# PATH COMPLEXES AND THEIR HOMOLOGIES 

A. A. Grigor'yan, Yong Lin, Yu. V. Muranov, and Shing-Tung Yau


#### Abstract

We introduce the notions of a path complex and its homologies. Particular cases of path homologies are simplicial homologies and digraph homologies. We state and prove some properties of path homologies, in particular, the Künneth formulas for Cartesian product and join, which happen to be true at the level of chain complexes.


## 1. Introduction

The subject of this paper is the notion of a path complex, which unifies and generalizes the notions of a simplicial complex and a digraph (=directed graph). In short, a path complex $P$ on a finite set $V$ is a collection of paths (=sequences of points) on $V$ such that if a path $v$ belongs to $P$, then a truncated path, which is obtained from $v$ by removing either the first or the last point, is also in $P$. Given a path complex $P$, all the paths in $P$ are called allowed.

Any simplicial complex $S$ determines naturally a path complex by associating with any simplex from $S$ the sequence of its vertices (see Sec. 3 for details).

However, the main motivation for considering path complexes comes from digraphs. A digraph $G$ is a pair $(V, E)$, where $V$ is any set and $E$ is a binary relation on $V$, i.e., $E$ is a subset of $V \times V$. If $(a, b) \in E$, then the pair $(a, b)$ is called a directed edge or arrow; this fact is also denoted by $a \rightarrow b$. Any digraph naturally gives rise to a path complex where allowed paths are those that go along arrows of the digraph.

One of our key observations is that any path complex $P$ allows one to define a chain complex with an appropriate boundary operator that leads to the notion of homology groups of $P$. We refer to this notion as a path homology.

In the case where $P$ arises from a simplicial complex $S$, the path homology of $P$ coincides with the simplicial homology of $S$. If $P$ arises from a digraph $G$, then we obtain a new notion: the path homology of a digraph. Although most of the results are presented in this paper for arbitrary path complexes, we always have in mind applications for digraphs. On the other hand, the notion of a path complex provides an alternative viewpoint for the classical results about simplicial complexes.

There has been a number of attempts to define the notion of (co)homology for graphs. At a trivial level, any graph can be regarded as a one-dimensional simplicial complex, so that its simplicial homologies are defined. However, all homology groups in dimension 2 and higher are trivial, which makes this approach uninteresting.

Another way to make a graph into a simplicial complex is to consider all its cliques (=complete subgraphs) as simplexes of the corresponding dimensions (cf. [4,15]). Then higher dimensional homologies may be nontrivial, but in this approach the notion of graph loses its identity and becomes a particular case of the notion of a simplicial complex. Besides, some desirable functorial properties of such homologies fail; for example, the Künneth formula is not true for the Cartesian product of graphs (for example, the Cartesian product of two 4 -cycles has trivial $H_{2}$ whereas $H_{1}$ of 4 -cycle is nontrivial).

Yet another approach to homologies of digraphs can be realized via Hochschild homology. Indeed, allowed paths on a digraph have a natural operation of product, which allows to define the notion of

Translated from Fundamentalnaya i Prikladnaya Matematika, Vol. 21, No. 5, pp. 79-128, 2016.
a path algebra of a digraph. The Hochschild homology of the path algebra is a natural object to consider. However, it was shown in [14] that Hochschild homologies of order $\geq 2$ are trivial, which makes this approach not so attractive.

In singular homology theories of graphs one uses predefined "small" graphs as basic cells and defines singular chains as formal sums of the maps of the basic cell into the graph (see, for example, [15, 18]). However, simple examples show that the homology groups obtained in this way, depend essentially on the choice of the basic cells. Moreover, such homologies are extremely difficult to compute, even for small graphs, and the functorial properties are not known at all.

The path homologies of digraphs that we present in this paper have the following advantages in comparison with the previously studied notions of graph homologies.
(1) The path homologies of all dimensions can be nontrivial; even for planar graphs the path homologies can be nontrivial in dimension 2. Also, the chain complex associated with a path complex has a richer structure than simplicial chain complexes. It contains not only cliques but also binary hypercubes and other interesting subgraphs, some of them are reminiscent of polyhedra.
(2) The path homologies are easy to compute. For small digraphs their path homologies can be computed by hand, either by definition or by using simple properties. For larger digraphs it can be done using any software package containing operations with matrices, in particular, computation of the rank of a matrix.
(3) The path homology theory is compatible with the homotopy theory of digraphs. The latter was introduced by the authors in [9] (a homotopy theory for undirected graphs was developed earlier in $[1,2]$ ), where they proved that the path homologies of digraphs are invariant with respect to homotopy and that the abelization of the fundamental group is isomorphic to the one-dimensional homology group.
(4) Path homologies have good functorial properties with respect to graph-theoretical operations, for example, morphisms of digraphs induce homomorphisms of path homologies. Also, the homologies of the Cartesian product of digraphs (as well as of the join) satisfy the Künneth formula (Theorems 5.5 and 6.6 of the present paper).
(5) The path homology theory is dual to the cohomology theory of digraphs that was introduced by Dimakis and Müller-Hoissen [5,6] and was further developed in [12]. The latter theory is based on a classification of [3] of exterior derivations on algebras, and the coboundary operator arises naturally as an exterior derivative on the algebra of functions on the vertex set of the digraph. However, in the present paper we do not discuss cohomologies.

We feel that the notion of path homologies (and the dual notion of cohomologies) has a rich mathematical content and hope that it will become a useful tool in various areas of pure and applied mathematics. For example, this notion was employed in [11] to give a new elementary proof of a theorem of Gerstenhaber and Schack [7] that gives a representation of simplicial homology as a Hochschild homology. A link between path homologies of digraphs and cubical homologies was revealed in [10]. Homology and homotopy of digraphs may become use in some graph coloring problems; a simple example of this type has appeared in [9]. On the other hand, it is conceivable that the notion of path homologies of digraphs can be used in practical applications such as coverage verification in sensor networks (cf. [17]), and many others.

Let us briefly describe the structure of the paper and the main results. In Sec. 2 we introduce the notion of a boundary operator on paths on a finite set $V$. In Sec. 3 we define the notions of a path complex, a $\partial$-invariant path (an element of a chain complex), and the path homologies.

In Sec. 4, we give some examples of digraphs and $\partial$-invariant paths there. We state some basic results about path homologies of digraphs, which allow to compute homology groups of simple digraphs (the proofs can be found in [8]).

In Sec. 5, we introduce the operation join of two path complexes and prove the Künneth formula for it (Theorem 5.5). Particular cases of join are operation of taking a cone and suspension of a digraph that behave homologically in the same way as those in the classical algebraic topology.

In Sec. 6, we introduce the notions of cross product of paths and Cartesian product of path complexes. The latter matches the notion of the Cartesian product of digraphs. We state and prove the Künneth formula for Cartesian product (Theorem 6.6) and give some examples.

Most difficult and interesting results of this paper are Theorems 5.5 and 6.6. In the setting digraphs these theorem were proved in [13], while in the present paper we prove them in a more general setting of path complexes.

## 2. Paths on a Finite Set

Let $V$ be an arbitrary nonempty finite set whose elements will be called vertices. For any nonnegative integer $p$, an elementary $p$-path on a set $V$ is any sequence $\left\{i_{k}\right\}_{k=0}^{p}$ of $p+1$ vertices of $V$ (a priori the vertices in the path do not have to be distinct). For $p=-1$, an elementary $p$-path is an empty set $\varnothing$. The $p$-path $\left\{i_{k}\right\}_{k=0}^{p}$ will also be denoted simply by $i_{0} \ldots i_{p}$, without delimiters between the vertices.
2.1. Boundary Operator. Fix a field $\mathbb{K}$ and consider the $\mathbb{K}$-linear space $\Lambda_{p}=\Lambda_{p}(V)$ that consists of all formal linear combinations of all elementary $p$-paths with coefficients from $\mathbb{K}$. The elements of $\Lambda_{p}$ are called $p$-paths on $V$. An elementary $p$-path $i_{0} \ldots i_{p}$ as an element of $\Lambda_{p}$ will be denoted by $e_{i_{0} \ldots i_{p}}$. The empty set as an element of $\Lambda_{-1}$ will be denoted by $e$.

By definition, the family $\left\{e_{i_{0} \ldots i_{p}}: i_{0}, \ldots, i_{p} \in V\right\}$ is a basis in $\Lambda_{p}$, and any $p$-path $v \in \Lambda_{p}$ has a unique representation in the form

$$
\begin{equation*}
v=\sum_{i_{0}, \ldots, i_{p} \in V} v^{i_{0} \ldots i_{p}} e_{i_{0} \ldots i_{p}} \tag{2.1}
\end{equation*}
$$

where $v^{i_{0} \ldots i_{p}} \in \mathbb{K}$. For example, $\Lambda_{0}$ consists of all linear combinations of $e_{i}$, where $i \in V, \Lambda_{1}$ consists of all linear combinations of $e_{i j}$, where $i, j \in V$, etc. Note that $\Lambda_{-1}$ consists of all multiples of $e$ so that $\Lambda_{-1} \cong \mathbb{K}$.

For any $p \geq 0$, define the boundary operator $\partial: \Lambda_{p} \rightarrow \Lambda_{p-1}$ as a linear operator that acts on elementary paths by

$$
\begin{equation*}
\partial e_{i_{0} \ldots i_{p}}=\sum_{q=0}^{p}(-1)^{q} e_{i_{0} \ldots \hat{\imath}_{q} \ldots i_{p}}, \tag{2.2}
\end{equation*}
$$

where the hat $\hat{\imath}_{q}$ means omission of the index $i_{q}$. For example, we have

$$
\begin{equation*}
\partial e_{i}=e, \quad \partial e_{i j}=e_{j}-e_{i}, \quad \partial e_{i j k}=e_{j k}-e_{i k}+e_{i j} \tag{2.3}
\end{equation*}
$$

It follows that, for any $v \in \Lambda_{p}$,

$$
\begin{equation*}
(\partial v)^{j_{0} \ldots j_{p-1}}=\sum_{k \in V} \sum_{q=0}^{p}(-1)^{q} v^{j_{0} \ldots j_{q-1} k j_{q} \ldots j_{p-1}} \tag{2.4}
\end{equation*}
$$

For example, for any $u \in \Lambda_{0}$ and $v \in \Lambda_{1}$ we have

$$
\partial u=\sum_{k \in V} u^{k} \text { and }(\partial v)^{i}=\sum_{k \in V}\left(v^{k i}-v^{i k}\right) .
$$

Set also $\Lambda_{-2}=\{0\}$ and define $\partial: \Lambda_{-1} \rightarrow \Lambda_{-2}$ to be zero.
Lemma 2.1. We have $\partial^{2}=0$. Hence, $\Lambda_{*}=\left\{\Lambda_{p}\right\}$ is a chain complex.

Proof. The operator $\partial^{2}$ acts from $\Lambda_{p}$ to $\Lambda_{p-2}$, so that the identity $\partial^{2}=0$ makes sense for all $p \geq 0$. In the case $p=0$, the identity $\partial^{2}=0$ is trivial. For $p \geq 1$, we have by (2.2)

$$
\begin{aligned}
\partial^{2} e_{i_{0} \ldots i_{p}}=\sum_{q=0}^{p}(-1)^{q} \partial e_{i_{0} \ldots \hat{\imath}_{q} \ldots i_{p}}=\sum_{q=0}^{p}(-1)^{q} & \left(\sum_{r=0}^{q-1}(-1)^{r} e_{i_{0} \ldots \hat{\imath}_{r} \ldots \hat{\imath}_{q} \ldots i_{p}}+\sum_{r=q+1}^{p}(-1)^{r-1} e_{i_{0} \ldots \hat{\imath}_{q} \ldots \hat{\imath}_{r} \ldots i_{p}}\right) \\
& =\sum_{0 \leq r<q \leq p}(-1)^{q+r} e_{i_{0} \ldots \hat{r}_{r} \ldots \hat{\imath}_{q} \ldots i_{p}}-\sum_{0 \leq q<r \leq p}(-1)^{q+r} e_{i_{0} \ldots \hat{\imath}_{q} \ldots \hat{\imath}_{r} \ldots i_{p}} .
\end{aligned}
$$

After switching $q$ and $r$ in the last sum, we see that the two sums cancel out, whence $\partial^{2} e_{i_{0} \ldots i_{p}}=0$. This implies that $\partial^{2} v=0$ for all $v \in \Lambda_{p}$.
2.2. Join of Paths. For all $p, q \geq-1$ and for any two paths $u \in \Lambda_{p}$ and $v \in \Lambda_{q}$ define their join $u v \in \Lambda_{p+q+1}$ as follows:

$$
\begin{equation*}
(u v)^{i_{0} \ldots i_{p} j_{0} \ldots j_{q}}=u^{i_{0} \ldots i_{p}} v^{j_{0} \ldots j_{q}} . \tag{2.5}
\end{equation*}
$$

Clearly, join of paths is a bilinear operation that satisfies the associative law (but is not commutative). It follows from (2.5) that

$$
\begin{equation*}
e_{i_{0} \ldots i_{p}} e_{j_{0} \ldots j_{q}}=e_{i_{0} \ldots i_{p} j_{0} \ldots j_{q}} . \tag{2.6}
\end{equation*}
$$

If $p=-2$ and $q \geq-1$, then set $u v=0 \in \Lambda_{q-1}$. A similar rule applies if $q=-2$ and $p \geq-1$.
Lemma 2.2 (product rule). For all $p, q \geq-1$ and $u \in \Lambda_{p}, v \in \Lambda_{q}$, we have

$$
\begin{equation*}
\partial(u v)=(\partial u) v+(-1)^{p+1} u \partial v . \tag{2.7}
\end{equation*}
$$

Proof. It suffices to prove (2.7) for $u=e_{i_{0} \ldots i_{p}}$ and $v=e_{j_{0} \ldots j_{q}}$. We have

$$
\begin{array}{r}
\partial(u v)=\partial e_{i_{0} \ldots i_{p} j_{0} \ldots j_{q}}=e_{i_{1} \ldots i_{p} j_{0} \ldots j_{q}}-e_{i_{0} i_{2} \ldots i_{p} j_{0} \ldots j_{q}}+\cdots+(-1)^{p+1}\left(e_{i_{0} \ldots i_{p} j_{1} \ldots j_{q}}-e_{i_{0} \ldots i_{p} j_{0} j_{2} \ldots j_{q}}+\ldots\right) \\
\\
=\left(\partial e_{i_{0} \ldots i_{p}}\right) e_{j_{0} \ldots j_{q}}+(-1)^{p+1} e_{i_{0} \ldots i_{p}} \partial e_{j_{0} \ldots j_{q}},
\end{array}
$$

whence (2.7) follows.
2.3. Regular Paths. We say that an elementary path $i_{0} \ldots i_{p}$ is regular if $i_{k-1} \neq i_{k}$ for all $k=1, \ldots, p$, and nonregular otherwise. For example, a 2-path iij is nonregular, while a 2 -path $i j i$ is regular provided $i \neq j$.

For any $p \geq-1$, consider the following subspace of $\Lambda_{p}$ spanned by the regular elementary paths:

$$
\mathcal{R}_{p}=\mathcal{R}_{p}(V):=\operatorname{span}\left\{e_{i_{0} \ldots i_{p}}: i_{0} \ldots i_{p} \text { is regular }\right\} .
$$

The elements of $\mathcal{R}_{p}$ are called regular $p$-paths.
We would like to consider the operator $\partial$ on the spaces $\mathcal{R}_{p}$. However, $\partial$ is not invariant on the family $\left\{\mathcal{R}_{p}\right\}$. For example, $e_{i j i} \in \mathcal{R}_{2}$ for $i \neq j$ while

$$
\partial e_{i j i}=e_{j i}-e_{i i}+e_{i j} \notin \mathcal{R}_{1}
$$

as it has a nonregular term $e_{i i}$. The same applies to the notion of join of paths: the join of two regular paths does not have to be regular, for example, $e_{i} e_{i}=e_{i i}$.

However, it is easy to show that $\partial$ is invariant on the complementary spaces $\mathcal{N}_{p}$ spanned by nonregular $p$-paths, which allows us to extend $\partial$ to the quotient spaces $\Lambda_{p} / \mathcal{N}_{p}$. Then we pull this $\partial$ back to $\mathcal{R}_{p}$ using $\mathcal{R}_{p} \cong \Lambda_{p} / \mathcal{N}_{p}$. The operator $\partial: \mathcal{R}_{p} \rightarrow \mathcal{R}_{p-1}$ defined in this way is called the regular boundary operator. The formula (2.2) remains true for the regular $\partial$ except that in this case all nonregular terms on the right-hand side should be treated as zero. For example, we have for the regular operator $\partial$

$$
\partial e_{i j i}=e_{j i}-e_{i i}+e_{i j}=e_{j i}+e_{i j} \in \mathcal{R}_{1}
$$

provided $i \neq j$.
Similarly one defines the regular join, using the fact that the join of an element of $\mathcal{N}_{p}$ with any element of $\Lambda_{q}$ is in $\mathcal{N}_{p+q+1}$ (see [8] for details). This allows us to define join on the quotients $\Lambda_{p} / \mathcal{N}_{p}$ and then pull
back to $\mathcal{R}_{p}$. The formula (2.6) remains true for regular join provided we treat a nonregular path in the right-hand side as zero. For example, for the regular join we have $e_{i j} e_{j i}=e_{i j j i}=0$.

It follows from the above constructions that the regular versions of $\partial$ and join also satisfy $\partial^{2}=0$ and the product rule (2.7), for all $u \in \mathcal{R}_{p}$ and $v \in \mathcal{R}_{q}$. In particular, $\mathcal{R}_{*}=\left\{\mathcal{R}_{p}\right\}$ is a chain complex.

Let $V$ and $V^{\prime}$ be two finite sets. Any map $f: V \rightarrow V^{\prime}$ induces the map

$$
f_{*}: \Lambda_{p}(V) \rightarrow \Lambda_{p}\left(V^{\prime}\right)
$$

by the rule

$$
f_{*}\left(e_{i_{0} \ldots i_{p}}\right)=e_{f\left(i_{0}\right) \ldots f\left(i_{p}\right)} .
$$

The map $f_{*}$ evidently commutes with $\partial$ and, hence, is a morphism $\Lambda_{*}(V) \rightarrow \Lambda_{*}\left(V^{\prime}\right)$ of chain complexes. Since $f_{*}$ maps nonregular paths to nonregular, it induces a morphism $\mathcal{R}_{*}(V) \rightarrow \mathcal{R}_{*}\left(V^{\prime}\right)$ of chain complexes.

