



Non-Kähler SYZ Mirror Symmetry

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Abstract: We study SYZ mirror symmetry in the context of non-Kähler Calabi–Yau manifolds. In particular, we study the six-dimensional Type II supersymmetric $SU(3)$ systems with Ramond–Ramond fluxes, and generalize them to higher dimensions. We show that Fourier–Mukai transform provides the mirror map between these Type IIA and Type IIB supersymmetric systems in the semi-flat setting. This is concretely exhibited by nilmanifolds.

1. Introduction

The Strominger–Yau–Zaslow (SYZ) approach [[SYZ96](#)] to mirror symmetry has brought many fruitful results in the past two decades. For a mirror pair of Calabi–Yau manifolds (X, \check{X}) , it asserts that there exist special Lagrangian fibrations $\mu : X \rightarrow B$ and $\check{\mu} : \check{X} \rightarrow B$ such that $\mu^{-1}(\{b\})$ and $\check{\mu}^{-1}(\{b\})$ are dual tori. As a consequence, Lagrangian sections of μ should correspond to holomorphic line bundles on \check{X} , which explains the interchange between symplectic geometry of X and complex geometry of \check{X} . Gross [[Gro01](#)] gave a verification of the above picture in the topological level. The Gross–Siebert program [[GS11](#)] gave a sophisticated algebraic formulation of the SYZ construction. Moreover, the SYZ program was successfully carried out in various situations for Kähler manifolds [[LYZ00](#), [Leu05](#), [Aur07](#), [CO06](#), [CL10](#), [FOOO10](#), [CLL12](#), [AAK](#)].

This paper explores the SYZ approach for non-Kähler Calabi–Yau manifolds, i.e., non-Kähler almost Hermitian manifolds with $c_1 = 0$. We shall consider two classes of non-Kähler Calabi–Yau geometries, which we will call Type IIA and Type IIB supersymmetric systems. In six dimensions, the systems arise directly from the imposition of supersymmetry in Type IIA/IIB string theory [[GMPT05](#), [Tom08](#), [TY](#)]. The six-dimensional Type IIA system is a symplectic manifold (X, ω) with an almost complex structure induced from a complex decomposable three-form Ω with $d \operatorname{Re} \Omega = 0$ (instead of $d \Omega = 0$). Type IIB system is a complex threefold \check{X} with a holomorphic

volume form $\check{\Omega}$ and a balanced Hermitian metric, whose associated $(1, 1)$ form $\check{\omega}$ satisfies $d(\check{\omega}^2) = 0$ (instead of $d\check{\omega} = 0$). We also define and study their higher dimensional analogs. Here, we preserve on the IIB side the balanced metric condition, which has a number of desirable properties [Mic82, AB93, AB95, AB04]. The mirror dual condition on the symplectic IIA side will be shown to require the introduction of a special real polarization.

Though there is now a fairly decent understanding of mirror symmetry in the Kähler situation, the mirror phenomenon for non-Kähler Calabi–Yau geometries has not been studied as much and is not well-understood. This motivates us to study mirror symmetry in the presence of the so-called Ramond–Ramond (RR) flux using SYZ transformation. The aim is to construct a duality between Type IIA and Type IIB supersymmetric systems (and their higher dimensional analogs) by using SYZ and Fourier–Mukai transform.

While SYZ fibrations in general may not exist in the presence of flux, the SYZ transformation (when fibrations exist) does provide important clues on how mirror symmetry should behave in the non-Kähler setting. We expect mirror symmetry between type IIA and IIB systems still to occur in a similar way, even in cases when SYZ fibrations may not exist. Namely, the flux source terms (denoted as ρ_A and ρ_B later on in this paper) are mirror to each other in the sense of homological mirror symmetry.

Construction of non-Kähler Calabi–Yau manifolds has been studied in several recent works [Cal58, STY02, GP04, GGP08, Wu06, FP10, FLY12, FP13]. The survey by Fu [Fu10] gave an excellent introduction to this topic. In this paper we focus on the semi-flat setting [LYZ00, Leu05], namely we consider Lagrangian fibrations away from singular fibers. We will see that interesting correspondences between the Type IIA and IIB systems and their RR fluxes already appear in such a simple setting. The Iwasawa manifold and its higher-dimensional analogs serves as important examples. The main theorem is:

Theorem 1.1 (See Theorem 5.1). *Under SYZ and Fourier–Mukai transform, a semi-flat supersymmetric Type IIA $SU(n)$ structure is transformed to a semi-flat supersymmetric Type IIB $SU(n)$ structure, and their fluxes also correspond to each other by Fourier–Mukai transform.*

The study of non-Kähler Calabi–Yau geometries was largely motivated by string theory (see, for example [Str86, BBDG03, BBD⁺04]). In physical terms, the presence of fluxes in supersymmetric systems results in geometries that are generically non-Kähler. In Type IIA and IIB string theory, there are mainly two types of fluxes, namely Ramond–Ramond (RR) flux and H-flux (which is also called NS–NS flux). The settings of Type IIA and IIB supersymmetric systems in this paper follow the form expressed in Tseng–Yau [TY], in which an RR flux is present. These are special cases of the more general systems, as given in Grana–Minasian–Petrini–Tomasuolo [GMPT05] and Tomasiuolo [Tom08], which include the H-flux and are expressed in terms of generalized complex geometry [Hit03, Gua11]. In this paper, we place our focus on mirrors of balanced metrics and generalize the definition of Type IIA systems to higher dimensions, which does not involve the use of generalized geometry.

T-duality and SYZ in the setting of generalized Calabi–Yau manifolds were studied in [BEM04, BHM04, FMT05, GSN07, CG10], where H-flux played the key role, and also from the bispinor perspective, which includes RR fluxes in [GMPT07, GMPW09]. The emphasis of this paper is different: we study SYZ in the presence of RR-flux and in particular focus in on the balanced Hermitian metric condition on non-Kähler manifolds, which also appears as part of the Strominger system [Str86].

2. The Supersymmetric Systems and Their Higher-Dimensional Analogs

In this section we introduce Type IIA and IIB supersymmetric $SU(n)$ systems, which are the main objects of study in this paper.

Definition 2.1. Let X be a real manifold of dimension $2n$. An $SU(n)$ structure on X is a pair (ω, Ω) of differential forms satisfying the following conditions:

- (1) Ω is a nowhere-vanishing decomposable complex-valued n -form on X such that by defining

$$T^{(0,1)}X := \{v \in TX \otimes \mathbb{C} : \iota_v \Omega = 0\}$$

and $T^{(1,0)}X$ to be the complex conjugate of $T^{(0,1)}X$, one has a splitting

$$TX \otimes \mathbb{C} = T^{(1,0)}X \oplus T^{(0,1)}X$$

which induces an almost complex structure J on X . Then Ω is an $(n, 0)$ form with respect to this almost complex structure J . (Note that we do not require $d\Omega = 0$ here.)

- (2) ω is a non-degenerate real¹ $(1, 1)$ -form with respect to this complex structure J such that $\omega(\cdot, J\cdot)$ defines a Hermitian metric on X . (Note that we do not require $d\omega = 0$ here.) This in particular implies that $\Omega \wedge \omega = 0$.

Since both $(\Omega \wedge \bar{\Omega})/i^n$ and ω^n are real nowhere-vanishing top-forms, we have

$$\Omega \wedge \bar{\Omega} = i^n F \cdot \frac{\omega^n}{n!}$$

for some nowhere-vanishing function F on X . F is called to be the conformal factor of the $SU(n)$ structure.

In other words an $SU(n)$ structure is a pointwise Calabi–Yau structure without imposing any integrability condition. Supersymmetry imposes integrability conditions on $SU(n)$ structures. In string theory one mostly focuses on $n = 3$.

Definition 2.2. An $SU(3)$ structure (X, ω, Ω) is said to be supersymmetric of type IIB if Ω defines an honest complex structure and ω defines a balanced metric, that is, $d\Omega = 0$ and $d(\omega^2) = 0$.

Let F be the conformal factor of the $SU(3)$ structure. Define

$$\rho_B = 2i \partial \bar{\partial} \left(F^{-1} \cdot \omega \right)$$

which is an exact $(2, 2)$ form.

¹ More generally we should include B -field here, and ω can be complex-valued. Such a complexification is necessary for making the mirror map to be an isomorphism. This paper focuses on RR flux and we omit it for simplicity.

In conclusion, we have the following system of equations for a supersymmetric $SU(3)$ structure of type IIB:

$$d\Omega = 0, \tag{2.1}$$

$$d(\omega^2) = 0, \tag{2.2}$$

$$\Omega \wedge \bar{\Omega} = -\mathbf{i} F \cdot \frac{\omega^3}{6}, \tag{2.3}$$

$$2\mathbf{i} \partial \bar{\partial} (F^{-1} \cdot \omega) = \rho_B. \tag{2.4}$$

When ω is symplectic (that is $d\omega = 0$) and F is constant, (X, ω, Ω) is Calabi–Yau, and the RR flux source current ρ_B is zero. In such case the corresponding metric has $SU(3)$ holonomy.

Definition 2.3. An $SU(3)$ structure (X, ω, Ω) is said to be supersymmetric of Type IIA if $d\omega = 0$ and $d \operatorname{Re} \Omega = 0$.

Let F be the conformal factor of the $SU(3)$ structure. We define

$$\rho_A = d d^\Lambda (F \cdot \operatorname{Im} \Omega)$$

which is an exact three-form. Here

$$d^\Lambda = d \Lambda - \Lambda d$$

is the symplectic adjoint operator, where Λ is the adjoint of the Lefschetz operator $L = \omega \wedge (\cdot)$.

Thus the Type IIA supersymmetric $SU(3)$ structure satisfies the following system of equations:

$$d\omega = 0, \tag{2.5}$$

$$d(\operatorname{Re} \Omega) = 0, \tag{2.6}$$

$$\Omega \wedge \bar{\Omega} = -\mathbf{i} F \cdot \frac{\omega^3}{6}, \tag{2.7}$$

$$d d^\Lambda (F \cdot \operatorname{Im} \Omega) = \rho_A. \tag{2.8}$$

When $d\Omega = 0$ and F is constant, Ω defines an honest complex structure and X is Calabi–Yau; the RR flux source current ρ_A is zero.

