) be the curvature of $\left(E, D_{s}^{\prime \prime}, I\right)$. Because

$$
F_{s, T}=F_{s}+D_{s}^{\prime \prime}\left(D_{s}^{\prime} H_{s, T} \cdot H_{s, T}^{-1}\right)
$$

because $D_{0}^{\prime} H_{0, T}=0$, and because $D_{s}$ is a direct sum of a flat connection on $\mathbb{C}_{X}^{\oplus r}$ and a Hermitian Yang-Mills connection on $T X$,

$$
\left[\dot{F}_{0, T}\right]_{1}=\left[\dot{F}_{0}\right]_{1}+D_{0}^{\prime \prime}\left[\dot{D}_{0}^{\prime} H_{0, T} \cdot H_{0, T}^{-1}\right]_{1}+D_{0}^{\prime \prime}\left[D_{0}^{\prime} \dot{H}_{0, T} \cdot H_{0, T}^{-1}\right]_{1}
$$

Using the expression of $F_{s}$ in (2.4), and that $C_{11}=0$ as stated in (4.1),

$$
\begin{equation*}
\left[\dot{F}_{0}\right]_{1}=D_{0}^{\prime} C_{11}-D_{0}^{\prime \prime} C_{11}^{*}=0 \tag{4.10}
\end{equation*}
$$

Hence

$$
\left[\dot{F}_{0, T}\right]_{1}=D_{0}^{\prime} \varphi_{1}+D_{0}^{\prime \prime} \varphi_{2}
$$

for some sections $\varphi_{1}$ and $\varphi_{2}$. Therefore, by Lemma 2.3

$$
\int_{X} T^{1 / 2} \dot{\mathbf{c}}(0, T) T^{-1 / 2}=\int_{X}\left[\dot{F}_{0, T}\right]_{1} \wedge \omega_{0, T}^{2}=\int_{X}\left(D_{0}^{\prime} \varphi_{1}+D_{0}^{\prime \prime} \varphi_{2}\right) \wedge \omega_{0, T}^{2}=0
$$

Since $\dot{\mathbf{c}}(0, T) / \omega_{0}^{3}$ is a constant section of $\operatorname{End}\left(\mathbb{C}_{X}^{\oplus r}\right)$, the above vanishing forces $\dot{\mathbf{c}}(0, T)=0$, which simplifies (4.8) to

$$
\dot{F}_{0, T} \wedge \omega_{0, T}^{2}+2 F_{0, T} \wedge \omega_{0, T} \wedge \dot{\omega}_{0, T}=0
$$

Finally, because $F_{0, T}$ has vanishing entries as shown in (4.7),

$$
\dot{F}_{0, T} \wedge \omega_{0, T}^{2}=\left(\begin{array}{cc}
0 & 0  \tag{4.11}\\
0 & *
\end{array}\right) \in \Omega_{\mathbb{R}}^{6}(\mathfrak{s} u E)
$$

The vanishing (4.6) follows from (4.7) and 4.11).
We next compute $\ddot{\mathbf{r}}(0, T)$. First, because $F_{0, T}=0$,

$$
\left.\left(H_{s, T}^{-1 / 2} F_{s, T} H_{s, T}^{1 / 2} \cdot \frac{d^{2}}{d s^{2}} \omega_{s, T}^{2}\right)\right|_{s=0}=0
$$

Because $\left[\dot{F}_{0, T}\right]_{1}=0$,

$$
\left[\left.\frac{d}{d s}\left(H_{s, T}^{-1 / 2} F_{s, T} H_{s, T}^{1 / 2}\right) \wedge \frac{d}{d s}\left(\omega_{s, T}^{2}\right)\right|_{s=0}\right]_{1}=0
$$

Hence

$$
\left[\left.\frac{d^{2}}{d s^{2}}\left(H_{s, T}^{-1 / 2} F_{s, T} H_{s, T}^{1 / 2} \wedge \omega_{s, T}^{2}\right)\right|_{s=0}\right]_{1}=\left[\left.\frac{d^{2}}{d s^{2}}\left(H_{s, T}^{-1 / 2} F_{s, T} H_{s, T}^{1 / 2}\right)\right|_{s=0} \wedge \omega_{0, T}^{2}\right]_{1}
$$

Taking second order derivative of $H_{s, T}^{-1 / 2} F_{s, T} H_{s, T}^{1 / 2}$, we will encounter terms like

$$
\left.\frac{d^{2}}{d s^{2}}\left(H_{s, T}^{-1 / 2}\right)\right|_{s=0} \cdot F_{0, T} \cdot H_{0, T}^{1 / 2}
$$

which are all zero because $F_{0, T}=0$. We will also encounter terms like

$$
\left.\frac{d}{d s}\left(H_{s, T}^{-1 / 2}\right)\right|_{s=0} \cdot \dot{F}_{0, T} \cdot H_{0, T}^{1 / 2}
$$

after wedging it with $\omega_{0, T}^{2}$, because $H_{0, T}^{1 / 2}$ is diagonal and $\dot{F}_{0, T} \wedge \omega_{0, T}^{2}$ has vanishing shown in (4.11), their projections to $\Omega_{\mathbb{R}}^{6}\left(\mathfrak{u}\left(\mathbb{C}_{X}^{\oplus r}\right)\right)$ are zero also. Hence the only term left is

$$
\left[\left.\frac{d^{2}}{d s^{2}}\left(H_{s, T}^{-1 / 2} F_{s, T} H_{s, T}^{1 / 2} \wedge \omega_{s, T}^{2}\right)\right|_{s=0}\right]_{1}=H_{s, T}^{-1 / 2} \ddot{F}_{0, T} H_{0, T}^{1 / 2} \wedge \omega_{0, T}^{2}
$$