## 3. Path Complexes

### 3.1. The Notion of a Path Complex.

Definition 3.1. A path complex over a set $V$ is a nonempty collection $P$ of elementary paths on $V$ with the following property:

$$
\begin{equation*}
\text { if } i_{0} \ldots i_{n} \in P \text {, then } i_{0} \ldots i_{n-1} \in P \text { and } i_{1} \ldots i_{n} \in P . \tag{3.1}
\end{equation*}
$$

When a path complex $P$ is fixed, all the paths from $P$ are called allowed, whereas the elementary paths that are not in $P$ are called nonallowed. Condition (3.1) means that if we remove the first or the last element of an allowed $n$-path, then the resulting $(n-1)$-path is also allowed.

The set of all $n$-paths from $P$ is denoted by $P_{n}$. The set $P_{-1}$ consists of a single empty path $e$. The elements of $P_{0}$ (i.e., allowed 0-paths) are called the vertices of $P$. Clearly, $P_{0}$ is a subset of $V$. By the property 3.1 , if $i_{0} \ldots i_{n} \in P$, then all $i_{k}$ are vertices of $P$. Hence, we can (and will) remove from the set $V$ all nonvertices so that $V=P_{0}$.
Example 3.2. By definition, an abstract finite simplicial complex $S$ is a collection of subsets of a finite vertex set $V$ that satisfies the following property:

$$
\text { if } \sigma \in S \text {, then any subset of } \sigma \text { is also in } S \text {. }
$$

Let us enumerate the elements of $V$ by distinct reals and identify any subset $s$ of $V$ with the elementary path that consists of the elements of $s$ put in the (strictly) increasing order. Denote by $P(S)$ this collections of elementary paths on $V$, which uniquely determines $S$. The defining property of a simplex can be restated the following:

$$
\begin{equation*}
\text { if } v \in P(S) \text {, then any subsequence of } v \text { is also in } P(S) \text {. } \tag{3.2}
\end{equation*}
$$

Consequently, the family $P(S)$ satisfies the property (3.1) so that $P(S)$ is a path complex. The allowed $n$-paths in $P(S)$ are exactly the $n$-simplexes.


Fig. 1. A simplicial complex (left) and a digraph (right).

For example, the simplicial complex on Fig. 1 (left) has the following path complex:

$$
\begin{aligned}
& P_{0}=\{0,1, \ldots, 8\}, \\
& P_{1}=\{01,02,03,04,05,06,07,08,12,34,35,45,67,68,78\}, \\
& P_{2}=\{012,034,035,045,345,678\}, \\
& P_{3}=\{0345\} .
\end{aligned}
$$

Example 3.3. Let $G=(V, E)$ be a finite digraph, where $V$ is a finite set of vertices and $E$ is the set of directed edges, i.e., $E \subset V \times V$. The fact that $(i, j) \in E$ will also be denoted by $i \rightarrow j$.

An elementary $n$-path $i_{0} \ldots i_{n}$ on $V$ is called allowed if $i_{k-1} \rightarrow i_{k}$ for any $k=1, \ldots, n$. Denote by $P_{n}=P_{n}(G)$ the set of all allowed $n$-paths. In particular, we have $P_{0}=V$ and $P_{1}=E$. Clearly, the collection $P=\bigcup_{n} P_{n}$ of all allowed paths satisfies the condition (3.1) so that $P$ is a path complex. This path complex is naturally associated with the digraph $G$ and will be denoted by $P(G)$.

For example, a digraph on Fig. 1 (right) has the following path complex:

$$
\begin{aligned}
& P_{0}=\{0,1, \ldots, 8\}, \\
& P_{1}=\{01,02,03,04,05,06,07,08,12,34,35,45,67,68,78\}, \\
& P_{2}=\{012,034,035,045,067,068,678\}, \\
& P_{3}=\{0345,0678\} .
\end{aligned}
$$

It is easy to see that a path complex arises from a digraph if and only if it satisfies the following additional condition: if in a path $i_{0} \ldots i_{n}$ all pairs $i_{k-1} i_{k}$ are allowed, then the whole path $i_{0} \ldots i_{n}$ is allowed.

It is easy to show that a path complex $P$ arises from a simplicial complex if and only if it satisfies the following two properties.
(1) Any subsequence of any path from $P$ is also in $P$ (we say in this case that the path complex $P$ is perfect).
(2) There is an injective real-valued function on the vertex set of $P$ that is strictly monotone increasing along any path from $P$.
3.2. Homologies of Path Complex. Given an arbitrary path complex $P=\left\{P_{n}\right\}_{n=0}^{\infty}$ over a finite set $V$, consider for any integer $n \geq-1$ the $\mathbb{K}$-linear space $\mathcal{A}_{n}$ that is spanned by all the elementary $n$-paths from $P$, i.e.

$$
\mathcal{A}_{n}=\mathcal{A}_{n}(P)=\operatorname{span}\left\{e_{i_{0} \ldots i_{n}}: i_{0} \ldots i_{n} \in P_{n}\right\} .
$$

The elements of $\mathcal{A}_{n}$ are called allowed $n$-paths. By construction, $\mathcal{A}_{n}$ is a subspace of $\Lambda_{n}$. For example, $\mathcal{A}_{p}=\Lambda_{p}$ for $p \leq 0$, while $\mathcal{A}_{1}$ is spanned by all edges of $P$ and can be smaller than $\Lambda_{1}$.

We would like to restrict the operator $\partial$ defined on spaces $\Lambda_{n}$ to the subspaces $\mathcal{A}_{n}$. For some path complexes it can happen that $\partial \mathcal{A}_{n} \subset \mathcal{A}_{n-1}$, so that the restriction is straightforward. If it is not the case, then an additional construction is needed as will be explained below. The inclusion $\partial \mathcal{A}_{n} \subset \mathcal{A}_{n-1}$ takes place, for example, for perfect path complexes. In this case, we obtain a chain complex

$$
\begin{equation*}
0 \leftarrow \mathbb{K} \leftarrow \mathcal{A}_{0} \leftarrow \ldots \leftarrow \mathcal{A}_{n-1} \leftarrow \mathcal{A}_{n} \leftarrow \ldots \tag{3.3}
\end{equation*}
$$

whose homology groups are denoted by $\tilde{H}_{n}(P), n \geq-1$, and are referred to as the reduced path homologies of $P$. Consider also the truncated complex

$$
\begin{equation*}
0 \leftarrow \mathcal{A}_{0} \leftarrow \ldots \leftarrow \mathcal{A}_{n-1} \leftarrow \mathcal{A}_{n} \leftarrow \ldots, \tag{3.4}
\end{equation*}
$$

whose homology groups are denoted by $H_{n}(P), n \geq 0$, and are referred to as the path homologies of $P$. For example, this construction works if the path complex $P$ arises from a simplicial complex $S$. Then the path homology groups of $P$ coincide with the corresponding simplicial homology groups of $S$.

Now consider the general case where $\partial \mathcal{A}_{n}$ does not have to be a subspace of $\mathcal{A}_{n-1}$. For example, this is the case for a digraph

where the 2-path $e_{012}$ is allowed, while $\partial e_{012}=e_{12}-e_{02}+e_{01}$ is nonallowed because $e_{02}$ is nonallowed.
For a general path complex $P$ and for any $n \geq-1$, define the following subspace of $\mathcal{A}_{n}$ :

$$
\begin{equation*}
\Omega_{n}=\Omega_{n}(P)=\left\{v \in \mathcal{A}_{n}: \partial v \in \mathcal{A}_{n-1}\right\} . \tag{3.5}
\end{equation*}
$$

Note that $\Omega_{n}=\mathcal{A}_{n}$ for $n \leq 1$ while for $n \geq 2$ the space $\Omega_{n}$ can be actually smaller that $\mathcal{A}_{n}$. We claim that always $\partial \Omega_{n} \subset \Omega_{n-1}$. Indeed, if $v \in \Omega_{n}$, then $\partial v \in \mathcal{A}_{n-1}$ and $\partial(\partial v)=0 \in \mathcal{A}_{n-2}$ whence it follows that $\partial v \in \Omega_{n-1}$, which was to be proved.

The elements of $\Omega_{n}$ are called $\partial$-invariant $n$-paths. Thus, we obtain the augmented chain complex of $\partial$-invariant paths:

$$
\begin{equation*}
0 \leftarrow \mathbb{K} \leftarrow \Omega_{0} \leftarrow \ldots \leftarrow \Omega_{n-1} \leftarrow \Omega_{n} \leftarrow \Omega_{n+1} \leftarrow \ldots, \tag{3.6}
\end{equation*}
$$

where all mappings are given by $\partial$. Consider also its standard (nonaugmented) version

$$
\begin{equation*}
0 \leftarrow \Omega_{0} \leftarrow \ldots \leftarrow \Omega_{n-1} \leftarrow \Omega_{n} \leftarrow \Omega_{n+1} \leftarrow \ldots \tag{3.7}
\end{equation*}
$$

The homology groups of (3.7) are referred to as the path homology groups of the path complex $P$ and are denoted by $H_{n}(P), n \geq 0$. The homology groups of (3.6) are called the reduced path homology groups of $P$ and are denoted by $\tilde{H}_{n}(P), n \geq-1$.

Definition 3.4. A path complex $P$ is called regular if it contains no 1-path of the form $i i$. Equivalently, $P$ is regular if all the paths $i_{0} \ldots i_{n} \in P$ are regular.

For example, the path complex of a simplicial complex is always regular. The path complex of a digraph is regular if and only if the digraph is loopless, i.e., if the 1-paths $i i$ are not edges.

For a regular path complex the above construction of the spaces $\Omega_{n}$ allows the following variation. As the space $\mathcal{A}_{n}$ of allowed $n$-path is in this case a subspace of the space $\mathcal{R}_{n}$ of regular $n$-paths, we can replace in (3.5) the nonregular boundary operator $\partial$ on $\Lambda_{n}$ by the regular boundary operator on $\mathcal{R}_{n}$ as described in Sec. 2.3. The resulting space $\Omega_{n}$ is referred to as a regular space of $\partial$-invariant paths. Hence, if the path complex $P$ is regular then we can consider also regular versions of the chain complexes (3.6) and (3.7) and the regular versions of homology groups.

If the path complex $P$ is perfect, then we obtain $\Omega_{n}(P)=\mathcal{A}_{n}(P)$ for all $n$ (in this case, there is no difference between regular and nonregular versions). Hence, in this case the chain complex (3.6) is identical to (3.3), and (3.7) is identical to (3.4).

If $P(G)$ is the path complex of a digraph $G$, then we use the notation $\Omega_{n}(G):=\Omega_{n}(P(G))$. The corresponding homology groups are denoted by $H_{n}(G)$, respectively $\tilde{H}_{n}(G)$, and are referred to as the path homologies of the digraph $G$.

The Euler characteristic of the path complex is defined by

$$
\begin{equation*}
\chi(P)=\sum_{p=0}^{n}(-1)^{p} \operatorname{dim} H_{p}(P) \tag{3.8}
\end{equation*}
$$

provided there exists $n$ such that $\operatorname{dim} H_{p}(P)=0$ for all $p>n$. For a regular path complex $P$, there are a regular and nonregular versions of $\chi(P)$, which do not have to match.
3.3. Some Properties of Path Homologies. Let us state some simple properties of the space $\Omega_{n}(P)$ and $H_{n}(P)$.

Proposition 3.5 ([8]).
(a) If $\operatorname{dim} \Omega_{n}=0$, then $\operatorname{dim} \Omega_{p}=0$ for all $p>n$.
(b) For a regular chain complex $\left\{\Omega_{*}\right\}$, the condition $\operatorname{dim} \Omega_{n} \leq 1$ for some $n$ implies that $\operatorname{dim} \Omega_{p}=0$ for all $p>n$.

A connected component of a path complex $P$ is any minimal subset $U$ of $V$ such that if $i \in U$, then $U$ contains any vertex $j \in V$ such that $i j$ or $j i$ is an allowed 1-path.

Proposition 3.6 ([8]). For any path complex $P$, we have $\operatorname{dim} H_{0}(P)=k$, where $k$ is the number of connected components of $P$. Moreover, $H_{0}(P)$ is generated by any set $\left\{e_{i_{1}}, \ldots, e_{i_{k}}\right\}$ of $k$ vertices belonging to different connected components. In particular, if $P$ is connected, then $\operatorname{dim} H_{0}(P)=1$ and, hence, $\operatorname{dim} \tilde{H}_{0}(P)=0$.

Let $P$ be a regular path complex over a set $V$ and $P^{\prime}$ be a regular path complex over a set $V^{\prime}$.
Definition 3.7. We say that a map $f: V \rightarrow V^{\prime}$ is a morphism of path complexes from $P$ to $P^{\prime}$ if, for any path $v \in P$, the path $f_{*}(v)$ either lies in $P^{\prime}$ or is nonregular.
Proposition 3.8. Any morphism $f: V \rightarrow V^{\prime}$ of path complexes $P$ and $P^{\prime}$ induces a morphism of regular chain complexes

$$
f_{*}: \Omega_{*}(P) \rightarrow \Omega_{*}\left(P^{\prime}\right)
$$

and, consequently, a homomorphism of regular homology groups

$$
f_{*}: H_{*}(P) \rightarrow H_{*}\left(P^{\prime}\right)
$$

Proof. Any allowed path $v \in \mathcal{A}_{n}(P)$ is a linear combination of paths $e_{i_{0} \ldots i_{n}} \in P$ and, hence, $f_{*}(v)$ is a linear combination of paths $f_{*}\left(e_{i_{0} \ldots i_{n}}\right)$ that are either in $P^{\prime}$ or nonregular. Since nonregular paths are treated as zero, we obtain that $f_{*}(v) \in \mathcal{A}_{n}\left(P^{\prime}\right)$. If $v \in \Omega_{n}(P)$, then $\partial v \in \mathcal{A}_{n-1}(P)$ and, hence,

$$
\partial\left(f_{*}(v)\right)=f_{*}(\partial v) \in \mathcal{A}_{n-1}\left(P^{\prime}\right)
$$

which implies $f_{*}(v) \in \Omega_{n}\left(P^{\prime}\right)$. Hence, $f_{*}$ is a morphism of regular chain complexes. The second claim is standard.

## 4. Digraphs

4.1. Path Homologies on Digraphs. In this section, we give some examples of $\partial$-invariant paths on digraphs without loops, i.e., edges of the form $a \rightarrow a$. If $G=(V, E)$ is a digraph without loops, then its path complex $P(G)$ is regular. We deal here with the regular spaces $\Omega_{n}(G)=\Omega_{n}(P(G))$ and regular homology groups $H_{n}(G)=H_{n}(P(G))$ and $\tilde{H}_{n}(G)=\tilde{H}_{n}(P(G))$.
4.1.1. Triangles and squares. Let us call by a triangle a sequence of three distinct vertices $a, b, c \in V$ such that there are arrows $a \rightarrow b, b \rightarrow c$, and $a \rightarrow c$ :


Note that a triangle determines a 2-path $e_{a b c} \in \Omega_{2}$ as $e_{a b c} \in \mathcal{A}_{2}$ and $\partial e_{a b c}=e_{b c}-e_{a c}+e_{a b} \in \mathcal{A}_{1}$. The 2-path $e_{a b c}$ will also be referred to as a triangle.

Let us call by a square a sequence of four distinct vertices $a, b, b^{\prime}, c \in V$ such that there are arrows $a \rightarrow b, b \rightarrow c, a \rightarrow b^{\prime}$, and $b^{\prime} \rightarrow c:$


Note that a square determines a 2-path $v:=e_{a b c}-e_{a b^{\prime} c} \in \Omega_{2}$ as $v \in \mathcal{A}_{2}$ and

$$
\partial v=\left(e_{b c}-e_{a c}+e_{a b}\right)-\left(e_{b^{\prime} c}-e_{a c}+e_{a b^{\prime}}\right)=e_{a b}+e_{b c}-e_{a b^{\prime}}-e_{b^{\prime} c} \in \mathcal{A}_{1} .
$$

The 2-path $v$ will also be referred to as a square.

A double edge is a pair of distinct vertices $a, b \in V$ such that there are arrows $a \rightarrow b$ and $b \rightarrow a$. It determines a 2-path $e_{a b a} \in \Omega_{2}$ because $e_{a b a} \in \mathcal{A}_{2}$ and

$$
\partial e_{a b a}=e_{b a}-e_{a a}+e_{a b}=e_{b a}+e_{a b} \in \mathcal{A}_{2}
$$

(since the chain complex $\left\{\Omega_{*}\right\}$ is regular, we have $e_{a a}=0$ ). The 2-path $e_{a b a}$ will also be referred to as a double edge.

Proposition 4.1 ([9, Proposition 2.9; 8]).
(a) Any element of $\Omega_{2}(G)$ is a linear combination of double edges, triangles, and squares.
(b) Assume that a digraph $G=(V, E)$ contains neither double edges nor squares. Then $\operatorname{dim} \Omega_{2}(G)$ is equal to the number of distinct triangles in $G$, and $\operatorname{dim} \Omega_{p}(G)=0$ for all $p>2$.

Consequently, if $G$ contains neither double edges nor triangles nor squares, then $\operatorname{dim} \Omega_{p}(G)=$ $\operatorname{dim} H_{p}(G)=0$ for all $p \geq 2$.

In part (a) one cannot relate directly $\operatorname{dim} \Omega_{2}$ to the number of squares and triangles, since there may be a linear dependence between. Indeed, consider the following digraph:


It contains three squares 0124,0134 , and 0234 , which determine three $\partial$-invariant paths

$$
e_{014}-e_{024}, \quad e_{024}-e_{034}, \quad e_{034}-e_{014} .
$$

These paths are linearly dependent as their sum is equal to 0 . It is easy to see that $\operatorname{dim} \Omega_{2}=2$. For this digraph, all reduced homologies are trivial.