Type IIB supersymmetric structures have a natural generalization to all dimensions:

Definition 2.4. An $SU(n)$ structure (X, ω, Ω) is said to be supersymmetric of type IIB if Ω defines an honest complex structure and ω defines a balanced metric, that is, $d\Omega = 0$ and $d(\omega^{n-1}) = 0$.

Remark 2.5. It is well known that supersymmetric $SU(3)$ system satisfies the equation of motion. See, for example [GMPT07].

Nilmanifolds introduced in Sect. 7 serve as examples of such systems.

However, generalizing Type IIA supersymmetric $SU(n)$ structure to all dimensions is not as obvious as it appears. The naive definition, which is to require $d \operatorname{Re} \Omega = 0$ as in dimension three, does not match with SYZ transformation. It turns out that choosing

a special real polarization is important in the definition of Type IIA supersymmetric structure in higher dimensions.

A complex structure automatically comes with a complex polarization, which is the splitting

$$TX \otimes \mathbb{C} = T^{(1,0)}X \oplus T^{(0,1)}X.$$

This gives rise to the notion of (p, q) forms. On the other hand, given a symplectic structure, it does not automatically come with a real polarization, and we have to fix one in order to define Type IIA supersymmetric structure in higher dimensions.

Definition 2.6. Let X be a real $2n$ -fold and ω a non-degenerate two-form. A real polarization with respect to ω is an integrable Lagrangian distribution $\{\Lambda_x \subset T_x X : x \in U\}$ over an open dense subset $U \subset X$. (Lagrangian means that $\omega|_{\Lambda_x} = 0$ for all $x \in U$.)

Let (X, ω, Ω) be an $SU(n)$ structure. A real polarization (U, Λ) is said to be special with respect to Ω of phase $\theta \in \mathbb{R}/2\pi\mathbb{Z}$ if $\Omega|_{\Lambda_x} \in \mathbb{R}_{>0} \cdot e^{i\theta}$ for all $x \in U$.

Note that the symbol Λ appearing in d^Λ refers to the adjoint of the Lefschetz operator. We will also use Λ to denote a real polarization. It should be clear from the context which meaning we refer to.

Given a real polarization on (X, ω) , the metric on X induces a splitting $TU = \Lambda \oplus \Lambda^\perp$. We have

$$\Omega_U^n = \bigoplus_{p+q=n} \Omega_U^{(p,q)\Lambda},$$

where forms in $\Omega_U^{(p,q)\Lambda}$ are defined over U and consist of p Λ -directions and q Λ^\perp -directions, and the corresponding projection operators $\pi_\Lambda^{p,q} : \Omega_U^n \rightarrow \Omega_U^{(p,q)\Lambda}$. Let $\Omega^{(p,q)\Lambda}$ be the space of differential forms on X whose restriction to U belongs to $\Omega_U^{(p,q)\Lambda}$.

Then define a generalization of Definition 2.3 as follows:

Definition 2.7. Let (X, ω, Ω) be an $SU(n)$ structure with a special real polarization (U, Λ) . (X, ω, Ω) is said to be supersymmetric of Type IIA if

- (1) $d\omega = 0$.
- (2) $d(\pi_\Lambda^{n,0} \cdot \Omega|_U) = 0$.
- (3) $d(\pi_\Lambda^{1,n-1} \cdot \Omega|_U) = 0$.

Definition 2.8. Let F be the conformal factor of an $SU(n)$ structure (X, ω, Ω) . If (X, ω, Ω) is supersymmetric of Type IIA (with respect to a special real polarization (U, Λ)), define

$$\rho_A = -i d d^\Lambda (F \cdot (\pi_\Lambda^{n-1,1} \cdot \Omega|_U + \pi_\Lambda^{0,n} \cdot \Omega|_U)).$$

If (X, ω, Ω) is supersymmetric of Type IIB, define

$$\rho_B = 2i \partial \bar{\partial} (F^{-1} \cdot \omega).$$

Definition 2.7 reduces to Definition 2.3 when $n = 3$:

Proposition 2.9. *Let (X, ω, Ω) be an $SU(3)$ structure with a special real polarization (U, Λ) of phase zero or π . Then $d(\operatorname{Re} \Omega) = 0$ if and only if $d(\pi_\Lambda^{3,0} \cdot \Omega|_U) = d(\pi_\Lambda^{1,2} \cdot \Omega|_U) = 0$.*

Proof. Since U is an open dense subset of X , $d(\operatorname{Re} \Omega) = 0$ if and only if $d(\operatorname{Re} \Omega|_U) = 0$. For $x_0 \in U$, let $(\theta_1, \theta_2, \theta_3, r_1, r_2, r_3)$ be local coordinates around x such that each leaf of Λ is given by $(r_1, r_2, r_3) = (c_1, c_2, c_3)$ for some constants c_i 's. Then Ω can be written as

$$\Omega = f(\theta, r) \cdot (d\theta_1 + \mathbf{i}\psi_1) \wedge (d\theta_2 + \mathbf{i}\psi_2) \wedge (d\theta_3 + \mathbf{i}\psi_3)$$

where $\psi_i = J \cdot d\theta_i$ are one-forms and $f(\theta, r)$ is complex-valued. Since (U, Λ) is special of phase zero or π , $\Omega|_{\Lambda_x} = f(\theta, r) \cdot d\theta_1 \wedge d\theta_2 \wedge d\theta_3$ is real-valued, and hence $f(\theta, r)$ is real-valued. Then

$$\begin{aligned} \operatorname{Re} \Omega &= f(\theta, r) \cdot (d\theta_1 \wedge d\theta_2 \wedge d\theta_3 - d\theta_1 \wedge \psi_2 \wedge \psi_3 - \psi_1 \wedge d\theta_2 \wedge \psi_3 \\ &\quad - \psi_1 \wedge \psi_2 \wedge d\theta_3) \\ &= (\pi_\Lambda^{3,0} \oplus \pi_\Lambda^{1,2}) \cdot \Omega. \end{aligned}$$

It follows that $d(\operatorname{Re} \Omega) = 0$ if and only if $d(\pi_\Lambda^{3,0} \cdot \Omega|_U) = d(\pi_\Lambda^{1,2} \cdot \Omega|_U) = 0$. \square

Note also when $n = 3$, $\operatorname{Im} \Omega = -\mathbf{i}(\pi_\Lambda^{2,1} \cdot \Omega + \pi_\Lambda^{0,3} \cdot \Omega)$. Therefore, to conclude, a Type IIA supersymmetric $SU(n)$ system satisfies

$$d\omega = 0, \quad (2.9)$$

$$d((\pi_\Lambda^{n,0} \oplus \pi_\Lambda^{1,n-1}) \cdot \Omega) = 0, \quad (2.10)$$

$$\Omega \wedge \bar{\Omega} = -\mathbf{i}^n F \cdot \frac{\omega^n}{n!}, \quad (2.11)$$

$$-\mathbf{i} d d^\Lambda (F \cdot (\pi_\Lambda^{n-1,1} \cdot \Omega + \pi_\Lambda^{0,n} \cdot \Omega)) = \rho_A. \quad (2.12)$$

A Type IIB supersymmetric $SU(n)$ system satisfies

$$d\Omega = 0, \quad (2.13)$$

$$d(\omega^{n-1}) = 0, \quad (2.14)$$

$$\Omega \wedge \bar{\Omega} = -\mathbf{i} F \cdot \frac{\omega^n}{n!}, \quad (2.15)$$

$$2\mathbf{i} \partial \bar{\partial} (F^{-1} \cdot \omega) = \rho_B. \quad (2.16)$$

Remark 2.10. The general $SU(n)$ systems we introduced here have similarities with the higher dimensional supersymmetric compactifications in string theory. For instance, for $n=4$, they are very similar to special cases of the supersymmetric equations in [PT13, Ros14]. It is interesting to expand upon this issue in future works.

3. SYZ Transformation

The SYZ transform we use in this paper follows from [LYZ00,Leu05]. In this section we briefly review the setting and definitions which will be used in the rest of the paper.

Let (X, ω) be a symplectic manifold and $\pi : X \rightarrow B$ a Lagrangian torus bundle. By Arnold–Liouville’s action-angle coordinates [Arn91, Section 50], for each $p \in B$ there exists open subset $U \subset B$ containing p , action coordinates r_1, \dots, r_n of U and symplectomorphism $(\pi^{-1}(U), \omega) \cong (T^*U/\Lambda^*, \omega_{\text{can}})$, where Λ^* is a lattice bundle generated by $d r_1, \dots, d r_n$. The corresponding fiber coordinates of T^*U are denoted as θ_i ’s, and so $\omega = \sum_{i=1}^n d \theta_i \wedge d r_i$.

The dual torus bundle is defined as the set of all fiberwise flat $U(1)$ -connections:

$$\check{X} := \{(r, \nabla) : r \in B, \nabla \text{ is a flat } U(1) \text{ connection over } F_r\}$$

where F_r denotes the fiber of π at r . The torus bundle map $\check{\pi} : \check{X} \rightarrow B$ is given by forgetting the fiberwise flat $U(1)$ connections ∇ .

\check{X} is endowed with a canonical complex structure. Locally for each $p \in B$, there exists open subset $U \subset B$ containing p and a biholomorphism $\check{\pi}^{-1}(U) \cong TU/\Lambda$, where $\Lambda \subset TU$ is the lattice bundle generated by $\frac{\partial}{\partial r_1}, \dots, \frac{\partial}{\partial r_n}$, and r_i ’s are the action coordinates mentioned before. The corresponding fiber coordinates of TU are denoted as $\check{\theta}_i$ ’s, and so complex coordinates of \check{X} can be taken to be $\zeta_i := \exp(\check{\theta}_i + \mathbf{i} r_i)$ or $z_i := \check{\theta}_i + \mathbf{i} r_i$ for $i = 1, \dots, n$.

The transition between any two local action-coordinate systems of B belongs to $GL(n, \mathbb{Z}) \times \mathbb{R}^n$, and so B is endowed with a tropical affine structure. We assume that the action coordinate systems can be chosen such that all the transitions belong to $SL(n, \mathbb{Z}) \times \mathbb{R}^n$. In such a situation \check{X} has a holomorphic volume form $\check{\Omega}$, which is locally written as

$$\check{\Omega} = d z_1 \wedge \dots \wedge d z_n = (d \check{\theta}_1 + \mathbf{i} d r_1) \wedge \dots \wedge (d \check{\theta}_n + \mathbf{i} d r_n).$$

(X, ω) and $(\check{X}, \check{\Omega})$ are said to form a semi-flat mirror pair. The semi-flat A -branes on X are mirror to semi-flat B -branes on \check{X} under Fourier–Mukai transform. The readers are referred to [LYZ00] for details.