As in the previous section, we compute

$$
\begin{aligned}
\int\left[H_{0, T}^{-1 / 2}\right. & \left.\ddot{F}_{0, T} H_{0, T}^{1 / 2}\right]_{1} \wedge \omega_{0, T}^{2}= \\
& =\int_{X} T^{-1 / 2}\left[\ddot{F}_{0}\right]_{1} T^{1 / 2} \wedge \omega_{0, T}^{2}-2 \int_{X} T^{-1 / 2}\left[\left[\dot{A}_{0},\left[\dot{A}_{0}^{*}, H_{0, T}\right] H_{0, T}^{-1}\right]\right]_{1} T^{1 / 2} \wedge \omega_{0, T}^{2}- \\
& -2 \int_{X} T^{-1 / 2}\left[\left[\dot{A}_{0}, D_{0}^{\prime} \dot{H}_{0, T} \cdot H_{0, T}^{-1}\right]\right]_{1} T^{1 / 2} \wedge \omega_{0, T}^{2}+\int_{X} T^{-1 / 2}\left[D_{0}^{\prime \prime} \Phi_{T}\right]_{1} T^{1 / 2} \wedge \omega_{0, T}^{2}
\end{aligned}
$$

for some form $\Phi_{0, T}$. We now look at the four terms in the above identity: the last term vanishes because of Lemma 2.3 the next-to-last term is
$-2 \int_{X} T^{-1 / 2}\left[\dot{A}_{0} \cdot D_{0}^{\prime} \dot{H}_{0, T} \cdot H_{0, T}^{-1}\right]_{1} T^{1 / 2} \wedge \omega_{0, T}^{2}+2 \int_{X} T^{-1 / 2}\left[D_{0}^{\prime} \dot{H}_{0, T} \cdot H_{0, T}^{-1} \cdot \dot{A}_{0}\right]_{1} T^{1 / 2} \wedge \omega_{0, T}^{2}$, which is zero because $D_{0}^{\prime * *} \dot{A}_{0}=0$ and Lemma 2.3 Using

$$
\dot{A}_{0}=\left(\begin{array}{cc}
0 & C_{12} \\
C_{21} & C_{22}
\end{array}\right) \quad \text { and } \quad H_{0, T}=\left(\begin{array}{cc}
T & 0 \\
0 & \alpha I_{2}
\end{array}\right), \quad \alpha=|T|^{-1 / 3}
$$

one computes

$$
\left[\left[\dot{A}_{0}, D_{0}^{\prime} \dot{H}_{0, T} \cdot H_{0, T}^{-1}\right]\right]_{1}=C_{12} \wedge C_{12}^{*}\left(I_{1}-\alpha T^{-1}\right)+\left(I_{1}-\alpha^{-1} T\right) C_{21}^{*} \wedge C_{21}
$$

For the same reason,

$$
\left[\ddot{F}_{0}\right]_{1} \wedge \omega_{0, T}^{2}=\left[2 \dot{A}_{0} \wedge \dot{A}_{0}^{*}+2 \dot{A}_{0}^{*} \wedge \dot{A}_{0}\right]_{1} \wedge \omega_{0, T}^{2}=2\left(C_{12} \wedge C_{12}^{*}+C_{21}^{*} \wedge C_{21}\right) \wedge \omega_{0, T}^{2}
$$

Therefore,

$$
\ddot{\mathbf{r}}(0, T)=2 \int_{X}\left(\alpha T^{-1 / 2} C_{12} \wedge C_{12}^{*} T^{-1 / 2}+\alpha^{-1} T^{1 / 2} C_{21}^{*} \wedge C_{21} T^{1 / 2}\right) \wedge \omega_{0, T}^{2}
$$

We now investigate the solvability of $\mathbf{r}(s, T)=0$ for small $s$. For this, we need to make an assumption on the class $C_{12}$ and $C_{21}$. Recall that $C_{12}$ is a column vector $\left[\alpha_{1}, \cdots, \alpha_{r}\right]^{t}$ whose components are $D_{0}^{\prime \prime}$-harmonic

$$
\alpha_{i} \in \Omega^{0,1}\left(T X^{\vee} \otimes \mathbb{C}_{X}\right)
$$

$C_{21}$ is a row vector $\left[\beta_{1}, \cdots, \beta_{r}\right]$ whose components are $D_{0}^{\prime \prime}$-harmonic

$$
\beta_{i} \in \Omega^{0,1}\left(\mathbb{C}_{X}^{\vee} \otimes T X\right)
$$

Since both $\alpha_{i}$ and $\beta_{i}$ are ( 1,0 )-forms,

$$
\begin{equation*}
\sqrt{-1} B=\sqrt{-1} \int_{X} C_{12} \wedge C_{12}^{*} \wedge \omega_{0, T}^{2} \quad \text { and } \quad \sqrt{-1} B^{\prime}=-\sqrt{-1} \int_{X} C_{21}^{*} \wedge C_{21} \wedge \omega_{0, T}^{2} \tag{4.12}
\end{equation*}
$$

are non-negative definite hermitian symmetric matrices. Because $\alpha_{i}$ are $D_{0}^{\prime \prime}$-harmonic, $\sqrt{-1} B$ is positive definite if and only if $\left[\alpha_{1}\right], \cdots,\left[\alpha_{r}\right]$ are linearly independent elements in $H_{\bar{\partial}}^{1}\left(T X^{\vee}\right)$. Similarly, $\sqrt{-1} B^{\prime}$ is positive definite if $\left[\beta_{1}\right], \cdots,\left[\beta_{r}\right]$ are linearly independent in $H_{\bar{\partial}}^{1}(X, T X)$. Hence the positivity of $\sqrt{-1} B$ and $\sqrt{-1} B^{\prime}$ only depend on the KodairaSpencer class $\kappa \in H_{\bar{\partial}}^{1}\left(X, E^{\vee} \otimes E\right)$.