In the presence of squares one may have nontrivial $\Omega_{p}$ for arbitrary $p$ as one can see from numerous examples in the next sections.
4.1.2. Snake. A snake of length $p$ is a digraph with $p+1$ vertices, say $0,1, \ldots, p$, and with the arrows $i \rightarrow(i+1)$ and $i \rightarrow(i+2)$ (see Fig. 2). In particular, any triple $i(i+1)(i+2)$ is a triangle.


Fig. 2. A snake.
A snake of length $p$ contains a $\partial$-invariant $p$-path $v=e_{01 \ldots p}$. Indeed, this path is obviously allowed, its boundary

$$
\partial v=\sum_{k=0}^{p}(-1)^{k} e_{0 \ldots \hat{k} \ldots p}
$$

is also allowed (because $(k-1)(k+1)$ is an arrow), whence $v \in \Omega_{p}$.
4.1.3. Simplex-digraph. Let us define for any $n \geq 0$ a simplex-digraph $\mathrm{Sm}_{n}$ as follows: its set of vertices is $\{0,1, \ldots, n\}$ and the arrows are $i \rightarrow j$ for all $i<j$. For example, we have

$$
\operatorname{Sm}_{1}={ }^{0} \bullet \rightarrow \bullet^{1}, \quad \operatorname{Sm}_{2}=\stackrel{\substack{\bullet \\ \bullet}}{\substack{1 \\ \hline}}
$$

and $\mathrm{Sm}_{3}$ is shown on Fig. 3.


Fig. 3. A 3-simplex digraph $\mathrm{Sm}_{3}$.
Since a simplex contains a snake as a subgraph, the $n$-path $v=e_{01 \ldots n}$ is $\partial$-invariant on $\operatorname{Sm}_{n}$.
4.1.4. Star-shaped digraphs. We say that a digraph $G$ is star-shaped if there is a vertex $a$ (called a star center) such that there is an arrow $a \rightarrow b$ for all $b \neq a$. Similarly, a digraph $G$ is called inverse star-shaped if there is a vertex $a$ (called a star center) such that there is an arrow $b \rightarrow a$ for all $b \neq a$.

For example, any simplex-digraph is star-shaped and inverse star-shaped.
Proposition 4.2 (a Poincaré lemma). If $G$ is a (inverse) star-shaped digraph, then all reduced homologies $\tilde{H}_{n}(G)$ are trivial.

The proof can be found in [8]. Alternatively, Proposition 4.2 is an easy consequence of Theorem 5.5, as will be explained below in Sec. 5.2.

It follows from Proposition 4.2 that all reduced homologies of $\mathrm{Sm}_{n}$ are trivial.
4.1.5. Cycles. We say that a digraph $G=(V, E)$ is a cycle-graph if it is connected (as an undirected graph) and every vertex has the degree 2. For a cycle-graph we have $\operatorname{dim} H_{0}(G)=1$ and $\operatorname{dim} \Omega_{0}(G)=$ $|V|=|E|=\operatorname{dim} \Omega_{1}(G)$.

Proposition 4.3 ([8; 9, Ex. 2.8]). Let $G$ be a cycle-graph. Then

$$
\operatorname{dim} \Omega_{p}(G)=0 \text { for all } p \geq 3 \text { and } \operatorname{dim} H_{p}(G)=0 \text { for all } p \geq 2
$$

If $G$ is a triangle or a square, then

$$
\operatorname{dim} \Omega_{2}(G)=1, \quad \operatorname{dim} H_{1}(G)=0, \quad \chi(G)=1,
$$

whereas otherwise

$$
\operatorname{dim} \Omega_{2}(G)=0, \quad \operatorname{dim} H_{1}(G)=1, \quad \chi(G)=0
$$

In the latter case, the spanning element of $H_{1}(G)$ is the 1-path $\sigma$ such that

$$
\sigma^{i(i+1)}= \begin{cases}1 & \text { if } i(i+1) \text { is an edge },  \tag{4.1}\\ -1 & \text { if }(i+1) i \text { is an edge },\end{cases}
$$

and all other components of $\sigma$ vanish.


Fig. 4. Graph $G$ in two representations: embedded on the Möbius band (left) and in $\mathbb{R}^{3}$ (right).
4.1.6. Möbius band. Consider a (undirected) graph $G$ on Fig. 4 with 6 vertices and 12 edges. As a one-dimensional simplicial complex, $G$ has simplicial homologies $H_{*}\left(C_{*}(G)\right)$.

On the other hand, let us introduce arbitrarily a set $D$ of directions on the edges of $G$, so that $(G, D)$ is a digraph and, hence, has the digraph homologies $H_{*}(G, D)$. Let us show that for, any choice of $D$,

$$
\begin{equation*}
H_{1}\left(C_{*}(G)\right) \neq H_{1}(G, D) . \tag{4.2}
\end{equation*}
$$

Let $\Omega_{*}$ be the chain complex of the digraph $(G, D)$. In particular, $\operatorname{dim} \Omega_{0}=6$, which is the number of vertices, and $\operatorname{dim} \Omega_{1}=12$, which is the number of edges. By homological algebra, we have the following universal identity

$$
\operatorname{dim} H_{1}(\Omega)-\operatorname{dim} H_{0}(\Omega)=\operatorname{dim} \Omega_{1}-\operatorname{dim} \Omega_{0}-\operatorname{dim} \partial \Omega_{2}
$$

and an analogous identity for the simplicial homologies. Since the graph $G$ is connected, we have $\operatorname{dim} H_{0}(\Omega)=1$. It follows that

$$
\operatorname{dim} H_{1}(\Omega)=7-\operatorname{dim} \partial \Omega_{2} .
$$

A similar formula holds for the simplicial homologies:

$$
\operatorname{dim} H_{1}\left(C_{*}(G)\right)=7-\operatorname{dim} \partial C_{2}(G)=7,
$$

since $C_{2}(G)$ is trivial.
It remains to show that the space $\partial \Omega_{2}$ is nontrivial for any choice $D$ of the edge directions, which will yield

$$
\operatorname{dim} H_{1}(G, D) \leq 6
$$

and, hence, (4.2). It suffices to verify that there is at least one triangle $a b c$ in $(G, D)$, since $e_{a b c} \in \Omega_{2}$ and $\partial e_{a b c} \neq 0$. Indeed, let us try to define directions $D$ on the edges of $G$ so that ( $G, D$ ) contains no triangles. Then any undirected triangle in $G$ must become one of the two cycles


Fig. 5. Any direction of the edge 23 will create a triangle.

Given a direction of the edge 03 , this requirement determines uniquely the directions of all other edges (cf. Fig. 5), up to the edge 23. However, with any direction on 23 the sequence 023 will become a triangle, which finishes the proof.
4.1.7. Connected sum. A digraph $G=(V, E)$ is called the connected sum of digraphs $G^{\prime}=\left(V^{\prime}, E^{\prime}\right)$ and $G^{\prime \prime}=\left(V^{\prime \prime}, E^{\prime \prime}\right)$ if $V=V^{\prime} \cup V^{\prime \prime}, E=E^{\prime} \cup E^{\prime \prime}$, and $V^{\prime} \cap V^{\prime \prime}$ consists of a single vertex.
Proposition 4.4 ([12]). If $G$ is a connected sum of $G^{\prime}$ and $G^{\prime \prime}$, then

$$
\tilde{H}_{*}(G) \cong \tilde{H}_{*}\left(G^{\prime}\right) \oplus \tilde{H}_{*}\left(G^{\prime \prime}\right)
$$

For example, the digraph $G$ on the right panel of Fig. 1 is a connected sum of a triangle 012 and two 3 -simplexes 0678 and 0345 . Since all reduced homologies of simplexes are trivial, we obtain that all the reduced homology groups of $G$ are trivial.

### 4.2. Homologies of Subgraphs.

Proposition $4.5([8,9])$. Suppose that a digraph $G$ has a vertex a with $n$ outcoming arrows $a \rightarrow b_{0}$, $a \rightarrow b_{1}, \ldots, a \rightarrow b_{n-1}$ and no incoming arrows. Assume also that there are arrows $b_{0} \rightarrow b_{i}$ for all $i \geq 1$ :


Denote by $G^{\prime}$ the digraph that is obtained from $G$ by removing the vertex a with all adjacent edges. Then $H_{*}(G) \cong H_{*}\left(G^{\prime}\right)$.

The same is true if a vertex $a$ has $n$ incoming arrows $b_{0} \rightarrow a, b_{1} \rightarrow a, \ldots, b_{n-1} \rightarrow a$ and no outcoming arrows, while there are arrows $b_{i} \rightarrow b_{0}$ for all $i \geq 1$.
Corollary 4.6. Let a digraph $G$ be a tree (i.e., the underlying undirected graph is a tree). Then $H_{p}(G)=0$ for all $p \geq 1$.
Example 4.7. Consider a digraph $G$ as shown in Fig. 6.


Fig. 6. A digraph with many triangles and squares.
Each of the vertices $a_{k}$ satisfies the hypotheses of Proposition 4.5 with $n=2$ (either with incoming or outcoming arrows). Removing successively the vertices $a_{k}$, we see that all the homologies of $G$ are the same as those of the remaining digraph ${ }^{b} \bullet \rightarrow \bullet$. Since it is a star-shaped digraph, we obtain $\operatorname{dim} H_{0}=1$ and $\operatorname{dim} H_{p}=0$ for all $p \geq 1$. In particular, $\chi=1$.

A pair $c b$ of distinct vertices on a digraph is called a semi-edge if $c \nrightarrow b$ but there is a vertex $j$ such that $c \rightarrow j$ and $j \rightarrow b$ as on the diagram:


Proposition 4.8 ([8]). Let the field $\mathbb{K}$ has characteristic 0 . Suppose that a digraph ( $V, E)$ has a vertex a such that there is only one outcoming arrow $a \rightarrow b$ from $a$ and only one incoming arrow $c \rightarrow a$, where $b \neq c$. Denote by $G^{\prime}$ the digraph that is obtained from $G$ by removing the vertex a and the adjacent edges $a \rightarrow b$ and $c \rightarrow a$ :


Then the following is true.
(a) For any $p \geq 2$,

$$
\begin{equation*}
\operatorname{dim} H_{p}(G)=\operatorname{dim} H_{p}\left(G^{\prime}\right) \tag{4.3}
\end{equation*}
$$

(b) If $c b$ is an edge or a semi-edge in $G^{\prime}$, then (4.3) is satisfied also for $p=0,1$, i.e., for all $p \geq 0$.
(c) If $c b$ is neither edge nor semi-edge in $G^{\prime}$, but $b$ and $c$ belong to the same connected component of $G^{\prime}$, then $\operatorname{dim} H_{1}(G)=\operatorname{dim} H_{1}\left(G^{\prime}\right)+1$ and $\operatorname{dim} H_{0}(G)=\operatorname{dim} H_{0}\left(G^{\prime}\right)$.
(d) If $b$ and $c$ belong to different connected components of $G^{\prime}$, then $\operatorname{dim} H_{1}(G)=\operatorname{dim} H_{1}\left(G^{\prime}\right)$ and $\operatorname{dim} H_{0}(G)=\operatorname{dim} H_{0}\left(G^{\prime}\right)-1$.
Consequently, in the case (b), $\chi(G)=\chi\left(G^{\prime}\right)$, whereas in the cases (c) and (d), $\chi(G)=\chi\left(G^{\prime}\right)-1$.
Example 4.9. Consider the digraphs


Since $c b$ is semi-edge in $G^{\prime}$, we have case (b) so that all homologies of $G$ and $G^{\prime}$ are the same. Removing further vertex $d$, we obtain a digraph ${ }^{b} \bullet \rightarrow \bullet^{c}$, which will be denoted by $G^{\prime \prime}$. It is a star-shaped digraph with $\operatorname{dim} H_{p}\left(G^{\prime \prime}\right)=0$ for $p \geq 1$. Since $c b$ is neither edge nor semi-edge in $G^{\prime \prime}$, but the digraph is connected, we conclude by case (c) that

$$
H_{p}\left(G^{\prime}\right)=H_{p}\left(G^{\prime \prime}\right) \text { for } p \geq 2
$$

and

$$
\operatorname{dim} H_{1}\left(G^{\prime}\right)=\operatorname{dim} H_{1}\left(G^{\prime \prime}\right)+1=1
$$

It follows that $\operatorname{dim} H_{p}(G)=0$ for $p \geq 2$ and $\operatorname{dim} H_{1}(G)=1$.
Example 4.10. Consider a digraph on Fig. 7 (an anti-snake).


Fig. 7. An anti-snake.
We start building this digraph with $1 \rightarrow 2$. Since 21 is neither edge nor semi-edge, adding a path $2 \rightarrow 3 \rightarrow 1$ increases $\operatorname{dim} H_{1}$ by 1 and preserves other homologies. Since 23 is an edge, adding a path $2 \rightarrow 4 \rightarrow 3$ preserves all homologies. Since 34 is neither edge nor semi-edge, adding a path $3 \rightarrow 5 \rightarrow 4$ increases $\operatorname{dim} H_{1}$ by 1 and preserves other homologies. Similarly, adding a path $5 \rightarrow 6 \rightarrow 4$ preserves all homologies.

One can repeat this pattern arbitrarily many times. By doing so we construct a digraph with a prescribed positive integer value of $\operatorname{dim} H_{1}$ while keeping $\operatorname{dim} H_{p}=0$ for all $p \geq 2$. Consequently, the Euler characteristic $\chi$ can take arbitrary negative integer values.
Example 4.11. Consider a digraph on Fig. 1 (right). By Proposition 4.5, we can remove the vertices 5 and 8 (and their adjacent edges) without change of homologies. Then by the same proposition we can remove 4 and 7 . By Proposition 4.8 we can remove the vertex 1 . The resulting digraph with the vertices $0,2,3$, and 6 is star-shaped, so that by Proposition 4.2 the homology groups $H_{p}$ are trivial for all $p \geq 1$, while $\operatorname{dim} H_{0}=1$.

## 5. Join of Path Complexes

In this and the next sections, we use a slightly different way of denoting the path spaces associated with a given path complex as we will have to consider path complexes on more than one set. Given a finite set $V$, denote by $P(V)$ a path complex on $V$. The space $\mathcal{A}_{n}(P(V))$ of all allowed $n$-paths will be denoted shortly by $\mathcal{A}_{n}(V)$. Similarly, the space $\Omega_{n}(P(V))$ of all $\partial$-invariant $n$-paths will be denoted by $\Omega_{n}(V)$. Similar notation will apply to all other relevant notions including path homologies $H_{n}(V)$, etc.

In this section, the range of $n$ is $n \geq-1$, so that we use the augmented chain complexes (3.6).

### 5.1. Definition and Examples of Join.

Definition 5.1. Given two disjoint finite sets $X$ and $Y$ and their path complexes $P(X)$ and $P(Y)$, set $Z=X \sqcup Y$ and define a path complex $P(Z)$ as follows: $P(Z)$ consists of all paths of the form $u v$, where $u \in P(X)$ and $v \in P(Y)$. The path complex $P(Z)$ is called a join of $P(X)$ and $P(Y)$ and is denoted by $P(Z)=P(X) * P(Z)$.

The operation $*$ on the path complexes is obviously noncommutative but associative. An example of the path $u v \in P(Z)$ is shown on Fig. 8 (left). Note that each of $u, v$ can be empty so that all allowed paths on $X$ and $Y$ will also be allowed on $Z$.


Fig. 8. Join of two paths (left) and join of two digraphs (right).
Example 5.2. Let $X$ and $Y$ be two digraphs with disjoint sets of vertices. Consider the digraph $Z$ whose set of vertices is $X \sqcup Y$, while the set of edges of $Z$ consists of all the edges of $X$ and $Y$, as well as of all the edges $x \rightarrow y$ for all $x \in X$ and $y \in Y$. The digraph $Z$ is called a join of $X$ and $Y$ and is denoted by $X * Y$. An example of a join of two digraphs is shown on Fig. 8 (right).

Let $P(Z)$ be the path complex arising from the digraph structure of $Z$. Then it is obvious from the definition that $P(Z)$ is the join of $P(X)$ and $P(Y)$ so that $P(X * Y)=P(X) * P(Y)$. Hence, the operation of joining of digraphs is compatible with the operation of joining path complexes.

Example 5.3. Let $X$ and $Y$ be the vertex sets of finite simplicial complexes $S(X)$ and $S(Y)$. Let us construct a simplicial complex $S(Z)$ with the vertex set $Z=X \sqcup Y$ as follows. Assuming that $|X|=n$ and $|Y|=m$, embed the set $X$ (together with all simplexes from $S(X)$ ) into a hyperplane $h^{n-1} \subset \mathbb{R}^{n+m-1}$ and $Y$ into a hyperplane $h^{m-1} \subset \mathbb{R}^{n+m-1}$, where the hyperplanes $h^{n-1}$, $h^{m-1}$ are orthogonal and nonintersecting. For any two simplexes $\sigma_{1} \in S(X)$ and $\sigma_{2} \in S(Y)$, define their join $\sigma_{1} * \sigma_{2}$ as the convex hull of $\sigma_{1}$ and $\sigma_{2}$ embedded in $\mathbb{R}^{n+m-1}$ as above (see Fig. 9).


Fig. 9. A join $\sigma_{1} * \sigma_{2}$ of two one-dimensional simplexes $\sigma_{1}, \sigma_{2}$ (case $n=m=2$ ).
Due to a general position of $\sigma_{1}$ and $\sigma_{2}$, the join $\sigma_{1} * \sigma_{2}$ is also a simplex. Then $S(Z)$ is a collection of all simplexes $\sigma_{1} * \sigma_{2}$ with $\sigma_{1} \in S(X)$ and $\sigma_{2} \in S(Y)$. We refer to $S(Z)$ as a join of simplicial complexes $S(X), S(Y)$ and denote it by $S(X) * S(Y)$.

