

Global-in-time Stability of Hartmann Layer in Two Space Dimension

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Abstract: In this paper, we prove global existence of solutions with Gevrey regularity to the 2D MHD boundary layer equations in the mixed Prandtl and Hartmann regime derived by formal multi-scale expansion in [9]. The analysis shows that the combined effect of the magnetic diffusivity and transversal magnetic field to the boundary leads to a linear damping on the tangential velocity field in the Prandtl regime near the boundary. Precisely, such damping term on tangential velocity yields global in time energy estimate in Gevrey norms in the tangential space variable for the perturbation of the classical Hartmann profile.

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1 Introduction

The following mixed Prandtl and Hartmann boundary layer equations from the classical incompressible MHD system derived in [9] for flat boundary in two space dimension when the physical parameters such as Reynolds number, magnetic Reynolds number and the Hartmann number satisfy some constraints in the high Reynolds numbers limit.

$$\begin{cases} \partial_t u_1 + u_1 \partial_x u_1 + u_2 \partial_y u_1 = \partial_y b_1 + \partial_y^2 u_1, \\ \partial_y u_1 + \partial_y^2 b_1 = 0, \\ \partial_x u_1 + \partial_y u_2 = 0, \end{cases} \quad (1.1)$$

with $x \in \mathbb{R}, y \in \mathbb{R}_+$. (u_1, u_2) denotes the velocity boundary layer functions and b_1 is the magnetic field boundary layer.

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For this system, there is a well known solution called Hartmann layer. In this paper, we will study the global-in-time stability of this Hartmann layer when the solution is in the Gevrey function space. For this, we consider the system (1.1) with initial data denoted by

$$u_1(t = 0, x, y) = u_{10}(x, y), \quad (1.2)$$

and the no-slip boundary condition

$$u_1|_{y=0} = 0, \quad u_2|_{y=0} = 0. \quad (1.3)$$

The far-field conditions are taken as the uniform constant states. Consequently, there is no pressure term appearing in equation of (1.1)₁.

$$\lim_{y \rightarrow +\infty} u_1 = \bar{u}, \quad \lim_{y \rightarrow +\infty} b_1 = \bar{b}. \quad (1.4)$$

Integration the equation of (1.1)₂ over $[y, +\infty]$ yields that

$$-u_1(t, x, y) + \bar{u} = \partial_y b_1. \quad (1.5)$$

Thus, the equations (1.1) can be reduced into the following form.

$$\begin{cases} \partial_t u_1 + u_1 \partial_x u_1 + u_2 \partial_y u_1 = -u_1(t, x, y) + \bar{u} + \partial_y^2 u_1, \\ \partial_x u_1 + \partial_y u_2 = 0. \end{cases} \quad (1.6)$$

It is not difficult to find that

$$u_1 = (1 - e^{-y})\bar{u}, \quad u_2 = 0, \quad (1.7)$$

is a special steady solution to (1.6), which is called the classical Hartmann profiles.

Without loss of generality, we assume $\bar{u} = 1$ here and in sequel.

By setting

$$u_1 = (1 - e^{-y}) + u, \quad u_2 = v, \quad (1.8)$$

we obtain

$$\begin{cases} \partial_t u + (1 - e^{-y} + u) \partial_x u + v \partial_y (-e^{-y} + u) = -u + \partial_y^2 u, \\ \partial_x u + \partial_y v = 0, \end{cases} \quad (1.9)$$

and initial and boundary conditions of u are given by

$$u_0(x, y) = u_{10}(x, y) - (1 - e^{-y}), \quad (1.10)$$

and

$$\begin{cases} u|_{y=0} = 0, \\ v|_{y=0} = 0. \end{cases} \quad (1.11)$$

Our main results can be stated as follows.

Theorem 1.1 *There exists a small constant $\delta_0 > 0$. Let the initial data $u_{10}(x, y)$ be a small perturbation around the Hartmann profile $\bar{u}(1 - e^{-y})$ with a Gevrey regularity radius $\tau_0 > 0$. Precisely speaking, the initial data (1.2) satisfies*

$$\|\partial_y u_{10} + u_{10} - \bar{u}\|_{X_{\tau_0, \alpha}^{r, \beta}} \leq \delta_0, \quad (1.12)$$

with $0 < \alpha < \sqrt{2}/2$ and $1 \leq \beta < \min\{(2r+1)/3, 2r-1\}, r > 1$. Then there exists a unique global solution (u_1, u_2) to the mixed Prandtl and Hartmann boundary layer equations (1.1)-(1.4), which is Gevrey regular for x variable, and belongs to a weighted H^1 space with respect to y variable.