We now assume that both matrices $\sqrt{-1} B$ and $\sqrt{-1} B^{\prime}$ are positive definite. By a $\mathrm{GL}(\mathrm{r}, \mathbb{C})$ change of basis of $\mathbb{C}_{X}^{\oplus r}$, we can assume that $\sqrt{-1} B^{\prime}=I_{r \times r}$. Then

$$
\ddot{\mathbf{r}}(0, T)=2|T|^{-1 / 3} T^{-1 / 2} B T^{-1 / 2}+2 \sqrt{-1}|T|^{1 / 3} T \in \mathfrak{u}(r) .
$$

Clearly, $\ddot{\mathbf{r}}(0, T)=0$ if $T$ is

$$
T_{0} \triangleq\left|\sqrt{-1} B_{1}\right|^{1 / 2(r+3)}(\sqrt{-1} B)^{1 / 2}
$$

Lemma 4.2. The map $\Phi: \partial B_{\epsilon}\left(T_{0}\right) \rightarrow S(1)$ to the unit sphere $S(1) \subset \mathfrak{u}(r)$ defined by

$$
\Phi(T)=\frac{\ddot{\mathbf{r}}(0, T)}{\|\ddot{\mathbf{r}}(0, T)\|}
$$

is a degree one map.
Proof. We define

$$
\mathbf{u}_{t}(T)=|T|^{-1 / 3}(t T+(1-t) I)^{-1 / 2}\left(B+\sqrt{-1}|T|^{1 / 3} T^{2}\right)(t T+(1-t) I)^{-1 / 2}
$$

and consider

$$
\frac{\mathbf{u}_{t}(\cdot)}{\left\|\mathbf{u}_{t}(\cdot)\right\|}: \partial B_{\epsilon}\left(T_{0}\right) \rightarrow S(1)
$$

It is well-defined since $T$ and $I$ are positive definite; it is $\Phi$ when $t=1$. Hence it provides a homotopy between $\Phi$ and

$$
\Phi_{1}(\cdot)=\frac{\mathbf{u}_{0}(\cdot)}{\left\|\mathbf{u}_{0}(\cdot)\right\|}: \partial B_{\epsilon}\left(T_{0}\right) \rightarrow S(1)
$$

Next we consider

$$
\mathbf{v}_{t}(T)=\mathbf{B}+\sqrt{-1}\left((1-t)|T|^{2 / 3}+t\left|T_{0}\right|^{2 / 3}\right) T^{2}
$$

We claim that $\mathbf{v}_{t}(T) \neq 0$ for all $t \in[0,1]$. Suppose for some $t_{0} \in[0,1]$ and $T \in \partial B_{\epsilon}\left(T_{0}\right)$,

$$
\mathbf{B}+\sqrt{-1}\left(\left(1-t_{0}\right)|T|^{2 / 3}+t_{0}\left|T_{0}\right|^{2 / 3}\right) T^{2}=0
$$

then $T=\eta(\sqrt{-1} B)^{1 / 2}$ for some $\eta \in \mathbb{R}^{+}$. Since $T \in \partial B_{\epsilon}\left(T_{0}\right), \eta$ satisfies

$$
\left\|T-T_{0}\right\|=\left|\eta-|\sqrt{-1} B|^{-1 / 2(r+3)}\right|\left\|(\sqrt{-1} B)^{1 / 2}\right\|=\epsilon
$$

Hence $\eta$ can only take values

$$
\eta_{ \pm}=|\sqrt{-1} B|^{-1 / 2(r+3)} \pm \epsilon^{\prime}, \quad \epsilon^{\prime}=\epsilon /\left\|(\sqrt{-1} B)^{1 / 2}\right\| .
$$

But then $\left|\eta_{+}(\sqrt{-1} B)^{1 / 2}\right|>|\sqrt{-1} B|^{3 / 2(r+3)}=\left|T_{0}\right|$; and then

$$
\begin{aligned}
&\left(t_{0}\left|\eta_{+}(\sqrt{-1} B)^{1 / 2}\right|^{2 / 3}+\left(1-t_{0}\right)\left|T_{0}\right|^{2 / 3}\right) \eta_{+}^{2}> \\
&>\left(t_{0}\left|T_{0}\right|^{2 / 3}+\left(1-t_{0}\right)\left|T_{0}\right|^{2 / 3}\right)\left(|\sqrt{-1} B|^{-1 / 2(r+3)}+\epsilon^{\prime}\right)^{2}>1
\end{aligned}
$$

Hence $\mathbf{v}_{t_{0}}\left(\eta_{+}(\sqrt{-1} B)^{1 / 2}\right) \neq 0$. Similarly, $\mathbf{v}_{t_{0}}\left(\eta_{-}(\sqrt{-1} B)^{1 / 2}\right) \neq 0$. This proves that

$$
\frac{\mathbf{v}_{t}(\cdot)}{\left\|\mathbf{v}_{t}(\cdot)\right\|}: \partial B_{\epsilon}\left(T_{0}\right) \longrightarrow S(1)
$$

are well-defined and is a homotopy between $\Phi_{1}$ and

$$
\Phi_{2}: \partial B_{\epsilon}\left(T_{0}\right) \longrightarrow S(1) ; \quad \Phi_{2}(T)=\frac{\mathbf{B}+\sqrt{-1}\left|T_{0}\right|^{2 / 3} T^{2}}{\left\|\mathbf{B}+\sqrt{-1}\left|T_{0}\right|^{2 / 3} T^{2}\right\|}
$$

It remains to show that $\operatorname{deg} \Phi_{2}=1$. We write $T=T_{0}+\epsilon \Delta T$ with $\Delta T$ varies in the unit sphere in the space of hermitian symmetric matrices $\mathcal{H}_{r \times r}$. Under this form the numerator of $\Phi_{2}$ is

$$
\mathbf{B}+\sqrt{-1}\left|T_{0}\right|^{2 / 3}\left(T_{0}+\epsilon \Delta T\right)^{2}=\sqrt{-1}\left|T_{0}\right|^{2 / 3}\left(\Delta T T_{0}+T_{0} \Delta T\right)+\epsilon^{2}\left|T_{0}\right|^{2 / 3}(\Delta T)^{2}
$$

For $\epsilon$ small enough, the degree of $\Phi_{2}$ is the same as the degree of

$$
\begin{equation*}
\Delta T \longmapsto \sqrt{-1} \frac{\Delta T T_{0}+T_{0} \Delta T}{\left\|\Delta T T_{0}+T_{0} \Delta T\right\|} \tag{4.13}
\end{equation*}
$$

which is the same as

$$
\Delta T \longmapsto \sqrt{-1} \Delta T
$$

Because the map $\partial B_{1}(0) \subset \mathcal{H}_{r \times r} \rightarrow S(1) \subset \mathfrak{u}(r)$ by multiplying $\sqrt{-1}$ has degree one, the map $\Phi$ has degree one as well. This proves the Lemma.