In this paper, we mostly focus on Fourier–Mukai transform of differential forms, which will be discussed in the next section. We will consider a semi-flat real $(1, 1)$ form $\check{\omega}$ on \check{X} , which is given by

$$\check{\omega} = \frac{\mathbf{i}}{2} \sum_{i,j} \mu_{ij}(r) d z_i \wedge \overline{d z_j}$$

where $\sum_{i,j} \mu_{ij}(r) d r_i d r_j$ defines a Riemannian metric on B (that is, μ_{ij} is symmetric on i, j and positive definite). We will impose the balanced condition $d \check{\omega}^{n-1} = 0$ instead of the Kähler condition $d \check{\omega} = 0$, and consider its mirror structure by applying the Fourier–Mukai transform.

4. Fourier–Mukai Transform of Differential Forms

Let (X, ω) and $(\check{X}, \check{\Omega})$ be a semi-flat mirror pair of real dimension $2n$ as in Sect. 3. In this section we introduce Fourier–Mukai transform for differential forms on X and

\check{X} . We will restrict the construction to T -invariant differential forms, while keeping in mind that Fourier–Mukai transform can also be done for general differential forms, which is an important tool for quantum corrections [CL10, CLL12]. Fourier–Mukai transform of differential forms was used to study SYZ mirror symmetry without flux in [Leu05, CL10, CLL12, CLM11]. There is an important subtlety in the treatment here, namely we take a switch from the complex to the real polarization (Definition 4.2) along with the transform. A new result in this section is a direct relation between the Doubealt operators $(\bar{\partial}, \partial)$ on \check{X} and the differentials (d, d^Λ) on X .

Let $\Omega_B^k(X, \mathbb{C})$ denote the space of complex-valued k -forms on X which depend only on base, that is, $\phi \in \Omega_B^k(X, \mathbb{C})$ is locally written as

$$\phi = \sum_{\substack{I=(i_1, \dots, i_p) \\ J=(j_1, \dots, j_q) \\ p+q=k}} a_{IJ}(r) d\theta_{i_1} \wedge \dots \wedge d\theta_{i_p} \wedge dr_{j_1} \wedge \dots \wedge dr_{j_q}$$

where $(r_1, \dots, r_n, \theta_1, \dots, \theta_n)$ is an action-angle coordinate system of X , and $a_{IJ}(r)$'s are complex-valued functions on B . Such a ϕ is also said to be T -invariant, where T denotes a torus fiber of $X \rightarrow B$.

Definition 4.1. A semi-flat (supersymmetric) $SU(n)$ structure is a (supersymmetric) $SU(n)$ structure (X, ω, Ω) such that X has a Lagrangian torus bundle structure $X \rightarrow B$ and $\omega, \Omega \in \Omega_B^*(X, \mathbb{C})$.

Similarly, let $\Omega_B^{p,q}(\check{X})$ denote the space of (p, q) -forms on \check{X} which depend only on base. $\check{\phi} \in \Omega_B^{p,q}(\check{X})$ is locally of the form

$$\check{\phi} = \sum_{\substack{I=(i_1, \dots, i_p) \\ J=(j_1, \dots, j_q)}} a_{IJ}(r) dz_{i_1} \wedge \dots \wedge dz_{i_p} \wedge \overline{dz_{j_1}} \wedge \dots \wedge \overline{dz_{j_q}}.$$

The above expression of $\check{\phi}$ is written in terms of complex polarization. We can switch to real polarization by the following definition:

Definition 4.2 (Polarization switch operator). The polarization switch operator \mathcal{P} on $\Omega_B^*(\check{X})$ is defined by sending

$$\check{\phi} = \sum_{\substack{I=(i_1, \dots, i_p) \\ J=(j_1, \dots, j_q)}} a_{IJ}(r) dz_{i_1} \wedge \dots \wedge dz_{i_p} \wedge \overline{dz_{j_1}} \wedge \dots \wedge \overline{dz_{j_q}}$$

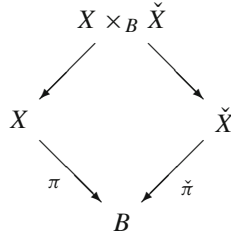
to

$$\mathcal{P} \cdot \check{\phi} = \sum_{\substack{I=(i_1, \dots, i_p) \\ J=(j_1, \dots, j_q)}} a_{IJ}(r) d\check{\theta}_{i_1} \wedge \dots \wedge d\check{\theta}_{i_p} \wedge dr_{j_1} \wedge \dots \wedge dr_{j_q}.$$

Now we define Fourier–Mukai transform of differential forms on X and \check{X} , which gives an isomorphism

$$\Omega_B^k(X, \mathbb{C}) \cong \bigoplus_{p=0}^k \left(\Omega_B^{p, n-k+p}(\check{X}) \right).$$

Consider the following commutative diagram:



where $\pi : X \rightarrow B$ and $\check{\pi} : \check{X} \rightarrow B$ are dual torus bundle maps given in the semi-flat setting, and the fiber product $X \times_B \check{X}$ is defined using these bundle maps. We have the universal connection on $X \times_B \check{X}$, which is $d + \mathbf{i}\check{\theta}_i d\theta_i - \mathbf{i}\theta_i d\check{\theta}_i$ in terms of semi-flat local coordinates. The curvature of the universal connection is

$$\mathbf{F} = 2\mathbf{i} \sum_{i=1}^n d\check{\theta}_i \wedge d\theta_i.$$

Definition 4.3 (Fourier–Mukai transform). Let $\check{\phi}$ be a T -invariant differential form on \check{X} . The Fourier transform of $\check{\phi}$ is defined as

$$\text{FT} \cdot \check{\phi} := \pi_* \left((\check{\pi}^*(\mathcal{P} \cdot \check{\phi})) \wedge \exp \frac{\mathbf{F}}{2\mathbf{i}} \right)$$

where the push-forward π_* induced by $\pi : X \rightarrow B$ is defined by integration along torus fibers.

Similarly for a T -invariant differential form ϕ on X , its Fourier transform is defined as

$$\text{FT} \cdot \phi := \mathcal{P}^{-1} \cdot \left(\check{\pi}_* \left((\pi^* \phi) \wedge \exp \frac{-\mathbf{F}}{2\mathbf{i}} \right) \right).$$

By carefully keeping track of the sign in the transform, we see that applying Fourier–Mukai transform two times is simply identity up to a sign only dependent on the dimension.

Proposition 4.4.

$$\text{FT} \circ \text{FT} = (-1)^{\frac{n(n-1)}{2}}$$

where $n = \dim B$.

Proof. It suffices to consider the basic elements $d z_I \wedge \overline{d z_J} = d z_{i_1} \wedge \cdots \wedge d z_{i_p} \wedge \overline{d z_{j_1}} \wedge \cdots \wedge \overline{d z_{j_q}}$. Switching to real polarization gives $d \check{\theta}_I \wedge d r_J = d \check{\theta}_{i_1} \wedge \cdots \wedge d \check{\theta}_{i_p} \wedge d r_{j_1} \wedge \cdots \wedge d r_{j_q}$. Multiplication by

$$\exp \left(\sum_i d \check{\theta}_i \wedge d \theta_i \right) = \sum_{p=0}^n (-1)^{\frac{p(p-1)}{2}} \sum_{K=\{i_1, \dots, i_p\}} d \check{\theta}_K \wedge d \theta_K$$

gives

$$\begin{aligned} & (-1)^{\frac{(n-p)(n-p-1)}{2}} d\check{\theta}_{I^c} \wedge d\theta_{I^c} \wedge d\check{\theta}_I \wedge dr_J \\ &= (-1)^{\frac{(n-p)(n-p-1)}{2}} (-1)^{p(n-p)} d\check{\theta}_{I^c} \wedge d\check{\theta}_I \wedge d\theta_{I^c} \wedge dr_J \end{aligned}$$

where $I^c := \{1, \dots, n\} - I$ and $p = |I|$. Then integrating along the fiber directions $\check{\theta}_i$'s gives

$$\begin{aligned} & (-1)^{\frac{(n-p)(n-p-1)}{2}} (-1)^{p(n-p)} \text{sign}(I^c, I) d\theta_{I^c} \wedge dr_J \\ &= (-1)^{\frac{(n-p)(n-p-1)}{2}} \text{sign}(I, I^c) d\theta_{I^c} \wedge dr_J. \end{aligned}$$

Thus we have

$$\text{FT} \cdot (dz_I \wedge \overline{dz_J}) = (-1)^{\frac{(n-p)(n-p-1)}{2}} \text{sign}(I, I^c) d\theta_{I^c} \wedge dr_J. \tag{4.1}$$

Now we take Fourier transform again. Multiplying $d\theta_{I^c} \wedge dr_J$ by $\exp\left(-\sum_i d\check{\theta}_i \wedge d\theta_i\right)$ gives gives

$$\begin{aligned} & (-1)^p (-1)^{\frac{p(p-1)}{2}} d\check{\theta}_I \wedge d\theta_I \wedge d\theta_{I^c} \wedge dr_J \\ &= (-1)^p (-1)^{\frac{p(p-1)}{2}} (-1)^{np} d\theta_I \wedge d\theta_{I^c} \wedge d\check{\theta}_I \wedge dr_J. \end{aligned}$$

Integrating along the fiber directions θ_i 's gives

$$(-1)^p (-1)^{\frac{p(p-1)}{2}} (-1)^{np} \text{sign}(I, I^c) d\check{\theta}_I \wedge dr_J.$$

Switching the real polarization back to complex polarization, we have

$$\text{FT}(d\theta_{I^c} \wedge dr_J) = (-1)^p (-1)^{\frac{p(p-1)}{2}} (-1)^{np} \text{sign}(I, I^c) dz_I \wedge \overline{dz_J}.$$

Hence $\text{FT} \circ \text{FT}(dz_I \wedge \overline{dz_J})$ equals to

$$(-1)^{\frac{(n-p)(n-p-1)}{2}} (-1)^p (-1)^{\frac{p(p-1)}{2}} (-1)^{np} \cdot dz_I \wedge \overline{dz_J} = (-1)^{\frac{n(n-1)}{2}} dz_I \wedge \overline{dz_J}.$$

□

In the theorem below we see that d on $\Omega_B^*(X, \mathbb{C})$ is transformed to $\bar{\partial}$ on $\Omega_B^*(\check{X}, \mathbb{C})$, and d^Λ on $\Omega_B^*(X, \mathbb{C})$ is transformed to ∂ on $\Omega_B^*(\check{X}, \mathbb{C})$. We recall that $d^\Lambda := d \circ \Lambda - \Lambda \circ d$ which decreases the degree by one, where Λ is the dual Lefschetz operator. To our knowledge the theorem has not appeared in previous literature.