Remark 1.1 *We will introduce the Gevrey regularity function spaces $X_{\tau_0, \alpha}^{r, \beta}$ and others in details in Subsection 2. It is necessary to explain the condition $1 \leq \beta < \min\{(2r+1)/3, 2r-1\}, r > 1$ a little more. That means that the regime of Gevrey regularity index β depends on the choice of parameter $r > 1$. Precisely speaking, the parameter r is more large, the value interval of index β is more large. In particular, if one takes $r > 1$ and $\beta = 1$, $X_{\tau_0, \alpha}^{r, 1}$ is exactly the weighted analytic function space. It shows that Theorem 1.12 also holds true for the weighted analytic function spaces. That is, the well-posedness of (1.1)-(1.4) in the analytic setting is a direct corollary of Theorem 1.12. In addition, the Gevrey regularity radius τ_0 and the small parameter δ_0 should satisfy the condition (3.19). When the initial Gevrey regularity radius τ_0 is fixed, then the condition (3.19) is guaranteed by choosing suitably small δ_0 .*

Remark 1.2 *It is not necessary to require the initial data u_{10} is the small perturbation around the given Hartmann profile $\bar{u}(1 - e^{-y})$. It can be taken any small Gevrey regularity initial data with suitable small far-field state \bar{u} . The main results in this paper still hold true.*

As is well-known that the Prandtl boundary layer is the leading order characteristic boundary layer for the incompressible Navier-Stokes equations with non-slip boundary condition in high Reynolds number case, which were first proposed to describe the structure of viscous high Reynolds number flows by Prandtl [25] in 1904. From that time on, such an important fluid dynamics model attracts much attention from mathematicians. Under the monotone assumption on the tangential velocity in the normal direction, Oleinik firstly obtained the local existence of classical solutions in the two spatial dimension by using the classical Crocco transformation, cf. [23]. This result together with some other extensions in this direction are presented in Oleinik-Samokhin's classical book [24]. Recently, this well-posedness result was re-proved by using an energy method in the framework of weighted Sobolev spaces in [1] and [21] independently. It is noted that all the above well-posedness results are achieved in the local time interval. By imposing an additional favorable pressure condition, a global in time weak solution was given by Xin and Zhang in [27].

Very recently, the lower bound of life-span for small analytic solution to the classical Prandtl equations with small perturbation analytic initial data was given by Zhang and Zhang in [28]. Precisely speaking, when the strength of background shear flow $(u_s(t, y), 0)$ is a size of $\varepsilon^{5/3}$, and the initial perturbation around such a shear flow is a size of ε , then the classical Prandtl system admits a unique analytic solution with the life-span being greater than $\varepsilon^{-4/3}$. Furthermore, when the initial data is chosen to a small perturbation around some given Gaussian function, the almost global existence for the Prandtl boundary layer equations is obtained by Ignatova and

Vicol in [13]. Where the cancellation methods developed in [21] and the monotonicity conditions of background solution are essentially used in [13].

When the monotonicity condition is violated, separation of the boundary layer is well expected and observed. For this, E-Engquist constructed a finite time blowup solution to the Prandtl equations in [5]. And this kind of blowup result is extended for the case of van Dommelen and Shen singularity in [15], where the outer Euler flows are periodic functions of sin and cos functions. In addition, when the background shear flow $u_s(t, y)$ has a non-degenerate critical point, that is, there exists a curve of $y = y(t)$ such that $\partial_y u(t, y(t)) = 0$ and $\partial_y^2 u(t, y(t)) \neq 0$. And the existence of such a curve is guaranteed by imposing the same conditions on initial data of $u(t, y)$. Then some interesting ill-posedness (or instability) phenomena of solutions to both the linear and nonlinear Prandtl equations around the shear flow are studied, cf. [6, 7, 11]. All these results show that the monotone assumption on the tangential velocity plays a key role for well-posedness except in the frameworks of analytic functions and Gevrey classes. For the data is analytic in terms of the space variables x, y , Sammartino and Caflisch [26, 3] established the local well-posedness result of the Prandtl system. Later, the analyticity requirement about the normal variable y was removed by Lombardo, Cannone and Sammartino in [20]. The main argument used in [20, 26] is to apply the abstract Cauchy-Kowalewskaya (CK) theorem. For Gevrey regularity solutions to Prandtl equations, one can refer to [8, 16] and references cited therein.

A natural question is that whether the global existence of smooth (or strong) solution can be achieved for the classical Prandtl equations in either analytic setting or Gevrey regularity function spaces. To our knowledge, this problem is still open up to now, even for the monotone data. It is believed that suitable magnetic field can stabilize the boundary layer in some physical regime [22, 2, 4, 10]. One can also refer to some very recent results in [9, 17, 18, 19] for the derivation of MHD boundary layer equations, stability analysis of magnetic field on the boundary layer from the mathematical point of view. Upon this consideration, we will establish the global existence of solutions to a mixed Prandtl and Hartmann MHD boundary layer equations in this paper. These results, together with those in [9, 17, 18], indeed show that the magnetic field has stability effect on boundary layers. One of the key point of this paper is that the effect of magnetic field boundary layer function behaves like a damping term in the classical Prandtl equations. By using the good properties of such a damping term, we can obtain the exponential decay of Gevrey regularity norms for solutions with respect to the time variable. Then the global Gevrey regularity solutions to the mixed Prandtl and Hartmann boundary layer equations near the classical Hartmann profile are proved. The proof depends on Gevrey class energy estimates with respect to tangential variable t .

Finally, the rest of the paper is organized as follows. We will reformulate the problem in a convenient form, introduce some weighted Gevrey regularity function spaces, and then give some preliminaries in Section 2. The uniform estimates of the solutions are established in Section 3, Based on these uniform estimates of solutions, the global existence and unique solutions to (1.1) are proved in Section 4.

In this paper the constant C , \bar{C} and C_0 are generic, which may change line by line..