We are now ready to prove the theorem
Theorem 4.3. Let $\left(X, \omega_{0}\right)$ be a Calabi-Yau threefold; let $D_{s}^{\prime \prime}$ be a smooth deformation of the tautological holomorphic structure $D_{0}^{\prime \prime}$ on $E=\mathbb{C}_{X}^{\oplus r} \oplus T X$. Suppose the Kodaira-Spencer class $\kappa \in H_{\bar{\partial}}^{1}\left(X, E^{\vee} \otimes E\right)$ of the family $D_{s}^{\prime \prime}$ at $s=0$ satisfies the non-degeneracy condition that both $\sqrt{-1} B$ and $\sqrt{-1} B^{\prime}$ in 4.13) are positive definite. Then for sufficiently large $c \in \mathbb{R}$ and small $a>0$, there is a family of pairs of hermitian metrics and hermitian forms $\left(H_{s}, \omega_{s}\right)$, not necessarily continuous in $s \in[0, a)$, so that

1. the $\omega_{0}$-harmonic part of $\omega_{s}$ is $c \omega_{0}$;
2. the pair $\left(H_{s}, \omega_{s}\right)$ is a solution to Strominger's system for the holomorphic vector bundle $\left(E, D_{s}^{\prime \prime}\right)$;
3. $\lim _{s \rightarrow 0} \omega_{s}=c \omega_{0} ; \lim _{s \rightarrow 0} H_{s}$ is a Hermitian Yang-Mills connection of $E$ over $\left(X, \omega_{0}\right)$.

Proof. First, we pick a basis of $\mathbb{C}_{X}^{\oplus r}$ so that the matrix $\sqrt{-1} B^{\prime}$ in (4.13) is the identity matrix. We let $B$ be the other matrix and let $T_{0}=|\sqrt{-1} B|^{1 / 2(r+3)}(\sqrt{-1} B)^{1 / 2}$. By Lemma 4.1 we can choose $C$ so that Lemma 4.1 holds for $T_{0}$ chosen. Then for any $c>C$, we form solution set $\mathcal{S}_{s}$ of the system $\mathbf{P} \circ \mathbf{L}_{s}=0$ and parameterize the solutions near $\left(H_{T_{0}}, c \omega_{0}\right)$ by $(s, T) \in[0, a) \times B_{\epsilon}\left(T_{0}\right)$. Based in this parameterization, we then form the functional $\mathbf{r}(s, T)$ in (4.5). Because $\dot{\mathbf{r}}(0, T)=0$ and

$$
\begin{equation*}
\frac{\ddot{\mathbf{r}}(0, \cdot)}{\|\ddot{\mathbf{r}}(0, \cdot)\|}: \partial B_{\epsilon}\left(T_{0}\right) \longrightarrow S(1) \tag{4.14}
\end{equation*}
$$

has degree one, for some small $0<a^{\prime}<a$ the maps

$$
\mathbf{r}(s, \cdot): \partial B_{\epsilon}\left(T_{0}\right) \longrightarrow \mathfrak{u}(r), \quad s \in\left(0, a^{\prime}\right)
$$

does not take the value $0 \in \mathfrak{u}(r)$. Hence the associated map

$$
\begin{equation*}
\frac{\mathbf{r}(s, \cdot)}{\|\mathbf{r}(s, \cdot)\|}: \partial B_{\epsilon}\left(T_{0}\right) \longrightarrow S(1) \subset \mathfrak{u}(r), \quad s \in\left(0, a^{\prime}\right) \tag{4.15}
\end{equation*}
$$

has the same degree as that of (4.14), which is one. Hence the map

$$
\mathbf{r}(s, \cdot): B_{\epsilon}\left(T_{0}\right) \longrightarrow \mathfrak{u}(r), \quad s \in\left(0, a^{\prime}\right)
$$

attains value $0 \in \mathfrak{u}(r)$ for all $s \in\left(0, a^{\prime}\right)$ in $B_{\epsilon}\left(T_{0}\right)$. This proves the first two part of the theorem. The last part is true because we can choose $\epsilon$ arbitrarily small.

## 5. Irreducible Solutions on quintic threefolds

So far we have derived a sufficient condition for the existence of irreducible solutions to Strominger's system. Our next step is to find examples that satisfy this condition. It is the purpose of this section to work out examples for $\mathrm{SU}(4)$ and $\mathrm{SU}(5)$.

We will first consider the Fermat quintic

$$
X=\left\{z_{0}^{5}+z_{1}^{5}+z_{2}^{5}+z_{3}^{5}+z_{4}^{5}=0\right\} \subset \mathbf{P}^{4}
$$

we will find a deformation of the holomorphic structure of $\mathbb{C}_{X} \oplus T X$ and show that it satisfies the requirement of theorem4.3 This will provide us $\mathrm{SU}(4)$ solutions to Strominger's system.

We begin with the Euler exact sequence of $T \mathbf{P}^{4}$ (the middle column), and the exact sequence relating $T X$ and the restriction to $X$ of the tangent bundle $T_{X} \mathbf{P}^{4}=\left.T \mathbf{P}^{4}\right|_{X}$ (the top row):


We take $F$ be the kernel of $\mathcal{O}_{X}(1)^{\oplus 5} \longrightarrow \mathcal{O}_{X}(5)$ and fill in the remainder entries to make up the exact diagram as shown above.

We claim that the left column in (5.1) is non-split. Assume not, say $F=T X \oplus \mathcal{O}_{X}$. Then since $F$ is a subsheaf of $\mathcal{O}_{X}(1)^{\oplus 5}$ with quotient sheaf $\mathcal{O}_{X}(5), \mathcal{O}_{X}(1)^{\oplus 5} / T X$ must be locally free and an extension of $\mathcal{O}_{X}(5)$ by $\mathcal{O}_{X}$. Because $\operatorname{Ext}_{X}^{1}\left(\mathcal{O}_{X}(5), \mathcal{O}_{X}\right)=0$, the only extension of $\mathcal{O}_{X}(5)$ by $\mathcal{O}_{X}$ is the direct sum $\mathcal{O}_{X}(5) \oplus \mathcal{O}_{X}$. Hence

$$
\mathcal{O}_{X}(1)^{\oplus 5} / T X \cong \mathcal{O}_{X} \oplus \mathcal{O}_{X}(5)
$$

In particular, $\mathcal{O}_{X}$ becomes a quotient sheaf of $\mathcal{O}_{X}(1)^{\oplus 5}$ that is impossible. This proves that it does not split.