Theorem 4.5. *Fourier–Mukai transform gives an isomorphism*

$$\left(\Omega_B^*(X, \mathbb{C}), \frac{(-1)^n \mathbf{i}}{2} d, \frac{(-1)^n \mathbf{i}}{2} d^\Lambda \right) \cong \left(\Omega_B^*(\check{X}, \mathbb{C}), \bar{\partial}, \partial \right)$$

as double complexes.

Proof. Let $\phi = \phi_{I,J} d z_I \wedge d z_J$ where I and J are multi-indices. By assuming $\phi_{I,J}$ is skew-symmetric on I and J , the expression is independent of the orderings of I and J . We need to prove that

$$\text{FT} \circ \bar{\partial} \cdot \phi = \frac{(-1)^n \mathbf{i}}{2} \cdot d \circ \text{FT} \cdot \phi$$

and

$$\text{FT} \circ \partial \cdot \phi = \frac{(-1)^n \mathbf{i}}{2} \cdot d^\wedge \circ \text{FT} \cdot \phi.$$

Consider the first equation. By Eq. (4.1), Fourier transform of ϕ is

$$\text{FT} \cdot \phi = (-1)^{\frac{(n-p)(n-p-1)}{2}} \text{sign}(I, I^c) \phi_{I,J} d \theta_{I^c} \wedge d r_J \quad (4.2)$$

where $I^c = \{1, \dots, n\} - I$. Note that the above expression is independent of the orderings of I^c and J .

Let $p := |I|$. We have

$$\begin{aligned} \text{FT} \circ \bar{\partial} \cdot \phi &= \text{FT} \cdot \left(\frac{\mathbf{i}}{2} (\partial_i \phi_{I,J}) \bar{d} z_i \wedge d z_I \wedge \bar{d} z_J \right) \\ &= \frac{\mathbf{i}}{2} (-1)^{\frac{(n-p)(n-p-1)}{2}} \text{sign}(I, I^c) (\partial_i \phi_{I,J}) (-1)^p d \theta_{I^c} \wedge d r_i \wedge d r_J \\ &= \frac{\mathbf{i}}{2} (-1)^{\frac{(n-p)(n-p-1)}{2}} \text{sign}(I, I^c) (\partial_i \phi_{I,J}) (-1)^n d r_i \wedge d \theta_{I^c} \wedge d r_J. \end{aligned}$$

Comparing with Eq. 4.2, we see that $\text{FT} \circ \bar{\partial} \cdot \phi = (-1)^n \frac{\mathbf{i}}{2} \cdot d \circ \text{FT} \cdot \phi$.

To prove the second equation, let's recall that $d^\wedge = d \circ \Lambda - \Lambda \circ d$, where

$$\Lambda \phi = \sum_{i=1}^n \iota_{r_i} \iota_{\theta_i} \phi$$

for $\omega = \sum_i d \theta_i \wedge d r_i$. We remark that more generally for $\omega = \sum_{i,j} \omega_{ij} d x_i \wedge d x_j$,

$$\Lambda \phi = \frac{1}{2} \sum_{i,j} (\omega^{-1})^{ij} \iota_{x_i} \iota_{x_j} \phi.$$

Writing $K = I^c - \{i\}$, we have

$$\begin{aligned} \text{FT} \circ \partial \cdot \phi &= \text{FT} \cdot \left(\frac{-\mathbf{i}}{2} \sum_{i \in I^c} \partial_i \phi_{I,J} d z_i \wedge d z_I \wedge \bar{d} z_J \right) \\ &= \frac{-\mathbf{i}}{2} (-1)^{\frac{(n-p-1)(n-p-2)}{2}} \sum_{i \in I^c} \text{sign}(i, I, K) (\partial_i \phi_{I,J}) d \theta_K \wedge d r_J. \end{aligned}$$

On the other hand, let's compute $d \circ \Lambda \circ \text{FT} \cdot \phi$ and $\Lambda \circ d \circ \text{FT} \cdot \phi$.

$$d \circ \text{FT} \cdot \phi = (-1)^{\frac{(n-p)(n-p-1)}{2}} \text{sign}(I, I^c) \sum_{i \notin J} (\partial_i \phi_{I,J}) d r_i \wedge d \theta_{I^c} \wedge d r_J.$$

Again the above expression is independent of orderings of I^c and J . Since $\Lambda = \sum_j \iota_{r_j} \iota_{\theta_j}$, taking $I^c = (j, K)$ and $J = (j, L)$, we have

$$\begin{aligned} \Lambda \circ d \circ \text{FT} \cdot \phi &= (-1)^{\frac{(n-p)(n-p-1)}{2}} \text{sign}(I, I^c) \sum_{\substack{j=i \notin J \\ j \in I^c}} (\partial_i \phi_{I,J}) (-d\theta_K \wedge dr_J) \\ &\quad + (-1)^{\frac{(n-p)(n-p-1)}{2}} \text{sign}(I, I^c) \sum_{\substack{i \notin J \\ j \neq i \\ j \in I^c \cap J}} (\partial_i \phi_{I,J}) dr_i \\ &\quad \wedge ((-1)^{n-p-1} d\theta_K \wedge dr_L). \end{aligned}$$

To compute $d \circ \Lambda \circ \text{FT} \cdot \phi$ (again taking $I^c = (j, K)$ and $J = (j, L)$), we have

$$\Lambda \circ \text{FT} \cdot \phi = (-1)^{\frac{(n-p)(n-p-1)}{2}} \text{sign}(I, I^c) \sum_{j \in I^c \cap J} \phi_{I,J} (-1)^{n-p-1} d\theta_K \wedge dr_L$$

and hence

$$\begin{aligned} d \circ \Lambda \circ \text{FT} \cdot \phi &= (-1)^{\frac{(n-p-2)(n-p-1)}{2}} \text{sign}(I, I^c) \sum_{i \in I^c \cap J} \partial_j \phi_{I,J} dr_j \wedge d\theta_K \wedge dr_L \\ &\quad + (-1)^{\frac{(n-p)(n-p-1)}{2}} \text{sign}(I, I^c) \sum_{\substack{i \notin J \\ i \neq j \\ j \in I^c \cap J}} \partial_i \phi_{I,J} dr_i \wedge (-1)^{n-p-1} d\theta_K \wedge dr_L. \end{aligned}$$

We see that the second terms of $\Lambda \circ d \circ \text{FT} \cdot \phi$ and $d \circ \Lambda \circ \text{FT} \cdot \phi$ are equal. Thus

$$\begin{aligned} d^\Lambda \circ \text{FT} \cdot \phi &= (-1)^{\frac{(n-p-2)(n-p-1)}{2}} \text{sign}(I, I^c) \sum_{j \in I^c \cap J} \partial_j \phi_{I,J} dr_j \wedge d\theta_K \wedge dr_L \\ &\quad - (-1)^{\frac{(n-p)(n-p-1)}{2}} \text{sign}(I, I^c) \sum_{\substack{i \notin J \\ j \in I^c}} (\partial_i \phi_{I,J}) (-d\theta_K \wedge dr_J) \\ &= (-1)^{\frac{(n-p)(n-p-1)}{2}} \sum_{i \in I^c} \text{sign}(I, I^c) (\partial_i \phi_{I,J}) d\theta_K \wedge dr_J \\ &= (-1)^{n-1} (-1)^{\frac{(n-p-2)(n-p-1)}{2}} \sum_{i \in I^c} \text{sign}(i, I, K) (\partial_i \phi_{I,J}) d\theta_K \wedge dr_J \\ &= (-1)^n \left(\frac{\mathbf{i}}{2}\right)^{-1} \text{FT} \cdot (\partial\phi). \end{aligned}$$

□

5. SYZ Between Type-A and Type-B Supersymmetric Systems

Let (X, ω) and $(\check{X}, \check{\Omega})$ be a semi-flat mirror pair as described in Sect. 3. (X, ω) has the required real polarization Λ given by the given Lagrangian torus bundle (where Λ_x is the tangent space of the torus fiber at $x \in X$). The purpose of this section is to prove Theorem 1.1, namely Fourier–Mukai transform introduced in Sect. 4 gives a symmetry between Type-A and Type-B supersymmetric $SU(n)$ structures.

Theorem 5.1 (Detailed version of Theorem 1.1). *Let $\check{\omega}$ be a torus-invariant real $(1, 1)$ -form on \check{X} and Ω the Fourier–Mukai transform of $e^{2\check{\omega}}$.*

- (1) *$(\check{X}, \check{\omega}, \check{\Omega})$ forms an $SU(n)$ structure if and only if (X, ω, Ω) forms an $SU(n)$ structure. For such a pair the conformal factor F of (X, ω, Ω) is related to the conformal factor \check{F} of $(\check{X}, \check{\omega}, \check{\Omega})$ by $\check{F} = 2^{2n} F^{-1}$.*
- (2) *(X, ω, Ω) is supersymmetric of Type-A if and only if $(\check{X}, \check{\omega}, \check{\Omega})$ is supersymmetric of Type-B.*
- (3) *Let ρ_A be the Type-A RR flux source current of (X, ω, Ω) . Then its Fourier–Mukai transform equals to the Type-B RR flux source current $\check{\rho}_B$ of $(\check{X}, \check{\omega}, \check{\Omega})$ up to a constant multiple.*

Proof. Let $(\theta_1, \dots, \theta_n, r_1, \dots, r_n)$ be local semi-flat coordinates. The $(1, 1)$ form $\check{\omega}$ can be written as

$$\begin{aligned} \check{\omega} &= \frac{\mathbf{i}}{2} \sum_{i,j} \mu_{ij}(r) \mathrm{d}z_i \wedge \overline{\mathrm{d}z_j} \\ &= \sum_{i,j} \mu_{ij}(r) \mathrm{d}\check{\theta}_i \wedge \mathrm{d}r_j + \frac{\mathbf{i}}{2} \left(\sum_{i<j} (\mu_{ij} - \mu_{ji}) (\mathrm{d}\check{\theta}_i \wedge \mathrm{d}\check{\theta}_j + \mathrm{d}r_i \wedge \mathrm{d}r_j) \right). \end{aligned}$$