2 Preliminary

To establish the global existence of solution to (1.9), we shall reformulate the problem in a convenient form. To this end, the vorticity of the velocity $\omega = \partial_y u$ are taken into consideration.

$$\partial_t \omega + (1 - e^{-y} + u) \partial_x \omega - v e^{-y} + v \partial_y \omega = -\omega + \partial_y^2 \omega. \quad (2.1)$$

Introduce

$$g = \omega + u \quad (2.2)$$

then one has

$$\partial_t g + (1 - e^{-y} + u) \partial_x g + v \partial_y g = -g + \partial_y^2 g. \quad (2.3)$$

The relationship between the new unknown function of g and u can be written as follows.

$$u = e^{-y} \int_0^y e^z g(t, x, z) dz. \quad (2.4)$$

It is easy to obtain the initial data of g in term of (2.2).

$$g(0, x, y) = \partial_y u_{10}(x, y) + u_{10}(x, y) - 1. \quad (2.5)$$

And the boundary condition of g is derived as follows.

It implies from (1.9) and (1.11) that

$$(\partial_y \omega - u)|_{y=0} = 0,$$

then by the definition of g in (2.2), one has

$$(\partial_y g - g)|_{y=0} = 0. \quad (2.6)$$

In the remainder of this paper, we shall establish the global existence of solutions to (2.3)-(2.6). Then, by the definition of u in (2.4), we indeed show the global existence of solutions to (1.9)-(1.11).

Below, we introduce the weighted Gevrey regularity function spaces used in this paper. Denote Gevrey class weights M_m given by

$$M_m = \frac{(m+1)^r}{(m!)^\beta}$$

for some $r > 1$ and $\beta \geq 1$. In particular, when $\beta = 1$, it corresponds to the analytic function class. Let

$$X_m = \|e^{\alpha y} \partial_x^m g\|_{L^2} \tau^m M_m, \quad (2.7)$$

$$Z_m = \|e^{\alpha y} \partial_y \partial_x^m g\|_{L^2} \tau^m M_m, \quad (2.8)$$

$$Y_m = \|e^{\alpha y} \partial_x^m g\|_{L^2} \tau^{m-1/2} m^{1/2} M_m, \quad (2.9)$$

$$D_m = \|e^{\alpha y} \partial_x^m g\|_{L_y^\infty L_x^2} \tau^m M_m, \quad (2.10)$$

and we define

$$\|g\|_{X_{\tau,\alpha}^{r,\beta}}^2 = \sum_{m \geq 0} X_m^2, \quad (2.11)$$

$$\|g\|_{Z_{\tau,\alpha}^{r,\beta}}^2 = \sum_{m \geq 0} Z_m^2, \quad (2.12)$$

$$\|g\|_{Y_{\tau,\alpha}^{r,\beta}}^2 = \sum_{m \geq 0} Y_m^2, \quad (2.13)$$

$$\|g\|_{D_{\tau,\alpha}^{r,\beta}}^2 = \sum_{m \geq 0} D_m^2. \quad (2.14)$$

Here τ denotes the Gevrey radius, which depends on the time variable t with initial data $\tau_0 > 0$. We write $g \in X_{\tau,\alpha}^{r,\beta}$ if $\|g\|_{X_{\tau,\alpha}^{r,\beta}} < \infty$, and the definitions of $Z_{\tau,\alpha}^{r,\beta}$, $Y_{\tau,\alpha}^{r,\beta}$ and $D_{\tau,\alpha}^{r,\beta}$ are similar.

Remark 2.1 *Once the global uniform estimates of g is established, that is, $\|g\|_{X_{\tau,\alpha}^{r,\beta}} < \infty$, then it follows from (2.4) that $\|u\|_{X_{\tau,\alpha'}^{r,\beta}} < \infty$ and $\|u\|_{Z_{\tau,\alpha'}^{r,\beta}} < \infty$ with $0 \leq \alpha' < \alpha$. Moreover, $\|u\|_{D_{\tau,\alpha}^{r,\beta}} < \infty$.*

3 Uniform A Priori Energy Estimates

In this section, we shall derive the uniform estimates of solutions to (2.3)-(2.6) in Gevrey regularity norms through energy estimate methods.

Applying the operator ∂_x^m on the equation (2.3), multiplying the resulting equation by $e^{2\alpha y} \partial_x^m g$, and integrating it over \mathbb{R}_+^2 lead to

$$\int_{\mathbb{R}_+^2} \partial_x^m (\partial_t g + (1 - e^{-y} + u) \partial_x g + v \partial_y g + g - \partial_y^2 g) e^{2\alpha y} \partial_x^m g dx dy = 0 \quad (3.1)$$

We will estimate each term below. It is obvious to obtain

$$\int_{\mathbb{R}_+^2} \partial_x^m \partial_t g e^{2\alpha y} \partial_x^m g dx dy = \frac{1}{2} \frac{d}{dt} \|e^{\alpha y} \partial_x^m g\|_{L^2}^2 \quad (3.2)$$

and

$$\int_{\mathbb{R}_+^2} \partial_x^m g e^{2\alpha y} \partial_x^m g dx dy = \|e^{\alpha y} \partial_x^m g\|_{L^2}^2. \quad (3.3)$$