Next, we will construct a deformation of holomorphic structure of $\mathbb{C}_{X} \oplus T X$ so that its Kodaira-Spencer class is of the form

$$
\kappa=\left(\begin{array}{ll}
0 & 0  \tag{5.2}\\
\xi & 0
\end{array}\right) \in \operatorname{Ext}_{X}^{1}\left(\mathcal{O}_{X} \oplus T X, \mathcal{O}_{X} \oplus T X\right)
$$

whose only non-trivial entry is the extension class $\xi \in \operatorname{Ext}_{X}^{1}\left(T X, \mathcal{O}_{X}\right)$ of the left column exact sequence in (5.1); $\xi$ is non-trivial because the exact sequence does not split. We let

$$
\pi_{1}: X \times \mathbf{A}^{1} \longrightarrow X \quad \text { and } \quad \pi_{2}: X \times \mathbf{A}^{1} \longrightarrow \mathbf{A}^{1}
$$

be the projections; we let $t$ be the standard coordinate function on $\mathbf{A}^{1}$. The class

$$
t \cdot \xi \in \Gamma\left(\mathcal{O}_{\mathbf{A}^{1}}\right) \otimes \operatorname{Ext}_{X}^{1}\left(T X, \mathcal{O}_{X}\right)=\operatorname{Ext}_{X \times \mathbf{A}^{1}}^{1}\left(\pi_{1}^{*} T X, \mathcal{O}_{X \times \mathbf{A}^{1}}\right)
$$

defines an extension sheaf over $X \times \mathbf{A}^{1}$ :

$$
\begin{equation*}
0 \longrightarrow \mathcal{O}_{X \times \mathbf{A}^{1}} \longrightarrow \mathcal{F} \longrightarrow \pi_{1}^{*} T X \longrightarrow 0 \tag{5.3}
\end{equation*}
$$

The extension sheaf $\mathcal{F}$ is locally free; its restriction to $X \times t$, which we denote by $F_{t}$, form a one parameter family of holomorphic vector bundles whose special member $F_{0} \cong \mathcal{O}_{X} \oplus T X$ and its general member $F_{t} \cong F$ for $t \neq 0$. Here by abuse of notation we use $t$ to denote the point in $\mathbf{A}^{1}$ having coordinate $t$. It is a tautology that the Kodaira-Spencer class of this family at $t=0$ is the $\kappa$ in (5.2).

In terms of differential geometry, if we fix smooth isomorphisms $F_{t} \cong \mathbb{C}_{X} \oplus T X$ that also depend smoothly on $t$, then the holomorphic structure on $F_{t}$ induces a family of holomorphic structures $D_{t}^{\prime \prime}$ on $E=\mathbb{C}_{X} \oplus T X$ that is a deformation of the holomorphic structure $D_{0}^{\prime \prime}$ on $\mathbb{C}_{X} \oplus T X$. Following the convention of the first part of this paper, if we write $D_{t}^{\prime \prime}=D_{0}^{\prime \prime}+A_{t}$ and use the splitting $E=\mathbb{C}_{X} \oplus T X$, then

$$
\dot{D}_{0}^{\prime \prime}=\dot{A}_{0}=\left(\begin{array}{cc}
0 & 0 \\
C_{21} & 0
\end{array}\right)
$$

and $C_{21}$ represents the class $\xi$ in $H^{1}\left(T X^{\vee}\right)$; thus $\left[C_{21}\right] \neq 0$.
What we aim at is to find a deformation of holomorphic structures $D_{t}^{\prime \prime}$ of $\left(E, D_{0}^{\prime \prime}\right)$ so that the first order deformation

$$
\dot{D}_{0}^{\prime \prime}=\left(\begin{array}{cc}
0 & C_{12} \\
C_{21} & C_{22}
\end{array}\right)
$$

will have $\left[C_{12}\right] \neq 0$ and $\left[C_{21}\right] \neq 0$. To achieve this, we will construct a smooth family of holomorphic vector bundles $\left(E, D_{u}^{\prime \prime}\right)$ parameterized by a smooth pointed domain $0 \in U$ so that
(1) $D_{0}^{\prime \prime}$ is the holomorphic structure on $\mathbb{C}_{X} \oplus T X$;
(2) there is a path $u=\rho_{1}(t)$ in $U$ with $\rho_{1}(0)=0$ so that $\dot{D}_{\rho_{1}(0)}^{\prime \prime}=\left(\begin{array}{cc}0 & * \\ C_{21} & *\end{array}\right)$ and $\left[C_{21}\right] \neq 0 ;$
(3) there is another path $u=\rho_{2}(t)$ in $U$ with $\rho_{2}(0)=0$ so that $\dot{D}_{\rho_{2}(0)}^{\prime \prime}=\left(\begin{array}{cc}0 & C_{12} \\ * & *\end{array}\right)$ and $\left[C_{12}\right] \neq 0$.

As we saw before, for the first path all we need is to have it represent the family $F_{t}$ constructed in (5.7). We now construct the second family that will represent the path $\rho_{2}$ that we need. We will work out the family over $U$ after we have done this.

Using the top row exact sequence of the diagram (5.1), we can fit $\mathcal{O}_{X} \oplus T X$ into the exact sequence

$$
\begin{equation*}
0 \longrightarrow \mathcal{O}_{X} \oplus T X \longrightarrow \mathcal{O}_{X} \oplus T_{X} \mathbf{P}^{4} \xrightarrow{\varphi} \mathcal{O}_{X}(5) \longrightarrow 0 \tag{5.4}
\end{equation*}
$$