Equivalently, one can define $S(Z)$ in an abstract way without embedding into a Euclidean space. Indeed, considering simplexes as sequences of vertices, we can say that $S(Z)$ consists of all simplexes of the form $\left[x_{0}, \ldots, x_{p}, y_{0}, \ldots, y_{q}\right]$, where $\left[x_{0}, \ldots, x_{p}\right] \in S(X)$ and $\left[y_{0}, \ldots, y_{q}\right] \in S(Y)$. It is clear that $S(Z)$ is a simplicial complex as it satisfies the defining property (3.2). It is also obvious that the path complexes $P(X), P(Y)$, and $P(Z)$ of the simplicial complexes $S(X), S(Y)$, and $S(Z)$, respectively, satisfy $P(Z)=P(X) * P(Y)$. Hence, the operation of joining of simplicial complexes is compatible with the operation of joining path complexes.
Proposition 5.4. Let $P(X)$ and $P(Y)$ be two path complexes and let $P(Z)=P(X) * P(Y)$. If $u \in \Omega_{p}(X)$ and $v \in \Omega_{q}(Y)$, then $u v \in \Omega_{p+q+1}(Z)$. Moreover, the operation $u, v \mapsto u v$ of join extends to that for the homology classes $u \in \tilde{H}_{p}(X)$ and $v \in \tilde{H}_{q}(Y)$ so that $u v \in \tilde{H}_{p+q+1}(Z)$.
Proof. If $u$ and $v$ are allowed, then $u v$ is allowed on $Z$ by definition. In particular, if $u \in \Omega_{p}(X)$ and $v \in \Omega_{q}(Y)$, then $u v \in \mathcal{A}_{p+q+1}(Z)$. Let us show that $\partial(u v) \in \mathcal{A}_{p+q}(Z)$, which would imply $u v \in \Omega_{p+q+1}(Z)$. Indeed, we have by (2.7)

$$
\begin{equation*}
\partial(u v)=(\partial u) v+(-1)^{p+1} u(\partial v) . \tag{5.1}
\end{equation*}
$$

Since $\partial u$ and $\partial v$ are also allowed, we obtain that the right-hand side here is allowed, whence the claim follows.

If $u$ and $v$ are cycles, then by (5.1) the join $u v$ is a cycle for $Z$. We are left to verify that the homology class of $u v$ depends only on the homology classes of $u$ and $v$. For that it suffices to prove that if either $u$ or $v$ is a boundary, then so is $u v$. Indeed, if $u=d w$, then $\partial(w v)=(\partial w) v+(-1)^{p} w(\partial v)=u v$, so that $u v$ is a boundary.
5.2. Path Homologies of Join. Before we state the main theorem, let us recall some notation from homological algebra. Let $\left\{A_{p}\right\}_{p \geq p_{0}}$ be a sequence of finite-dimensional linear spaces over $\mathbb{K}$ enumerated by an integer parameter $p$. Denote by $A_{\bullet}$ the direct sum of all $A_{p}$, i.e.,

$$
A_{\bullet}=\bigoplus_{p \geq p_{0}} A_{p}
$$

so that $A_{\mathbf{\bullet}}$ is a graded linear space. If $\left\{A_{p}\right\}$ is a chain complex with the boundary operator $\partial_{A}$, then $\partial_{A}$ extends linearly to an operator in $A_{\bullet}$ that respects a graded structure. It will be convenient to identify $A_{\bullet}$ with the chain complex $A_{*}=\left\{A_{p}\right\}$ as $A_{\bullet}$ contains the same information as $A_{*}$. The sequence of homologies $\left\{H_{p}\left(A_{\bullet}\right)\right\}$ of the chain complex $A_{\bullet}$ gives rise to a graded linear space $H_{\bullet}\left(A_{\bullet}\right)$.

Given two graded linear spaces $A_{\bullet}$ and $B_{\bullet}$ as above, define their tensor product by

$$
A \bullet \otimes B \bullet=\bigoplus_{p, q}\left(A_{p} \otimes B_{q}\right),
$$

where $A_{p} \otimes B_{q}$ is the tensor product over $\mathbb{K}$ of the linear spaces $A_{p}$ and $B_{q}$. In other words, $A_{\bullet} \otimes B_{\bullet}=C_{\bullet}$, where

$$
C_{r}=\bigoplus_{\{p, q: p+q=r\}}\left(A_{p} \otimes B_{q}\right) .
$$

If $A_{\bullet}$ and $B_{\bullet}$ are chain complexes with the boundary operators $\partial_{A}$ and $\partial_{B}$, respectively, then define the boundary operator $\partial_{C}$ in $C_{\bullet}$ by

$$
\begin{equation*}
\partial_{C}(u \otimes v)=\left(\partial_{A} u\right) \otimes v+(-1)^{p} u \otimes\left(\partial_{B} v\right) \tag{5.2}
\end{equation*}
$$

for all $u \in A_{p}$ and $v \in B_{q}$. It is well known that $\partial_{C}^{2}=0$ so that $C \bullet$ with $\partial_{C}$ is a chain complex. Furthermore, by a theorem of Künneth, we have the following identity for homologies:

$$
\begin{equation*}
H_{\bullet}\left(C_{\bullet}\right) \cong H_{\bullet}\left(A_{\bullet}\right) \otimes H_{\bullet}\left(B_{\bullet}\right) \tag{5.3}
\end{equation*}
$$

i.e.,

$$
H_{r}\left(C_{\bullet}\right) \cong \bigoplus_{\{p, q: p+q=r\}} H_{p}\left(A_{\bullet}\right) \otimes H_{q}\left(B_{\bullet}\right)
$$

(see [16]). Given a graded linear space $A_{\bullet}$, define a graded space $A_{\bullet}^{\prime}$ by

$$
A_{n}^{\prime}:=A_{n-1}
$$

If $A_{\bullet}$ is a chain complex, then also $A_{\bullet}^{\prime}$ is a chain complex with the same boundary operator.
Given a regular path complex $P(V)$ on a finite set $V$, we consider as before the spaces $\mathcal{R}_{n}(V), \mathcal{A}_{n}(V)$, and $\Omega_{n}(V)$, where $n \geq-1$. Then we have the chain complexes $\mathcal{R}_{\bullet}(V), \mathcal{R}_{\bullet}^{\prime}(V), \Omega_{\bullet}(V), \Omega_{\bullet}^{\prime}(V)$ with the regular boundary operator $\partial$ and a graded space $\mathcal{A} \cdot(V)$.
Theorem 5.5. Let $X$ and $Y$ be two finite nonempty sets and $P(X)$ and $P(Y)$ be regular path complexes on $X$ and $Y$, respectively. Set $Z=X \sqcup Y$ and consider the join path complex $P(Z)=P(X) * P(Y)$. Then we have the following isomorphism of the chain complexes:

$$
\begin{equation*}
\Omega_{\bullet}(Z) \cong \Omega_{\bullet}^{\prime}(X) \otimes \Omega_{\bullet}(Y), \tag{5.4}
\end{equation*}
$$

where the mapping $\Omega_{\bullet}^{\prime}(X) \otimes \Omega_{\bullet}(Y) \rightarrow \Omega_{\bullet}(Z)$ is given by $u \otimes v \mapsto u v$.
It follows from (5.4) that, for any $r \geq-1$,

$$
\begin{equation*}
\Omega_{r}(Z) \cong \bigoplus_{\{p, q \geq-1: p+q=r-1\}}\left(\Omega_{p}(X) \otimes \Omega_{q}(Y)\right) \tag{5.5}
\end{equation*}
$$

and, for any $r \geq 0$,

$$
\begin{equation*}
\tilde{H}_{r}(Z) \cong \bigoplus_{\{p, q \geq 0: p+q=r-1\}}\left(\tilde{H}_{p}(X) \otimes \tilde{H}_{q}(Y)\right) \tag{5.6}
\end{equation*}
$$

(a Künneth formula for join).

The identity (5.6) gives easily the proof of Proposition 4.2. Indeed, let $G$ be a star-shaped digraph with a star center $a$. Denote by $G^{\prime}$ the digraph that is obtained from $G$ by removing the vertex $a$ and all adjacent edges. Then $G=\{a\} * G^{\prime}$, and by (5.6) we obtain $\tilde{H}_{r}(G) \cong\{0\}$ for all $r \geq 0$ because $\tilde{H}_{p}(\{a\}) \cong\{0\}$ for all $p \geq 0$. If $G$ is an inverse star-shaped digraph, then $G=G^{\prime} *\{a\}$ and again $\tilde{H}_{r}(G) \cong\{0\}$.

Example 5.6. Consider the digraph $Z=X * Y$ as on Fig. 8 (right). In this case, we have by Proposition 4.3 that all homologies $\tilde{H}_{p}(X)$ and $\tilde{H}_{q}(Y)$ are trivial except for

$$
\begin{aligned}
& H_{1}(X)=\operatorname{span}\left\{e_{01}+e_{12}+e_{20}\right\} \\
& H_{1}(Y)=\operatorname{span}\left\{e_{35}-e_{65}+e_{64}-e_{34}\right\}
\end{aligned}
$$

Therefore, all $\tilde{H}_{r}(Z)$ are trivial except for $H_{3}(Z)$, which is generated by a single element

$$
e_{0135}-e_{0165}+e_{0164}-e_{0134}+e_{1235}-e_{1265}+e_{1264}-e_{1234}+e_{2035}-e_{2065}+e_{2064}-e_{2034} .
$$

5.3. Cone and Suspension. A cone over a digraph $X$ is a digraph Cone $X$ that is obtained from $X$ by adding one more vertex $a$ and all the edges of the form $b \rightarrow a$ for all $b \in X$. The vertex $a$ is called the cone vertex. Clearly, we have Cone $X=X * Y$, where $Y$ consists of a single vertex $a$.

Proposition 5.7. For any digraph $X$, we have for any $r \geq 0$

$$
\begin{equation*}
\Omega_{r}(\operatorname{Cone} X) \cong \Omega_{r}(X) \oplus \Omega_{r-1}(X), \tag{5.7}
\end{equation*}
$$

where the isomorphism is given by the map $u, v \mapsto u+v e_{a}$, where $u \in \Omega_{r}(X), v \in \Omega_{r-1}(X)$, and $a$ is the cone vertex. Furthermore, all the reduced homologies of Cone $X$ are trivial.

Proof. Since Cone $X=X * Y$ with $Y=\{a\}$, the isomorphism (5.7) follows from (5.5), $\Omega_{-1}(Y)=\operatorname{span}\left\{1_{\mathbb{K}}\right\}$, $\Omega_{0}(Y)=\operatorname{span}\left\{e_{a}\right\}$, and $\Omega_{q}(Y)=\{0\}$ for $q \geq 1$. Since all the homologies $\tilde{H}_{q}(Y)$ are trivial, it follows from (5.6) that all homologies $\tilde{H}_{r}(Z)$ are also trivial. The latter follows also from Proposition 4.2, since Cone $X$ is inverse star-shaped.

Example 5.8. Clearly, a simplex-digraph $\mathrm{Sm}_{n}$ can be regarded as a cone over $\mathrm{Sm}_{n-1}$ (cf. Sec. 4.1.3). Since $\Omega_{0}\left(\mathrm{Sm}_{0}\right)$ is spanned by a 0 -path $e_{0}$, we obtain by induction from (5.7) that $\Omega_{n}\left(\mathrm{Sm}_{n}\right)$ is spanned by a path $e_{01 \ldots n}$.

Definition 5.9. A suspension over a digraph $X$ is a digraph $\operatorname{Sus} X$ that is obtained from $X$ by adding two vertices $a$ and $b$ and all the edges $c \rightarrow a$ and $c \rightarrow b$ for all $c \in X$. The vertices $a$ and $b$ are called the suspension vertices.

Clearly, we have Sus $X=X * Y$, where $Y=\{a, b\}$ is a digraph that consists of two vertices $a$ and $b$ and no edges.

Proposition 5.10. For any digraph $X$ and for any $r \geq 0$, we have that

$$
\begin{equation*}
\Omega_{r}(\text { Sus } X) \cong \Omega_{r}(X) \oplus \Omega_{r-1}(X) \oplus \Omega_{r-1}(X), \tag{5.8}
\end{equation*}
$$

where the isomorphism is given by the map $u, v, w \mapsto u+v e_{a}+$ we $e_{b}$ where $u \in \Omega_{r}(X), v, w \in \Omega_{r-1}(X)$, and $a$ and $b$ are the suspension vertices. Furthermore, we have that

$$
\begin{equation*}
\tilde{H}_{r}(\operatorname{Sus} X) \cong \tilde{H}_{r-1}(X), \tag{5.9}
\end{equation*}
$$

where the isomorphism is given by the map $u \mapsto u\left(e_{a}-e_{b}\right), u \in \tilde{H}_{r-1}(X)$. Consequently, we have

$$
\begin{equation*}
\chi(\operatorname{Sus} X)=2-\chi(X) \tag{5.10}
\end{equation*}
$$

Proof. Let $Y$ as above. The isomorphism (5.8) follows from (5.5) because $\Omega_{-1}(Y)=\operatorname{span}\left\{1_{\mathbb{K}}\right\}, \Omega_{0}(Y)=$ $\operatorname{span}\left\{e_{a}, e_{b}\right\}$, and $\Omega_{q}(Y)=\{0\}$ for $q \geq 1$. Since $\tilde{H}_{q}(Y)=\{0\}$ for all $q \neq 0$ and $\tilde{H}_{0}(Y)=\operatorname{span}\left\{e_{a}-e_{b}\right\}$, (5.9) follows from (5.6). Finally, setting $Z=\operatorname{Sus} X$ and using (5.9), we obtain

$$
\begin{aligned}
\chi(Z)=1+\sum_{r \geq 1}(-1)^{r} \operatorname{dim} H_{r}(Z)= & 1+\sum_{r \geq 1}(-1)^{r} \operatorname{dim} \tilde{H}_{r-1}(X) \\
& =1-\sum_{s \geq 0}(-1)^{s} \operatorname{dim} \tilde{H}_{s}(X)=2-\sum_{s \geq 0}(-1)^{s} \operatorname{dim} H_{s}(X)=2-\chi(X),
\end{aligned}
$$

that proves (5.10).
In particular, having examples of digraphs $X$ with arbitrary negative integer values of $\chi$ (cf. Example 4.10), we obtain examples of digraphs Sus $X$ with arbitrary positive integer values of $\chi$.

Example 5.11. Let $S$ be any cycle-graph that is neither triangle nor square; it will be considered as an analog of a circle. Define $S_{n}$ inductively by $S_{1}=S$ and $S_{n+1}=\operatorname{Sus} S_{n}$. Then $S_{n}$ can be regarded as an $n$-dimensional sphere-graph. Since $\chi(S)=0$ by Proposition 4.3, it follows that $\chi\left(S_{n}\right)=0$ if $n$ is odd and $\chi\left(S_{n}\right)=2$ if $n$ is even. Proposition 5.10 implies that $\operatorname{dim} H_{n}\left(S_{n}\right)=\operatorname{dim} H_{1}(S)=1$, which gives an example of a nontrivial $H_{n}$ for an arbitrary $n$.

For example, the octahedron digraph Oct on Fig. 10 is $S_{2}$ based on the cycle $S$ with the vertices $0,1,2,3$. It follows that Oct has nontrivial $H_{2}$ (Oct) despite the fact that this digraph is obviously planar.


Fig. 10. The octahedron digraph.
Let $v$ be a 1-path on $S$ that spans $H_{1}(S)$ (see Sec. 4.1.5). If $S_{n+1}$ is a suspension of $S_{n}$ on the vertices $a_{n}, b_{n}$, then we obtain by induction that the spanning element of $H_{n}\left(S_{n}\right)$ is

$$
u=v\left(e_{a_{1}}-e_{b_{1}}\right)\left(e_{a_{2}}-e_{b_{2}}\right) \ldots\left(e_{a_{n-1}}-e_{b_{n-1}}\right) .
$$

For the cycle $S$ on Fig. 10, by Proposition 4.3 we have $v=e_{12}-e_{02}+e_{03}-e_{13}$, which implies that the spanning element of $H_{2}(\mathrm{Oct})$ is

$$
u=v\left(e_{4}-e_{5}\right)=e_{124}-e_{024}+e_{034}-e_{134}-e_{125}+e_{025}-e_{035}+e_{135} .
$$

Obviously, each term in this sum corresponds to one of the eight faces of the octahedron, and the sum $u$ represents in some sense the surface of the octahedron.

Applying Proposition 4.3 to compute the homology groups of $S$ and then Proposition 5.10, we obtain

$$
\begin{equation*}
\operatorname{dim} H_{0}(O c t)=\operatorname{dim} H_{2}(O c t)=1, \quad \operatorname{dim} H_{p}(O c t)=0 \quad \text { if } p=1 \quad \text { or } p \geq 3 . \tag{5.11}
\end{equation*}
$$



Fig. 11. A digraph with 12 vertices and 32 edges.
Example 5.12. Consider a digraph $G$ on Fig. 11 (left).
Removing successively the vertices $A, B, 8,9,6$, and 7 , by Proposition 4.5 we obtain a digraph $G^{\prime}$ as on Fig. 11 (right) with the vertex set $\{0,1,2,3,4,5\}$ that has the same homologies as $G$. The digraph $G^{\prime}$ is clearly the same as Oct on Fig. 10. Hence, we obtain by (5.11) that $\operatorname{dim} H_{2}(G)=1$ while $H_{p}(G)=\{0\}$ for $p=1$ and $p>2$. The spanning element of $H_{2}(G)$ is hence

$$
u=e_{124}-e_{024}+e_{034}-e_{134}-e_{125}+e_{025}-e_{035}+e_{135} .
$$

In other words, this 2-path $u$ determines a 2-dimensional "hole" in $G$ given by the octahedron. Note that on Fig. 11 this octahedron is hardy visible, but it can be determined purely algebraically using the above tools.
5.4. Some Properties of $\boldsymbol{\partial}$-Invariant Paths on Joins. We prove here some auxiliary results needed for the proof of Theorem 5.5. For a finite set $V$, denote by $R(V)$ the path complex on $V$ consisting of all regular elementary paths on $V$. Then, for any $n \geq-1, R_{n}(V)$ denotes the set of all regular elementary $n$-paths on $V$. As before, $\mathcal{R}_{n}(V)$ is the space of all finite $\mathbb{K}$-linear combinations of the paths from $R_{n}(V)$.