Integration by parts leads to

$$\begin{aligned} & - \int_{\mathbb{R}_+^2} \partial_y^2 \partial_x^m g e^{2\alpha y} \partial_x^m g dx dy \\ &= \int_{\mathbb{R}} \partial_y \partial_x^m g(t, x, 0) \partial_x^m g(t, x, 0) dx + \|e^{\alpha y} \partial_y \partial_x^m g\|_{L^2}^2 + 2\alpha \int_{\mathbb{R}_+^2} \partial_y \partial_x^m g e^{2\alpha y} \partial_x^m g dx dy \end{aligned}$$

$$\begin{aligned}
&= \|\partial_x^m g(t, x, 0)\|_{L_x^2}^2 + \|e^{\alpha y} \partial_y \partial_x^m g\|_{L^2}^2 - \alpha \|\partial_x^m g(t, x, 0)\|_{L_x^2}^2 - 2\alpha^2 \|e^{\alpha y} \partial_x^m g\|_{L^2}^2 \\
&= (1 - \alpha) \|\partial_x^m g(t, x, 0)\|_{L_x^2}^2 + \|e^{\alpha y} \partial_y \partial_x^m g\|_{L^2}^2 - 2\alpha^2 \|e^{\alpha y} \partial_x^m g\|_{L^2}^2,
\end{aligned} \tag{3.4}$$

where in the second equality, we used the boundary condition (2.6). Below, we will estimate the two mixed nonlinear terms in (3.1). First,

$$\begin{aligned}
&\int_{\mathbb{R}_+^2} \partial_x^m ((1 - e^{-y} + u) \partial_x g) e^{2\alpha y} \partial_x^m g dx dy \\
&= \sum_{j=0}^m \binom{m}{j} \int_{\mathbb{R}_+^2} \partial_x^{m-j} u \partial_x^{j+1} g e^{2\alpha y} \partial_x^m g dx dy \\
&\triangleq R_1,
\end{aligned}$$

and

$$\begin{aligned}
|R_1| &\leq \sum_{j=0}^{\lfloor m/2 \rfloor} \binom{m}{j} \|\partial_x^{m-j} u\|_{L_x^2 L_y^\infty} \|e^{\alpha y} \partial_x^{j+1} g\|_{L_x^\infty L_y^2} \|e^{\alpha y} \partial_x^m g\|_{L^2} \\
&\quad + \sum_{j=\lfloor m/2 \rfloor + 1}^m \binom{m}{j} \|\partial_x^{m-j} u\|_{L_{xy}^\infty} \|e^{\alpha y} \partial_x^{j+1} g\|_{L^2} \|e^{\alpha y} \partial_x^m g\|_{L^2}.
\end{aligned}$$

For $0 \leq j \leq \lfloor m/2 \rfloor$, by (2.4), one has

$$\begin{aligned}
&\|\partial_x^{m-j} u\|_{L_x^2 L_y^\infty} = \|\partial_x^{m-j} \int_0^y e^{-(y-z)} g(t, x, z) dz\|_{L_x^2 L_y^\infty} \\
&\leq \|e^{\alpha y} \partial_x^{m-j} \int_0^y e^{-(y-z)} g(t, x, z) e^{\alpha z} e^{-\alpha z} dz\|_{L_x^2 L_y^\infty} \\
&= \|\int_0^y e^{-(1-\alpha)(y-z)} \partial_x^{m-j} g(t, x, z) e^{\alpha z} dz\|_{L_x^2 L_y^\infty} \\
&\leq C \|e^{\alpha y} \partial_x^{m-j} g\|_{L^2},
\end{aligned}$$

provided that $\alpha < 1$.

Using the Agmon inequality gives that

$$\|e^{\alpha y} \partial_x^{j+1} g\|_{L_x^\infty L_y^2} \leq C \|e^{\alpha y} \partial_x^{j+1} g\|_{L^2}^{1/2} \|e^{\alpha y} \partial_x^{j+2} g\|_{L^2}^{1/2}.$$

For $\lfloor m/2 \rfloor + 1 \leq j \leq m$,

$$\begin{aligned}
&\|\partial_x^{m-j} u\|_{L_{xy}^\infty} \\
&= \|\partial_x^{m-j} \int_0^y e^{-(y-z)} g(t, x, z) dz\|_{L_{xy}^\infty} \\
&\leq \|e^{\alpha y} \partial_x^{m-j} \int_0^y e^{-(y-z)} g(t, x, z) e^{\alpha z} e^{-\alpha z} dz\|_{L_{xy}^\infty} \\
&= \|\int_0^y e^{-(1-\alpha)(y-z)} \partial_x^{m-j} g(t, x, z) e^{\alpha z} dz\|_{L_{xy}^\infty}
\end{aligned}$$

$$\begin{aligned}
&\leq C \|e^{\alpha y} \partial_x^{m-j} g\|_{L_y^2 L_x^\infty}, \\
&\leq C \|e^{\alpha y} \partial_x^{m-j} g\|_{L^2}^{1/2} \|e^{\alpha y} \partial_x^{m-j+1} g\|_{L^2}^{1/2}.
\end{aligned}$$