Here $\varphi=\left(0, \varphi_{2}\right)^{t}$ is 0 when restricted to $\mathcal{O}_{X}$, and is the $\varphi_{2}$ in the diagram when restricted to $T_{X} \mathbf{P}^{4}$. We then pick a section $u \in H^{0}\left(\mathcal{O}_{X}(5)\right)$, viewed as a homomorphism $\mathcal{O}_{X} \rightarrow \mathcal{O}_{X}(5)$, to form a new homomorphism of sheaves over $X \times \mathbf{A}^{1}$ :

$$
\Phi=\left(t u, \pi_{1}^{*} \varphi_{2}\right)^{t}: \mathcal{O}_{X \times \mathbf{A}^{1}} \oplus \pi_{1}^{*} T_{X} \mathbf{P}^{4} \xrightarrow{\Phi} \pi_{1}^{*} \mathcal{O}_{X}(5)
$$

whose restriction to $\mathcal{O}_{X \times \mathbf{A}^{1}}$ (resp. $\pi_{1}^{*} T_{X} \mathbf{P}^{4}$ ) is $t u$ (resp. $\pi_{1}^{*} \varphi_{2}$ ). We let $\mathcal{F}^{\prime}$ be the kernel of $\Phi . \mathcal{F}^{\prime}$ fits into the middle rwo exact sequence


Because the composite

$$
\Phi \circ\left(0, \pi_{1}^{*} \varphi_{1}\right)=0
$$

$\left(0, \pi_{1}^{*} \varphi_{1}\right)$ lifts to $\Psi$, shown in the diagram; its cokernel is $\mathcal{O}_{X \times \mathbf{A}^{1}}$.
We denote the restriction to $X \times\{t\}$ of $\mathcal{F}^{\prime}$ by $F_{t}^{\prime}$. Clearly, $F_{0}^{\prime} \cong \mathcal{O}_{X} \oplus T X$. The Kodaira-Spencer class of the first order deformation of the family $\mathcal{F}^{\prime}$ at $t=0$ is

$$
\kappa^{\prime}=\left(\begin{array}{cc}
0 & \kappa_{12}^{\prime} \\
0 & 0
\end{array}\right)
$$

To show that $\mathcal{F}^{\prime}$ is the desired family we need to show that $\kappa_{12}^{\prime} \neq 0$. We now prove that this is true. We let $\mathbf{A}_{2}=\operatorname{Spec} \mathbb{C}[t] /\left(t^{2}\right)$, which in plain language is the first order infinitesimal neighborhood of $0 \in \mathbf{A}^{1}$. Suppose $\kappa_{12}^{\prime}=0$, then based on deformation theory of vector bundles, the induced sheaf homomorphism

$$
\psi_{2}: \mathcal{F}^{\prime} \otimes \mathcal{O}_{X \times \mathbf{A}^{1}} \mathcal{O}_{X \times \mathbf{A}_{2}} \longrightarrow \mathcal{O}_{X \times \mathbf{A}_{2}}, \text { or equivalently }\left.\mathcal{F}^{\prime}\right|_{X \times \mathbf{A}_{2}} \rightarrow \mathbb{C}_{X \times \mathbf{A}_{2}}
$$

splits. Namely, there is a homomorphism

$$
\begin{equation*}
\tilde{\psi}_{2}: \mathcal{O}_{X \times \mathbf{A}_{2}} \longrightarrow \mathcal{F}^{\prime} \otimes_{\mathcal{O}_{X \times \mathbf{A}^{1}}} \mathcal{O}_{X \times \mathbf{A}_{2}} \tag{5.6}
\end{equation*}
$$

so that

$$
\psi_{2} \circ \tilde{\psi}_{2}=\mathrm{id}
$$

Let $p: X \times \mathbf{A}_{2} \rightarrow X$ be the projection. Since $\mathcal{F}^{\prime}$ is defined by the exact sequence (5.5), the homomorphism $\tilde{\psi}_{2}$ induces a homomorphism

$$
\mathcal{O}_{X \times \mathbf{A}_{2}} \longrightarrow \mathcal{O}_{X \times \mathbf{A}_{2}} \oplus p^{*} T_{X} \mathbf{P}^{4}
$$

because $\operatorname{Ext}_{X}^{1}\left(\mathcal{O}_{X}, \mathcal{O}_{X}\right)=0$ it lifts to a

$$
\mu: \mathcal{O}_{X \times \mathbf{A}_{2}} \longrightarrow \mathcal{O}_{X \times \mathbf{A}_{2}} \oplus p^{*} \mathcal{O}_{X}(1)^{\oplus 5}
$$

Let

$$
\lambda: \mathcal{O}_{X \times \mathbf{A}_{2}} \oplus p^{*} \mathcal{O}_{X}(1)^{\oplus 5} \longrightarrow p^{*} \mathcal{O}_{X}(5)
$$

be the restriction of the composite of

$$
\mathcal{O}_{X \times \mathbf{A}^{1}} \oplus p^{*} \mathcal{O}_{X}(1)^{\oplus 5} \longrightarrow \mathcal{O}_{X \times \mathbf{A}^{1}} \oplus p^{*} T_{X} \mathbf{P}^{4}
$$

and $\Phi$ in (5.5) to $X \times \mathbf{A}_{2}$. Then by definition

$$
\lambda \circ \mu=0 .
$$

To study this identity, we notice that the homomorphism $\mu$ must be of the form

$$
\mu=\left[1+a t, b z_{0}+t \alpha_{0}, \cdots, b z_{4}+t \alpha_{4}\right]
$$

with $\left[z_{0}, \cdots, z_{4}\right]$ the homogeneous coordinate of $\mathbf{P}^{4}, \alpha_{i} \in H^{0}\left(\mathcal{O}_{X}(1)\right), a \in \mathbb{C}$ and $b \in$ $\mathbb{C}[t] /\left(t^{2}\right)$; the homomorphism $\lambda$ is of the form

$$
\left[\begin{array}{c}
t u \\
z_{0}^{4} \\
\vdots \\
z_{4}^{4}
\end{array}\right]
$$

Because $\lambda \circ \mu=0$ holds over $X \times \mathbf{A}_{2}$, we have

$$
\left[1+a_{1} t, b z_{0}+t \alpha_{0}, \cdots, b z_{4}+t \alpha_{4}\right]\left[\begin{array}{c}
t u \\
z_{0}^{4} \\
\vdots \\
z_{4}^{4}
\end{array}\right] \equiv 0 \quad \bmod \left(t^{2}, z_{0}^{5}+\cdots+z_{4}^{5}\right)
$$

After simplification, the above identity reduces to

$$
u+\alpha_{0} z_{0}^{4}+\cdots+\alpha_{4} z_{4}^{4} \equiv 0 \quad \bmod \left(z_{0}^{5}+\cdots+z_{4}^{5}\right)
$$

Now we choose $u=z_{0}^{2} z_{1}^{3}$. It is clear that there are no $\alpha_{i} \in H^{0}\left(\mathcal{O}_{X}(1)\right)$ that make the above identity holds. Hence with such choice of $u$ the lift $\tilde{\psi}_{2}$ does not exist. This proves $\kappa_{12}^{\prime} \neq 0$.