Let $X$ and $Y$ be two finite nonempty sets and $P(X)$ and $P(Y)$ be regular path complexes on $X$ and $Y$, respectively. Set $Z=X \sqcup Y$ and consider the join of path complexes $P(Z)=P(X) * P(Y)$.
Lemma 5.13. Any $w \in \Omega_{\bullet}(Z)$ admits a representation

$$
\begin{equation*}
w=\sum_{x \in P(X)} e_{x} a^{x}=\sum_{y \in P(Y)} b^{y} e_{y}, \tag{5.12}
\end{equation*}
$$

where $a^{x} \in \Omega_{\bullet}(Y)$ and $b^{y} \in \Omega_{\bullet}(X)$ are uniquely determined.
Proof. Since any allowed elementary path on $X$ is a join of elementary paths on $X$ and $Y$, we see that any $w \in \mathcal{A}_{\bullet}(Z)$ admits a representation

$$
\begin{equation*}
w=\sum_{x \in P(X), y \in P(Y)} c^{x y} e_{x} e_{y}, \tag{5.13}
\end{equation*}
$$

where the coefficients $c^{x y} \in \mathbb{K}$ are uniquely determined. It follows from (5.13) that

$$
\begin{equation*}
w=\sum_{x \in P(X)} e_{x} a^{x} \tag{5.14}
\end{equation*}
$$

where

$$
a^{x}=\sum_{y \in P(Y)} c^{x y} e_{y} \in \mathcal{A}(Y) .
$$

Clearly, $a^{x}$ are uniquely determined.

Now assume that $w \in \Omega_{\bullet}(Z)$ and show that $a^{x} \in \Omega_{\bullet}(Y)$. Let us define the coefficients $\delta_{x^{\prime}}^{x} \in\{0,1,-1\}$ by

$$
\begin{equation*}
\partial e_{x}=\sum_{x^{\prime} \in R(X)} \delta_{x}^{x^{\prime}} e_{x^{\prime}} \tag{5.15}
\end{equation*}
$$

Also, if $x \in P_{p}(X)$, then set $\varepsilon_{x}=(-1)^{p+1}$. Using (5.14) and the product rule (2.7), we obtain

$$
\partial w=\sum_{x \in P(X)}\left(\partial e_{x}\right) a^{x}+\varepsilon_{x} e_{x}\left(\partial a^{x}\right)=\sum_{x \in P(X)} \sum_{x^{\prime} \in R(X)} \delta_{x}^{x^{\prime}} e_{x^{\prime}} a^{x}+\sum_{x \in P(X)} \varepsilon_{x} e_{x} \partial a^{x}
$$

Switching in the double sum the designations $x$ and $x^{\prime}$ and interchanging the summation signs, we obtain

$$
\begin{align*}
\partial w & =\sum_{x \in R(X)} \sum_{x^{\prime} \in P(X)} \delta_{x^{\prime}}^{x} e_{x} a^{x^{\prime}}+\sum_{x \in P(X)} \varepsilon_{x} e_{x} \partial a^{x} \\
& =\sum_{x \in P(X)} e_{x}\left(\sum_{x^{\prime} \in P(X)} \delta_{x^{\prime}}^{x} a^{x^{\prime}}+\varepsilon_{x} \partial a^{x}\right)  \tag{5.16}\\
& +\sum_{x \in R(X) \backslash P(X)} e_{x}\left(\sum_{x^{\prime} \in P(X)} \delta_{x^{\prime}}^{x} a^{x^{\prime}}\right) . \tag{5.17}
\end{align*}
$$

Note that any elementary path of the full expansion of the sum (5.17) has a nonallowed $X$-part, while that of (5.16) has the allowed $X$-part. Therefore, there is no cross cancellation between the elementary paths of (5.16) and (5.17). Since their sum $\partial w$ is allowed, it follows that the sum (5.17) consisting only of nonallowed paths must vanish.

On the other hand, since $\partial w \in \Omega_{*}(Z)$, we have analogously to (5.14) a representation

$$
\partial w=\sum_{x \in P(X)} e_{x} \tilde{a}^{x},
$$

where $\tilde{a}^{x} \in \mathcal{A}_{*}(Y)$. Comparison with (5.16) yields

$$
\tilde{a}^{x}=\sum_{x^{\prime} \in P(X)} \delta_{x^{\prime}}^{x} a^{x^{\prime}}+\varepsilon_{x} \partial a^{x} .
$$

Since $a^{x^{\prime}} \in \mathcal{A}_{*}(Y)$, it follows that $\partial a^{x} \in \mathcal{A}_{*}(Y)$, which proves that $a^{x} \in \Omega_{*}(Y)$.
The second identity in (5.12) is proved similarly.
Let $V$ be a finite set. If $u \in \mathcal{R}_{n}(V)$ and $x \in R_{m}(V)$, then we denote by $u^{x} \in \mathbb{K}$ the coefficient of $x$-component of $u$ if $n=m$ and set $u^{x}=0 \in \mathbb{K}$ if $n \neq m$. Let us introduce in $\mathcal{A}_{p}(V)$ the $\mathbb{K}$-scalar product as follows: for all $u, v \in \mathcal{A}_{p}(V)$ we put

$$
\begin{equation*}
[u, v]:=\sum_{x \in P(V)} u^{x} v^{x} \tag{5.18}
\end{equation*}
$$

where as before $u^{x}$ and $v^{x}$ are the coefficients of the components of $u$ and $v$, respectively. If $\mathbb{K}=\mathbb{R}$, then $[\cdot, \cdot]$ is a proper scalar product, but for a general field $\mathbb{K}$ there is no positivity property (in fact, it can happen that $[u, u]=0)$. Set also

$$
\begin{equation*}
\Omega_{p}^{\perp}(V)=\left\{u \in \mathcal{A}_{p}(V):[u, v]=0 \text { for all } v \in \Omega_{p}(V)\right\} \tag{5.19}
\end{equation*}
$$

If $\mathbb{K}=\mathbb{R}$, then $\Omega_{p}^{\perp}$ is an orthogonal complement of $\Omega_{p}$ in $\mathcal{A}_{p}$ and $\mathcal{A}_{p}=\Omega_{p} \oplus \Omega_{p}^{\perp}$.
For a general $\mathbb{K}$, this is not true, since $\Omega_{p}$ and $\Omega_{p}^{\perp}$ may have a nontrivial intersection. However, for any field $\mathbb{K}$, it is still true that

$$
\operatorname{dim} \Omega_{p}+\operatorname{dim} \Omega_{p}^{\perp}=\operatorname{dim} \mathcal{A}_{p}
$$

(see [13, Lemma 6.1]).

Lemma 5.14. If $u \in \Omega_{p}^{\perp}(X)$ and $v \in \mathcal{A}_{q}(Y)$, then $u v \in \Omega_{r}^{\perp}(Z)$, where $r=p+q+1$. Similarly, if $u \in \mathcal{A}_{p}(X)$ and $v \in \Omega_{q}^{\perp}(Y)$, then $u v \in \Omega_{r}^{\perp}(Z)$.
Proof. To prove the first claim, we need to show that $[u v, w]=0$ for any $w \in \Omega_{r}(Z)$. By Lemma 5.13, $w$ is a sum of the joins $\varphi \psi$, where $\varphi \in \Omega_{\bullet}(X)$ and $\psi \in \mathcal{A}_{\bullet}(Y)$. Hence, it suffices to prove that

$$
\begin{equation*}
[u v, \varphi \psi]=0, \tag{5.20}
\end{equation*}
$$

assuming that $\varphi \in \Omega_{p^{\prime}}(X)$ and $\psi \in \mathcal{A}_{q^{\prime}}(Y)$. If $p^{\prime}+q^{\prime}+1 \neq r$, then $u v$ and $\varphi \psi$ do not have common elementary paths in their expansions, and (5.20) is trivially satisfied. Assuming $p^{\prime}+q^{\prime}+1=r$, we obtain

$$
[u v, \varphi \psi]=\sum_{z \in P_{r}(Z)}(u v)^{z}(\varphi \psi)^{z}=\sum_{x \in P_{p}(X), y \in P q(Y)} u^{x} v^{y} \varphi^{x} \psi^{y}
$$

If $p^{\prime} \neq p$, then $\varphi^{x}=0$ and again (5.20) holds trivially. Finally, if $p^{\prime}=p$ and, hence, $q^{\prime}=q$, then we obtain

$$
[u v, \varphi \psi]=\sum_{x \in P_{p}(X)} u^{x} \varphi^{x} \sum_{y \in P_{q}(Y)} v^{y} \psi^{y}=[u, \varphi][v, \psi]=0
$$

because $[u, \varphi]=0$ based on the assumption that $u \in \Omega_{p}^{\perp}(X)$. The second claim is proved similarly.
5.5. Proof of the Künneth Formula for Join. The main technical part of the proof of Theorem 5.5 is contained in the following theorem.
Theorem 5.15. Let $P(X)$ and $P(Y)$ be two regular path complexes and let $P(Z)=P(X) * P(Y)$ be their join. Then any $\partial$-invariant path $w$ on $Z$ admits a representation in the form

$$
\begin{equation*}
w=\sum_{i=1}^{k} u_{i} v_{i} \tag{5.21}
\end{equation*}
$$

for some finite $k$, where $u_{i}$ and $v_{i}$ are $\partial$-invariant paths on $X$ and $Y$, respectively.
The proof of Theorem 5.15 will be given at the end of Sec. 6.5 because it is similar to the proof of an analogous property for Cartesian products of path complexes (Theorem 6.12 below).

Proof of Theorem 5.5. First, let us show how (5.5) and (5.6) follow from (5.4). By definition the isomorphism (5.4) means that

$$
\Omega_{r}(Z) \cong \bigoplus_{\{p \geq 0, p \geq-1: p+q=r\}}\left(\Omega_{p}^{\prime}(X) \otimes \Omega_{q}(Y)\right)
$$

whence (5.5) follows by changing $p-1$ to $p$. The isomorphism (5.4) of the chain complexes $\Omega_{\bullet}(Z)$ and $\Omega_{\bullet}^{\prime}(X) \otimes \Omega_{\bullet}(Y)$ implies that their homologies are also isomorphic. On the other hand, by (5.3) we obtain

$$
H_{\bullet}\left(\Omega_{\bullet}^{\prime}(X) \otimes \Omega_{\bullet}(Y)\right) \cong H_{\bullet}\left(\Omega_{\bullet}^{\prime}(X)\right) \otimes H_{\bullet}\left(\Omega_{\bullet}(Y)\right),
$$

whence

$$
H_{\bullet}\left(\Omega_{\bullet}(Z)\right) \cong H_{\bullet}\left(\Omega_{\bullet}^{\prime}(X)\right) \otimes H_{\bullet}\left(\Omega_{\bullet}(Y)\right)
$$

More explicitly this means that, for any $r \geq-1$,

$$
\begin{aligned}
H_{r}\left(\Omega_{\bullet}(Z)\right) \cong & \bigoplus_{\left\{p^{\prime} \geq 0, q \geq-1: p^{\prime}+q=r\right\}}\left(H_{p^{\prime}}\left(\Omega_{\bullet}^{\prime}(X)\right) \otimes H_{q}\left(\Omega_{\bullet}(Y)\right)\right) \\
& =\bigoplus_{\{p, q \geq-1: p+q=r-1\}}\left(H_{p}\left(\Omega_{\bullet}(X)\right) \otimes H_{q}\left(\Omega_{\bullet}(Y)\right)\right) .
\end{aligned}
$$

Since the homology group $H_{-1}\left(\Omega_{\bullet}\right)$ is always trivial, the condition $p, q \geq-1$ can be replaced here by $p, q \geq 0$. Finally, using that $H_{p}\left(\Omega_{\bullet}(X)\right)=\tilde{H}_{p}(X)$ and $H_{q}\left(\Omega_{\bullet}(Y)\right)=\tilde{H}_{q}(Y)$ are the reduced homologies, we obtain (5.6).

Now we concentrate on the proof of (5.4). We use the graded spaces $\left\{\mathcal{R}_{\bullet}\right\},\left\{\mathcal{A}_{\bullet}\right\}$, and $\left\{\Omega_{\bullet}\right\}$ associated with the path complexes $P(X), P(Y)$, and $P(Z)$. If $\left\{W_{\bullet}\right\}$ is one of these spaces, then set

$$
W_{\bullet}(X, Y)=W_{\bullet}^{\prime}(X) \otimes W_{\bullet}(Y)
$$

Then (5.4) can be restated as follows:

$$
\Omega_{\bullet}(Z) \cong \Omega_{\bullet}(X, Y)
$$

To prove this, we will construct explicitly a mapping

$$
\Phi: \Omega_{r}(X, Y) \rightarrow \Omega_{r}(Z)
$$

that will be isomorphism of linear spaces and will commute with the boundary operator $\partial$.
First, consider a larger chain complex

$$
\mathcal{R}_{\bullet}(X, Y)=\mathcal{R}_{\bullet}^{\prime}(X) \otimes \mathcal{R}_{\bullet}(Y)
$$

and define for any $r \geq-1$ the linear mapping

$$
\Phi: \mathcal{R}_{r}(X, Y) \rightarrow \mathcal{R}_{r}(Z)
$$

as follows: for all $u \in \mathcal{R}_{p}^{\prime}(X)$ and $v \in \mathcal{R}_{q}(Y)$ with $p+q=r$, set

$$
\Phi(u \otimes v)=u v
$$

where $u v$ is the join of $u$ and $v$ on $Z$ (note that $X$ and $Y$ are subsets of $Z$ ).
It follows from Lemma 2.2 that, for $u, v$ as above,

$$
\begin{equation*}
\partial(u v)=(\partial u) v+(-1)^{p} u \partial v \tag{5.22}
\end{equation*}
$$

Here the operator $\partial$ is the boundary operator on $\mathcal{R}_{\bullet}(Z)$, but in the expressions $\partial u$ and $\partial v$ it coincides with the boundary operators on $\mathcal{R}_{\bullet}(X)$ and $\mathcal{R}_{\bullet}(Y)$, respectively. By (5.2) we have for the operator $\partial$ on $\mathcal{R}$ • $(X, Y)$

$$
\partial(u \otimes v)=(\partial u) \otimes v+(-1)^{p} u \otimes \partial v .
$$

The comparison with (5.22) shows that the following diagram is commutative:


Hence, the mapping $\Phi$ is a homomorphism of chain complexes $\mathcal{R}_{\bullet}(X, Y)$ and $\mathcal{R}_{\bullet}(Z)$.
Let us verify that $\Phi$ is in fact a monomorphism. Indeed, the basis in $\mathcal{R}_{r}(X, Y)$ consists of all elements of the form $e_{x} \otimes e_{y}$, where $x \in R_{p}(X)$ and $y \in R_{q}(Y)$ with $p+q=r$. Since $\Phi\left(e_{x} \otimes e_{y}\right)=e_{x y}$ and all such paths $e_{x y}$ are linearly independent in $\mathcal{R}_{r}(Z)$, we see that $\Phi$ is injective.

Next, observe that

$$
\Phi\left(\mathcal{A}_{r}(X, Y)\right)=\mathcal{A}_{r}(Z) .
$$

Indeed, the basis in $\mathcal{A}_{r}(X, Y)$ consists of all elements of the form $e_{x} \otimes e_{y}$, where $x \in R_{p}(X), y \in R_{q}(Y)$ with $p+q=r$, while the basis in $\mathcal{A}_{r}(Z)$ consists of the paths $e_{x y}$ with the same set of $x, y$, whence the claim follows. In particular, the linear spaces $\mathcal{A}_{r}(X, Y)$ and $\mathcal{A}_{r}(Z)$ are isomorphic.

Finally, let us prove that, for all $r \geq-1$,

$$
\Phi\left(\Omega_{r}(X, Y)\right)=\Omega_{r}(Z)
$$

which will finish the proof of (5.4). The inclusion

$$
\Phi\left(\Omega_{r}(X, Y)\right) \subset \Omega_{r}(Z)
$$

is trivial because by Proposition $5.4 u \in \Omega_{p}^{\prime}(X)$ and $v \in \Omega_{q}(Y)$ with $p+q=r$ imply $u v \in \Omega_{r}(Z)$. The opposite inclusion

$$
\Phi\left(\Omega_{r}(X, Y)\right) \supset \Omega_{r}(Z)
$$

follows from Theorem 5.15. Indeed, any $w \in \Omega_{r}(Z)$ admits a representation in the form

$$
w=\sum_{i} u_{i} v_{i}
$$

where $u_{i}$ and $v_{i}$ are $\partial$-invariant paths on $X$ and $Y$, respectively. It follows that

$$
\Phi\left(\sum_{i} u_{i} \otimes v_{i}\right)=\sum_{i} u_{i} v_{i}=w
$$

and, hence, $w \in \Phi\left(\Omega_{r}(X, Y)\right)$.

## 6. Cartesian Product of Path Complexes

In this section, we slightly redefine the sequence $\left\{\mathcal{R}_{n}(V)\right\}$ of spaces of regular paths on a finite set $V$. Namely, instead of the previous convention $\mathcal{R}_{-1}=\operatorname{span}\{e\}$, now we set $\mathcal{R}_{-1}=\{0\}$. In other words, the index $n$ has now the range $n \geq 0$ instead of $n \geq-1$ in Sec. 5 .

All path complexes in this section are regular, and we always use a regular standard chain complex $\left\{\Omega_{n}\right\}_{n \geq 0}$ given in (3.7) and the associated homology groups $\left\{H_{n}\right\}_{n \geq 0}$.
6.1. Cross Product of Paths. Given two finite sets $X$ and $Y$, consider their Cartesian product $Z=$ $X \times Y$. Let $z=z_{0} z_{1} \ldots z_{r}$ be a regular elementary $r$-path on $Z$, where $z_{k}=\left(x_{k}, y_{k}\right)$ with $x_{k} \in X$ and $y_{k} \in Y$. We say that the path $z$ is step-like if, for any $k=1, \ldots, r$, either $x_{k-1}=x_{k}$ or $y_{k-1}=y_{k}$. In fact, exactly one of these conditions holds as $z$ is regular.