Consequently

$$\begin{aligned}
&\sum_{m \geq 0} |R_1| \tau^{2m} M_m^2 \\
&\leq \frac{C}{(\tau(t))^{1/2}} \left\{ \sum_{m \geq 0} \sum_{j=0}^{[m/2]} X_{m-j} Y_{j+1}^{1/2} Y_{j+2}^{1/2} Y_m \frac{\binom{m}{j} M_m}{M_{m-j} M_{j+1}^{1/2} M_{j+2}^{1/2} (j+1)^{1/4} (j+2)^{1/4} m^{1/2}} \right. \\
&\quad \left. + \sum_{m \geq 0} \sum_{j=[m/2]+1}^m X_{m-j}^{1/2} X_{m-j+1}^{1/2} Y_{j+1} Y_m \frac{\binom{m}{j} M_m}{M_{m-j}^{1/2} M_{m-j+1}^{1/2} M_{j+1} (j+1)^{1/2} m^{1/2}} \right\}. \tag{3.5}
\end{aligned}$$

And the second nonlinear term is estimated as follows.

$$\begin{aligned}
&\int_{\mathbb{R}_+^2} \partial_x^m (v \partial_y g) e^{2\alpha y} \partial_x^m g dx dy \\
&= \sum_{j=0}^m \binom{m}{j} \int_{\mathbb{R}_+^2} \partial_x^{m-j} v \partial_x^j \partial_y g e^{2\alpha y} \partial_x^m g dx dy \\
&\triangleq R_2
\end{aligned}$$

and

$$\begin{aligned}
|R_2| &\leq \sum_{j=0}^{[m/2]} \binom{m}{j} \|\partial_x^{m-j} v\|_{L_x^2 L_y^\infty} \|e^{\alpha y} \partial_x^j \partial_y g\|_{L_x^\infty L_y^2} \|e^{\alpha y} \partial_x^m g\|_{L^2} \\
&\quad + \sum_{j=[m/2]+1}^m \binom{m}{j} \|\partial_x^{m-j} v\|_{L_{xy}^\infty} \|e^{\alpha y} \partial_x^j \partial_y g\|_{L^2} \|e^{\alpha y} \partial_x^m g\|_{L^2}.
\end{aligned}$$

For $0 \leq j \leq [m/2]$,

$$\begin{aligned}
\|\partial_x^{m-j} v\|_{L_x^2 L_y^\infty} &= \left\| \int_0^y (e^{-z} \int_0^z e^s \partial_x^{m-j+1} g(t, x, s) ds) dz \right\|_{L_x^2 L_y^\infty} \\
&= \left\| \int_0^y e^{-\alpha z} \left(\int_0^z e^{(1-\alpha)(s-z)} \partial_x^{m-j+1} g(t, x, s) e^{\alpha s} ds \right) dz \right\|_{L_x^2 L_y^\infty} \\
&\leq C \|e^{\alpha y} \partial_x^{m-j+1} g\|_{L^2}
\end{aligned}$$

here the fact that $0 < \alpha < 1$ is also used. And

$$\|e^{\alpha y} \partial_x^j \partial_y g\|_{L_x^\infty L_y^2} \leq C \|e^{\alpha y} \partial_x^j \partial_y g\|_{L^2}^{1/2} \|e^{\alpha y} \partial_x^{j+1} \partial_y g\|_{L^2}^{1/2}.$$

For $[m/2] + 1 \leq j \leq m$,

$$\begin{aligned} \|\partial_x^{m-j} v\|_{L^\infty} &= \left\| \int_0^y (e^{-z} \int_0^z e^s \partial_x^{m-j+1} g(t, x, s) ds) dz \right\|_{L^\infty} \\ &= \left\| \int_0^y e^{-\alpha z} \left(\int_0^z e^{(1-\alpha)(s-z)} \partial_x^{m-j+1} g(t, x, s) e^{\alpha s} ds \right) dz \right\|_{L^\infty} \\ &\leq C \|e^{\alpha y} \partial_x^{m-j+1} g\|_{L^2}^{1/2} \|e^{\alpha y} \partial_x^{m-j+2} g\|_{L^2}^{1/2}. \end{aligned}$$

Consequently

$$\begin{aligned} &\sum_{m \geq 0} |R_2| \tau^{2m} M_m^2 \\ &\leq \frac{C}{(\tau(t))^{1/2}} \left\{ \sum_{m \geq 0} \sum_{j=0}^{[m/2]} Y_{m-j+1} Z_j^{1/2} Z_{j+1}^{1/2} Y_m \frac{\binom{m}{j} M_m}{M_{m-j+1} M_j^{1/2} M_{j+1}^{1/2} (m-j+1)^{1/2} m^{1/2}} \right. \\ &\quad \left. + \sum_{m \geq 0} \sum_{j=[m/2]+1}^m Y_{m-j+1}^{1/2} Y_{m-j+2}^{1/2} Z_j Y_m \frac{\binom{m}{j} M_m}{M_{m-j+1}^{1/2} M_{m-j+2}^{1/2} M_j (m-j+1)^{1/4} (m-j+2)^{1/4} m^{1/2}} \right\}. \end{aligned} \quad (3.6)$$

Combining the above estimates and using the definitions of $X_{\tau, \alpha}$, $Z_{\tau, \alpha}$ and $Y_{\tau, \alpha}$ yield that

$$\begin{aligned} &\frac{1}{2} \frac{d}{dt} \|g\|_{X_{\tau, \alpha}}^2 - \dot{\tau} \|g\|_{Y_{\tau, \alpha}}^2 + \|g\|_{Z_{\tau, \alpha}}^2 + (1 - 2\alpha^2) \|g\|_{X_{\tau, \alpha}}^2 + (1 - \alpha) \|g(t, x, 0)\|_{X_{\tau, \alpha}}^2 \\ &\leq \sum_{m \geq 0} |R_1| \tau^{2m} M_m^2 + \sum_{m \geq 0} |R_2| \tau^{2m} M_m^2 \end{aligned} \quad (3.7)$$