It remains to find a family of holomorphic vector bundles that includes the two families $\mathcal{F}$ and $\mathcal{F}^{\prime}$ as its subfamilies. We let $\eta \in \operatorname{Ext}_{X}^{1}\left(T_{X} \mathbf{P}^{4}, \mathcal{O}_{X}\right)$ be the extension class of the Euler exact sequence

$$
\begin{equation*}
0 \longrightarrow \mathcal{O}_{X} \longrightarrow \mathcal{O}_{X}(1)^{\oplus 5} \longrightarrow T_{X} \mathbf{P}^{4} \longrightarrow 0 \tag{5.7}
\end{equation*}
$$

Then $t \eta$ is an extension class

$$
t \eta \in \Gamma\left(\mathcal{O}_{\mathbf{A}^{1}}\right) \otimes \operatorname{Ext}^{1}\left(T_{X} \mathbf{P}^{4}, \mathcal{O}_{X}\right)=\operatorname{Ext}_{X \times \mathbf{A}^{1}}^{1}\left(\pi_{1}^{*} T_{X} \mathbf{P}^{4}, \mathcal{O}_{X \times \mathbf{A}^{1}}\right)
$$

that defines an exact sequence over $X \times \mathbf{A}^{1}$ :

$$
0 \longrightarrow \mathcal{O}_{X \times \mathbf{A}^{1}} \longrightarrow \mathcal{W} \longrightarrow \pi_{1}^{*} T_{X} \mathbf{P}^{4} \longrightarrow 0
$$

Clearly, $\mathcal{W} \otimes_{\mathcal{O}_{X \times \mathbf{A}^{1}}} \mathcal{O}_{X \times\{0\}}=\mathcal{O}_{X} \oplus T_{X} \mathbf{P}^{4}$ while $\mathcal{W} \otimes_{\mathcal{O}_{X \times \mathbf{A}^{1}}} \mathcal{O}_{X \times\{t\}}=\mathcal{O}_{X}(1)^{\oplus 5}$ for $t \neq 0$. We claim that

$$
\begin{equation*}
\pi_{2 *}\left(\mathcal{W}^{\vee} \otimes \pi_{1}^{*} \mathcal{O}_{X}(5)\right) \tag{5.8}
\end{equation*}
$$

is a locally free sheaf of $\mathcal{O}_{\mathbf{A}^{1}-\text { modules. By base change property, this is true if }}$

$$
H^{1}\left(X,\left(\mathcal{O}_{X} \oplus T_{X} \mathbf{P}^{4}\right)^{\vee} \otimes \mathcal{O}_{X}(5)\right)=0 \quad \text { and } \quad H^{1}\left(X,\left(\mathcal{O}_{X}(1)^{\oplus 5}\right)^{\vee} \otimes \mathcal{O}_{X}(5)\right)=0
$$

Since $X \subset \mathbf{P}^{4}$ is a smooth hypersurface, a standard long exact sequence chasing shows that $H^{1}\left(X, \mathcal{O}_{X}(a)\right)=0$ for any integer $a$. To prove the above two identities, we only need to check that $H^{1}\left(X, T_{X}^{\vee} \mathbf{P}^{4} \otimes \mathcal{O}_{X}(5)\right)=0$. For this, we apply the long exact sequence of cohomologies to the dual of (5.7) tensored with $\mathcal{O}_{X}(5)$ :

$$
H^{0}\left(\mathcal{O}_{X}(4)^{\oplus 5}\right) \longrightarrow H^{0}\left(\mathcal{O}_{X}(5)\right) \longrightarrow H^{1}\left(T_{X}^{\vee} \mathbf{P}^{4}(5)\right) \longrightarrow H^{1}\left(\mathcal{O}_{X}(4)^{\oplus 5}\right)
$$

Because the last term is zero, and because $H^{0}\left(\mathcal{O}_{\mathbf{P}^{4}}(a)\right) \rightarrow H^{0}\left(\mathcal{O}_{X}(a)\right)$ is surjective, the first arrow is surjective. This shows that $H^{1}\left(T_{X}^{\vee} \mathbf{P}^{4}(5)\right)=0$, and hence (5.8) is locally free.

We now let $W$ be the total space of the vector bundle (5.8) and let

$$
q: X \times W \rightarrow X \times \mathbf{A}^{1}
$$

be the projection. Over $X \times W$ there is a tautological homomorphism

$$
q^{*} \mathcal{W} \longrightarrow q^{*} \pi_{1}^{*} \mathcal{O}_{X}(5)
$$

Let $\mathcal{E}$ be the kernel of the above sheaf homomorphism; for $w \in W$ we denote by $E_{w}$ the restriction of $\mathcal{E}$ to $X \times w$.

It is now a matter of direct checking that there are two paths $\rho_{1}(t)$ and $\rho_{2}(t)$ in $W$ so that $E_{\rho_{1}(t)}$ and $E_{\rho_{2}(t)}$ represent $F_{t}$ and $F_{t}^{\prime}$ respectively. First of all, the homomorphism $\varphi: \mathcal{O}_{X} \oplus T_{X} \mathbf{P}^{4} \rightarrow \mathcal{O}_{X}(5)$ in (5.4) represents a point in $W$; we designate this point to be the marked point $0 \in W$. The family $\mathcal{F}^{\prime}$ is constructed as the kernel of $\Phi$ in (5.5) with $\Phi$ restricting to $X \times\{0\}$ being $\varphi$. Hence $\Phi$ represents a path $\rho_{2}$ in $W$ initiating from 0 and is contained in the fiber of $W \rightarrow \mathbf{A}^{1}$ over $0 \in \mathbf{A}^{1}$ that satisfies $E_{\rho_{2}(t)} \cong F_{t}^{\prime}$.