Any step-like path $z$ on $Z$ determines by projection regular elementary paths $x$ on $X$ and $y$ on $Y$. More precisely, $x$ is obtained from $z$ by taking the sequence of all $X$-components of the vertices of $z$ and then by collapsing in it any subsequence of repeated vertices to one vertex. The same rule applies to $y$. By construction, the projections $x$ and $y$ are regular elementary paths on $X$ and $Y$, respectively. If the projections of $z=z_{0} \ldots z_{r}$ are $x=x_{0} \ldots x_{p}$ and $y=y_{0} \ldots y_{q}$, then $p+q=r$ (cf. Fig. 12 (left)).



Fig. 12. Left: a step-like path $z$ and its projections $x$ and $y$. Right: a staircase $S(z)$ and its elevation $L(z)$ (here $L(z)=30$ ).

Every vertex $z_{k}=\left(x_{i}, y_{j}\right)$ of a step-like path $z$ can be represented as a point $(i, j)$ of $\mathbb{Z}^{2}$ so that the whole path $z$ is represented by a staircase $S(z)$ in $\mathbb{Z}^{2}$ connecting the points $(0,0)$ and $(p, q)$. Define the elevation $L(z)$ of the path $z$ as the number of cells in $\mathbb{Z}_{+}^{2}$ below the staircase $S(z)$ (the shaded area on Fig. 12 (right)).
Definition 6.1. Given paths $u \in \mathcal{R}_{p}(X)$ and $v \in \mathcal{R}_{q}(Y)$ with some $p, q \geq 0$, define a path $u \times v$ on $Z$ by the following rule: for any step-like elementary $(p+q)$-path $z$ on $Z$, the component $(u \times v)^{z}$ is defined by

$$
\begin{equation*}
(u \times v)^{z}=(-1)^{L(z)} u^{x} v^{y} \tag{6.1}
\end{equation*}
$$

where $x$ and $y$ are the projections of $z$ onto $X$ and $Y$, respectively, and $u^{x}$ and $v^{y}$ are the corresponding components of $u$ and $v$. For nonstep-like paths $z$, set $(u \times v)^{z}=0$.

The path $u \times v$ is called the cross product of $u$ and $v$. It follows that $u \times v \in \mathcal{R}_{p+q}(Z)$.

For given elementary regular $p$-path $x$ on $X$ and $q$-path $y$ on $Y$, denote by $\Pi_{x, y}$ the set of all step-like paths $z$ on $Z$ whose projections on $X$ and $Y$ are $x$ and $y$, respectively. It follows from (6.1) that

$$
\begin{equation*}
e_{x} \times e_{y}=\sum_{z \in \Pi_{x, y}}(-1)^{L(z)} e_{z} . \tag{6.2}
\end{equation*}
$$

It is not difficult to see that the cross product is associative.
Example 6.2. Let us denote the vertices of $X$ by the letters $a, b, c, \ldots$ and the vertices of $Y$ by the integers $0,1,2, \ldots$ so that the vertices of $Z$ can be denoted as chessboard fields, for example, a0, b1, etc. Then we have

$$
e_{a b c} \times e_{012}=e_{a 0 b 0 c 0 c 1 c 2}-e_{a 0 b 0 b 1 c 1 c 2}+e_{a 0 b 0 b 1 b 2 c 2}+e_{a 0 a 1 b 1 c 1 c 2}-e_{a 0 a 1 b 1 b 2 c 2}+e_{a 0 a 1 a 2 b 2 c 2}
$$

as one can see on Fig. 13.


Fig. 13. The staircase $a 0 b 0 b 1 c 1 c 2$ has elevation 1. Hence, $e_{a 0 b 0 b 1 c 1 c 2}$ enters the product $e_{a b c} \times e_{012}$ with the negative sign.

From now on and throughout this section we use the regular boundary operator $\partial$ acting on the chain complex $\left\{\mathcal{R}_{n}\right\}_{n \geq 0}$ (note the difference with Sec. 5 , where we used $\left\{\mathcal{R}_{n}\right\}_{n \geq-1}$ ).

It turns out that the boundary operator $\partial$ satisfies the product rule with respect to the cross product.
Proposition 6.3 (product rule). If $u \in \mathcal{R}_{p}(X)$ and $v \in \mathcal{R}_{q}(Y)$, where $p, q \geq 0$, then

$$
\begin{equation*}
\partial(u \times v)=(\partial u) \times v+(-1)^{p} u \times(\partial v) . \tag{6.3}
\end{equation*}
$$

The proof of this statement is rather involved and can be found in [13, Proposition 4.4].

### 6.2. Path Homologies of Cartesian Product.

Definition 6.4. Given two finite sets $X$ and $Y$ with path complexes $P(X)$ and $P(Y)$, respectively, define on the set $Z=X \times Y$ a path complex $P(Z)$ as follows: the elements of $P(Z)$ are step-like paths on $Z$ whose projections on $X$ and $Y$ belong to $P(X)$ and $P(Y)$, respectively. The path complex $P(Z)$ is called the Cartesian product of the path complexes $P(X)$ and $P(Y)$ and is denoted by $P(X) \square P(Y)$.

In short, a step-like path $z$ on $Z$ is allowed if and only if its projections on $X$ and $Y$ are allowed. In particular, if $x$ and $y$ are elementary allowed paths on $X$ and $Y$, respectively, then all the paths $z \in \Pi_{x, y}$ are allowed on $Z$. It clearly follows from (6.2) that

$$
u \in \mathcal{A}_{p}(X) \text { and } v \in \mathcal{A}_{q}(Y) \Longrightarrow u \times v \in \mathcal{A}_{p+q}(Z)
$$

Furthermore, the following is true.
Proposition 6.5. If $u \in \Omega_{p}(X)$ and $v \in \Omega_{q}(Y)$, then $u \times v \in \Omega_{p+q}(Z)$.

Proof. Indeed, $\partial u$ and $\partial v$ are allowed, whence also $\partial u \times v$ and $u \times \partial v$ are allowed, whence $\partial(u \times v)$ is allowed by the product rule (6.3). It follows that $u \times v \in \Omega_{p+q}(Z)$.

The next theorem is one of the main results of this paper. It gives a complete description of $\partial$-invariant paths on $Z$.
Theorem 6.6. Let $P(X)$ and $P(Y)$ be two regular path complexes. Then for their Cartesian product $P(Z)=P(X) \square P(Y)$ the following isomorphism of chain complexes holds:

$$
\begin{equation*}
\Omega_{\bullet}(Z) \cong \Omega_{\bullet}(X) \otimes \Omega_{\bullet}(Y) \tag{6.4}
\end{equation*}
$$

where the mapping $\Omega_{\bullet}(X) \otimes \Omega_{\bullet}(Y) \rightarrow \Omega_{\bullet}(Z)$ is given by $u \otimes v \mapsto u \times v$.
A more detailed version of (6.4) is the following: for any $r \geq 0$,

$$
\begin{equation*}
\Omega_{r}(Z) \cong \bigoplus_{\{p, q \geq 0: p+q=r\}}\left(\Omega_{p}(X) \otimes \Omega_{q}(Y)\right) \tag{6.5}
\end{equation*}
$$

Consequently, we obtain the Künneth formula

$$
\begin{equation*}
H_{\bullet}(Z) \cong H_{\bullet}(X) \otimes H_{\bullet}(Y) \tag{6.6}
\end{equation*}
$$

i.e., for any $r \geq 0$,

$$
\begin{equation*}
H_{r}(Z) \cong \bigoplus_{\{p, q \geq 0: p+q=r\}}\left(H_{p}(X) \otimes H_{q}(Y)\right) \tag{6.7}
\end{equation*}
$$

The proof of Theorem 6.6 will be given in Sec. 6.5 after a necessary preparation in Sec. 6.4. Before that we consider some examples of Cartesian products.

Let $X$ be a digraph. For simplicity of notation, we denote the set of vertices of $X$ by the same letter $X$, and the set of edges denote by $E_{X}$. Given two digraphs $X$ and $Y$, their Cartesian product is the digraph $Z=X \square Y$, where the set of vertices of $Z$ is the Cartesian product of the sets of vertices of $X$ and $Y$, while the set $E_{Z}$ of edges is defined as follows: $(x, y) \rightarrow\left(x^{\prime}, y^{\prime}\right)$ if and only if either $x \rightarrow x^{\prime}$ and $y=y^{\prime}$, or $y \rightarrow y^{\prime}$ and $x=x^{\prime}$ :


Clearly, any allowed path on $Z$ is step-like, and its projections onto $X$ and $Y$ are also allowed. Hence, the path complex of the digraph $Z$ is the Cartesian product of the path complexes of the digraphs $X$ and $Y$.
Example 6.7. Let $Z=X \square Y$, where $X$ is a 3-cycle and $Y$ is a square, i.e.,

We have

$$
\Omega_{0}(X)=\operatorname{span}\left\{e_{a}, e_{b}, e_{c}\right\}, \quad \Omega_{1}(X)=\operatorname{span}\left\{e_{a b}, e_{b c}, e_{c a}\right\}, \quad \Omega_{p}(X)=\{0\} \text { for } p \geq 2
$$

and

$$
\begin{gathered}
\Omega_{0}(Y)=\operatorname{span}\left\{e_{0}, e_{1}, e_{2}, e_{3}\right\}, \quad \Omega_{1}(Y)=\operatorname{span}\left\{e_{01}, e_{13}, e_{23}, e_{02}\right\} \\
\Omega_{2}(Y)=\operatorname{span}\left\{e_{013}-e_{023}\right\}, \quad \Omega_{q}(Y)=\{0\} \text { for } q \geq 3
\end{gathered}
$$

Hence, by (6.5) we obtain that

$$
\Omega_{3}(Z) \cong \Omega_{1}(X) \otimes \Omega_{2}(Y)
$$

and

$$
\Omega_{3}(Z)=\operatorname{span}\left\{e_{a b} \times\left(e_{013}-e_{023}\right), e_{b c} \times\left(e_{013}-e_{023}\right), e_{c a} \times\left(e_{013}-e_{023}\right)\right\}
$$

Similarly one computes $\Omega_{r}(Z)$ for other values of $r$.
By Proposition 4.3, we have that

$$
H_{1}(X)=\operatorname{span}\left\{e_{a b}+e_{b c}+e_{c a}\right\}, \quad H_{p}(X)=\{0\} \text { for } p \geq 2
$$

and

$$
H_{0}(Y)=\operatorname{span}\left\{e_{0}\right\}, \quad H_{q}(Y)=\{0\} \text { for all } q \geq 1
$$

By (6.7) we obtain that

$$
H_{1}(Z) \cong H_{1}(X) \otimes H_{0}(Y)
$$

and

$$
H_{1}(Z)=\operatorname{span}\left\{\left(e_{a b}+e_{b c}+e_{c a}\right) \times e_{0}\right\} .
$$

It follows also from (6.7) that $H_{r}(Z)=\{0\}$ for all $r \geq 2$.
6.3. Cylinders and Cubes. For any digraph $X$, the cylinder over $X$ is the digraph

$$
\operatorname{Cyl} X:=X \square\left\{{ }^{0} \bullet \rightarrow \bullet^{1}\right\} .
$$

Assuming that the vertices of $X$ are enumerated by $0,1, \ldots, n-1$, we can enumerate the vertices of Cyl $X$ by $0,1, \ldots, 2 n-1$ using the following rule: $(x, 0)$ is assigned the number $x$, while $(x, 1)$ is assigned $x+n$.

Every regular $p$-path $v$ on $X$ has two copies on $\mathrm{Cyl} X: v_{(0)}=v \times e_{0}$ and $v_{(1)}=v \times e_{1}$. Moreover, $v$ gives rise to the following $(p+1)$-path on $\operatorname{Cyl} X: v_{(01)}=v \times e_{01}$, which is called the lifting of $v$. For example, if $v=e_{i_{0} \ldots i_{p}}$, then

$$
\begin{equation*}
v_{(01)}=e_{i_{0} \ldots i_{p}} \times e_{01}=\sum_{k=0}^{p}(-1)^{p-k} e_{i_{0} \ldots i_{k}\left(i_{k}+n\right) \ldots\left(i_{p}+n\right)} . \tag{6.8}
\end{equation*}
$$

By Proposition 6.5, if $v$ is $\partial$-invariant, then $v_{(0)}, v_{(1)}, v_{(01)}$ are also $\partial$-invariant.
Proposition 6.8. For any digraph $X$ and for any $r \geq 0$, we have

$$
\Omega_{r}(\operatorname{Cyl} X) \cong \Omega_{r}(X) \oplus \Omega_{r}(X) \oplus \Omega_{r-1}(X)
$$

where the isomorphism is given by the map $u, v, w \mapsto u_{(0)}+v_{(1)}+w_{(01)}$, for $u, v \in \Omega_{r}(X)$ and $w \in$ $\Omega_{r-1}(X)$. Furthermore, we have

$$
H_{r}(\mathrm{Cyl} X) \cong H_{r}(X),
$$

where the isomorphism is given by the map $u \mapsto u_{(0)}$ for $u \in H_{r}(X)$.
Proof. All claims follow directly from Theorem 6.6 and the knowledge of $\Omega_{*}$ and $H_{*}$ of the digraph $Y=\left\{{ }^{0} \bullet \rightarrow \bullet^{1}\right\}$.

Define for any nonnegative integer $n$ the $n$-cube digraph by

$$
\text { Cube }_{n}=\text { Cyl Cube }_{n-1}, \quad \text { Cube }_{0}=\{0\} .
$$

For example, Cube $_{1}=\left\{{ }^{0} \bullet \bullet^{1}\right\}$, Cube $_{2}$ is a square:

and $\mathrm{Cube}_{3}$ is shown in Fig. 14.
Lifting a $\partial$-invariant 1 -path $v_{1}=e_{01}$ on 1 -cube, we obtain the following $\partial$-invariant 2-path on 2-cube: $v_{2}=e_{013}-e_{023}$. Lifting further $v_{2}$, we obtain the following $\partial$-invariant 3 -path on the 3 -cube:

$$
v_{3}=e_{0457}-e_{0157}+e_{0137}-e_{0467}+e_{0267}-e_{0237}
$$

We obtain by induction a $\partial$-invariant $n$-path $v_{n}$ on Cube $_{n}$ that is a lifting of a $\partial$-invariant ( $n-1$ )-path $v_{n-1}$ on Cube ${ }_{n-1}$. It is easy to see that $v_{n}$ is an alternating sum of $n$ ! elementary terms, corresponding to


Fig. 14. A 3-cube.
partitioning of a geometric $n$-cube into $n$ ! simplexes. It follows from Proposition 6.8 that $\Omega_{n}\left(\right.$ Cube $\left._{n}\right)=$ $\operatorname{span}\left(v_{n}\right)$ so that the path $v_{n}$ represents the $n$-cube. Proposition 6.8 also implies that homology groups of Cube $_{n}$ are trivial except for $H_{0}$.
6.4. Some Properties of $\partial$-Invariant Paths on Products. Here we prove some lemma needed for the proof of Theorem 6.6. Given a regular path complex $P(V)$ on a finite set $V$, we consider the spaces $\mathcal{R}_{n}(V), \mathcal{A}_{n}(V)$, and $\Omega_{n}(V)$ with $n \geq 0$, as well as their direct sums $\mathcal{R}_{\bullet}(V), \mathcal{A}_{\bullet}(V)$, and $\Omega_{\bullet}(V)$.

In all statements, we consider two regular paths complexes $P(X)$ and $P(Y)$ and their Cartesian product $P(Z)=P(X) \square P(Y)$, where $Z=X \times Y$.

Lemma 6.9. Any path $w \in \Omega_{\bullet}(Z)$ admits a representation

$$
\begin{equation*}
w=\sum_{x \in P(X), y \in P(Y)} c^{x y}\left(e_{x} \times e_{y}\right) \tag{6.9}
\end{equation*}
$$

with some coefficients $c^{x y} \in \mathbb{K}$ (only finitely many coefficients are nonvanishing). Furthermore, the coefficients $c^{x y}$ are uniquely determined by $w$.