Since

$$\begin{aligned} &\frac{\binom{m}{j} M_m}{M_{m-j} M_{j+1}^{1/2} M_{j+2}^{1/2} (j+1)^{1/4} (j+2)^{1/4} m^{1/2}} \\ &= \frac{((m-j)!)^{\beta-1} (j!)^{\beta-1} (m+1)^r (j+1)^\beta (j+2)^{\beta/2}}{(m!)^{\beta-1} (m-j+1)^r (j+2)^{r/2} (j+3)^{r/2} (j+1)^{1/4} (j+2)^{1/4} m^{1/2}} \\ &\leq C(1+j)^{3\beta/2-r-1} \end{aligned} \quad (3.8)$$

for all $0 \leq j \leq [m/2]$. In the last inequality, we used that $(p!q!)^{\beta-1} \leq ((p+q)!)^{\beta-1}$. Then,

$$\begin{aligned} &\frac{\binom{m}{j} M_m}{M_{m-j}^{1/2} M_{m-j+1}^{1/2} M_{j+1} (j+1)^{1/2} m^{1/2}} \\ &= \frac{((m-j)!)^{\beta-1} ((j+1)!)^{\beta-1} (m+1)^r (m-j+1)^{\beta/2} (j+1)}{(m!)^{\beta-1} (m-j+1)^{r/2} (m-j+2)^{r/2} (j+2)^r (j+1)^{1/2} m^{1/2}} \end{aligned}$$

$$\leq C(m-j+1)^{\beta/2-r} \quad (3.9)$$

In the last inequality, we used that $((p+1)q!)^{\beta-1} \leq C((p+q)!)^{\beta-1}$.
Consequently

$$\begin{aligned} \sum_{m \geq 0} |R_1| \tau^{2m} M_m^2 &\leq \frac{C}{(\tau(t))^{1/2}} \left\{ \sum_{m \geq 0} \sum_{j=0}^{[m/2]} X_{m-j} Y_{j+1}^{1/2} Y_{j+2}^{1/2} Y_m (1+j)^{3\beta/2-r-1} \right. \\ &\quad \left. + \sum_{m \geq 0} \sum_{j=[m/2]+1}^m X_{m-j}^{1/2} X_{m-j+1}^{1/2} Y_{j+1} Y_m (m-j+1)^{\beta/2-r} \right\} \\ &\leq \frac{C}{(\tau(t))^{1/2}} \|g\|_{X_{\tau,\alpha}^{r,\beta}} \|g\|_{Y_{\tau,\alpha}^{r,\beta}}^2 \end{aligned} \quad (3.10)$$

In the last inequality, we used the following discrete Young inequality.

$$\|\zeta \cdot (\eta * \xi)\|_{l^1} \leq C \|\zeta\|_{l^2} \|\eta\|_{l^1} \|\xi\|_{l^2}$$

with $\zeta_k = Y_k$, $\eta_k = Y_k^{1/2} Y_{k+1}^{1/2} k^{3\beta/2-r-1}$, $\xi_k = X_k$ for the first term of the RHS in (3.10), and then the Hölder inequality is also used

$$\|\eta\|_{l^1} \leq C \|g\|_{Y_{\tau,\alpha}^{r,\beta}}$$

provided that $3\beta/2 - r - 1 < -1/2$. That is, $\beta < (2r+1)/3$. And $\zeta_k = Y_k$, $\eta_k = X_k^{1/2} X_{k+1}^{1/2} (k+1)^{\beta/2-r}$, $\xi_k = Y_{k+1}$ for the second term of the RHS in (3.10), then

$$\|\eta\|_{l^1} \leq C \|g\|_{X_{\tau,\alpha}^{r,\beta}}.$$

provided that $\beta/2 - r < -1/2$. That is, $\beta < 2r - 1$. In conclusion, (3.10) holds true, provided that

$$\beta < \min\{(2r+1)/3, 2r-1\}.$$

Similarly,

$$\begin{aligned} \sum_{m \geq 0} |R_2| \tau^{2m} M_m^2 &\leq \frac{C}{(\tau(t))^{1/2}} \left\{ \sum_{m \geq 0} \sum_{j=0}^{[m/2]} Y_{m-j+1} Z_j^{1/2} Z_{j+1}^{1/2} Y_m (1+j)^{\beta/2-r} \right. \\ &\quad \left. + \sum_{m \geq 0} \sum_{j=[m/2]+1}^m Y_{m-j+1}^{1/2} Y_{m-j+2}^{1/2} Z_j Y_m (m-j+1)^{3\beta/2-r-1} \right\} \\ &\leq \frac{C}{(\tau(t))^{1/2}} \|g\|_{Z_{\tau,\alpha}^{r,\beta}} \|g\|_{Y_{\tau,\alpha}^{r,\beta}}^2 \end{aligned} \quad (3.11)$$

provided that

$$\beta < \min\{(2r+1)/3, 2r-1\}.$$

It follows, from (3.7), (3.10) and (3.11), that

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \|g\|_{X_{\tau,\alpha}^{r,\beta}}^2 + \|g\|_{Z_{\tau,\alpha}^{r,\beta}}^2 + (1 - 2\alpha^2) \|g\|_{X_{\tau,\alpha}^{r,\beta}}^2 + (1 - \alpha) \|g(\cdot, 0)\|_{X_{\tau,\alpha}^{r,\beta}}^2 \\ & \leq \left(\dot{\tau} + \frac{C}{(\tau(t))^{1/2}} (\|g\|_{X_{\tau,\alpha}^{r,\beta}} + \|g\|_{Z_{\tau,\alpha}^{r,\beta}}) \right) \|g\|_{Y_{\tau,\alpha}^{r,\beta}}^2 \end{aligned} \quad (3.12)$$