Since $\check{\omega}$ is real, $\mu_{ij} = \mu_{ji}$ are real-valued. Defining the one-forms

$$\mu_i := \sum_j \mu_{ij} \mathrm{d}r_j$$

on B , $\check{\omega}$ can also be written as

$$\check{\omega} = \sum_i \mathrm{d}\check{\theta}_i \wedge \mu_i.$$

Changing to real polarization,

$$\mathcal{P} \cdot \exp(2\check{\omega}) = \exp \left(\mathbf{i} \sum_{i,j} \mu_{ij}(r) \mathrm{d}\check{\theta}_i \wedge \mathrm{d}r_j \right).$$

Then

$$\begin{aligned} \Omega &= \mathrm{FT} \cdot \exp(2\check{\omega}) = \pi_* \cdot \exp \left(- \sum_i \mathrm{d}\check{\theta}_i \wedge \mathrm{d}\theta_i \right) \wedge \exp \left(\mathbf{i} \sum_{i,j} \mu_{ij}(r) \mathrm{d}\check{\theta}_i \wedge \mathrm{d}r_j \right) \\ &= \pi_* \cdot \exp \left(- \sum_i \mathrm{d}\check{\theta}_i \wedge (\mathrm{d}\theta_i + \mathbf{i}\mu_i) \right) \\ &= (-1)^{\frac{n(n-1)}{2}} (\mathrm{d}\theta_1 + \mathbf{i}\mu_1) \wedge \dots \wedge (\mathrm{d}\theta_n + \mathbf{i}\mu_n). \end{aligned} \tag{5.1}$$

Ω defines a complex structure J on X by

$$J \cdot \mathrm{d}\theta_i = -\mu_i, \quad J \cdot \mu_i = \mathrm{d}\theta_i$$

if and only if the one-forms μ_i for $i = 1, \dots, n$ are linearly independent, which is equivalent to the condition that ω is non-degenerate.

Moreover

$$\omega = \sum_{ij} d\theta_i \wedge dr_j = \sum_{ij} \frac{\eta_i + \bar{\eta}_i}{2} \wedge \frac{\mu_{ji}^{-1}(\eta_j - \bar{\eta}_j)}{2\mathbf{i}} = \frac{\mathbf{i}}{2} \sum_{ij} \mu_{ji}^{-1} \eta_i \wedge \bar{\eta}_j$$

has no $(2, 0)$ and $(0, 2)$ components because μ_{ji}^{-1} is symmetric in i, j , where μ^{-1} is the inverse matrix of μ_{ij} and $\eta_i := d\theta_i + \mathbf{i}\mu_i$ are $(1, 0)$ -forms with respect to Ω . Thus ω is a real $(1, 1)$ form with respect to J .

Finally

$$\begin{aligned} (\omega, J) \text{ is Hermitian} &\Leftrightarrow \mu_{ij} \text{ is positive definite} \\ &\Leftrightarrow (\mu^{-1})_{ij} \text{ is positive definite} \Leftrightarrow (\check{\omega}, \check{J}) \text{ is Hermitian.} \end{aligned}$$

This proves $(\check{X}, \check{\omega}, \check{\Omega})$ forms an $SU(n)$ structure if and only if (X, ω, Ω) forms an $SU(n)$ structure.

Recall that the conformal factor F for (X, ω, Ω) is defined by

$$\Omega \wedge \bar{\Omega} = \mathbf{i}^n \cdot F \cdot \frac{\omega^n}{n!}$$

and similarly for the conformal factor \check{F} of $(\check{X}, \check{\omega}, \check{\Omega})$. By direct computations, we have

$$\check{F} = \frac{2^{2n}}{F} = \frac{2^n(-1)^{\frac{n(n+1)}{2}}}{\det(\mu_{ij})}.$$

Now we consider the supersymmetry conditions. $d\check{\omega} = 0$ and $d(\pi_{\Lambda}^{n,0} \cdot \Omega|_U) = 0$ are automatic. It suffices to prove that $d(\pi_{\Lambda}^{1,n-1} \cdot \Omega|_U) = 0$ if and only if $d\check{\omega}^{n-1} = 0$. The k -th summand of

$$\mathcal{P} \cdot \exp 2\check{\omega} = \sum_{k=0}^n \frac{(2\mathcal{P} \cdot \check{\omega})^k}{k!}$$

has k torus-fiber directions ($d\check{\theta}$) and k base directions (dr). After Fourier–Mukai transform it has $n - k$ torus-fiber directions ($d\theta$) and k base directions (dr). Thus $\pi_{\Lambda}^{n-k,k} \cdot \Omega$ is the Fourier–Mukai transform of $(2\check{\omega})^k / (k)!$ (up to a constant multiple). By Theorem 4.5, d is transformed to $\bar{\partial}$ (up to a constant multiple). Thus $d(\pi_{\Lambda}^{1,n-1} \cdot \Omega) = 0$ if and only if $\bar{\partial}(\check{\omega}^{n-1}) = 0$. Since $\check{\omega}$ is real, $\partial(\check{\omega}^{n-1}) = \bar{\partial}(\check{\omega}^{n-1})$. Thus $d(\pi_{\Lambda}^{1,n-1} \cdot \Omega) = 0$ if and only if $d\check{\omega}^{n-1} = 0$.

Now consider the fluxes of the supersymmetric systems, which are defined by

$$\begin{aligned} \rho_A &= -\mathbf{i} d d^{\Lambda} (F \cdot (\pi_{\Lambda}^{n-1,1} \cdot \Omega + \pi_{\Lambda}^{0,n} \cdot \Omega)), \\ \check{\rho}_B &= 2\mathbf{i} \partial \bar{\partial} (\check{F}^{-1} \cdot \check{\omega}). \end{aligned}$$

From above $\pi_{\Lambda}^{n-1,1} \cdot \Omega$ is the Fourier–Mukai transform of $2\check{\omega}$, and $\check{F} = 2^{2n} F^{-1}$. The component $\pi_{\Lambda}^{0,n} \cdot \Omega$ is the transform of $\check{\omega}^n$, which contributes zero to $\check{\rho}_B$. Moreover by Theorem 4.5, $\frac{(-1)^n \mathbf{i}}{2} \cdot d$ is transformed to $\bar{\partial}$ and $\frac{(-1)^n \mathbf{i}}{2} \cdot d^{\Lambda}$ is transformed to ∂ . It follows that the Fourier transform of ρ_A is $2^{2n+2} \check{\rho}_B$. \square

6. Deformation Theory

Since Type IIA and IIB supersymmetric $SU(n)$ systems correspond to each other under the SYZ mirror transform, their deformations should also correspond to each other. The following cohomologies are keys to study their deformations:

Definition 6.1 ([BC65, Aep65]). Let \check{X} be a complex manifold. The Bott–Chern cohomology of \check{X} is defined as

$$H_{B.C.}^{p,q}(\check{X}) := \frac{\text{Ker}(d) \cap \Omega^{p,q}(\check{X})}{\text{Im}(\partial\bar{\partial}) \cap \Omega^{p,q}(\check{X})}$$

Definition 6.2 ([TY12a, TY12b]). Let X be a symplectic manifold. The Tseng–Yau symplectic cohomology of X is defined as

$$H_{d+d^\Lambda}^k(X) := \frac{\text{Ker}(d + d^\Lambda) \cap \Omega^k(X)}{\text{Im}(d d^\Lambda) \cap \Omega^k(X)}.$$

Indeed we have a more refined version for a given real polarization (U, Λ) on X .

Definition 6.3. Let X be a symplectic manifold with a real polarization (U, Λ) . Define

$$H_{d+d^\Lambda}^{(p,q)^\Lambda}(X) := \frac{\text{Ker}(d + d^\Lambda) \cap \Omega^{(p,q)^\Lambda}(X)}{\text{Im}(d d^\Lambda) \cap \Omega^{(p,q)^\Lambda}(X)}$$

where we recall that $\Omega^{(p,q)^\Lambda}(X)$ consists of forms whose restrictions to U consist of p Λ -directions and q Λ^\perp -directions.

In the semi-flat setting given in Sect. 4, we also have the torus-invariant counterparts

$$H_{B,B.C.}^{p,q}(\check{X}) := \frac{\text{Ker}(d) \cap \Omega_B^{p,q}(\check{X})}{\text{Im}(\partial\bar{\partial}) \cap \Omega_B^{p,q}(\check{X})} \tag{6.1}$$

and

$$H_{B,d+d^\Lambda}^{(p,q)^\Lambda}(X) := \frac{\text{Ker}(d + d^\Lambda) \cap \Omega_B^{(p,q)^\Lambda}(X)}{\text{Im}(d d^\Lambda) \cap \Omega_B^{(p,q)^\Lambda}(X)}. \tag{6.2}$$

For a Type IIB supersymmetric $SU(3)$ system $(\check{X}, \omega, \Omega)$, suppose that ω_t for $t \in (-\epsilon, \epsilon)$ is a deformation of the balanced metric ω (meaning $\omega_{t=0} = \omega$) such that $(\check{X}, \omega_t, \Omega)$ is still a Type IIB supersymmetric $SU(3)$ system, with a fixed conformal factor F and fixed type-B flux ρ_B . As argued in [TY, Section 2.1], the first order deformation $\delta(\omega^2) = \frac{\partial}{\partial t}|_{t=0} \omega_t^2$ belongs to $H_{B.C.}^{2,2}(\check{X}) \cap \mathcal{L} \cdot \mathcal{P}^{1,1}(\check{X})$, where $\mathcal{P}^{1,1}(\check{X})$ denotes the space of primitive $(1, 1)$ classes and \mathcal{L} denotes the Lefschetz action $\omega \wedge \cdot$. It easily generalizes to all dimensions:

Proposition 6.4. *Let $(\check{X}, \omega_t, \Omega)$ for $t \in (-\epsilon, \epsilon)$ be a one-parameter family of Type IIB supersymmetric $SU(n)$ systems with a fixed conformal factor. Then the infinitesimal deformation $\frac{\partial}{\partial t}|_{t=0} (\omega_t^{n-1})$ represent a class in*

$$H_{B.C.}^{n-1,n-1}(\check{X}) \cap \mathcal{L}^{n-2} \cdot \mathcal{P}^{1,1}(\check{X})_{B.C.}$$