Proof. First, let us show the uniqueness of $c^{x y}$, which is equivalent to the linear independence of the family $\left\{e_{x} \times e_{y}\right\}$ across all $x \in P(X)$ and $y \in P(Y)$. Indeed, assume that, for some scalars $c^{x y}$,

$$
\sum_{x \in P(X), y \in P(Y)} c^{x y} e_{x} \times e_{y}=0
$$

and prove that $c^{x y}=0$ for any couple $x, y$ as in the summation. Fix such a couple $x, y$ and choose one $z \in \Pi_{x, y}$. Then by (6.1)

$$
\left(e_{x^{\prime}} \times e_{y^{\prime}}\right)^{z}= \begin{cases}(-1)^{L(z)}, & x^{\prime}=x \text { and } y^{\prime}=y \\ 0 & \text { otherwise }\end{cases}
$$

which implies that

$$
\left(\sum_{x^{\prime} \in P(X), y^{\prime} \in P(Y)} c^{x^{\prime} y^{\prime}} e_{x^{\prime}} \times e_{y^{\prime}}\right)^{z}=(-1)^{L(z)} c^{x y}
$$

and, hence, $c^{x y}=0$.
Let us show the existence of the representation (6.9) for any $w \in \Omega_{r}(Z)$ and any $r \geq 0$. As before, for any elementary $r$-path $z$ on $Z, w^{z}$ denotes the $e_{z}$-coordinate of $w$. If $z$ is an elementary $r^{\prime}$-path with $r^{\prime} \neq r$, then set $w^{z}=0$. For any $x \in P(X)$ and $y \in P(Y)$, choose some $z \in \Pi_{x, y}$ and set

$$
\begin{equation*}
c^{x y}=(-1)^{L(z)} w^{z} . \tag{6.10}
\end{equation*}
$$

First, let us show that the value of $c^{x y}$ in (6.10) is independent of the choice of $z \in \Pi_{x, y}$. Set $z=i_{0} \ldots i_{r}$. Let $k$ be an index such that one of the couples $i_{k-1} i_{k}, i_{k} i_{k+1}$ is vertical and the other is horizontal. If
$i_{k-1}=(a, b)$ and $i_{k+1}=\left(a^{\prime}, b^{\prime}\right)$, where $a, a^{\prime} \in X$ and $b, b^{\prime} \in Y$, then $i_{k}$ is either $\left(a^{\prime}, b\right)$ or $\left(a, b^{\prime}\right)$. Denote the other of these two vertices by $i_{k}^{\prime}$, as, for example, on the diagram:


Replacing in the path $z=i_{0} \ldots i_{r}$ the vertex $i_{k}$ by $i_{k}^{\prime}$, we obtain the path $z^{\prime}=i_{0} \ldots i_{k-1} i_{k}^{\prime} i_{k+1} \ldots i_{r}$ that clearly belongs to $\Pi_{x, y}$ and, hence, is allowed. Since the ( $r-1$ )-path $i_{0} \ldots i_{k-1} i_{k+1} \ldots i_{r}$ is regular but nonallowed (as it is not step-like), while $\partial w$ is allowed, we have

$$
\begin{equation*}
(\partial w)^{i_{0} \ldots i_{k-1} i_{k+1} \ldots i_{r}}=0 \tag{6.11}
\end{equation*}
$$

On the other hand, we have by (2.4)

$$
\begin{align*}
& (\partial w)^{i_{0} \ldots i_{k-1} i_{k+1} \ldots i_{r}}=\sum_{j \in Z}\left(\sum_{m=0}^{k-1}(-1)^{m} w^{i_{0} \ldots i_{m-1} j i_{m} \ldots i_{k-1} i_{k+1} \ldots i_{r}}\right.  \tag{6.12}\\
& \quad+(-1)^{k} w^{i_{0} \ldots i_{k-1} j i_{k+1} \ldots i_{r}}  \tag{6.13}\\
& \left.\quad+\sum_{m=k+2}^{r+1}(-1)^{m-1} w^{i_{0} \ldots i_{k-1} i_{k+1} \ldots i_{m-1} j i_{m} \ldots i_{r}}\right) . \tag{6.14}
\end{align*}
$$

All the components of $w$ in the sums (6.12) and (6.14) vanish, since they correspond to nonallowed paths, while $w$ is allowed. The path $i_{0} \ldots i_{k-1} j i_{k+1} \ldots i_{r}$ in the term (6.13) is also nonallowed unless $j=i_{k}$ or $j=i_{k}^{\prime}$ (note that $i_{k}$ and $i_{k}^{\prime}$ are uniquely determined by $i_{k-1}$ and $i_{k+1}$ ). Hence, the only nonzero terms in (6.12)-(6.14) are $w^{i_{0} \ldots i_{k-1} i_{k} i_{k+1} \ldots i_{r}}=w^{z}$ and $w^{i_{0} \ldots i_{k-1} i_{k}^{\prime} i_{k+1} \ldots i_{r}}=w^{z^{\prime}}$. Combining (6.11) and (6.12)-(6.14), we obtain $0=w^{z}+w^{z^{\prime}}$. Since $L\left(z^{\prime}\right)=L(z) \pm 1$, it follows that

$$
\begin{equation*}
(-1)^{L\left(z^{\prime}\right)} w^{z^{\prime}}=(-1)^{L(z)} w^{z} . \tag{6.15}
\end{equation*}
$$

The transformation $z \mapsto z^{\prime}$ described above, allows us to obtain from a given $z \in \Pi_{x, y}$ in a finite number of steps any other path in $\Pi_{x, y}$. Since the quantity $(-1)^{L(z)} w^{z}$ does not change under this transformation, it follows that it does not depend on a particular choice of $z \in \Pi_{x, y}$, which was claimed. Hence, the coefficients $c^{x y}$ are well-defined by (6.10).

Finally, let us show that the equality (6.9) holds with the coefficients $c^{x y}$ from (6.10). By (6.2) we have

$$
e_{x} \times e_{y}=\sum_{z \in \Pi_{x}, y}(-1)^{L(z)} e_{z}
$$

Using (6.10), we obtain

$$
\begin{aligned}
\sum_{x \in P(X), y \in P(Y)} c^{x y}\left(e_{x} \times e_{y}\right)= & \sum_{x \in P(X), y \in P(Y)} c^{x y} \sum_{z \in \Pi_{x, y}}(-1)^{L(z)} e_{z} \\
& =\sum_{x \in P(X), y \in P(Y)} \sum_{z \in \Pi_{x, y}} w^{z} e_{z}=\sum_{z \in P(Z)} w^{z} e_{z}=w
\end{aligned}
$$

which finishes the proof.

Corollary 6.10. Any path $w \in \Omega .(Z)$ admits representations

$$
\begin{equation*}
w=\sum_{x \in P(X)} e_{x} \times a^{x}=\sum_{y \in P(Y)} b^{y} \times e_{y}, \tag{6.16}
\end{equation*}
$$

where $a^{x} \in \Omega_{\bullet}(Y)$ and $b^{y} \in \Omega_{\bullet}(X)$ are uniquely determined.
Proof. It follows from (6.9) that

$$
w=\sum_{x \in P(X)} e_{x} \times a^{x}
$$

where

$$
a^{x}=\sum_{y \in P(Y)} c^{x y} e_{y} \in \mathcal{A}_{\bullet}(Y) .
$$

It is obvious that $a^{x}$ are uniquely determined as so are the coefficients $c^{x y}$. Let us show that, in fact, $a^{x} \in \Omega_{\bullet}(Y)$. Let us define the coefficients $\delta_{x^{\prime}}^{x} \in\{0,1,-1\}$ by

$$
\begin{equation*}
\partial e_{x}=\sum_{x^{\prime} \in R(X)} \delta_{x}^{x^{\prime}} e_{x^{\prime}} \tag{6.17}
\end{equation*}
$$

Also, if $x \in P_{p}(X)$, then set $\varepsilon_{x}=(-1)^{p}$. By the product rule (6.3) and by (6.17) we have that

$$
\begin{align*}
\partial w & =\sum_{x \in P(X)} \partial e_{x} \times a^{x}+\varepsilon_{x} e_{x} \times \partial a^{x} \\
& =\sum_{x \in P(X)} \sum_{x^{\prime} \in R(X)} \delta_{x}^{x^{\prime}} e_{x^{\prime}} \times a^{x}+\sum_{x \in P(X)} \varepsilon_{x} e_{x} \times \partial a^{x} \\
& =\sum_{x \in R(X)} \sum_{x^{\prime} \in P(X)} \delta_{x^{\prime}}^{x} e_{x} \times a^{x^{\prime}}+\sum_{x \in P(X)} \varepsilon_{x} e_{x} \times \partial a^{x} \\
& =\sum_{x \in P(X)} e_{x} \times\left(\sum_{x^{\prime} \in P(X)} \delta_{x^{\prime}}^{x} a^{x^{\prime}}+\varepsilon_{x} \partial a^{x}\right)  \tag{6.18}\\
& +\sum_{x \in R(X) \backslash P(X)} e_{x} \times\left(\sum_{x^{\prime} \in P(X)} \delta_{x^{\prime}}^{x} a^{x^{\prime}}\right) . \tag{6.19}
\end{align*}
$$

Every elementary path on $Z$ that is present in the full expansion of the sums (6.18) and (6.19) has the $X$-projection equal to $x$. Since in (6.18) $x$ is allowed, while in (6.19) it is nonallowed, there is no cross cancellation of the elementary paths in (6.18) and (6.19). Since every elementary path in (6.19) is nonallowed, while the sum $\partial w$ of (6.18) and (6.19) is allowed, we see that the sum in (6.19) vanishes.

On the other hand, since $\partial w \in \Omega_{\bullet}(Z)$, we have by Lemma 6.9 a representation

$$
\partial w=\sum_{x \in P(X)} e_{x} \times \tilde{a}^{x},
$$

where $\tilde{a}^{x} \in \mathcal{A} \cdot(Y)$. Comparison with (6.18) shows that

$$
\tilde{a}^{x}=\sum_{x^{\prime} \in P(X)} \delta_{x^{\prime}}^{x} a^{x^{\prime}}+\varepsilon_{x} \partial a^{x} .
$$

Since $a^{x^{\prime}} \in \mathcal{A}_{\bullet}(Y)$, it follows that $\partial a^{x} \in \mathcal{A}_{\bullet}(Y)$, which proves that $a^{x} \in \Omega_{\bullet}(Y)$. The second identity in (6.16) is proved similarly.

In the next lemma, we use the $\mathbb{K}$-scalar product $[\cdot, \cdot]$ of paths that was introduced in Sec. 5.5 (see (5.18) and (5.19)).

Lemma 6.11. If $u \in \Omega_{p}^{\perp}(X)$ and $v \in \mathcal{A}_{q}(Y)$, then $u \times v \in \Omega_{r}^{\perp}(Z)$, where $r=p+q$. Similarly, if $u \in \mathcal{A}_{p}(X)$ and $v \in \Omega_{q}^{\perp}(Y)$, then $u \times v \in \Omega_{r}^{\perp}(Z)$.
Proof. We need to prove that, for any $w \in \Omega_{r}(Z)$,

$$
\begin{equation*}
[u \times v, w]=0 \tag{6.20}
\end{equation*}
$$

assuming that $u \in \Omega_{p}^{\perp}(X)$ (the second claim is proved similarly). We have

$$
\begin{aligned}
{[u \times v, w] } & =\sum_{z \in P_{r}(Z)}(u \times v)^{z} w^{z} \\
& =\sum_{z \in P_{r}(Z)}(-1)^{L(z)} u^{x} v^{y} w^{z} \quad(x, y \text { are projections of } z) \\
& =\sum_{x \in P_{p}(X)} \sum_{u \in P_{q}(Y)} \sum_{z \in \Pi_{x, y}}(-1)^{L(z)} u^{x} v^{y} w^{z} .
\end{aligned}
$$

By Corollary 6.10 , the path $w$ is a sum of the terms $\varphi \times \psi$, where $\varphi \in \Omega_{\bullet}(X)$ and $\psi \in \mathcal{A}_{\bullet}(Y)$, so that it suffices to prove (6.20) for $w=\varphi \times \psi$. Let $\varphi \in \Omega_{p}(X)$ and, hence, $\psi \in \mathcal{A}_{q}(Y)$. Then we have by (6.1)

$$
w^{z}=(-1)^{L(z)} \varphi^{x} \psi^{y}
$$

and, hence,

$$
[u \times v, w]=\sum_{x \in P_{p}(X)} \sum_{y \in P_{q}(Y)} \sum_{z \in \Pi_{x}, y} u^{x} \varphi^{x} v^{y} \psi^{y} .
$$

Since

$$
\sum_{x \in P_{p}(X)} u^{x} \varphi^{x}=[u, \varphi]=0
$$

we obtain (6.20). If $\varphi \in \Omega_{p^{\prime}}$ with $p^{\prime} \neq p$, then $w^{z}=0$ for any $z \in \Pi_{x, y}$ with $x \in P_{p}(X)$, and (6.20) is trivially satisfied.
6.5. Proof of the Künneth Formula for Product. Here we prove Theorem 6.6. The major part of the proof of Theorem 6.6 is contained in the following Theorem 6.12 that is similar to Theorem 5.15 for join. Since the proofs of Theorems 6.12 and 5.15 are practically identical, we prefer to give a detailed proof of Theorem 6.12 for the product and sketch of the proof of Theorem 5.15 for join at the end of this section.
Theorem 6.12. Let $P(X)$ and $P(Y)$ be two regular path complexes and let $P(Z)=P(X) \square P(Y)$ be their Cartesian product. Then any $\partial$-invariant path $w$ on $Z$ admits a representation in the form

$$
\begin{equation*}
w=\sum_{i=1}^{k} u_{i} \times v_{i} \tag{6.21}
\end{equation*}
$$

for some finite $k$, where $u_{i}$ and $v_{i}$ are $\partial$-invariant paths on $X$ and $Y$, respectively.
Proof. The representation (6.21) is simple in a special case where the path complexes $P(X)$ and $P(Y)$ are perfect, i.e., when all allowed paths are $\partial$-invariant. Indeed, by Lemma 6.9, any $w \in \Omega_{r}(Z)$ admits a representation in the form (6.9), where $e_{x}$ and $e_{y}$ are allowed paths on $X$ and $Y$, respectively. By the assumption of the perfectness of $P(X)$ and $P(Y)$, the paths $e_{x}$ and $e_{y}$ are $\partial$-invariant. Thus, (6.9) implies (6.21).

For arbitrary path complexes $P(X)$ and $P(Y)$, the previous argument does not work, since $e_{x} \times e_{y}$ does not have to be $\partial$-invariant. Hence, we need a more elaborate strategy. Given two subspaces $U \subset \mathcal{A}_{p}(X)$ and $V \subset \mathcal{A}_{q}(Y)$, denote by $U \times V$ the subspace of $\mathcal{A}_{r}(Z)$ that is spanned by all products $u \times v$ with $u \in U$ and $v \in V$. For any $r \geq 0$, set

$$
\begin{equation*}
\tilde{\Omega}_{r}(Z)=\sum_{p+q=r} \Omega_{p}(X) \times \Omega_{q}(Y) \tag{6.22}
\end{equation*}
$$

i.e., $\tilde{\Omega}_{r}(Z)$ is the space of paths on $Z$ that is spanned by all paths of the form $u \times v$, where $u \in \Omega_{p}(X)$ and $v \in \Omega_{q}(Y)$ with some $p, q \geq 0$ such that $p+q=r$. By Proposition 6.5 , we have $u \times v \in \Omega_{r}(Z)$ whence it follows that

$$
\tilde{\Omega}_{r}(Z) \subset \Omega_{r}(Z)
$$

The existence of the representation (6.21) is equivalent to the opposite inclusion, i.e., to the identity

$$
\tilde{\Omega}_{r}(Z)=\Omega_{r}(Z)
$$

Clearly, it suffices to show that

$$
\begin{equation*}
\operatorname{dim} \Omega_{r}(Z) \leq \operatorname{dim} \tilde{\Omega}_{r}(Z) \tag{6.23}
\end{equation*}
$$

Consider also the space

$$
\tilde{\mathcal{A}}_{r}(Z)=\sum_{p+q=r} \mathcal{A}_{p}(X) \times \mathcal{A}_{q}(Y)
$$

By definition of the cross product, all the paths in $\tilde{\mathcal{A}}_{r}(Z)$ are allowed, i.e.,

$$
\tilde{\mathcal{A}}_{r}(Z) \subset \mathcal{A}_{r}(Z)
$$

By Lemma 6.9, any path from $\Omega_{r}(Z)$ is a linear combination of paths $e_{x} \times e_{y}$ with allowed $x, y$, which means that

$$
\Omega_{r}(Z) \subset \tilde{\mathcal{A}}_{r}(Z)
$$

In particular, we have also

$$
\tilde{\Omega}_{r}(Z) \subset \tilde{\mathcal{A}}_{r}(Z)
$$

Fix some triple $p, q, r$ with $p+q=r$ and consider the following spaces (cf. (5.19)):

- $\Omega_{p}^{\perp}(X)$, an orthogonal complement of $\Omega_{p}(X)$ in $\mathcal{A}_{p}(X)$;
- $\Omega_{q}^{\perp}(Y)$, an orthogonal complement of $\Omega_{q}(Y)$ in $\mathcal{A}_{q}(Y)$;
- $\Omega_{r}^{\perp}(Z)$, an orthogonal complement of $\Omega_{r}(Z)$ in $\tilde{\mathcal{A}}_{r}(Z)$ (warning: not in $\mathcal{A}_{r}(Z)$ !).

First, consider the case where the field $\mathbb{K}$ is $\mathbb{R}$ or $\mathbb{Q}$. In this case, a linear space with a $\mathbb{K}$-scalar product is represented as a direct sum of a subspace with its orthogonal complement. For each $u \in \mathcal{A}_{p}(X)$ consider a decomposition

$$
\begin{equation*}
u=u_{\Omega}+u_{\perp}, \tag{6.24}
\end{equation*}
$$

where $u_{\Omega} \in \Omega_{p}(X)$ and $u_{\perp} \in \Omega_{p}^{\perp}(X)$, and a similar decomposition $v=v_{\Omega}+v_{\perp}$ for $v \in \mathcal{A}_{q}(Y)$. Then we have

$$
u \times v=u_{\Omega} \times v_{\Omega}+u_{\Omega} \times v_{\perp}+u_{\Omega} \times v_{\perp}+u_{\perp} \times v_{\perp} .
$$

Here $u_{\Omega} \times v_{\Omega} \in \tilde{\Omega}_{r}(Z)$, while by Lemma 6.11 all other terms in the right-hand side belong to $\Omega_{r}^{\perp}(Z)$, whence it follows that

$$
u \times v \in \tilde{\Omega}_{r}(Z)+\Omega_{r}^{\perp}(Z)
$$

Since $\tilde{\mathcal{A}}_{r}(Z)$ is spanned by the products $u \times v$, where $u$ and $v$ are allowed, we obtain that

$$
\tilde{\mathcal{A}}_{r}(Z)=\tilde{\Omega}_{r}(Z)+\Omega_{r}^{\perp}(Z)
$$

Comparing with the decomposition

$$
\tilde{\mathcal{A}}_{r}(Z)=\Omega_{r}(Z) \oplus \Omega_{r}^{\perp}(Z),
$$

we obtain (6.23).
Now consider the most general case of an arbitrary field $\mathbb{K}$. Let us introduce the following notation:

$$
\begin{array}{lll}
a_{p}=\operatorname{dim} \mathcal{A}_{p}(X), & a_{q}=\operatorname{dim} \mathcal{A}_{q}(Y), & a_{r}=\operatorname{dim} \tilde{\mathcal{A}}_{r}(Z), \\
\omega_{p}=\operatorname{dim} \Omega_{p}(X), & \omega_{q}=\operatorname{dim} \Omega_{q}(Y), & \omega_{r}=\operatorname{dim} \Omega_{r}(Z),
\end{array}
$$

and observe that

$$
\begin{equation*}
\operatorname{dim} \Omega_{p}^{\perp}(X)=a_{p}-\omega_{p}, \quad \operatorname{dim} \Omega_{q}^{\perp}(Y)=a_{q}-\omega_{q}, \quad \operatorname{dim} \Omega_{r}^{\perp}(Z)=a_{r}-\omega_{r} \tag{6.25}
\end{equation*}
$$

Let us prove that

$$
\begin{equation*}
a_{r}=\sum_{p+q=r} a_{p} a_{q} . \tag{6.26}
\end{equation*}
$$

Indeed, $\mathcal{A}_{p}(X)$ is spanned by all elementary paths $e_{x}$ with $x \in P_{p}(X)$ and $\mathcal{A}_{q}(Y)$ is spanned by all elementary paths $e_{y}$ with $y \in P_{q}(Y)$. Therefore, $\tilde{\mathcal{A}}_{r}(Z)$ is spanned by all products $e_{x} \times e_{y}$, where $x$ and $y$ as above are considered for all possible $p$ and $q$ such that $p+q=r$. The number of such products $e_{x} \times e_{y}$ is equal to the right-hand side of (6.26), so that the identity (6.26) follows from the linear independence of the family $\left\{e_{x} \times e_{y}\right\}$ (cf. Lemma 6.9).