As to the first family $\mathcal{F}$ constructed in (5.7), it fits into the exact diagram


Since $\Psi$ restricting to $X \times\{0\}$ is the $\varphi$ in (5.4), it represents a path $\rho_{1}$ in $W$ with $\rho_{1}(0)=0$ so that $E_{\rho_{1}(t)}$ is the first family $F_{t}$ constructed before.

From what we know of the families $F_{t}$ and $F_{t}^{\prime}$, their Kodaira-Spencer classes at $t=0$ are of the form

$$
\left(\begin{array}{cc}
0 & 0 \\
\kappa_{21} & 0
\end{array}\right) \quad \text { and } \quad\left(\begin{array}{cc}
0 & \kappa_{12}^{\prime} \\
0 & 0
\end{array}\right), \quad \kappa_{21} \neq 0, \quad \kappa_{12}^{\prime} \neq 0
$$

Since $W$ is smooth, there is a path $\rho(t)$ with $\rho(0)=0$ so that $\dot{\rho}(0)=\dot{\rho}_{1}(0)+\dot{\rho}_{2}(0)$; hence the family $E_{\rho(t)}$ has Kodaira-Spencer class at $t=0$

$$
\left(\begin{array}{cc}
0 & \kappa_{12}^{\prime} \\
\kappa_{21} & 0
\end{array}\right), \quad \kappa_{21} \neq 0, \quad \kappa_{12}^{\prime} \neq 0
$$

It satisfies the requirement of theorem 4.3. This proves
Theorem 5.1. Let $X \subset \mathbf{P}^{4}$ be a smooth quintic threefold and $\omega$ is a Calaby-Yau form (metric) on $X$. Then there is a smooth deformation $D_{s}^{\prime \prime}$ of $\left(E, D_{0}^{\prime \prime}\right)=\mathbb{C}_{X} \oplus T X$ so that for large $c>0$ and small $s$ there are irreducible regular solutions $\left(H_{s}, \omega_{s}\right)$ to Strominger's system on the vector bundle $\left(E, D_{s}^{\prime \prime}\right)$ so that $\lim _{s \rightarrow 0} \omega_{s}=c \omega$ and $\lim _{s \rightarrow 0} H_{s}$ is a regular Hermitian Yang-Mills connection on $\mathbb{C}_{X} \oplus T X$.

We next state the existence of solutions to $\mathrm{SU}(5)$-strominger's system.
Theorem 5.2. Let $X \subset \mathbf{P}^{3} \times \mathbf{P}^{3}$ be a smooth Calabi-Yau threefold cut out by three homogeneous polynomials of bi-degrees $(3,0),(0,3)$ and $(1,1)$. Let $\omega$ be a Calabi-Yau form on $X$.

Then there is a smooth deformation $D_{s}^{\prime \prime}$ of $\left(E, D_{0}^{\prime \prime}\right)=\mathbb{C}_{X}^{\oplus}{ }^{2} \oplus T X$ so that for large $c>0$ and small $s$ there are irreducible regular solution $\left(H_{s}, \omega_{s}\right)$ to Strominger's system on $\left(E, D_{s}^{\prime \prime}\right)$.
Proof. We only need to produce a deformation of holomorphic structure of $\mathbb{C}_{X}^{\oplus 2} \oplus T X$. Let $\pi_{1}$ and $\pi_{2}: X \rightarrow \mathbf{P}^{3}$ be the composite of the immersion $X \subset \mathbf{P}^{3} \times \mathbf{P}^{3}$ with the projections $\mathbf{P}^{3} \times \mathbf{P}^{3} \rightarrow \mathbf{P}^{3}$. Then $T X$ fits into the exact sequence

$$
\begin{equation*}
0 \longrightarrow T X \longrightarrow \pi_{1}^{*} \mathbf{T} \mathbf{P}^{3} \oplus \pi_{2}^{*} T \mathbf{P}^{3} \longrightarrow \mathcal{O}_{X}(3,0) \oplus \mathcal{O}_{X}(0,3) \oplus \mathcal{O}_{X}(1,1) \longrightarrow 0 \tag{5.9}
\end{equation*}
$$

Here $\mathcal{O}_{X}(i, j)$ is the restriction to $X$ of $\pi_{1}^{*} \mathcal{O}_{\mathbf{P}^{3}}(i) \otimes \pi_{2}^{*} \mathcal{O}_{\mathbf{P}^{3}}(j)$. Composing the canonical

$$
\mathcal{O}_{X}(1,0)^{\oplus 4} \oplus \mathcal{O}_{X}(0,1)^{\oplus 4} \longrightarrow \pi_{1}^{*} \mathbf{T} \mathbf{P}^{3} \oplus \pi_{2}^{*} T \mathbf{P}^{3}
$$

with the last arrow in (5.9), we obtain a surjective

$$
\mathcal{O}_{X}(1,0)^{\oplus 4} \oplus \mathcal{O}_{X}(0,1)^{\oplus 4} \xrightarrow{\varphi_{2}} \mathcal{O}_{X}(3,0) \oplus \mathcal{O}_{X}(0,3) \oplus \mathcal{O}_{X}(1,1)
$$

whose kernel, denoted by $F_{0}$, is an extension of $T X$ by $\mathcal{O}_{X}^{\oplus}$. Next we varies $\varphi_{2}$ to produce a variation of holomorphic structure of $F_{0}$. The bundle $F_{0}$ is a small deformation of $\mathbb{C}_{X}^{\oplus 2} \oplus T X$; varying $\varphi_{2}$ produces small deformation of $F_{0}$. We then mimic the argument in the proof of Theorem 5.1 to show that we can make this small deformation of small deformation into a single small deformation; it is our desired $D_{s}^{\prime \prime}$.

To complete the proof of the theorem, we need to check the non-degeneracy condition on the two matrices $B$ and $B^{\prime}$ associated to the Kodaira-Spencer class $\kappa$ of this family. It is routine shall be omitted. This completes the proof of the Theorem.

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Department of Mathematics, Stanford University, Stanford, CA 94305
E-mail address: jli@math.stanford.edu
Department of Mathematics, Harvard University, Cambridge, MA 02138
E-mail address: yau@math.harvard.edu


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[^1]:    ${ }^{1}$ The equation 1.3 in 24 has $\frac{1}{30} \operatorname{tr} F \wedge F$; this is because he worked with principle bundles and the trace is that of its adjoint bundle.