Proof. The balanced condition $d(\omega_t^{n-1}) = 0$ implies that $d \frac{\partial}{\partial t} \Big|_{t=0} (\omega_t^{n-1}) = 0$, and hence $\frac{\partial}{\partial t} \Big|_{t=0} (\omega_t^{n-1})$ represents a class in $H_{B.C.}^{n-1, n-1}(\check{X})$. Taking $\frac{\partial}{\partial t} \Big|_{t=0}$ on

$$\check{\Omega} \wedge \bar{\check{\Omega}} = \mathbf{i}^n \check{F} \cdot \frac{\check{\omega}_t^n}{n!}$$

where \check{F} is the conformal factor, we have $\omega^{n-1} \wedge \frac{\partial}{\partial t} \Big|_{t=0} \omega_t = 0$, and hence $\frac{\partial}{\partial t} \Big|_{t=0} \omega_t$ is a primitive $(1, 1)$ form. Thus $\frac{\partial}{\partial t} \Big|_{t=0} (\omega_t^{n-1}) = (n-1)\omega^{n-2} \wedge \frac{\partial}{\partial t} \Big|_{t=0} (\omega_t)$ belongs to $\mathcal{L}^{n-2} \cdot \mathcal{P}^{1,1}(\check{X})_{B.C.}$. \square

Remark 6.5. Indeed as in [TY] we can say more: if we also fix the Type-B flux of $(\check{X}, \omega_t, \Omega)$, then the infinitesimal deformation $\frac{\partial}{\partial t} \Big|_{t=0} (\omega_t^{n-1})$ is actually harmonic with respect to the Bott–Chern cohomology.

Now consider a Type IIA supersymmetric $SU(n)$ system (X, ω, Ω) . Its deformation theory is more tricky than the $n = 3$ case because it depends on a real polarization.

Proposition 6.6. *Let (X, ω, Ω_t) be a one-parameter family of Type IIA supersymmetric $SU(n)$ systems with a fixed special real polarization (U, Λ) on X and a fixed conformal factor. Then $\pi_\Lambda^{1, n-1} \cdot (\frac{\partial}{\partial t} \Big|_{t=0} \Omega_t) \Big|_U$ represents a class in*

$$H_{d+d^\Lambda}^{(1, n-1)^\Lambda}(U) \cap [\pi_\Lambda^{1, n-1} \cdot \Omega^{(n-1, 1)}(U)]$$

where $\Omega^{(n-1, 1)}$ denotes the space of $(n-1, 1)$ forms (with respect to the almost complex structure induced from $\Omega = \Omega_{t=0}$).

Proof. $\frac{\partial}{\partial t} \Big|_{t=0} \Omega_t$ only has $(n, 0)$ and $(n-1, 1)$ components. Taking $\frac{\partial}{\partial t} \Big|_{t=0}$ on $\Omega_t \wedge \bar{\Omega}_t = \mathbf{i}^n F \cdot \frac{\omega_t^n}{n!}$ where F is the conformal factor, we have $(\frac{\partial}{\partial t} \Big|_{t=0} \Omega_t) \wedge \bar{\Omega} = 0$, and hence $\frac{\partial}{\partial t} \Big|_{t=0} \Omega_t$ has no $(n, 0)$ component, and hence belongs to $\Omega^{(n-1, 1)}(X)$. By the condition $d(\pi_\Lambda^{1, n-1} \cdot \Omega_t \Big|_U) = 0$, we have $d(\pi_\Lambda^{1, n-1} \cdot (\frac{\partial}{\partial t} \Big|_{t=0} \Omega_t)) = 0$. Moreover Ω_t is a primitive form as $\omega \wedge \Omega_t = 0$, and hence $\frac{\partial}{\partial t} \Big|_{t=0} \Omega_t$ is also primitive. In particular $d^\Lambda \cdot \frac{\partial}{\partial t} \Big|_{t=0} \Omega_t = 0$. Thus $\pi_\Lambda^{1, n-1} \cdot \frac{\partial}{\partial t} \Big|_{t=0} \Omega_t \Big|_U$ defines a class in $H_{d+d^\Lambda}^{(1, n-1)^\Lambda}(U)$. \square

From Sect. 5, we see that SYZ and Fourier–Mukai transform gives the mirror map from the Type IIA moduli space to the Type IIB moduli space of the mirror. Indeed the above cohomologies are also mirror to each other by Fourier–Mukai transform:

Theorem 6.7. *Let $(X, \omega) \rightarrow B$ be a Lagrangian torus bundle and (\check{X}, Ω) be its mirror. Fourier–Mukai transform gives an isomorphism*

$$H_{B, d+d^\Lambda}^{(n-p, q)^\Lambda}(X, \mathbb{C}) \cong H_{B, B.C.}^{p, q}(\check{X})$$

where Λ is the real polarization on X induced from the bundle structure.

Proof. Fourier–Mukai transform maps a T -invariant (p, q) form on \check{X} to a T -invariant form on X with $(n-p)$ fiber directions and q base directions. By Theorem 4.5, $\bar{\partial}$ and ∂ on \check{X} correspond to d and d^Λ on X respectively under Fourier–Mukai transform. Hence $d, \bar{\partial}\partial$ on \check{X} correspond to $d + d^\Lambda$ and $d d^\Lambda$ on X respectively. By Eqs. (6.1) and (6.2), statement follows. \square

7. Nilmanifolds

We describe an important example of a mirror pair of non-Kähler supersymmetric Type-A and Type-B systems constructed from nilmanifolds. We first describe the three-dimensional case, and extend the discussion to all dimensions.

7.1. Three dimensional case. The three-dimensional real Iwasawa manifold B is given by the quotient of the Heisenberg group, which consists of matrices of the form

$$\begin{pmatrix} 1 & r_1 & r_3 \\ 0 & 1 & r_2 \\ 0 & 0 & 1 \end{pmatrix}, r_1, r_2, r_3 \in \mathbb{R},$$

by the discrete subgroup Γ consisting of matrices of the same form with r_1, r_2, r_3 being integers.

Explicitly Γ acts on the Heisenberg group by affine transformations: for

$$\gamma = \begin{pmatrix} 1 & a & c \\ 0 & 1 & b \\ 0 & 0 & 1 \end{pmatrix} \in \Gamma$$

we have

$$\gamma \cdot \begin{pmatrix} r_1 \\ r_2 \\ r_3 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & a & 1 \end{pmatrix} \begin{pmatrix} r_1 \\ r_2 \\ r_3 \end{pmatrix} + \begin{pmatrix} a \\ b \\ c \end{pmatrix}.$$

Thus B is an affine manifold.

Now consider $X = T^*B/\Lambda^*$ and $\check{X} = TB/\Lambda$. \check{X} has a canonical complex structure, and its complex coordinates are given by $\zeta_i = \check{\theta}_i + \mathbf{i}r_i, i = 1, 2, 3$. It has a holomorphic volume form

$$\check{\Omega} = d\zeta_1 \wedge d\zeta_2 \wedge d\zeta_3.$$

X has a canonical symplectic form $\omega = \sum_{i=1}^3 d\theta_i \wedge dr_i$.

Take the Hermitian two-form

$$\begin{aligned} \check{\omega} &= \frac{\mathbf{i}}{2} (d\zeta_1 \wedge d\bar{\zeta}_1 + d\zeta_2 \wedge d\bar{\zeta}_2 + (d\zeta_3 - r_1 d\zeta_2) \wedge (d\bar{\zeta}_3 - r_1 d\bar{\zeta}_2)) \\ &= (d\check{\theta}_1 \wedge dr_1 + d\check{\theta}_2 \wedge dr_2 + (d\check{\theta}_3 - r_1 d\check{\theta}_2) \wedge (dr_3 - r_1 dr_2)) \end{aligned}$$

on \check{X} . Notice that $d\check{\omega} \neq 0$ while $d\check{\omega}^2 = 0$ by direct computation. Moreover,

$$\check{\omega}^3 = d\check{\theta}_1 \wedge dr_1 \wedge d\check{\theta}_2 \wedge dr_2 \wedge d\check{\theta}_3 \wedge dr_3$$

which is a constant multiple of $\check{\Omega} \wedge \bar{\check{\Omega}}$. Thus $(\check{X}, \check{\omega}, \check{\Omega})$ forms a type IIB supersymmetric system with a constant conformal factor.

The type-B flux source is

$$\rho_B = 2\mathbf{i} \partial\bar{\partial}\check{\omega} \sim dr_1 \wedge d\check{\theta}_1 \wedge dr_2 \wedge d\check{\theta}_2$$

up to some constant multiple. ρ_B is the Poincaré dual of the complex manifold defined by $r_1 = r_2 = \check{\theta}_1 = \check{\theta}_2 = 0$, which can also be written as $TC/(C \cap \Lambda)$ for $C = \{r_1 = r_2 = 0\} \subset B$.

Now take the Fourier–Mukai transform of $e^{2\check{\omega}}$. Write

$$\check{\omega} = \frac{\mathbf{i}}{2} \left(d\check{\zeta}_1 \wedge d\bar{\zeta}_1 + d\check{\zeta}_2 \wedge (d\bar{\zeta}_2 - r_1 d\bar{\zeta}_3 + r_1^2 d\bar{\zeta}_2) + d\check{\zeta}_3 \wedge (d\bar{\zeta}_3 - r_1 d\bar{\zeta}_2) \right).$$

Switching polarization (Eq. (4.2)) gives

$$\mathcal{P} \cdot \check{\omega} = \frac{\mathbf{i}}{2} \left(d\check{\theta}_1 \wedge d r_1 + d\check{\theta}_2 \wedge (d r_2 - r_1 d r_3 + r_1^2 d r_2) + d\check{\theta}_3 \wedge (d r_3 - r_1 d r_2) \right).$$

Then

$$e^{2\check{\omega}} e^{\sum_{i=1}^3 d\check{\theta}_i \wedge d\theta_i} = \exp(d\check{\theta}_1 \wedge (d\theta_1 + \mathbf{i} d r_1) + d\check{\theta}_2 \wedge (d\theta_2 + \mathbf{i}(d r_2 - r_1 d r_3 + r_1^2 d r_2)) + d\check{\theta}_3 \wedge (d\theta_3 + \mathbf{i}(d r_3 - r_1 d r_2))).$$

Thus the Fourier–Mukai transform is

$$\begin{aligned} \Omega &= (d\theta_1 + \mathbf{i} d r_1) \wedge (d\theta_2 + \mathbf{i}(d r_2 - r_1 d r_3 + r_1^2 d r_2)) \wedge (d\theta_3 + \mathbf{i}(d r_3 - r_1 d r_2)) \\ &= (d\theta_1 + \mathbf{i} d r_1) \wedge ((d\theta_2 + r_1 d\theta_3) + \mathbf{i} d r_2) \wedge (d\theta_3 + \mathbf{i}(d r_3 - r_1 d r_2)) \end{aligned}$$

on X . It is easy to verify that $d(\operatorname{Re} \Omega) = 0$ and $\Omega \wedge \bar{\Omega}$ equals to ω^3 up to a constant multiple. Thus (X, ω, Ω) is a Type IIA supersymmetric $SU(n)$ system with a constant conformal factor.