It follows from the above argument that

$$
\begin{equation*}
\operatorname{dim}\left(\mathcal{A}_{p}(X) \times \mathcal{A}_{q}(Y)\right)=a_{p} a_{q} \tag{6.27}
\end{equation*}
$$

and that

$$
\begin{equation*}
\tilde{\mathcal{A}}_{r}(Z)=\bigoplus_{p+q=r}\left(\mathcal{A}_{p}(X) \times \mathcal{A}_{q}(Y)\right) . \tag{6.28}
\end{equation*}
$$

Before we can proceed further, let us prove two claims about properties of subspaces of $\mathcal{A}_{p}(X)$ and $\mathcal{A}_{q}(Y)$.
Claim 1. For any two subspaces $U \subset \mathcal{A}_{p}(X)$ and $V \subset \mathcal{A}_{q}(Y)$, we have

$$
\begin{equation*}
\operatorname{dim}(U \times V)=\operatorname{dim} U \operatorname{dim} V \tag{6.29}
\end{equation*}
$$

Indeed, let $u_{1}, u_{2}, \ldots, u_{k}$ be a basis in $U$ and $v_{1}, \ldots, v_{l}$ be a basis in $V$. Then $U \times V$ is spanned by all products $u_{i} \times v_{j}$, so that

$$
\begin{equation*}
\operatorname{dim}(U \times V) \leq k l . \tag{6.30}
\end{equation*}
$$

Let us complement the basis $\left\{u_{i}\right\}$ to a basis in $\mathcal{A}_{p}(X)$ by adding additional paths $u_{1}^{\prime}, \ldots, u_{k^{\prime}}^{\prime}$, and, similarly, complement $\left\{v_{j}\right\}$ to a basis in $\mathcal{A}_{q}(Y)$ by adding $v_{1}^{\prime}, \ldots, v_{l^{\prime}}^{\prime}$. Set $U^{\prime}=\operatorname{span}\left\{u_{i}^{\prime}\right\}$ and $V^{\prime}=\operatorname{span}\left\{v_{j}^{\prime}\right\}$. Then

$$
\begin{equation*}
\mathcal{A}_{p}(X) \times \mathcal{A}_{q}(Y)=\left(U+U^{\prime}\right) \times\left(V+V^{\prime}\right)=U \times V+U \times V^{\prime}+U^{\prime} \times V+U^{\prime} \times V^{\prime}, \tag{6.31}
\end{equation*}
$$

whence by (6.27) and (6.30) we have

$$
\begin{align*}
& a_{p} a_{q} \leq \operatorname{dim}(U \times V)+\operatorname{dim}\left(U \times V^{\prime}\right)+\operatorname{dim}\left(U^{\prime} \times V\right)+\operatorname{dim}\left(U^{\prime} \times V^{\prime}\right)  \tag{6.32}\\
& \quad \leq k l+k l^{\prime}+k^{\prime} l+k^{\prime} l^{\prime} .
\end{align*}
$$

The right-hand side here is equal to $\left(k+k^{\prime}\right)\left(l+l^{\prime}\right)=a_{p} a_{q}$; this implies that we must have the equality in (6.32), in particular, $\operatorname{dim}(U \times V)=k l$, which proves (6.29).
Claim 2. For any two subspaces $U \subset \mathcal{A}_{p}(X)$ and $V \subset \mathcal{A}_{q}(Y)$, we have

$$
\begin{equation*}
\left(U \times \mathcal{A}_{q}(Y)\right) \cap\left(A_{p}(X) \times V\right)=U \times V \tag{6.33}
\end{equation*}
$$

Indeed, it follows from Claim 1 that the sum on the right-hand side of (6.31) is direct and, hence,

$$
U \times \mathcal{A}_{q}(Y)=U \times\left(V \oplus V^{\prime}\right)=(U \times V) \oplus\left(U \times V^{\prime}\right)
$$

and

$$
A_{p}(X) \times V=\left(U \oplus U^{\prime}\right) \times V=(U \times V) \oplus\left(U^{\prime} \times V\right)
$$

whence (6.33) follows.
By Lemma 6.11, we have that

$$
\Omega_{p}^{\perp}(X) \times \mathcal{A}_{q}(Y) \subset \Omega_{r}^{\perp}(Z)
$$

and
so that

$$
\begin{equation*}
\sum_{p+q=r}\left[\left(\Omega_{p}^{\perp}(X) \times \mathcal{A}_{q}(Y)\right)+\left(\mathcal{A}_{p}(X) \times \Omega_{q}^{\perp}(Y)\right)\right] \subset \Omega_{r}^{\perp}(Z) \tag{6.34}
\end{equation*}
$$

(see Fig. 15).


Fig. 15. Space $\tilde{\mathcal{A}}_{r}(Z)$ and its subspaces $\Omega_{r}^{\perp}(Z), \mathcal{A}_{p}(X) \times \mathcal{A}_{q}(Y)$ (two instances), and $\Omega_{p}^{\perp}(X) \times \mathcal{A}_{q}(Y)+\mathcal{A}_{p}(X) \times \Omega_{q}^{\perp}(Y)$.

Note that the space in the square brackets in (6.34) is a subspace of $\mathcal{A}_{p}(X) \times \mathcal{A}_{q}(Y)$. It follows from (6.28) that the sum $\sum$ in (6.34) is direct, which implies an inequality

$$
\begin{equation*}
\sum_{p+q=r} \operatorname{dim}\left[\left(\Omega_{p}^{\perp}(X) \times \mathcal{A}_{q}(Y)\right)+\left(\mathcal{A}_{p}(X) \times \Omega_{q}^{\perp}(Y)\right)\right] \leq \operatorname{dim} \Omega_{r}^{\perp}(Z) \tag{6.35}
\end{equation*}
$$

By Claim 2, the subspaces $\Omega_{p}^{\perp}(X) \times \mathcal{A}_{q}(Y)$ and $\mathcal{A}_{p}(X) \times \Omega_{q}^{\perp}(Y)$ have intersection $\Omega_{p}^{\perp}(X) \times \Omega_{q}^{\perp}(Y)$, whence

$$
\begin{align*}
& \operatorname{dim}\left[\left(\Omega_{p}^{\perp}(X) \times \mathcal{A}_{q}(Y)\right)+\left(\mathcal{A}_{p}(X) \times \Omega_{q}^{\perp}(Y)\right)\right] \\
& \quad=\operatorname{dim}\left(\Omega_{p}^{\perp}(X) \times \mathcal{A}_{q}(Y)\right)+\operatorname{dim}\left(\mathcal{A}_{p}(X) \times \Omega_{q}^{\perp}(Y)\right)-\operatorname{dim}\left(\Omega_{p}^{\perp}(X) \times \Omega_{q}^{\perp}(Y)\right) \tag{6.36}
\end{align*}
$$

Using (6.25), we obtain that the right-hand side of (6.36) is equal to

$$
\left(a_{p}-\omega_{p}\right) a_{q}+a_{p}\left(a_{q}-\omega_{q}\right)-\left(a_{p}-\omega_{p}\right)\left(a_{q}-\omega_{q}\right)=a_{p} a_{q}-\omega_{p} \omega_{q} .
$$

Substituting this into (6.35) yields

$$
\sum_{p+q=r}\left(a_{p} a_{q}-\omega_{p} \omega_{q}\right) \leq a_{r}-\omega_{r},
$$

which together with (6.26) implies that

$$
\omega_{r} \leq \sum_{p+q=r} \omega_{p} \omega_{q} .
$$

Finally, we are left to observe that, by (6.22),

$$
\sum_{p+q=r} \omega_{p} \omega_{q}=\operatorname{dim} \tilde{\Omega}_{r}(Z),
$$

which finishes the proof of inequality (6.23).
Proof of Theorem 6.6. The isomorphism (6.6) follows from (6.4) and (5.3), so we only need to prove (6.4). Consider the tensor product of the graded linear spaces

$$
\mathcal{A}_{\bullet}(X, Y):=\mathcal{A}_{\bullet}(X) \otimes \mathcal{A}_{\bullet}(Y)
$$

and a linear mapping

$$
\Phi: \mathcal{A}_{r}(X, Y) \rightarrow \mathcal{A}_{r}(Z)
$$

defined on the basis by

$$
\Phi\left(e_{x} \otimes e_{y}\right)=e_{x} \times e_{y}
$$

for all $x \in P_{p}(X)$ and $y \in P_{q}(Y)$ with $p+q=r$. In fact, we have

$$
\Phi\left(\mathcal{A}_{r}(X, Y)\right)=\tilde{\mathcal{A}}_{r}(Z)
$$

where $\tilde{\mathcal{A}}_{r}(Z)$ is defined in (6.28). It follows from the argument in the proof of Theorem 6.12 that the mapping $\Phi$ is injective.

Now consider the tensor product of the chain complexes

$$
\Omega_{\bullet}(X, Y):=\Omega_{\bullet}(X) \otimes \Omega_{\bullet}(Y),
$$

i.e., set for any $r \geq 0$

$$
\Omega_{r}(X, Y)=\bigoplus_{\{p, q \geq 0: p+q=r\}}\left(\Omega_{p}(X) \otimes \Omega_{q}(Y)\right)
$$

and define the boundary operator $\partial$ on $\Omega_{r}(X, Y)$ by (5.2). It follows from the definition of $\Phi$ and $\tilde{\Omega}_{r}(Z)$ that

$$
\Phi\left(\Omega_{r}(X, Y)\right)=\tilde{\Omega}_{r}(Z)
$$

Since by Theorem 6.12

$$
\begin{equation*}
\tilde{\Omega}_{r}(Z)=\Omega_{r}(Z) \tag{6.37}
\end{equation*}
$$

we obtain that the mapping $\Phi$ provides a linear isomorphism of the spaces $\Omega_{\bullet}(X, Y)$ and $\Omega_{\bullet}(Z)$. Moreover, $\Phi$ commutes with $\partial$, which follows from (5.2) and the product rule of Proposition 6.3. Hence, $\Phi$ is an isomorphism of the chain complexes $\Omega_{\bullet}(X, Y)$ and $\Omega_{\bullet}(Z)$, which finishes the proof.

Proof of Theorem 5.15. The proof of Theorem 5.15 is obtained from the proof of Theorem 6.12 by a "search and replace" operation. Indeed, we need only to make the following changes in the proof of Theorem 6.12:

- remove everywhere the sign $\times$ of cross product, so that the cross product $u \times v$ of two paths $u$ on $X$ and $v$ on $Y$ will be replaced by their join $u v$. The same applies to the cross product $U \times V$ of subspaces $U \subset \mathcal{A}_{p}(X)$ and $V \subset \mathcal{A}_{q}(Y)$ : it is replaced by the join $U V$ that is by the space spanned by all joins $u v$ with $u \in U$ and $v \in V$;
- replace everywhere $\mathcal{A}_{p}(X)$ by $\mathcal{A}_{p}^{\prime}(X)$ and $\Omega_{p}(X)$ by $\Omega_{p}^{\prime}(X)$;
- replace the (implicitly used) range $p \geq 0, q \geq 0$ of the parameters $p$ and $q$ by $p \geq 0, q \geq-1$.

Let us verify that after these changes the proof remains valid. For that we only need to trace the places where the properties of the cross product were used and replace them by the corresponding properties (and references) of join. Here is the list of the properties of cross product that were used in the proof of Theorem 6.12, and their replacements for join.
(1) If $u \in \mathcal{A}_{p}(X)$ and $v \in \mathcal{A}_{q}(Y)$, then $u \times v \in \mathcal{A}_{p+q}(Z)$, which follows immediately from the definition of the cross product. The same property is true for join: if $u \in \mathcal{A}_{p}^{\prime}(X)$ and $v \in \mathcal{A}_{q}(Y)$, then $u v \in \mathcal{A}_{p+q}(Z)$, which is also a trivial consequence of the definition.
(2) Proposition 6.5: if $u \in \Omega_{p}(X)$ and $v \in \Omega_{q}(Y)$, then $u \times v \in \Omega_{p+q}(Z)$. It should be replaced by Proposition 5.4: if $u \in \Omega_{p}^{\prime}(X)$ and $v \in \Omega_{q}(Y)$, then $u v \in \Omega_{p+q}(Z)$.
(3) Lemma 6.9: any path $w \in \Omega_{r}(Z)$ is a unique linear combination of the products $e_{x} \times e_{y}$, where $x$ is an allowed path on $X$ and $y$ is an allowed path on $Y$. It should be replaced by the following property of join: any path $w \in \mathcal{A}_{r}(Z)$ is a unique linear combination of joins $e_{x} e_{y}$ with $x$ and $y$ as above, which is a trivial consequence of the definition of join of path complexes.
(4) Lemma 6.11: if $u \in \Omega_{p}^{\perp}(X)$ and $v \in \mathcal{A}_{q}(Y)$, then $u \times v \in \Omega_{p+q}^{\perp}(Z)$. It should be replaced by Lemma 5.14: if $u \in \Omega_{p}^{\perp \perp}(X)$ and $v \in \mathcal{A}_{q}(Y)$, then $u v \in \Omega_{p+q}^{\perp}(Z)$.
By these observations we finish the proof.
The first author was partially supported by SFB 701 of the German Research Council, Visiting Grants of Harvard University, and MSC of Tsinghua University. The second author was supported by the Fundamental Research Funds for the Central Universities and the Research Funds of Renmin University
of China (11XNI004). The third author was partially supported by SFB 701 of the German Research Council. The fourth author was partially supported by the grant "Geometry and Topology of Complex Networks," No. FA-9550-13-1-0097.

## REFERENCES

1. E. Babson, H. Barcelo, M. de Longueville, and R. Laubenbacher, "Homotopy theory of graphs," J. Algebraic Combin., 24, 31-44 (2006).
2. H. Barcelo, X. Kramer, R. Laubenbacher, and Ch. Weaver, "Foundations of a connectivity theory for simplicial complexes," Adv. Appl. Math., 26, 97-128 (2001).
3. N. Bourbaki, Elements of Mathematics. Algebra I. Chapters 1-3 (1989).
4. B. Chen, S.-T. Yau, and Y.-N. Yeh, "Graph homotopy and Graham homotopy," Discrete Math., 241, 153-170 (2001).
5. A. Dimakis and F. Müller-Hoissen, "Differential calculus and gauge theory on finite sets," J. Phys. A, Math. Gen., 27, No. 9, 3159-3178 (1994).
6. A. Dimakis and F. Müller-Hoissen, "Discrete differential calculus: graphs, topologies, and gauge theory," J. Math. Phys., 35, No. 12, 6703-6735 (1994).
7. M. Gerstenhaber and S. D. Schack, "Simplicial cohomology is Hochschild cohomology," J. Pure Appl. Algebra, 30, 143-156 (1983).
8. A. Grigor'yan, Y. Lin, Yu. Muranov, and S.-T. Yau, Homologies of Path Complexes and Digraphs, arXiv:1207.2834v4 (2013).
9. A. Grigor'yan, Y. Lin, Yu. Muranov, and S.-T. Yau, "Homotopy theory for digraphs," Pure Appl. Math. Quater., 10, No. 4, 619-674 (2014).
10. A. Grigor'yan, Yu. Muranov, and S.-T. Yau, "Graphs associated with simplicial complexes," Homology, Homotopy Appl., 16, No. 1, 295-311 (2014).
11. A. Grigor'yan, Yu. Muranov, and S.-T. Yau, "On a cohomology of digraphs and Hochschild cohomology," J. Homotopy Relat. Struct., 11, No. 2, 209-230 (2016).
12. A. Grigor'yan, Yu. Muranov, and S.-T. Yau, "Cohomology of digraphs and (undirected) graphs," Asian J. Math., 19, 887-932 (2015).
13. A. Grigor'yan, Yu. Muranov, and S.-T. Yau, "Homologies of digraphs and Künneth formulas," Comm. Anal. Geom. (2016).
14. D. Happel, "Hochschild cohomology of finite-dimensional algebras," in: Sém. d'Algèbre Paul Dubreil et Marie-Paul Malliavin, Lect. Notes Math., Vol. 1404, Springer, Berlin (1989), pp. 108-126.
15. A. V. Ivashchenko, "Contractible transformations do not change the homology groups of graphs," Discrete Math., 126, 159-170 (1994).
16. S. MacLane, Homology, Grundlag. Math. Wissensch., Vol. 114, Springer, Berlin (1963).
17. A. Tahbaz-Salehi and A. Jadbabaie, "Distributed coverage verification in sensor networks without location information," IEEE Trans. Automatic Control, 55, 1837-1849 (2010).
18. M. E. Talbi and D. Benayat, "Homology theory of graphs," Mediterranean J. Math., 11, 813-828 (2014).

Alexander Grigor'yan
Department of Mathematics, University of Bielefeld, 33613 Bielefeld, Germany;
Institute of Control Sciences of Russian Academy of Sciences, Moscow, Russia
E-mail: grigor@math.uni-bielefeld.de
Yong Lin
Department of Mathematics, Renmin University of China, Beijing 100872, P.R. China
E-mail: linyong01@ruc.edu.cn

Yuri Muranov
Faculty of Mathematics and Computer Sciences, University of Warmia and Mazury, Olsztyn, Poland E-mail: muranov@matman.uwm.edu.pl
Shing-Tung Yau
Department of Mathematics, Harvard University, Cambridge MA 02138, USA
E-mail: yau@math.harvard.edu