Set

$$\dot{\tau} + \frac{C}{(\tau(t))^{1/2}} (\|g\|_{X_{\tau,\alpha}^{r,\beta}} + \|g\|_{Z_{\tau,\alpha}^{r,\beta}}) = 0 \quad (3.13)$$

Then we have

$$\frac{1}{2} \frac{d}{dt} \|g\|_{X_{\tau,\alpha}^{r,\beta}}^2 + \|g\|_{Z_{\tau,\alpha}^{r,\beta}}^2 + (1 - 2\alpha^2) \|g\|_{X_{\tau,\alpha}^{r,\beta}}^2 + (1 - \alpha) \|g(\cdot, 0)\|_{X_{\tau,\alpha}^{r,\beta}}^2 \leq 0 \quad (3.14)$$

When

$$0 < \alpha < \sqrt{2}/2,$$

the following differential inequality holds

$$\frac{1}{2} \frac{d}{dt} \|g\|_{X_{\tau,\alpha}^{r,\beta}}^2 + \|g\|_{Z_{\tau,\alpha}^{r,\beta}}^2 + (1 - 2\alpha^2) \|g\|_{X_{\tau,\alpha}^{r,\beta}}^2 \leq 0. \quad (3.15)$$

with $(1 - 2\alpha^2) > 0$.

It follows that

$$e^{2(1-2\alpha^2)t} \frac{d}{dt} \|g\|_{X_{\tau,\alpha}^{r,\beta}}^2 + 2e^{2(1-2\alpha^2)t} \|g\|_{Z_{\tau,\alpha}^{r,\beta}}^2 + 2(1 - 2\alpha^2) e^{2(1-2\alpha^2)t} \|g\|_{X_{\tau,\alpha}^{r,\beta}}^2 \leq 0 \quad (3.16)$$

which implies

$$e^{2(1-2\alpha^2)t} \|g\|_{X_{\tau,\alpha}^{r,\beta}}^2 + \int_0^t 2e^{2(1-2\alpha^2)s} \|g(s)\|_{Z_{\tau,\alpha}^{r,\beta}}^2 ds \leq \|g(0)\|_{X_{\tau,\alpha}^{r,\beta}}^2 \quad (3.17)$$

From the ordinary differential equation (4.1), one has

$$\begin{aligned} & \tau(t)^{3/2} - \tau_0^{3/2} \\ & = -C \int_0^t (\|g(s)\|_{X_{\tau,\alpha}^{r,\beta}} + \|g(s)\|_{Z_{\tau,\alpha}^{r,\beta}}) ds \\ & \geq -C \int_0^t \|g(0)\|_{X_{\tau_0,\alpha}^{r,\beta}} e^{-(1-2\alpha^2)s} ds - C \int_0^t \|g(s)\|_{Z_{\tau,\alpha}^{r,\beta}} e^{(1-2\alpha^2)s} e^{-(1-2\alpha^2)s} ds \\ & \geq -C_1 \|g(0)\|_{X_{\tau_0,\alpha}^{r,\beta}}. \end{aligned} \quad (3.18)$$

If one choose the initial perturbation data is small, such that

$$\frac{\tau_0}{2} > C_1^{2/3} \|g(0)\|_{X_{\tau_0,\alpha}^{r,\beta}}^{2/3}, \quad (3.19)$$

then (3.18) implies that

$$\tau(t) > \tau_0/2 \quad (3.20)$$

for all $t \geq 0$.

Consequently,

Proposition 3.1 *Under the same conditions stated in Theorem 1.1, suppose the g is the Gevrey regularity solution to (2.3)-(2.6), then the following estimates hold true.*

$$e^{2(1-2\alpha^2)t} \|g\|_{X_{\tau,\alpha}^{r,\beta}}^2 + \int_0^t 2e^{2(1-2\alpha^2)s} \|g(s)\|_{Z_{\tau,\alpha}^{r,\beta}}^2 ds \leq \|g(0)\|_{X_{\tau_0,\alpha}^{r,\beta}}^2 \quad (3.21)$$

with $\tau(t) > \tau_0/2$ for all $t \geq 0$.

4 The Proof of Theorem 1.1

Once the uniform estimates of solutions to (2.3)-(2.6) are achieved in Proposition 3.1, and the local existence of solutions in Gevrey regularity class can be done by the similar arguments as in [8, 16], then the global existence of solutions to (2.3)-(2.6) is proved. Moreover, by the relationship of (2.4), one can show the global existence of u to the initial-boundary value problem (1.9)-(1.11). In addition, according to Remark 2.1 and Proposition 3.1, it follows that $\|u\|_{X_{\tau,\alpha'}^{r,\beta}} + \|\partial_y u\|_{X_{\tau,\alpha'}^{r,\beta}} < \infty$ with $0 \leq \alpha' < \alpha$ and $\tau > \tau_0/2$. As a consequence, We finish the proof of global existence part in Theorem 1.1.