The type-A flux source is

$$\rho_A = d d^\Lambda (\operatorname{Im} \Omega) \sim d r_1 \wedge d r_2 \wedge d\theta_3$$

up to a constant multiple. ρ_A is the Poincaré dual of the Lagrangian submanifold defined by $r_1 = r_2 = \theta_3 = 0$, which can also be written as the conormal bundle $N^*C/(C \cap \Lambda^*)$, where $C = \{r_1 = r_2 = 0\} \subset B$ is as defined above. Note that the type-A flux current ρ_A of X and type-B flux current ρ_B of the mirror \check{X} correspond to each other by Fourier–Mukai transform.

7.2. General dimension. We may extend the above example to general dimensions to construct type II-A and type II-B supersymmetric $SU(n)$ systems which are mirror to each other. Consider the vector space V of upper unitriangular matrices $(r_{ij})_{i,j=1}^K$, that is, $r_{ij} = 0$ for $i > j$ and $r_{ii} = 1$ for all $i = 1, \dots, K$. Then we consider the lattice Γ of upper unitriangular matrices $(a_{ij})_{i,j=1}^K$ with integer entries, $a_{ij} = 0$ for $i > j$ and $a_{ii} = 1$ for all $i = 1, \dots, K$. Γ acts on V by left multiplication, and the real Iwasawa manifold B is the quotient V/Γ . Explicitly $a = (a_{ij})_{i < j} \in \Gamma$ acts on $r = (r_{ij})_{i < j} \in V$ by $a \cdot r = r'$, where

$$r'_{ik} = r_{ik} + \sum_{j=i+1}^{k-1} a_{ij} r_{jk} + a_{ik}$$

for all $i < k$. In particular when $k = i + 1$, $r'_{i,i+1} = r_{i,i+1} + a_{i,i+1}$ for all $i = 1, \dots, K - 1$.

B is an affine manifold. We have the following global one-forms which will be useful to construct the non-Kähler geometries:

Proposition 7.1. *Define inductively over $k - i \in \mathbb{N}$ the following one forms on V :*

$$e_{ik} := \mathbf{d} r_{ik} - \sum_{j=i+1}^{k-1} r_{ij} e_{jk}$$

and $e_{i,i+1} := \mathbf{d} r_{i,i+1}$ for all $i = 1, \dots, K - 1$. These one forms are invariant under the action of Γ and hence descend to be global one-forms on $B = V/\Gamma$.

Proof. We prove by induction over $k - i \in \mathbb{N}$. For $k - i = 1$, since $a = (a_{ij})_{i < j} \in \Gamma$ acts by mapping $r_{i,i+1}$ to $r_{i,i+1} + a_{i,i+1}$, it follows that $e_{i,i+1} = \mathbf{d} r_{i,i+1}$ is invariant under Γ . Now consider

$$e_{ik} = \mathbf{d} r_{ik} - \sum_{j=i+1}^{k-1} r_{ij} e_{jk}$$

which is sent to

$$\begin{aligned} & (\mathbf{d} r_{ik} + a_{i,i+1} \mathbf{d} r_{i+1,k} + \dots + a_{i,k-1} \mathbf{d} r_{k-1,k}) \\ & - \sum_{j=i+1}^{k-1} (r_{ij} + a_{i,i+1} r_{i+1,j} + \dots + a_{i,j-1} r_{j-1,j} + a_{ij}) e_{jk} \\ & = e_{ik} + \left(a_{i,i+1} \mathbf{d} r_{i+1,k} + \dots + a_{i,k-1} \mathbf{d} r_{k-1,k} \right. \\ & \quad \left. - \sum_{j=i+1}^{k-1} (a_{i,i+1} r_{i+1,j} + \dots + a_{i,j-1} r_{j-1,j} + a_{ij}) e_{jk} \right) \end{aligned}$$

under the action, because by inductive assumption e_{jk} is invariant for all $j = i + 1, \dots, k - 1$. Consider the second term in the last expression:

$$\begin{aligned} & a_{i,i+1} \mathbf{d} r_{i+1,k} + \dots + a_{i,k-1} \mathbf{d} r_{k-1,k} - \sum_{j=i+1}^{k-1} (a_{i,i+1} r_{i+1,j} + \dots + a_{i,j-1} r_{j-1,j} + a_{ij}) e_{jk} \\ & = \sum_{j=i+1}^{k-1} \left(a_{ij} \mathbf{d} r_{jk} - \left(a_{ij} + \sum_{l=i+1}^{j-1} a_{il} r_{lj} \right) e_{jk} \right) \\ & = \sum_{j=i+1}^{k-1} \left(a_{ij} \sum_{l=j+1}^{k-1} r_{jl} e_{lk} - \left(\sum_{l=i+1}^{j-1} a_{il} r_{lj} \right) e_{jk} \right) \\ & = \sum_{j=i+1}^{k-1} \sum_{l=j+1}^{k-1} a_{ij} r_{jl} e_{lk} - \sum_{j=i+1}^{k-1} \sum_{l=i+1}^{j-1} a_{il} r_{lj} e_{jk} \\ & = 0 \end{aligned}$$

where we have used the equality

$$dr_{jk} - e_{jk} = \sum_{l=j+1}^{k-1} r_{jl}e_{lk}$$

by definition of e_{jk} . Thus e_{ik} is invariant under the action. \square

Now consider $X = TB/\Lambda$, which is automatically a complex manifold. Suppose θ_{ij} are the fiber coordinates of TB corresponding to the coordinates r_{ij} on B for $i < j$. Then θ_{ij} transforms in the similar way under the action of $a = (a_{ij})_{i < j} \in \Gamma$:

$$\theta'_{ik} = \theta_{ik} + \sum_{j=i+1}^{k-1} a_{ij}\theta_{jk}.$$

The global one-forms on B in Proposition 7.1 pulls back to be global one-forms on X . We also have the following global one-forms on X :

$$f_{ik} := d\theta_{ik} - \sum_{j=i+1}^{k-1} r_{ij}f_{jk}$$

defined inductively on $k - i \in \mathbb{N}$ as in the definition of e_{ik} 's.

The holomorphic volume form on X is defined as

$$\Omega = \bigwedge_{i < j} dz_{ij}$$

where $z_{ij} = \theta_{ij} + \mathbf{i}r_{ij}$. It automatically satisfies Eq. (2.13). (We fix an order, say dictionary order for $\{(i, j) : i < j\}$, to define the wedge product in the above expression.) Take

$$\omega := \sum_{i < j} e_{ij} \wedge f_{ij}$$

Proposition 7.2. ω is a Hermitian $(1, 1)$ -form on X . Moreover, $\Omega \wedge \bar{\Omega}$ equals to ω^n up to some constant multiple, that is, the conformal factor is a constant.

Proof. Since

$$\bigwedge_{i < j} e_{ij} = \bigwedge_{i < j} dr_{ij}$$

and

$$\bigwedge_{i < j} f_{ij} = \bigwedge_{i < j} d\theta_{ij},$$

it easily follows that $\Omega \wedge \bar{\Omega}$ equals to ω^n up to some constant multiple. In particular, ω is non-degenerate.

To see that ω is a $(1, 1)$ -form, it suffices to prove that $e_{ij} \wedge f_{kl} + e_{kl} \wedge f_{ij}$ is a $(1, 1)$ -form, and we will prove it using induction on $(j - i, l - k)$. This is true when $j - i = l - k = 1$

since in such a case $e_{ij} = d r_{ij}$ and $f_{kl} = d \theta_{kl}$, and $d r_{ij} \wedge d \theta_{kl} + d r_{kl} + d \theta_{ij}$ is a $(1, 1)$ -form. Now consider

$$\begin{aligned} & e_{ij} \wedge f_{kl} + e_{kl} \wedge f_{ij} \\ &= \left(d r_{ij} - \sum_{p=i+1}^{j-1} r_{ip} e_{pj} \right) \wedge \left(d \theta_{kl} - \sum_{q=k+1}^{l-1} r_{kq} f_{ql} \right) \\ &+ \left(d r_{kl} - \sum_{p=k+1}^{l-1} r_{kp} e_{pl} \right) \wedge \left(d \theta_{ij} - \sum_{q=i+1}^{j-1} r_{iq} f_{qj} \right). \end{aligned}$$

We already know that $d r_{ij} \wedge d \theta_{kl} + d r_{kl} \wedge d \theta_{ij}$ is a $(1, 1)$ -form. Moreover,

$$d r_{ij} \wedge \left(\sum_{q=k+1}^{l-1} r_{kq} f_{ql} \right) + \left(\sum_{p=k+1}^{l-1} r_{kp} e_{pl} \right) \wedge d \theta_{ij}$$

and

$$d r_{kl} \wedge \left(\sum_{q=i+1}^{j-1} r_{iq} f_{qj} \right) + \left(\sum_{p=i+1}^{j-1} r_{ip} e_{pj} \right) \wedge d \theta_{kl}$$

are $(1, 1)$ -forms, because they are linear combinations of $d r_{ab} \wedge d \theta_{cd} + d r_{cd} \wedge d \theta_{ab}$'s. Finally by inductive assumption, $e_{pj} \wedge f_{ql} + e_{ql} \wedge f_{pj}$'s are also $(1, 1)$ -forms for $j - p < j - i, l - q < l - k$.