Below we will prove the uniqueness part in Theorem 1.1. It suffices to show the uniqueness of solutions to (2.3)-(2.6).

Assume there are two solutions g_1 and g_2 to (2.3)-(2.6) with the same initial data g_0 , which satisfies $\|g_0\|_{X_{\tau_0,\alpha}^{r,\beta}} \leq \delta_0$. And the radii of Gevrey regularity of g_1 and g_2 are $\tau_1(t)$ and $\tau_2(t)$, respectively.

Define $\tau(t)$ by

$$\dot{\tau} + \frac{C}{(\tau(t))^{1/2}} (\|g_1\|_{X_{\tau_1,\alpha}^{r,\beta}} + \|g_1\|_{Z_{\tau_1,\alpha}^{r,\beta}}) = 0 \quad (4.1)$$

with initial data

$$\tau(0) = \frac{\tau_0}{4}. \quad (4.2)$$

In view of the estimate in Section 3, there exists a time interval $[0, T]$, such that

$$\frac{\tau_0}{8} \leq \tau(t) \leq \frac{\tau_0}{4} \leq \frac{\min\{\tau_1(t), \tau_2(t)\}}{2} \quad (4.3)$$

for all $t \in [0, T]$.

We consider the equations of difference of solutions by setting $\bar{g} = g_1 - g_2$, one has

$$\partial_t \bar{g} + (1 - e^{-y} + u_1) \partial_x \bar{g} + (v_1 - v_2) \partial_y \bar{g} = -\bar{g} + \partial_y^2 \bar{g} + R, \quad (4.4)$$

with the source terms R being defined by

$$R = -(u_1 - u_2)\partial_x g_2 - v_2 \partial_y \bar{g}. \quad (4.5)$$

The initial data and the boundary conditions are thus given by

$$\bar{g}(t = 0, x, y) = 0, \quad (4.6)$$

and

$$(\partial_y \bar{g} - \bar{g})|_{y=0} = 0. \quad (4.7)$$

By the similar arguments as those in Section 3, we have

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \|g\|_{X_{\tau, \alpha}^{r, \beta}}^2 + \|g\|_{Z_{\tau, \alpha}^{r, \beta}}^2 + (1 - 2\alpha^2) \|g\|_{X_{\tau, \alpha}^{r, \beta}}^2 + (1 - \alpha) \|g(\cdot, 0)\|_{X_{\tau, \alpha}^{r, \beta}}^2 \\ & \leq (\dot{\tau} + \frac{C}{(\tau(t))^{1/2}} (\|g_1\|_{X_{\tau, \alpha}^{r, \beta}} + \|g_1\|_{Z_{\tau, \alpha}^{r, \beta}})) \|\bar{g}\|_{Y_{\tau, \alpha}^{r, \beta}}^2 + \frac{C_0}{(\tau(t))^{1/2}} \|g_2\|_{Y_{\tau, \alpha}^{r, \beta}} (\|\bar{g}\|_{X_{\tau, \alpha}^{r, \beta}}^2 + \|\bar{g}\|_{Z_{\tau, \alpha}^{r, \beta}}^2) \end{aligned} \quad (4.8)$$

From (4.1), we have

$$\dot{\tau} + \frac{C}{(\tau(t))^{1/2}} (\|g_1\|_{X_{\tau, \alpha}^{r, \beta}} + \|g_1\|_{Z_{\tau, \alpha}^{r, \beta}}) \leq 0, \quad (4.9)$$

due to the facts that $\tau(t) \leq \tau_1(t)$ and the $X_{\tau, \alpha}^{r, \beta}$ and $Z_{\tau, \alpha}^{r, \beta}$ norms are increasing with respect to τ . Moreover,

$$\begin{aligned} \frac{C_0}{(\tau(t))^{1/2}} \|g_2\|_{Y_{\tau, \alpha}^{r, \beta}} & \leq \frac{C}{\tau} \|g_2\|_{X_{2\tau, \alpha}^{r, \beta}} \leq \frac{C}{\tau} \|g_2\|_{X_{\tau_2, \alpha}^{r, \beta}} \\ & \leq \frac{2C}{\tau_0} \|g(0)\|_{X_{\tau_0, \alpha}^{r, \beta}} e^{-2(1-2\alpha^2)t} \\ & \leq \bar{C} \delta_0^{1/3}. \end{aligned} \quad (4.10)$$

In the second inequality, $2\tau \leq \tau_2$. In the third inequality, (3.19) and (3.21) are used.

Since δ_0 is suitably small, it follows, from (4.8)-(4.10), that

$$\frac{d}{dt} \|\bar{g}\|_{X_{\tau, \alpha}^{r, \beta}}^2 \leq C \|\bar{g}\|_{X_{\tau, \alpha}^{r, \beta}}^2 \quad (4.11)$$

It implies uniqueness of solutions to (2.3) due to $\bar{g} = 0$ in whole time interval $[0, T]$.

Then by the continuous argument, we conclude the proof of uniqueness of solutions for all $t > 0$ in Theorem 1.1.

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