To prove that ω is a Hermitian form, it suffices to see that $\omega(\frac{\partial}{\partial r_{ij}}, \frac{\partial}{\partial \theta_{ij}}) > 0$ for all $i < j$. Consider

$$e_{cd} \wedge f_{cd} = \left(d r_{cd} - \sum_{p=c+1}^{d-1} r_{cp} e_{pd} \right) \wedge \left(d \theta_{cd} - \sum_{q=c+1}^{d-1} r_{cq} f_{qd} \right).$$

Note that $(e_{ij} \wedge f_{ij})(\frac{\partial}{\partial r_{ij}}, \frac{\partial}{\partial \theta_{ij}}) = 1$, and all other terms of the form $(e_{cd} \wedge f_{cd})(\frac{\partial}{\partial r_{ij}}, \frac{\partial}{\partial \theta_{ij}})$ contribute by squares of a function in r_{ab} 's which are non-negative. Thus ω is a Hermitian form. \square

Thus Eq. (2.11) is satisfied with the conformal factor f being a constant.

We will need the following lemma for the behavior of e_{ij} and f_{ij} upon differentiation:

Lemma 7.3.

$$d e_{ij} = - \sum_{k=i+1}^{j-1} e_{ik} \wedge e_{kj}$$

and

$$d f_{ij} = - \sum_{k=i+1}^{j-1} e_{ik} \wedge f_{kj}$$

for all $i < j$.

Proof. We prove by induction on $j - i \in \mathbb{N}$. When $j - i = 1$, $d e_{ij} = d f_{ij} = 0$. Recall that

$$e_{ij} = d r_{ij} - \sum_{l=i+1}^{j-1} r_{il} e_{lj}.$$

Upon differentiation,

$$\begin{aligned} d e_{ij} &= - \sum_{l=i+1}^{j-1} d r_{il} \wedge e_{lj} - \sum_{p=i+1}^{j-1} r_{ip} d e_{pj} \\ &= - \sum_{l=i+1}^{j-1} d r_{il} \wedge e_{lj} + \sum_{p=i+1}^{j-1} r_{ip} \left(\sum_{l=p+1}^{j-1} e_{pl} \wedge e_{lj} \right) \\ &= - \sum_{l=i+1}^{j-1} d r_{il} \wedge e_{lj} + \sum_{l=i+1}^{j-1} \sum_{p=i+1}^{l-1} r_{ip} e_{pl} \wedge e_{lj} \\ &= - \sum_{l=i+1}^{j-1} e_{il} \wedge e_{lj} \end{aligned}$$

where the second line follows from inductive assumption applied on $d e_{pj}$ for $j - p < j - i$. Similarly,

$$f_{ij} = d \theta_{ij} - \sum_{l=i+1}^{j-1} r_{il} f_{lj}.$$

Upon differentiation,

$$\begin{aligned} d f_{ij} &= - \sum_{l=i+1}^{j-1} d r_{il} \wedge f_{lj} - \sum_{p=i+1}^{j-1} r_{ip} d f_{pj} \\ &= - \sum_{l=i+1}^{j-1} d r_{il} \wedge f_{lj} + \sum_{p=i+1}^{j-1} r_{ip} \left(\sum_{l=p+1}^{j-1} e_{pl} \wedge f_{lj} \right) \\ &= - \sum_{l=i+1}^{j-1} d r_{il} \wedge f_{lj} + \sum_{l=i+1}^{j-1} \sum_{p=i+1}^{l-1} r_{ip} e_{pl} \wedge f_{lj} \\ &= - \sum_{l=i+1}^{j-1} e_{il} \wedge f_{lj}. \end{aligned}$$

This proves the required formulas. \square

We have

Proposition 7.4.

$$d(\omega^{n-1}) = 0$$

but

$$d(\omega^{n-2}) \neq 0$$

where $n = K(K - 1)/2$ is the (complex) dimension of X . Thus ω defines a balanced metric on X .

Proof.

$$\begin{aligned} d\omega &= d e_{ij} \wedge f_{ij} - e_{ij} \wedge d f_{ij} \\ &= - \sum_{k=i+1}^{j-1} e_{ik} \wedge e_{kj} \wedge f_{ij} - \sum_{l=i+1}^{j-1} e_{ij} \wedge e_{il} \wedge f_{lj}. \end{aligned}$$

All terms in the above expression are linearly independent. Since each term of ω^{n-2} contains all but two pairs of (e_{**}, f_{**}) , $\omega^{n-2} \wedge (e_{ik} \wedge e_{kj} \wedge f_{ij})$ must be zero since the index sets $\{i, k\}, \{k, j\}, \{i, j\}$ are pairwise distinct. Similarly $\omega^{n-2} \wedge (e_{ij} \wedge e_{il} \wedge f_{lj}) = 0$. Thus

$$d(\omega^{n-1}) = (n - 1)\omega^{n-2} \wedge d\omega = 0.$$

On the other hand, each term of ω^{n-3} contains all but three pairs of (e_{**}, f_{**}) . Thus for each $e_{ik} \wedge e_{kj} \wedge f_{ij}$, there exists a unique term in ω^{n-3} such that their product is non-zero. This also holds for $e_{ij} \wedge e_{il} \wedge f_{lj}$. Thus

$$d(\omega^{n-2}) = (n - 2)\omega^{n-3} \wedge d\omega \neq 0.$$

□

Thus we see that Eq. (2.14) is satisfied. The RR flux source ρ_B is $2i \partial \bar{\partial} \omega$, which is a closed four-form. Then we obtain a Type- B supersymmetric $SU(n)$ structure (up to a constant multiple in the first equation):

$$\begin{aligned} \Omega \wedge \bar{\Omega} &= \omega^n, \\ d(\omega^{n-1}) &= 0, \\ 2i \partial \bar{\partial} \omega &= \rho_B, \\ d\Omega &= 0. \end{aligned}$$

The mirror of this system is a Type- A supersymmetric $SU(n)$ structure defined on the dual torus bundle $\check{X} = T^*B/\Lambda^*$. Let $\check{\theta}_1, \dots, \check{\theta}_n$ be the fiber coordinates on T^*B corresponding to the coordinates r_1, \dots, r_n on B . Then $r_1, \dots, r_n, \check{\theta}_1, \dots, \check{\theta}_n$ descends to be local coordinates on \check{X} . \check{X} is equipped with a canonical symplectic form

$$\check{\omega} = d\check{\theta}_1 \wedge dr_1 + \dots + d\check{\theta}_n \wedge dr_n.$$

We have the global one-forms e_{ij} for $i < j$ on B defined inductively by Eq. (7.1), which are pulled back to be global one-forms on \check{X} . Also recall the global one-forms f_{ij} defined on X for $i < j$. The dual basis $\{\check{f}_{ij} : i < j\}$ gives global one-forms on \check{X} . The explicit expressions of \check{f}_{ij} s are given by the following proposition:

Proposition 7.5. Define \check{f}_{jk} inductively on $j \in \mathbb{N}$ by

$$\check{f}_{jk} := d\check{\theta}_{jk} + \sum_{i=1}^{j-1} r_{ij} \check{f}_{ik} \tag{7.1}$$

and $\check{f}_{1k} = d\check{\theta}_{1k}$ for all $k = 1, \dots, K$. Then we have $(f_{ij}, \check{f}_{ab}) = \delta_{ia}\delta_{jb}$, that is, $\{\check{f}_{ij} : i < j\}$ is a dual basis to $\{f_{ij} : i < j\}$.

Proof. We prove by induction on $j \in \mathbb{N}$. For $j = 1$, $\check{f}_{1k} = d\check{\theta}_{1k}$. Thus

$$\begin{aligned} (\check{f}_{1k}, f_{ab}) &= (d\check{\theta}_{1k}, d\theta_{ab}) - \sum_{c=a+1}^{b-1} r_{ac} (d\check{\theta}_{1k}, f_{cb}) \\ &= \delta_{1a}\delta_{kb} \end{aligned}$$

since f_{cb} is a linear combinations of $d\theta_{pb}$ for $p > c > 1$.

In general

$$\begin{aligned} (\check{f}_{jk}, f_{ab}) &= (d\check{\theta}_{jk}, f_{ab}) + \sum_{i=1}^{j-1} r_{ij} (\check{f}_{ik}, f_{ab}) \\ &= (d\check{\theta}_{jk}, d\theta_{ab}) - \sum_{c=a+1}^{b-1} r_{ac} (d\check{\theta}_{jk}, f_{cb}) + \sum_{i=1}^{j-1} r_{ij} (\check{f}_{ik}, f_{ab}). \end{aligned}$$

When $(j, k) = (a, b)$, the first term is 1; the second term is zero because f_{cb} contains no $d\theta_{jk}$ term; the third term is zero since $i < j = a$. Thus $(\check{f}_{jk}, f_{jk}) = 1$.

Now consider the case $(j, k) \neq (a, b)$. The first term is always zero. If $b \neq k$, the second term is zero automatically because f_{cb} only consists of terms $d\theta_{pb}$, and the third term is also zero by induction hypothesis on $\check{f}_{ik}, i < j$. When $b = k$, we further divides into two cases: $j < a$ and $j > a$. When $j < a$, the second and third terms are zero because only $d\theta_{pb}$ with $p > a > j$ appear in f_{cb} and f_{ab} . When $j > a$, the second term equals to $-r_{aj}$ and by induction hypothesis on \check{f}_{ik} for $i < j$ the third term equals to r_{aj} , and hence they cancel each other. This finishes the proof by induction. \square

Using these global one-forms, the complex volume form on \check{X} is defined as

$$\check{\Omega} = \bigwedge_{j < k} (\check{f}_{jk} + \mathbf{i}e_{jk})$$

where again we fix the dictionary order on $\{(j, k) : j < k\}$ to define the above product. It is then a direct verification that $(\check{X}, \check{\omega}, \check{\Omega})$ satisfies the following system (up to a constant multiple in the first equation)

$$\begin{aligned} \check{\Omega} \wedge \check{\check{\Omega}} &= \check{\omega}^n, \\ d((\pi_{\Lambda}^{n,0} \oplus \pi_{\Lambda}^{1,n-1}) \cdot \check{\check{\Omega}}) &= 0, \\ -\mathbf{i}d d^{\Lambda} \cdot (\pi_{\Lambda}^{n-1,1} \cdot \check{\check{\Omega}} + \pi_{\Lambda}^{0,n} \cdot \check{\check{\Omega}}) &= \check{\rho}_A, \\ d\check{\omega} &= 0. \end{aligned}$$

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